1. Metric spaces

1.1. Metrics

- **Definition**: **metric space** is (X, d), X is set, $d: X \times X \to [0, \infty)$ is **metric** satisfying:
 - $d(x,y) = 0 \iff x = y$
 - Symmetry: d(x,y) = d(y,x)
 - Triangle inequality: $d(x,y) \le d(x,z) + d(z,y)$
- Example:
 - p-adic metric: for $p \in [1, \infty)$

$$d_p(x,y) = \left(\sum_{i=1}^n \lvert x_i - y_i \rvert^p\right)^{\frac{1}{p}}$$

• Extension of the p-adic metric:

$$d_{\infty}(x,y) = \max\{|x_i - y_i| : i \in [n]\}$$

• Metric of C([a,b]):

$$d(f,g) = \sup\{|f(x) - g(x)| : x \in [a,b]\}$$

• Discrete metric:

$$d(x,y) = \begin{cases} 0 & \text{if } x = y \\ 1 & \text{if } x \neq y \end{cases}$$

• Definition: open ball of radius *r* around *x*:

$$B(x;r) := \{ y \in X : d(x,y) < r \}$$

• Definition: closed ball of radius r around x:

$$D(x;r)\coloneqq\{y\in X:d(x,y)\leq r\}$$

1.2. Open and closed sets

• **Definition**: $U \subseteq X$ is **open** if

$$\forall x \in U, \exists \varepsilon > 0 : B(x; \varepsilon) \subset U$$

- **Definition**: $A \subseteq X$ is **closed** if X A is open.
- Sets can be neither closed nor open, or both.
- With standard metric on \mathbb{R} , any singleton $\{x\} \in \mathbb{R}$ is closed and not open (same holds for \mathbb{R}^n).
- **Definition**: let X be metric space, $x \in N \subseteq X$. N is **neighbourhood** of x if

$$\exists$$
 open $V \subseteq X : x \in V \subseteq N$

- Corollary: let $x \in X$, then $N \subseteq X$ neighbourhood of x iff $\exists \varepsilon > 0 : x \in B(x; \varepsilon) \subseteq N$.
- **Proposition**: open balls are open, closed balls are closed.
- Lemma: let (X, d) metric space.
 - X and \emptyset are both open and closed.

- Arbitrary unions of open sets are open.
- Finite intersections of open sets are open.
- Finite unions of closed sets are closed.
- Arbitrary intersections of closed sets are closed.
- Example: if X has discrete metric, any $A \subseteq X$ is open and closed.

1.3. Continuity

- Definition:
 - Sequence in X is $a : \mathbb{N}_0 \to X$, written $(a_n)_{n \in \mathbb{N}}$.
 - (a_n) converges to a, $\lim_{n\to\infty} a_n = a$, if

$$\forall \varepsilon > 0, \exists n_0 \in \mathbb{N} : \forall n \ge n_0, d(a, a_n) < \varepsilon$$

- **Proposition**: let X, Y metric spaces, $a \in X, f : X \to Y$. The following are equivalent:
 - $\forall \varepsilon > 0, \exists \delta > 0 : \forall x \in X, d_X(a, x) < \delta \Longrightarrow d_Y(f(a), f(x)) < \varepsilon.$
 - For every sequence (a_n) in X with $a_n \to a$, $f(a_n) \to f(a)$.
 - For every open $U \subseteq Y$ with $f(a) \in U$, $f^{-1}(U)$ is a neighbourhood of a.

If f satisfies these, it is **continuous at** a.

- **Definition**: f continuous if continuous at every $a \in X$.
- **Proposition**: $f: X \to Y$ continuous iff $f^{-1}(U)$ open for every open $U \subseteq Y$.
- Example: let d be discrete metric, d_2 be 2-adic metric.
 - Any $f:(X,d)\to(\mathbb{R},d_2)$ is continuous.
 - id : $(\mathbb{R}, d_2) \to (\mathbb{R}, d)$ is not continuous.

2. Topological spaces

2.1. Topologies

- Definition: power set of X: $\mathcal{P}(X) \coloneqq \{A : A \subseteq X\}$.
- **Definition**: **topology** on set X is $\tau \subseteq \mathcal{P}(X)$ with:
 - $\emptyset \in \tau, X \in \tau$.
 - Closure under arbitrary unions: if $\forall i \in I, U_i \in \tau$, then

$$\bigcup_{i\in I} U_i \in \tau$$

• Closure under finite intersections: $U_1, U_2 \in \tau \Longrightarrow U_1 \cap U_2 \in \tau$ (this is equivalent to $U_1, ..., U_n \in \tau \Longrightarrow \bigcap_{i \in [n]} U_i \in \tau$).

 (X, τ) is **topological space**. Elements of τ are **open** subsets of X. $A \subseteq X$ **closed** if X - A is open.

- **Definition**: $\tau = \mathcal{P}(X)$ is the **discrete topology** on X.
- **Definition**: $\tau = \{\emptyset, X\}$ is the **indiscrete topology** on X.
- Example:
 - For metric space (M, d), let τ_d exactly contain sets which are open with respect to d. Then (M, τ_d) is a topological space. d induces topology τ_d .

- Let $X = \mathbb{N}_0$ and $\tau = \{\emptyset\} \cup \{U \subseteq X : X U \text{ is finite}\}$, then (X, τ) is topological space.
- **Proposition**: for topological space *X*:
 - X and \emptyset are closed
 - Arbitrary intersections of closed sets are closed
 - Finite unions of closed sets are closed
- Proposition: for topological space (X, τ) and $A \subseteq X$, the induced (subspace) topology on A

$$\tau_A = \{ A \cap U : U \in \tau \}$$

is a topology on A.

- **Example**: let $X = \mathbb{R}$ with standard topology induced by metric d(x, y) = |x y|. Let A = [1, 5]. Then $[1, 3) = A \cap (0, 3)$ and $[1, 5] = A \cap (0, 6)$ are open in A.
- **Example**: consider \mathbb{R} with standard topology τ . Then
 - $\tau_{\mathbb{Z}}$ is the discrete topology on \mathbb{Z} .
 - $\tau_{\mathbb{Q}}$ is not the discrete topology on \mathbb{Q} .
- **Proposition**: metrics d_p for $p \in [1, \infty)$ and d_∞ all induce same topology on \mathbb{R}^n , alled the **standard topology** on \mathbb{R}^n .
- **Definition**: (X, τ) is **Hausdorff** if

$$\forall x \neq y \in X, \exists U, V \in \tau : U \cap V = \emptyset \land x \in U, y \in V$$

- Lemma: any metric space (M, d) with topology induced by d is Hausdorff.
- **Example**: let $|X| \ge 2$ with indiscrete topology. Then X is not Hausdorff, since $\tau = \{X, \emptyset\}$ and if $x \ne y \in X$, only open set containing x is X (same for y). But $X \cap X = X \ne \emptyset$.
- Definition: Furstenberg's topology on \mathbb{Z} : define $U \subseteq \mathbb{Z}$ to be open if

$$\forall a \in U, \exists 0 \neq d \in \mathbb{Z} : a + d\mathbb{Z} := \{a + dn : n \in \mathbb{Z}\} \subseteq U$$

• Furstenberg's topology is Hausdorff.

2.2. Continuity

- **Definition**: let X, Y topological spaces.
 - $f: X \to Y$ is **continuous** if

$$\forall V$$
 open in $Y, f^{-1}(V)$ open in X

• f is continuous at $a \in X$ if

 $\forall V \text{ open in } Y \text{ with } f(a) \in V, \exists U \text{ open in } X : a \in U \subseteq f^{-1}(V)$

- Lemma: $f: X \to Y$ continuous iff f continuous at every $a \in X$. (Key idea for proof: $\bigcup_{a \in f^{-1}(V)} U_a \subseteq f^{-1}(V) = \bigcup_{a \in f^{-1}(V)} \{a\} \subseteq \bigcup_{a \in f^{-1}(V)} U_a$)
- Example: inclusion $i:(A,\tau_A)\to (X,\tau_X),\ A\subseteq X$, is always continuous.
- Lemma: compositions of continuous functions are continuous.
- Lemma: let $f: X \to Y$ be function between topological spaces. Then f is continuous iff

$$\forall A \text{ closed in } Y, \quad f^{-1}(A) \text{ closed in } X$$

- Remark: we can use continuous functions to decide that sets are open or closed.
- Definition: n-sphere is

$$S^n \coloneqq \left\{ \left(x_1,...,x_{n+1}\right) \in \mathbb{R}^{n+1} : \sum_{i=1}^{n+1} x_i^2 = 1 \right\}$$

- **Example**: in the standard topology, the *n*-sphere is a closed subset of \mathbb{R}^{n+1} . (Consider the preimage of $\{1\}$ which is closed in \mathbb{R}).
- Example:
 - Can consider set of square matrices $M_{n,n}(\mathbb{R}) \cong \mathbb{R}^{n^2}$ and give it the standard topology.
 - Note

$$\det(A) = \sum_{\sigma \in \operatorname{sym}(n)} \left(\operatorname{sgn}(\sigma) \prod_{i=1}^n a_{i,\sigma(i)} \right)$$

is a polynomial in the entries of A so is continuous function from $M_n(\mathbb{R})$ to \mathbb{R} .

- $\mathrm{GL}_n(\mathbb{R})=\{A\in M_n(\mathbb{R}): \det(A)\neq 0\}=\det^{-1}(\mathbb{R}-\{0\})$ is open.
- $SL_n(\mathbb{R}) = \{A \in M_n(\mathbb{R}) : \det(A) = 1\} = \det^{-1}(\{1\}) \text{ is closed.}$
- $O(n) = \{A \in M_n(\mathbb{R}) : AA^T = I\}$ is closed: $f_{i,j}(A) = (AA^T)_{i,j}$ is continuous and

$$O(n) = \bigcap_{1 < i, j < n} (f_{i,j})^{-1}(\{\delta_{i,j}\})$$

- $SO(n) = O(n) \cap SL_n(\mathbb{R})$ is closed.
- **Definition**: for X,Y topological spaces, $h:X\to Y$ is **homeomorphism** if h is bijective, continuous and h^{-1} is continuous. X and Y are **homeomorphic**, $X\cong Y$. h induces bijection between τ_X and τ_Y which commutes with unions and intersections.
- **Proposition**: compositions of homeomorphisms are homeomorphisms.
- **Example**: in standard topology, (0,1) is homeomorphic to \mathbb{R} . (Consider $f: \left(-\frac{\pi}{2}, \frac{\pi}{2}\right) \to (-\infty, \infty), f = \tan, g: (0,1) \to \left(-\frac{\pi}{2}, \frac{\pi}{2}\right), g(x) = \pi\left(x \frac{1}{2}\right)$ and $f \circ g$).
- Example: \mathbb{R} with standard topology τ_{st} is not homoeomorphic to \mathbb{R} with the discrete topology τ_d . (Consider $h^{-1}(\{a\}) = \{h^{-1}(a)\}, \{a\} \in \tau_{\mathrm{st}}$ but $\{h^{-1}(a)\} \notin \tau_{\mathrm{st}}$).
- Example: let $X = \mathbb{R} \cup \{\overline{0}\}$. Define $f_0 : \mathbb{R} \to X$, $f_0(a) = a$ and $f_{\overline{0}} : \mathbb{R} \to X$, $f_{\overline{0}}(a) = a$ for $a \neq 0$, $f_{\overline{0}}(0) = \overline{0}$. Topology on X has $A \subseteq X$ open iff $f_0^{-1}(A)$ and $f_{\overline{0}}^{-1}(A)$ open. Every point in X lies in open set: for $a \notin \{0, \overline{0}\}$, $a \in (a \frac{|a|}{2}, a + \frac{|a|}{2})$ and both pre-images of this are same open interval, for 0, set $U_0 = (-1, 0) \cup \{0\} \cup (0, 1) \subseteq X$ then $f_0^{-1}(U_0) = (-1, 1)$ and $f_0^{-1}(U_0) = (-1, 0) \cup \{\overline{0}\} \cup (0, 1)$ are both open. For $\overline{0}$, set $U_{\overline{0}} = (-1, 0) \cup \{\overline{0}\} \cup (0, 1) \subseteq X$, then $f_{\overline{0}}^{-1}(U_{\overline{0}}) = (-1, 1)$ and $f_0^{-1}(U_{\overline{0}}) = (-1, 0) \cup (0, 1)$ are both open. So U_0 and $U_{\overline{0}}$ both open in X. X is not Hausdorff since any open sets containing 0 and $\overline{0}$ must contain "open intervals" such as U_0 and $U_{\overline{0}}$.

• Example (Furstenberg's proof of infinitude of primes): since $a + d\mathbb{Z}$ is infinite, any nonempty finite set is not open, so any set with finite complement is not closed. For fixed d, sets $d\mathbb{Z}$, $1 + d\mathbb{Z}$, ..., $(d-1) + d\mathbb{Z}$ partition \mathbb{Z} . So the complement of each is the union of the rest, so each is open and closed. Every $n \in \mathbb{Z} - \{-1,1\}$ is prime or product of primes, so $\mathbb{Z} - \{-1,1\} = \bigcup_{p \text{ prime}} p\mathbb{Z}$, but finite unions of closed sets are closed, and since $\mathbb{Z} - \{-1,1\}$ has finite complement, the union must be infinite.

3. Limits, bases and products

3.1. Limit points, interiors and closures

- **Definition**: for topological space $X, x \in X, A \subseteq X$:
 - Open neighbourhood of x is open set $N, x \in N$.
 - x is **limit point** of A if every open neighbourhood N of x satisfies

$$(N - \{x\}) \cap A \neq \emptyset$$

• Corollary: x is not limit point of A iff exists neighbourhood N of x with

$$A \cap N = \begin{cases} \{x\} & \text{if } x \in A \\ \emptyset & \text{if } x \notin A \end{cases}$$

- Example: let $X = \mathbb{R}$ with standard topology.
 - $0 \in X$, then (-1/2, 1/2) is open neighbourhood of 0.
 - If $U \subseteq X$ open, U is open neighbourhood for any $x \in U$.
 - Let $A = \left\{ \frac{1}{n} : n \in \mathbb{Z} \{0\} \right\}$, then only limit point in A is 0.
- **Definition**: let $A \subseteq X$.
 - **Interior** of *A* is largest open set contained in *A*:

$$A^{\circ} \coloneqq \bigcup_{\substack{U \text{ open} \\ U \subset A}} U$$

• Closure of A is smallest closed set containing A:

$$\overline{A} \coloneqq \bigcap_{\substack{F \text{ closed} \\ A \subseteq F}}$$

If $\overline{A} = X$, A is **dense** in X.

- Lemma:
 - $\overline{X-A} = X A^{\circ}$
 - $\overline{A} = X (X A)^{\circ}$
- Example: let $\mathbb{Q} \subset \mathbb{R}$ with standard topology. Then $\mathbb{Q}^{\circ} = \emptyset$ and $\overline{\mathbb{Q}} = \mathbb{R}$ (since every nonempty open set in \mathbb{R} contains rational and irrational numbers).
- Lemma: $\overline{A} = A \cup L$ where L is the set of limit points of A.
- Dirichlet prime number theorem: let a, d coprime, then $a + d\mathbb{Z}$ contains infinitely many primes.

• Example: let A be set of primes in \mathbb{Z} with Furstenberg topology. By above lemma, only need to find limit points in $\mathbb{Z} - A$ to find \overline{A} . $10\mathbb{Z}$ is an open neighbourhood of 0 for 0 inside $\mathbb{Z} - A$. For $a \notin \{-1,0,1\}$, $a+10a\mathbb{Z}$ is an open neighbourhood of a. These sets have no primes so the corresponding points are not limit points of A. For ± 1 , any open neighbourhood of 1 contains a set $\pm 1 + d\mathbb{Z}$ for some $d \neq 0$, but by the Dirichlet prime number theorem, this set contains at least one prime. So $\overline{A} = A \cup \{\pm 1\}$.

• Lemma:

- Let $A \subseteq M$ for metric space M. If x is limit point of A then exists sequence x_n in A such that $\lim_{n\to\infty} x_n = x$.
- If $x \in M A$ and exists sequence x_n in A with $\lim_{n \to \infty} x_n = x$ then x is limit point of A.

3.2. Bases

• **Definition**: a basis for topology τ on X is collection $\mathcal{B} \subseteq \tau$ such that

$$\forall U \in \tau, \exists B \subseteq \mathcal{B} : U = \bigcup_{b \in B} b$$

(every open U is a union of sets in B).

• Example:

- For metric space (M,d), $\mathcal{B} = \{B(x;r): x \in M, r > 0\}$ is basis for the induced topology. (Since if U open, $U = \bigcup_{u \in U} \{u\} \subseteq \bigcup_{u \in U} B(u,r_u) \subseteq U$.)
- In \mathbb{R}^n with standard topology, $\mathcal{B} = \{B(q; 1/m) : q \in \mathbb{Q}^n, m \in \mathbb{N}\}$ is a **countable** basis. (Find $m \in \mathbb{N}$ such that $\frac{1}{m} < \frac{r}{2}$ and $q \in \mathbb{Q}^n$ such that $q \in B(p; \frac{1}{m})$, then $B(q; \frac{1}{m}) \subseteq B(p; r) \subseteq U$ using the triangle inequality).
- **Theorem**: let $f: X \to Y$ be map between topological spaces. The following are equivalent:
 - f is continuous.
 - If \mathcal{B} is basis for topology τ on Y then $f^{-1}(B)$ is open for every $B \in \mathcal{B}$.
 - $\bullet \quad \forall A\subseteq X, f(\overline{A})\subseteq \overline{f(A)}.$
 - $\bullet \quad \forall V \subseteq Y, \overline{f^{-1}(V)} \subseteq f^{-1}(\overline{V}).$
 - $f^{-1}(C)$ closed for any closed set $C \subseteq Y$.
- Theorem: let X be a set and collection $\mathcal{B} \subseteq \mathcal{P}(X)$ be such that:
 - $\forall x \in X, \exists B \in \mathcal{B} : x \in B$
 - If $x \in B_1 \cap B_2$ with $B_1, B_2 \in \mathcal{B}$, then $\exists B_3 \in \mathcal{B} : x \in B_3 \subseteq B_1 \cap B_2$.

Then there is unique topology $\tau_{\mathcal{B}}$ on X for which \mathcal{B} is a basis. We say \mathcal{B} generates $\tau_{\mathcal{B}}$. We have $\tau_{\mathcal{B}} = \{ \bigcup_{i \in I} B_i : B_i \in \mathcal{B}, I \text{ indexing set} \}$.

3.3. Product topologies

- Definition: Cartesian product of topological spaces X, Y is $X \times Y := \{(x, y) : x \in X, y \in Y\}$. We give it the **product topology** which is generated by $\mathcal{B}_{X \times Y} := \{U \times V : U \in \tau_X, V \in \tau_Y\}$.
- Example:
 - Let $X = Y = \mathbb{R}$, then product topology is same as standard topology on \mathbb{R}^2 .

• Let $X = Y = S^1$, then $X \times Y = T^2 = S^1 \times S^1$ is the **2-torus**. *n***-torus** is defined for $n \ge 3$ by

$$T^n := S^1 \times T^{n-1}$$

- **Definition**: if $\tau_1 \subseteq \tau_2$ are topologies, then τ_1 is **smaller** than τ_2 (τ_2 is **larger** than τ_1).
- **Definition**: for topological spaces X, Y, **projection maps** $\pi_X : X \times Y \to X$ and $\pi_Y : X \times Y \to Y$ are

$$\pi_X(x,y) = x, \quad \pi_Y(x,y) = y$$

- **Proposition**: for $X \times Y$ with product topology,
 - π_X and π_Y are continuous.
 - π_X and π_Y map open sets to open sets.
 - Product topology is smallest topology for which π_X and π_Y are continuous.
- **Proposition**: let X, Y, Z topological spaces, then $f: Z \to X \times Y$ (with product topology on $X \times Y$) continuous iff both $\pi_X \circ f: Z \to X$ and $\pi_Y \circ f: Z \to Y$ are continuous.
- Example: let $f: X \to \mathbb{R}^n$, $\pi_i: \mathbb{R}^n \to \mathbb{R}$, $\pi_i(x) = x_i$, $f_i = \pi_i \circ f$, then f is continuous iff all f_i are continuous.
- **Proposition**: let X, Y nonempty topological spaces. Then $X \times Y$ with product topology is Hausdorff iff X and Y are both Hausdorff.

4. Connectedness

4.1. Clopen sets and examples

- **Definition**: let X topological space, then $A \subseteq X$ is **clopen** if A is open and closed.
- **Definition**: X is **connected** if the only clopen sets in X are X and \emptyset .
- Example:
 - \mathbb{R} with standard topology is connected.
 - \mathbb{Q} with induced topology from \mathbb{R} is not connected (consider $L = \mathbb{Q} \cap (-\infty, \sqrt{2})$ and $\mathbb{Q} L = \mathbb{Q} \cap (\sqrt{2}, \infty)$).
 - The connected subsets of \mathbb{R} are the intervals.
- **Definition**: $A \subseteq \mathbb{R}$ is an interval iff $\forall x, y, z \in A, x < z < y \Longrightarrow z \in A$.
- Example:
 - $X = \{0, 1\}$ with discrete topology is not connected ($\{1\}$ and $\{0\}$ both open so both closed).
 - $X = \{0, 1\}$ with $\tau = \{\emptyset, \{1\}, \{0, 1\}\}$ is connected.
 - Z with Furstenberg topology is not connected.
- Theorem (continuity preserves connectedness): if $h: X \to Y$ continuous and X connected, then $h(X) \subseteq Y$ is connected.
- Corollary: if $h: X \to Y$ is homeomorphism and X is connected then Y is connected.
- **Theorem**: let *X* topological space. The following are equivalent:
 - X is connected.

- X cannot be written as disjoint union of two non-empty sets.
- There exists no continuous surjective function from X to a discrete space with more than one point.

• Example:

- $\operatorname{GL}_n(\mathbb{R})$ is not connected (since $\det : \operatorname{GL}_n(\mathbb{R}) \to \mathbb{R} \{0\}$ is continuous and surjective and $\mathbb{R} \{0\} = (-\infty, 0) \cup (0, \infty)$).
- O(n) is not connected.
- (0,1) is connected (since $\mathbb{R} \cong (0,1)$ and \mathbb{R} is connected).
- X = (0,1] and Y = (0,1) are not homeomorphic (if they are, then (0,1] is connected since (0,1) is).
- **Definition**: let $A = B \cup C$, $B \cap C = \emptyset$, then B and C are **complementary** subsets of A.
- Remark: if complementary B and C open in A, then B and C clopen in A. So if $B, C \neq \emptyset$ then A not connected.

4.2. Constructing more connected sets, components, pathconnectedness

- **Proposition**: let X topological space, $Z \subseteq X$ connected. If $Z \subseteq Y \subseteq \overline{Z}$ then Y is connected. In particular, with $Y = \overline{Z}$, the closure of a connected set is connected.
- **Proposition**: let $A_i \subseteq X$ connected, $i \in I$, $A_i \cap A_j \neq \emptyset$ and $\bigcup_{i \in I} A_i = X$. Then X is connected.
- **Theorem**: if X and Y are connected then $X \times Y$ is connected.
- Example:
 - \mathbb{R}^n is connected.
 - $B^n=\{x\in\mathbb{R}^n: d_2(0,x)<1\}\ (B^n \text{ is homeomorphic to }\mathbb{R}^n).$
 - $D^n = \{x \in \mathbb{R}^n : d_2(0, x) \le 1\} = \overline{B^n}$ is connected.

• Example:

- $\forall n \in \mathbb{N}, S^n$ is connected.
- $\forall n \in \mathbb{N}, T^n \text{ is connected.}$
- **Definition**: **component** of topological space *X* is maximal connected subset of *X*.
- **Proposition**: in a topological space X:
 - Every $p \in X$ is in a unique component.
 - If $C_1 \neq C_2$ are components, then $C_1 \cap C_2 = \emptyset$.
 - X is the union of its components.
 - Every component is closed in X.

• Example:

- If X connected, then its only component is itself.
- If X discrete, then each singleton in τ_X is a component.
- In \mathbb{Q} with induced standard topology from \mathbb{R} , every singleton is a component.
- **Definition**: **path** in topological space X is continuous function $\gamma : [0,1] \to X$. γ is said to be path from $\gamma(0)$ to $\gamma(1)$.
- **Definition**: X is **path-connected** if for every $p, q \in X$, there is a path from p to q.

- **Proposition**: every path-connected topological space is connected.
- Example: let

$$Z = \{(x, \sin(1/x)) \in \mathbb{R}^2 : 0 < x \le 1\}$$

Z is path-connected, as a path from $(x_1, \sin(1/x_1))$ to $(x_2, \sin(1/x_2))$ is given by

$$\gamma(t) = \left(x_1 + (x_2-x_1)t, \sin\left(\frac{1}{x_1 + (x_2-x_1)t}\right)\right)$$

So then Z is connected by the above proposition, and since the closure of a connected set is connected, \overline{Z} is connected.

Every point $(0,y), y \in [-1,1]$ is a limit point of Z. Assume \overline{Z} is path-connected. Then there is a path $\gamma:[0,1] \to \overline{Z}$ from (0,0) to $(1,\sin(1))$. Since $(\pi_X \circ \gamma)(0) = 0$ and $(\pi_X \circ \gamma)(1) = 1$ and $\pi_X \circ \gamma$ is continuous, by the Intermediate Value Theorem, $\exists t_1 \in [0,1]: (\pi_X \circ \gamma)(t_1) = 2/\pi$. By IVT again, $\exists t_2 \in [0,t_1]: (\pi_X \circ \gamma)(t_2) = \frac{2}{2\pi}$. We obtain a strictly decreasing sequence $(t_n) \subseteq [0,1]$ where $(\pi_X \circ \gamma)(t_n) = \frac{2}{n\pi}$ which is bounded below by 0, so must converge with limit t^* .

Now $\pi_Y \circ \gamma$ is continuous, so $\lim_{n \to \infty} (\pi_Y \circ \gamma)(t_n) = (\pi_Y \circ \gamma)(t^*)$. But $(\pi_Y \circ \gamma)(t_n) = \sin(\frac{n\pi}{2})$, and as $n \to \infty$, this oscillates between -1 and 1 and does not converge, so contradiction.

5. Compactness

• **Definition**: let X topological space, **cover** of X is collection $(U_i)_{i\in I}$ of subsets of X with

$$\bigcup_{i\in I} U_i = X$$

If every U_i is open, it is an **open cover**. If $J \subseteq I$, then $(U_i)_{i \in J}$ is a **subcover** of $(U_i)_{i \in I}$ if it is also a cover.

- **Definition**: X is **compact** if every open cover of X admits a finite subcover.
- Example:
 - If X is finite then X is compact.
 - \mathbb{R} is not compact.
 - If X infinite with $\tau = \{U \subseteq X : X U \text{ is finite}\} \cup \{\emptyset\}$, then X is compact.
- **Proposition**: let X have topology with basis \mathcal{B} . Then X is compact iff every cover $(B_i)_{i\in I}$ of X, $B_i \in \mathcal{B}$, admits a finite subcover of X.
- Remark: to determine compactness of $Y \subseteq X$ with induced topology, consider open covers $Y = \bigcup_{i \in I} (U_i \cap Y)$ for U_i open in X, which is equivalent to $Y \subseteq \bigcup_{i \in I} U_i$.
- **Example**: [0,1] is compact.
- **Proposition**: if $f: X \to Y$ continuous, X compact, then f(X) is compact.
- **Proposition**: if X compact, $A \subseteq X$ closed in X, then A is compact.
- Theorem: if X is Hausdorff and $A \subseteq X$ is compact then A is closed.

- Corollary: if X compact, Y is Hausdorff, $f: X \to Y$ continuous bijection, then f is homeomorphism.
- **Theorem**: if X, Y compact, then $X \times Y$ is compact.
- Definition: $S \subseteq \mathbb{R}^n$ is bounded if

$$\exists r \in \mathbb{R} : S \subseteq B(0;r)$$

- Theorem (Heine-Borel): $A \subseteq \mathbb{R}^n$ is compact iff it is closed and bounded.
- Example:
 - S^n is compact.
 - T^n is compact.
 - $X = \{x \in \mathbb{R}^3 : x_1^2 + x_2^2 x_3^3 = 1\}$ is not compact, since $\forall n \in \mathbb{N}$, $(n, 0, (n^2 1)^{1/3}) \in X$, so $X \nsubseteq B(n)$, so is unbounded, so not compact by Heine-Borel.
- Corollary: let $f: X \to \mathbb{R}$, X compact, f continuous. Then f attains its maximum and minimum.
- Theorem (Bolzano-Weierstrass): an infinite subset A of a compact space X has a limit point in X.

6. Quotient spaces

• **Definition**: let X topological space, \sim equivalence relation on X. Write X/\sim for the set of equivalence classes of \sim : for $x \in X$,

$$[x]\coloneqq\{y\in X:y\sim x\},\quad X/\sim\coloneqq\{[x]:x\in X\}$$

There is a surjective map, the **quotient map**, $\pi: X \to X/\sim$, $\pi(x) = [x]$.

• Example: let $X = \mathbb{R}^3$, define equivalence relation

$$(x_1, y_1, z_1) \sim (x_2, y_2, z_2) \Leftrightarrow z_1 = z_2$$

Then $\pi(a,b,c)=[(a,b,c)]=\{(x,y,z)\in\mathbb{R}^3:z=c\}$. Elements of \mathbb{R}^3/\sim are horizontal planes.

• **Definition**: let X topological space, \sim equivalence relation on X. Then X/\sim is given **quotient topology** defined by

$$U \subseteq X/\sim \text{\rm open} \Longleftrightarrow \pi^{-1}(U)$$
open in X

- **Proposition**: quotient topology defines a topology on X/\sim .
- Proposition: quotient topology on X/\sim is largest such that π is continuous.
- **Proposition**: let X topological space with equivalence relation \sim , Y topological space. Then $f: X/\sim \to Y$ continuous iff $f\circ \pi: X\to Y$ is continuous.
- **Example**: in \mathbb{R} , let $x \sim y \iff x y \in \mathbb{Z}$. Define $\exp : \mathbb{R} \to S^1 \subseteq \mathbb{C}$, $\exp(t) = e^{2\pi i t}$ and $\overline{\exp} : \mathbb{R} / \sim \to S^1$, $\overline{\exp}([t]) = \exp(t)$. Then

$$[s] = [t] \iff s - t = k \in \mathbb{Z} \iff \overline{\exp}(s) = e^{2\pi i k} e^{2\pi i t} = e^{2\pi i t} = \overline{\exp}(t)$$

Hence $\overline{\exp}$ is well-defined and injective, and is surjective since \exp is. Also, $\overline{\exp}$ is continuous since $\exp = \overline{\exp} \circ \pi$ is. \mathbb{R}^2 is a metric space and so is Hausdorff, so $S^1 \subset \mathbb{R}^2$ with the induced topology is Hausdorff. Now e.g. $\pi([-10, 10]) = \mathbb{R}/\sim$,

[-10, 10] is compact and π continuous so \mathbb{R}/\sim is compact. Since $\overline{\exp}$ is a continuous bijection, these three properties imply $\overline{\exp}$ is a homeomorphism. Hence $\mathbb{R}/\sim\cong S^1$.

- **Definition**: let $A \subseteq X$, define $x \sim y \iff x = y$ or $x, y \in A$. Then define $X/A := X/\sim$.
- Example: $S^n \cong D^n/S^{n-1}$. Any point in D^n can be written as $t \cdot \varphi$, $t \in [0,1]$, $\varphi \in S^{n-1}$. Define

$$f: D^n \to S^n, \quad f(t \cdot \varphi) \coloneqq (\cos(\pi t), \varphi \sin(\pi t)) \in \mathbb{R} \times \mathbb{R}^n = \mathbb{R}^{n+1}$$

$$\Longrightarrow f(0 \cdot \varphi) = (1, \mathbf{0}), f(1/2 \cdot \varphi) = (0, \varphi), f(1 \cdot \varphi) = (-1, \mathbf{0})$$
Define $\overline{f}: D^n/S^{n-1} \to S^n, \overline{f}([t \cdot \varphi]) = f(t \cdot \varphi)$. If $t_1 \cdot \varphi_1 \neq t_2 \cdot \varphi_2$, then

$$\begin{split} [t_1 \cdot \varphi_1] &= [t_2 \cdot \varphi_2] \Longleftrightarrow t_1 \cdot \varphi_1, t_2 \cdot \varphi_2 \in S^{n-1} \Longleftrightarrow t_1 = t_2 = 1 \\ &\iff f(t_1 \cdot \varphi_1) = (-1, \mathbf{0}) = f(t_2 \cdot \varphi_2) \\ &\iff \overline{f}([t_1 \cdot \varphi_1]) = \overline{f}([t_2 \cdot \varphi_2]) \end{split}$$

f is surjective, so \overline{f} is also. Now $\overline{f} \circ \pi = f$ which is continuous, so by above proposition, \overline{f} is continuous. $S^n \subset \mathbb{R}^{n+1}$ is Hausdorff, $D^n \subset \mathbb{R}^n$ is closed and bounded so is compact by Heine-Borel, and so D^n/S^{n-1} is compact (since π continuous). Also, f is a continuous bijection. These imply that \overline{f} is homeomorphism.

7. Topological groups

7.1. Examples

• **Definition**: a **topological group** G is Hausdorff space which is also a group such that

$$\bullet: G \times G \to G, \ \bullet(g,h) = gh \ \text{and} \ i: G \to G, \ i(g) = g^{-1}$$

are continuous.

- Example:
 - \mathbb{R}^n with addition is topological group.
 - $GL_n(\mathbb{R})$ with multiplication and its subgroups O(n) and SO(n) are topological groups (each entry in AB is sum of products of entries of A and B, so matrix multiplication is continuous, matrix inversion also continuous).

• Proposition:

- Any group with discrete topology is topological group.
- Any subgroup of topological group is also topological group.

• Example:

- $\mathbb{C} \{0\}$ with multiplication has topological subgroup $S^1 \subset \mathbb{C} \{0\}$.
- Define **quaternions** as vector space $\mathbb{H} := \langle 1, i, j, k \rangle$, with topology taken from \mathbb{R}^4 . $\mathbb{H} \{0\}$ is a multiplicative group with S^3 a topological subgroup. For $q = a + bi + cj + dk \in \mathbb{H}$, $a, b, c, d \in \mathbb{R}$, we have ij := k, jk := i, ki := j, ji := -k, kj := -i, ik := -j. For $q \neq 0$,

$$q^{-1} = \frac{a - bi - cj - dk}{a^2 + b^2 + c^2 + d^2}$$

- Note however that S^2 is not a topological group.
- **Definition**: for topological group $G, x \in G$, define **left translation by** x as

$$L_x:G o G,\quad L_x(g)\coloneqq xg$$

Similarly, **right translation by** x is

$$R_x:G o G,\quad R_x(g)\coloneqq gx$$

- Proposition: L_x has inverse $(L_x)^{-1} = L_{x^{-1}}$ and is homeomorphism. Similarly for R_x .
- **Notation**: a specified inclusion $G \stackrel{x}{\hookrightarrow} G \times G$ is the map $G \to \{x\} \times G$ composed with the inclusion map $\{x\} \times G \to G \times G$. (similarly for $G \times \{x\}$).
- **Proposition**: let G topological group, K the component containing identity of G. Then K is normal subgroup of G.
- Example: O(n) is not connected, but SO(n) is connected and contains I_n , so is a normal subgroup of O(n)

7.2. Actions, orbits, orbit spaces

- **Definition**: **action** of group G on topological space X is map : $G \times X \to X$ such that $\forall g, h \in G, \forall x \in X$,
 - $(hg) \bullet x = h \bullet (g \bullet x)$.
 - $1 \bullet x = x$.
 - $g: X \to X$ defined by $g(x) = g \bullet x$ is continous. Note: g has inverse map g^{-1} which is also continuous, so both are homeomorphisms.
- **Definition**: **action** of topological group G on topological space X is continuous map : $G \times X \to X$ such that $\forall g, h \in G, \forall x \in X$,
 - $(hg) \bullet x = h \bullet (g \bullet x)$.
 - $1 \bullet x = x$.
- **Remark**: for the above definition, the condition $g(x) = g \bullet x$ being continuous isn't required since g is the composition of continuous maps:

$$X \stackrel{g}{\hookrightarrow} G \times X \stackrel{\bullet}{\longrightarrow} X, \quad x \to (g, x) \to g \bullet x$$

- Example:
 - Trivial action: $(g, x) \mapsto g \bullet x = x$, so $\bullet = \pi_X$.
 - Let $G = GL_n(\mathbb{R})$, $X = \mathbb{R}^n$, let the action be matrix multiplication: $(A, \mathbf{x}) \to A \bullet \mathbf{x} = A\mathbf{x}$. This induces an action of subgroups O(n) or SO(n) on $X = \mathbb{R}^n$.
 - Let H subgroup of topological group G, left translation action of H on G is $\bullet: H \times G \to G, \ h \bullet g = hg$. Equivalently, $\varphi(h) = L_h$.
 - Let N normal subgroup of topological group G, conjugation action of G on N is : $G \times N \to N$, $g \bullet n = gng^{-1}$.
- **Definition**: let G act on topological space X, define equivalence relation \sim on X by

$$x \sim y \iff \exists g \in G : g(x) := g \bullet x = y$$

An equivalence class for this relation is an **orbit**, denoted Gx. **Orbit space**, X/G, is quotient space X/\sim . Action is **transitive** if X/G is a singleton.

- Example:
 - If G acts trivially, every orbit is singleton and X/G = X.
 - $\mathbb{R}^n/\mathrm{GL}_n(\mathbb{R})$ contains two points and has neither discrete nor indiscrete topology.
 - Action of O(n) on S^{n-1} is transitive for $n \in \mathbb{N}$. Action of SO(n) on S^{n-1} is transitive for n > 2.
- Lemma: if connected topological group G acts on topological space X, then the orbits are connected.
- **Theorem**: let G connected topological group act on topological space X. If X/G is connected, then X is connected.
- Notation: define specified inclusion $i_1: M_n(\mathbb{R}) \stackrel{1}{\hookrightarrow} M_{n+1}(\mathbb{R})$ by $A \to \begin{bmatrix} 1 & 0 \\ 0 & A \end{bmatrix}$. So $M_n(\mathbb{R})$ can be regarded as subspace of $M_{n+1}(\mathbb{R})$.
- Proposition:
 - Using the inclusion $\stackrel{1}{\hookrightarrow}$, SO(n) is subgroup of SO(n + 1).
 - Viewing these as topological groups, if subgroup SO(n) acts on SO(n+1), orbit space is $SO(n+1)/SO(n) \cong S^n$.
- Corollary: the topological group SO(n) is connected for $n \in \mathbb{N}$.

8. Introduction

- **Notation**: let I = [0, 1].
- Definition: closed n-disc is

$$D^n \coloneqq \{ \boldsymbol{x} \in \mathbb{R}^n : \|\boldsymbol{x}\| \le 1 \}$$

• Definition: open n-disc is

$$E^n := \{ \boldsymbol{x} \in \mathbb{R}^n : ||x|| < 1 \}$$

• **Definition**: *n*-sphere is

$$S^n := \{ x \in \mathbb{R}^{n+1} : ||x|| = 1 \}$$

- Definition: cylinder is $S^1 \times I$.
- **Definition**: the **2-torus (torus)** can be defined as $\mathbb{T} := S^1 \times S^1$ or $\mathbb{T} := (I \times I) / \sim$ where

$$\forall x \in I, (x,0) \sim (x,1), \quad \forall y \in I, (0,y) \sim (1,y)$$

• **Definition**: **Klein bottle** is given by $\mathbb{K} := (I \times I) / \sim$ where

$$\forall x \in I, (x, 0) \sim (x, 1), \quad \forall y \in I, (0, y) \sim (1, 1 - y)$$

• **Definition**: map is continuous $f: X \to Y$ where X, Y are topological spaces.

9. Simplicial complexes

9.1. Simplicial complexes and triangulations

- Definition: let $v_0,...,v_n\in\mathbb{R}^N,\,n\leq N.$
 - $v_0,...,v_n$ are in **general position** if $\{v_1-v_0,...,v_n-v_0\}$ are linearly independent.
 - Convex hull of $v_0,...,v_n$ is set of all convex linear combinations of $v_0,...,v_n$:

$$\langle v_0,...,v_n\rangle \coloneqq \left\{\sum_{i=0}^n \lambda_i v_i: \sum_{i=0}^n \lambda_i = 1, \forall i \in \{0,...,n\}, \lambda_i \geq 0\right\}$$

• An n-simplex $\sigma^n = \langle v_0,...,v_n \rangle$, is convex hull of $v_0,...,v_n$ in general position. $v_0,...,v_n$ span σ^n and σ^n is n-dimensional.