



GRAPH COVERAGE OVERVIEW

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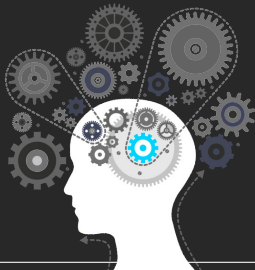
"All software is a graph" – Anonymous

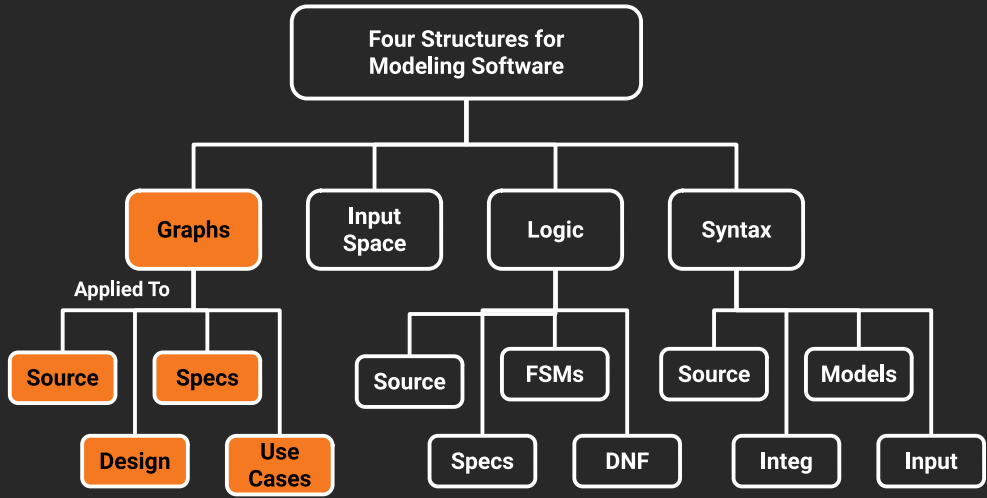
Outcomes



After today's lecture you will be able to:

- Understand the basic concepts of graph coverage
- Understand def, use, and du pairs
- Evaluate a given graph for graph coverage criteria





- Graphs are the most **commonly** used structure for testing
- Graphs can come from **many sources**
 - Control flow graphs
 - Design structure
 - FSMs and statecharts
 - Use cases
- Tests usually are intended to “**cover**” the graph in some way

Definition of a Graph



- A set N of **nodes**, N is not empty
- A set N_0 of **initial nodes**, N_0 is not empty
- A set N_f of **final nodes**, N_f is not empty
- A set E of **edges**, each edge from one node to another
 - (n_i, n_j) , i is **predecessor**, j is **successor**

Is this a
graph?



$$N_0 = \{1\}$$

$$N_f = \{1\}$$

$$E = \{\}$$



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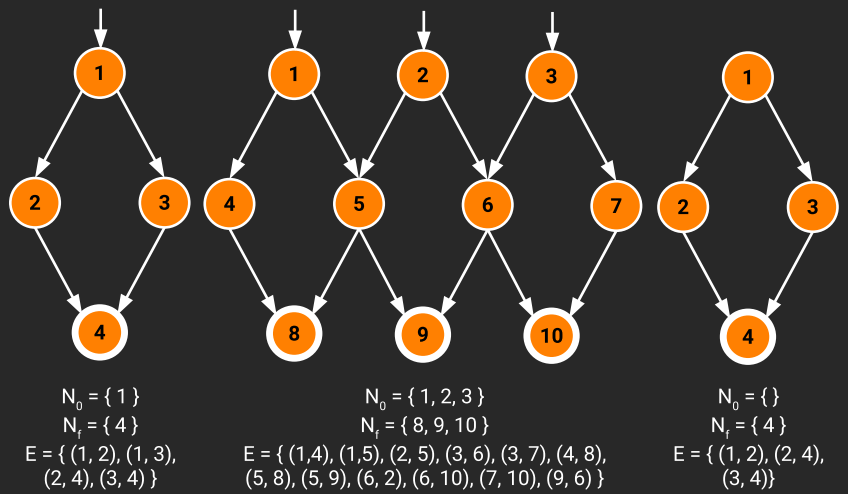
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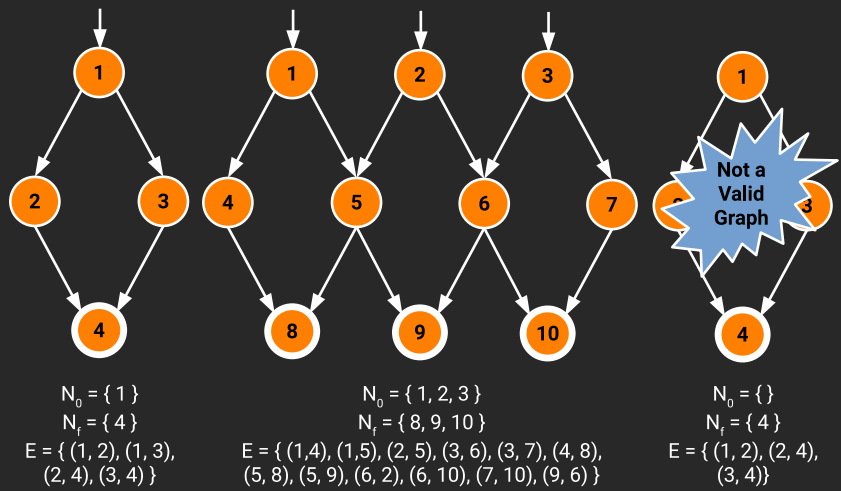
$$E = \{\}$$

Yes!

Example Graphs



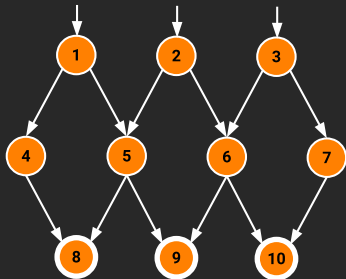
Example Graphs



Paths in Graphs



- **Path:** A sequence of nodes - $[n_1, n_2, \dots, n_M]$
 - Each pair of nodes is an edge
- **Length:** The number of edges
 - A single node is a path of length 0
- **Subpath:** A subsequence of nodes in p is a subpath of p

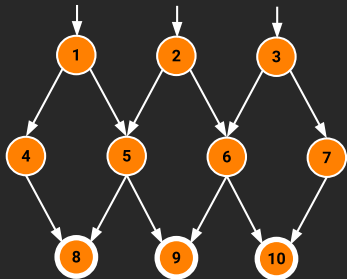


Write down three paths in this graph

Paths in Graphs



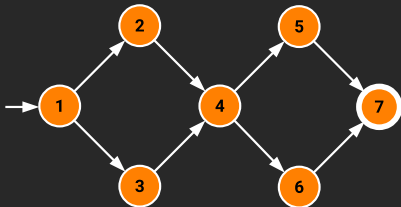
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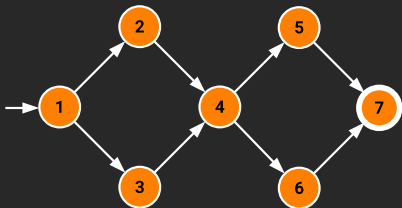
- $[1, 4, 8]$
- $[2, 5, 9]$
- $[3, 7, 10]$

- **Test Path:** A path that starts at an initial node and ends at a final node
- Test paths represent execution of test cases
 - Some test paths can be executed by many tests
 - Some test paths cannot be executed by any tests
- **SESE graphs:** All test paths start at a single node and end at another node
 - Single-entry, Single-exit
 - N_0 and N_f have exactly one node



Write down all the test paths in this graph

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Double-diamond Graph

Four Test paths

1. [1, 2, 4, 5, 7]
2. [1, 2, 4, 6, 7]
3. [1, 3, 4, 5, 7]
4. [1, 3, 4, 6, 7]

- **Visit**
 - A test path p **visits** node n , if n is in p
 - A test path p **visits** edge e , if e is in p
- **Tour**: A test path p **tours** subpath q , if q is a subpath of p

Test Path: [1, 2, 4, 5, 7]

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- **Visits Edges?**
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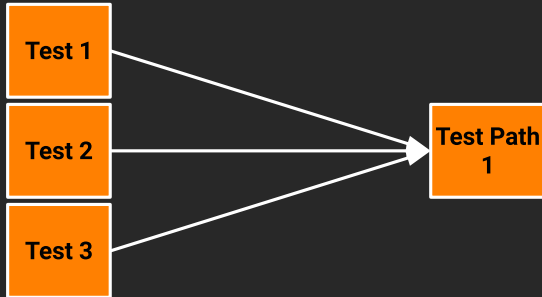
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- **Visits Nodes?** 1, 2, 4, 5, 7
- **Visits Edges?** (1,2), (2,4), (4,5), (5,7)
- **Tours subpaths?** [1,2,4], [2,4,5], [4,5,7], [1,2,4,5], [2,4,5,7], [1,2,4,5,7]

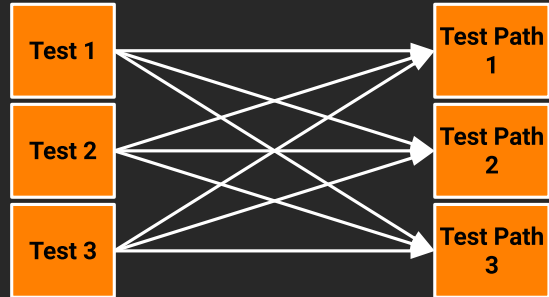
(Also, each edge is technically a subpath)

- **path (t)**: The test path executed by test t
- **path (T)**: The set of test paths executed by the set of tests T
- Each test executes **one and only one** test path
 - Complete execution from a start node to a final node
- A location in a graph (node or edge) can be **reached** from another location if there is a sequence of edges from the first location to the second
 - **Syntactic** reach: A subpath exists in the graph
 - **Semantic** reach: A test exists that can execute that subpath
 - This distinction becomes important in **section 7.3**

Tests and Test Paths



Deterministic software – test always executes the same test path



Non-deterministic software – the same test can execute different test paths

- We use graphs in testing as follows:
 - Develop a model of the software as a graph
 - Require tests to visit or tour specific sets of nodes, edges or subpaths
- **Test Requirements (TR):** Describe properties of test paths
- **Test Criterion:** Rules that define test requirements
- **Satisfaction:** Given a set TR of test requirements for a criterion C , a set of tests T satisfies C on a graph if and only if for every test requirement in TR , there is a test path in $path(T)$ that meets the test requirement tr
- **Structural Coverage Criteria:** Defined on a graph just in terms of nodes and edges.

- The first (and simplest) two criteria require that each node and edge in a graph be executed

Node Coverage (NC): Test set T satisfies node coverage on graph G iff for every syntactically reachable node n in N , there is some path p in $path(T)$ such that p visits n .

- This statement is a bit cumbersome, so we abbreviate it in terms of the set of test requirements

Node Coverage (NC): TR contains each reachable node in G .

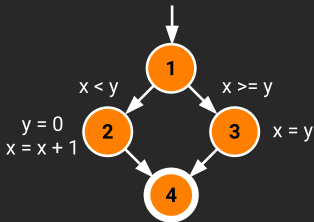
Node and Edge Coverage



- Edge coverage is slightly stronger than node coverage

Edge Coverage (EC): *TR* contains each reachable path of length up to 1, inclusive, in *G*.

- The phrase “*length up to 1*” allows for graphs with one node and no edges.
- NC and EC are only different when there is an edge and another subpath between a pair of nodes (as in an “if-else” statement)



Node Coverage

- *TR*? =
- Test Paths =

Edge Coverage

- *TR*? =
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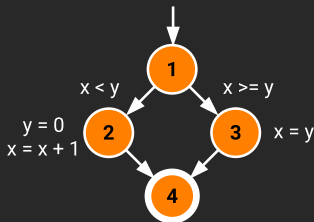
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Node Coverage

- $TR? = \{1, 2, 3, 4\}$
- Test Paths = $[1, 2, 4] [1, 3, 4]$

Edge Coverage

- $TR? = \{(1, 2), (1, 3), (2, 4), (3, 4)\}$
- Test Paths = $[1, 2, 4] [1, 3, 4]$

Paths of Length 1 and 0



- A graph with **only one node** will not have any edges



- It may seem trivial, but formally, Edge Coverage needs to require Node Coverage on this graph
- Otherwise, Edge Coverage will not subsume Node Coverage
 - So we define “**length up to 1**” instead of simply “length 1”
- We have the same issue with graphs that only have **one edge**
 - for Edge-Pair Coverage ...



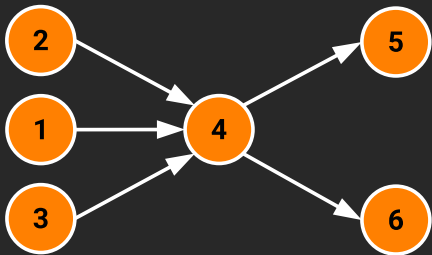
Covering Multiple Edges



- Edge-pair coverage requires **pairs of edges**, or subpaths of length 2 Edge-Pair Coverage (EPC): TR contains each reachable path of length up to 2, inclusive, in G .
- The phrase “**length up to 2**” is used to include graphs that have less than 2 edges

Edge-Pair Coverage:

- $TR = ?$

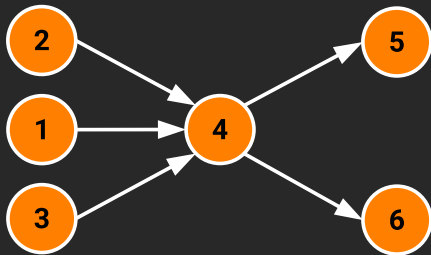


- The logical extension is to require **all paths** ...

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Edge-Pair Coverage:

- $TR = \{[1,4,5], [1,4,6], [2,4,5], [2,4,6], [3,4,5], [3,4,6]\}$

- The logical extension is to require **all paths** ...

Covering Multiple Edges

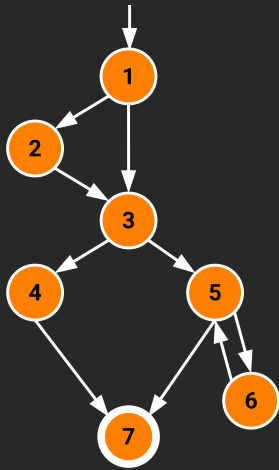


Complete Path Coverage (CPC): TR contains all paths in G .

Unfortunately, this is **impossible** if the graph has a loop, so a weak compromise makes the tester decide which paths;

Specified Path Coverage (SPC): TR contains a set S of test paths, where S is supplied as a parameter.

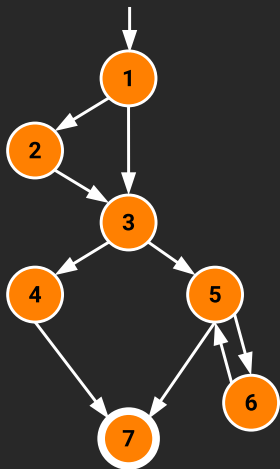
Structural Coverage Example



Write down the TRs and
Test paths for these criteria:

- Node Coverage
- Edge Coverage
- Edge-Pair Coverage
- Complete Path Coverage

Structural Coverage Example



- **Node Coverage**

TR = {1, 2, 3, 4, 5, 6, 7}

Test Paths: [1,2,3,4,7] [1,2,3,5,6,5,7]

- **Edge Coverage**

TR = {(1,2), (1,3), (2,3), (3,4), (3,5), (4,7), (5,6), (5,7), (6,5)}

Test Paths: [1,2,3,4,7] [1,3,5,6,5,7]

- **Edge-Pair Coverage**

TR = {[1,2,3], [1,3,4], [1,3,5], [2,3,4], [2,3,5], [3,4,7], [3,5,6], [3,5,7], [5,6,5], [6,5,6], [6,5,7]}

Test Paths: [1,2,3,4,7] [1,2,3,5,7] [1,3,4,7] [1,3,5,6,5,6,5,7]

- **Complete Path Coverage**

Test Paths: [1,2,3,4,7] [1,2,3,5,7] [1,2,3,5,7] [1,2,3,5,6,5,7] [1,2,3,5,6,5,6,5,7]

[1,2,3,5,6,5,6,5,6,5,7] ...

- If a graph contains a loop, it has an **infinite** number of paths
- Thus, CPC is **not feasible**
- SPC is not satisfactory because the results are **subjective** and vary with the tester
- Attempts to “deal with” **loops**:
 - **1970s**: Execute cycles once ([4,5,4] in previous example, informal)
 - **1980s**: Execute each loop, exactly once (formalized)
 - **1990s**: Execute loops 0 times, once, more than once (informal description)
 - **2000s**: Prime paths (touring, sidetrips, and detours)

For Next Time



Idaho State
University

Computer
Science

- Review the Reading
- Review this Lecture
- Come to Class





Are there any questions?