## Figure 8 Statistical Analysis

## **ROBOT INTERACTIONS**

```
Logistic Binary Regression
Input: Drop distance and Speed
Output: Robot Interactions (for "Repelled")
Deviance Residuals:
                       Median
                               3Q
-0.00005
     Min
                 10
          -0.34289
                                            3.09909
-0.40643
                     -0.12842
Coefficients:
                     Estimate Std. Error z value Pr(>|z|)
                    -20.35132 1703.49171
                                                      0.990
(Intercept)
                                            -0.012
Drop_distance20mm
                     15.90942 1703.49189
                                             0.009
                                                      0.993
                     17.89905 1703.49164
                                                      0.992
Drop_distance40mm
                                             0.011
Speed120mm/s
                     -0.07615
                                  1.03636
                                            -0.073
                                                      0.941
Speed160mm/s
                                  0.89519
                     -0.35202
                                           -0.393
                                                      0.694
(Dispersion parameter for binomial family taken to be 1)
    Null deviance: 74.871 on 320
                                     degrees of freedom
Residual deviance: 62.837 on 316
                                     degrees of freedom
AIC: 72.837
Number of Fisher Scoring iterations: 19
Chi-Square Test
Input: Drop distance
Output: Robot Interactions
        Pearson's Chi-squared test
X-squared = 11.028, df = 2, p-value = 0.004029
Chi-Square Test
Input: Speed
Output: Robot Interactions
Pearson's Chi-squared test
X-squared = 0.24843, df = 2, p-value = 0.8832
Table of Output count by Drop distance
       Repelled Crossed
  1mm
             108
                       0
                       1
  20mm
             105
  40mm
             100
Table of Output proportion by Drop distance
Repelled Crossed
  1mm 1.000000000 0.000000000
  20mm 0.990566038 0.009433962
  40mm 0.934579439 0.065420561
```

Input: Drop distance

One-way ANOVA

```
Output: Time for 50% coverage (Time)

Df Sum Sq Mean Sq F value Pr(>F)

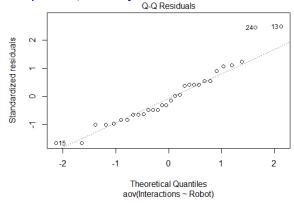
Drop_distance 2 447913 223957 5.621 0.0189
                                        5.621 0.0189 *
                12 478134
Residuals
                               39844
Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
Assumption for ANOVA test: Normality
Output: Time for 50% coverage (Time)
                   Normal Q-Q
   N
                                     10
Standardized residuals
                -0.00000
   0
   \overline{\phantom{a}}
   ņ
              -1
                      0
                              1
                Theoretical Quantiles
               aov(Time ~ Drop_distance)
Assumption for ANOVA test: Homogeneity of variances
Levene's Test
Input: Drop distance
Output: Time for 50% coverage (Time)
Levene's Test for Homogeneity of Variance (center = median)
       Df F value Pr(>F)
group 2
           4.6993 0.0311 *
       12
Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
Welch's ANOVA test
         One-way analysis of means (not assuming equal variances)
        Time and Drop_distance
F = 2.786, num df = 2.0000, denom df = 7.1754, p-value = 0.1272
```

## QUANTITY OF INTERACTIONS BY ROBOT

One-way ANOVA
Input: Robot
Output: Quantity of interactions

Df Sum Sq Mean Sq F value Pr(>F)
2 32.07 16.033 1.712 0.2
27 252.90 9.367

## Assumption for ANOVA test: Normality Output: Quantity of interactions $$_{\rm Q-Q\,Residuals}$$



Assumption for ANOVA test: Homogeneity of variances Levene's Test Input: Robot

Output: Quantity of interactions
Levene's Test for Homogeneity of Variance (center = median)

Of F value Pr(>F)

0.597 0.5576 group