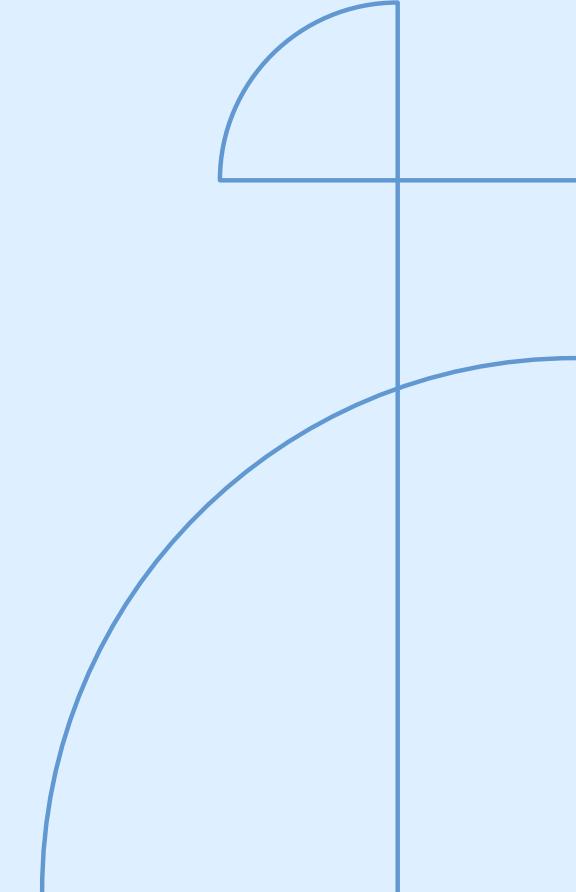




Morse theory of distance functions between algebraic hypersurfaces

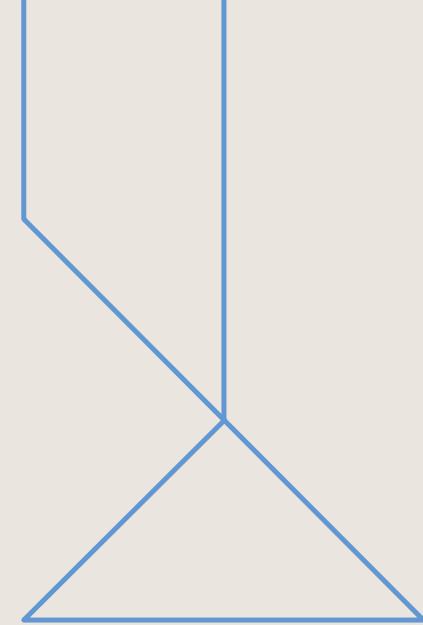
Isaac Ren with A. Guidolin, A. Lerario, and M. Scolamiero

November 27, 2024 — Metric Algebraic Geometry Workshop



Summary

- We (re)develop **Morse theory for distance functions** between subsets of \mathbb{R}^n .
- We establish that the **nondegeneracy** of distance functions between algebraic hypersurfaces is **generic**.
- We also compute bounds for the number of **critical points** of such functions.



Differential theory for locally Lipschitz functions



Subdifferential

- Let $X \subseteq \mathbf{R}^n$ be a smooth submanifold, $f: X \rightarrow \mathbf{R}$ a locally Lipschitz function, and $x \in X$.
- Denote by $\Omega(f)$ the set of differentiable points of f , of full measure by Rademacher's theorem.
- The **subdifferential of f at x** is the convex body

$$\partial_x f := \text{conv} \left\{ \lim_{\substack{x_k \rightarrow x \\ x_k \in \Omega(f)}} D_{x_k} f \mid \text{the limit exists} \right\}.$$

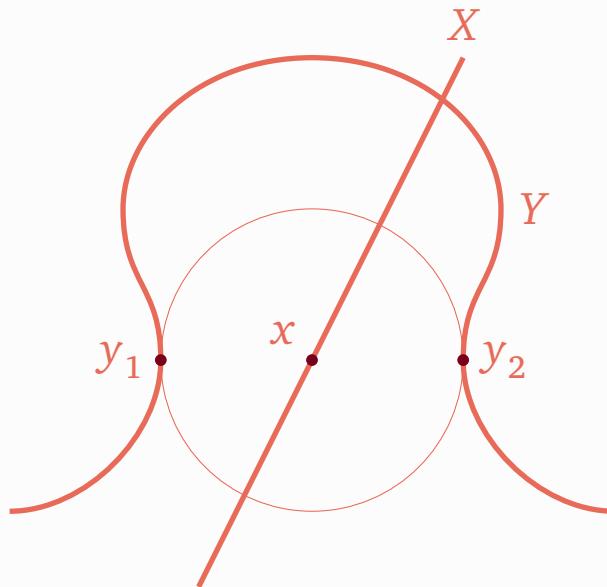
- The point x is **critical** if $0 \in \partial_x f$.

Proposition

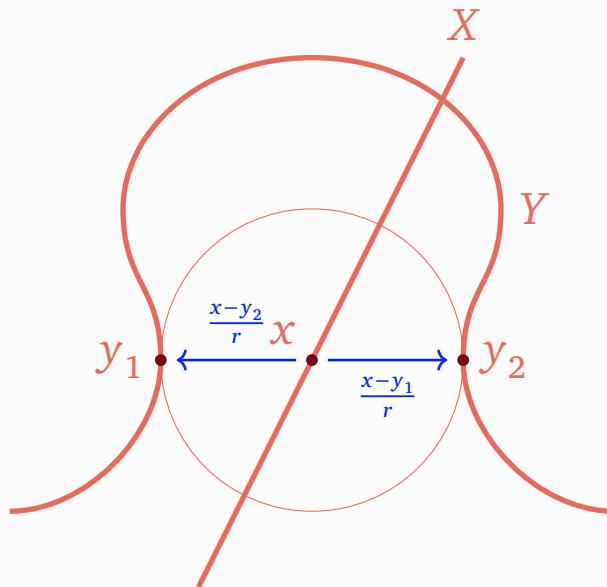
- Let $X \subseteq \mathbb{R}^n$ be a submanifold and $Y \subseteq \mathbb{R}^n$ a closed semialgebraic set such that X is transverse to Y (and the closure of its medial axis).
- Then the subdifferential of $f = \text{dist}_Y|_X$ at a point $x \in X$ is

$$\partial_x f = \text{proj}_{T_x X} \text{conv} \left\{ \frac{x - y}{\|x - y\|} \mid y \in B(x, \text{dist}_Y(x)) \cap Y \right\}.$$

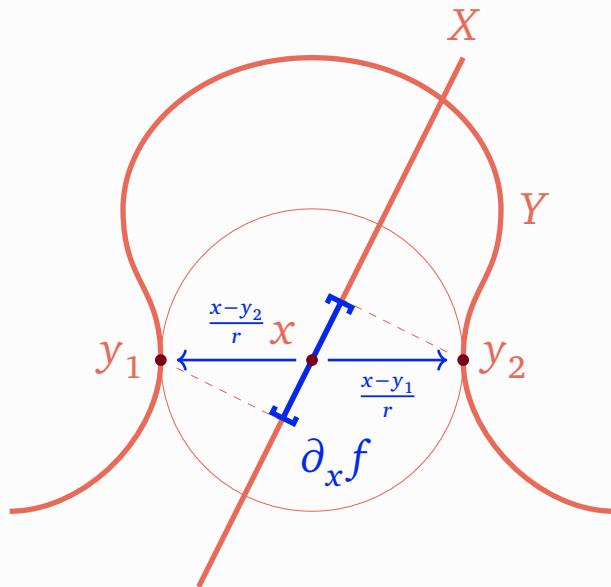
Example:



Example:



Example:



Continuous selections

- Let $f_0, \dots, f_m: X \rightarrow \mathbf{R}$ be continuous functions.
- A **continuous selection** of f_0, \dots, f_m is a function $f: X \rightarrow \mathbf{R}$ if f is continuous and, for all $x \in X$, there exists $i \in \{0, \dots, m\}$ such that $f(x) = f_i(x)$.

Continuous selections

- Let $f_0, \dots, f_m: X \rightarrow \mathbf{R}$ be continuous functions.
- A **continuous selection** of f_0, \dots, f_m is a function $f: X \rightarrow \mathbf{R}$ if f is continuous and, for all $x \in X$, there exists $i \in \{0, \dots, m\}$ such that $f(x) = f_i(x)$.
- For all $x \in X$, we define its **effective index set** as

$$I(x) := \{i \in \{0, \dots, m\} \mid x \in \text{clos int}\{y \in X \mid f(y) = f_i(y)\}\}.$$

- **Fact:** the subdifferential of f at x is $\text{conv}\{D_x f_i \mid i \in I(x)\}$.

Example:

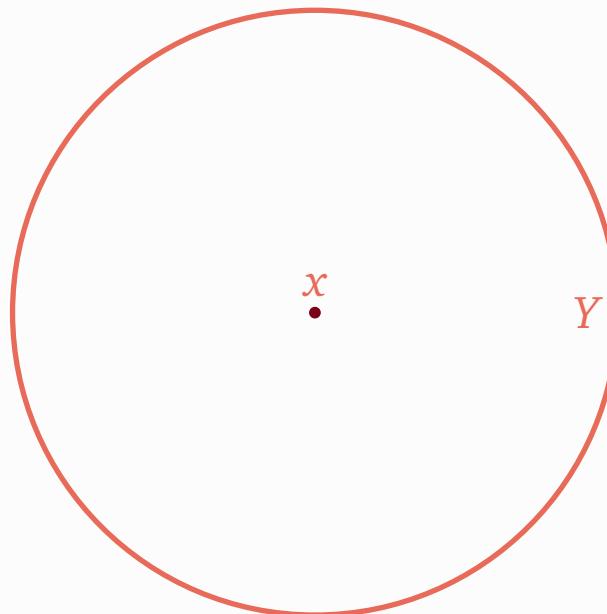
y_2

x

y_3

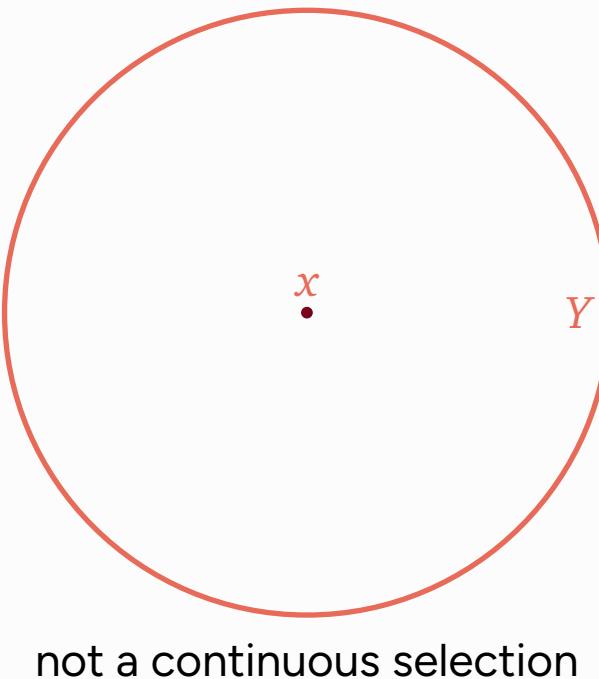
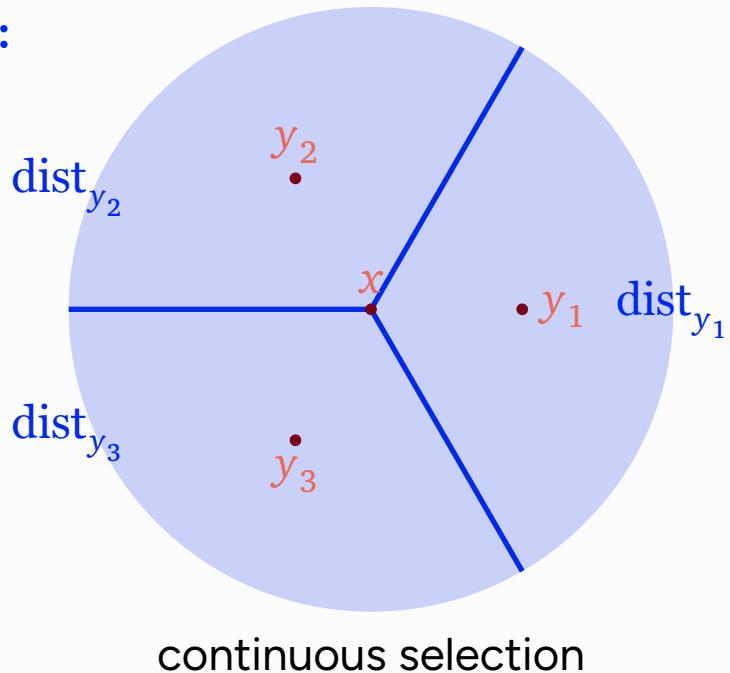
y_1

continuous selection



not a continuous selection

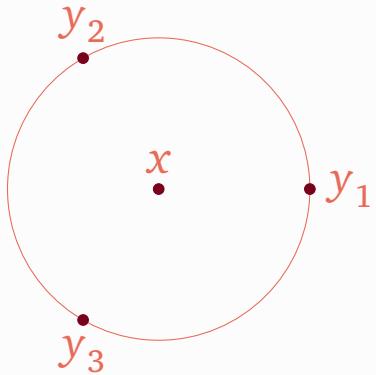
Example:



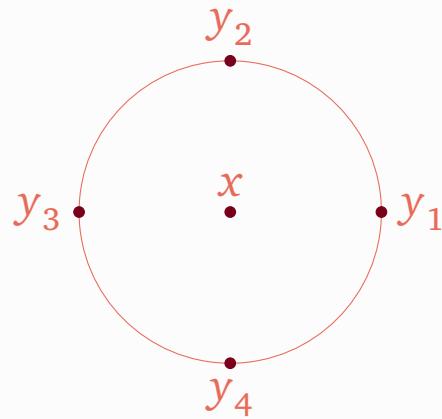
- A critical point x of f is **nondegenerate** if:
 1. for every $i \in I(x)$, the set of differentials $\{D_x f_j \mid j \in I(x) \setminus \{i\}\}$ is linearly independent; and
 2. writing $\sum_{i \in I(x)} \lambda_i D_x f_i = 0$ for the convex combination showing criticalness, the second differential of $\sum_{i \in I(x)} \lambda_i f_i$ is nondegenerate on $\bigcap_{i \in I(x)} \ker D_x f_i$.

- A critical point x of f is **nondegenerate** if:
 1. for every $i \in I(x)$, the set of differentials $\{D_x f_j \mid j \in I(x) \setminus \{i\}\}$ is linearly independent; and
 2. writing $\sum_{i \in I(x)} \lambda_i D_x f_i = 0$ for the convex combination showing criticalness, the second differential of $\sum_{i \in I(x)} \lambda_i f_i$ is nondegenerate on $\bigcap_{i \in I(x)} \ker D_x f_i$.
- We denote by $k(x) := \#I(x) - 1$ the **piecewise linear index of x** and by $\iota(x)$ the negative inertia index of the above restricted second differential, which we call the **quadratic index of x** .
 - We denote by $C_{k,\iota}(X, Y)$ the set of nondegenerate critical points with piecewise linear index k and quadratic index ι .

Example:

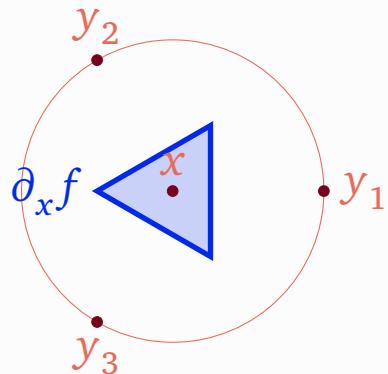


nondegenerate critical point

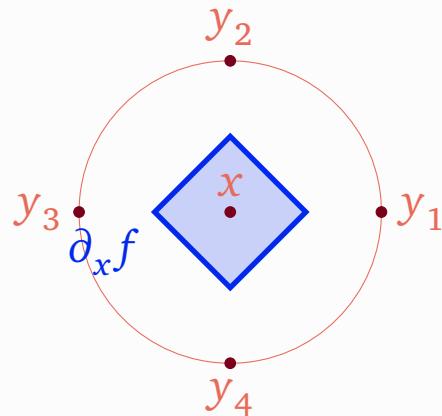


degenerate critical point

Example:

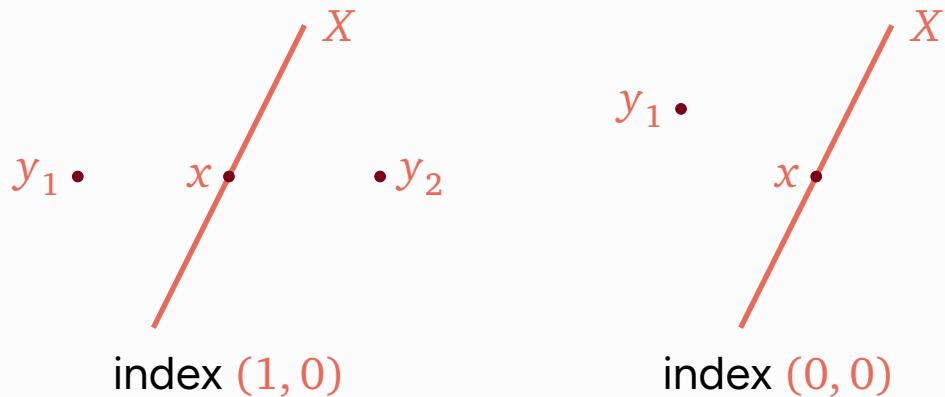


nondegenerate critical point



degenerate critical point

Example:



Normal forms

Proposition [Jongen-Pallaschke 1988]

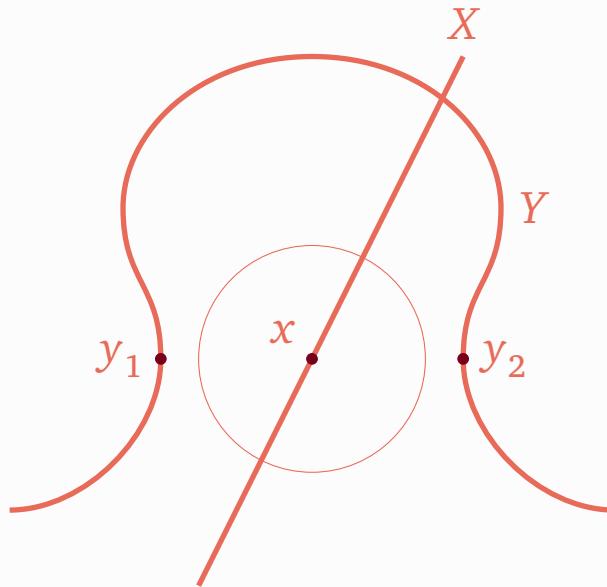
- For a continuous selection $f: X \rightarrow \mathbf{R}$ and a nondegenerate critical point $x \in X$ with piecewise linear index k and quadratic index ι , there exists a neighborhood U of x and a locally Lipschitz homeomorphism $\psi: \mathbf{R}^k \times \mathbf{R}^{n-k} \rightarrow U$ such that

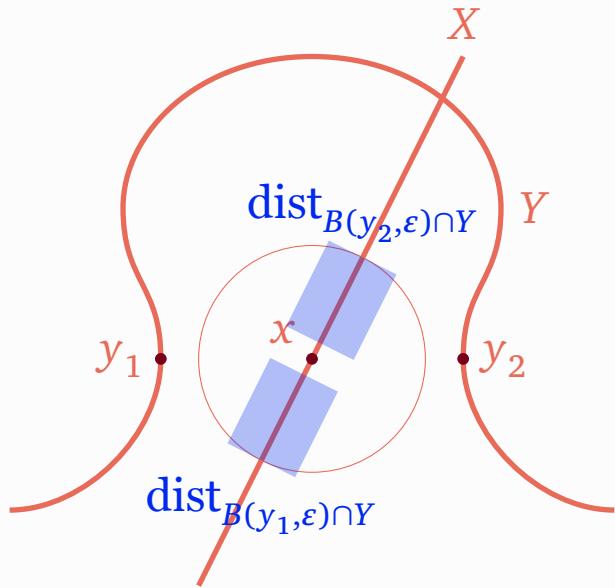
$$f(\psi(t_1, \dots, t_n)) = f(x) + \ell(t_1, \dots, t_k) - \sum_{j=k+1}^{k+\iota} t_j^2 + \sum_{j=k+\iota+1}^n t_j^2,$$

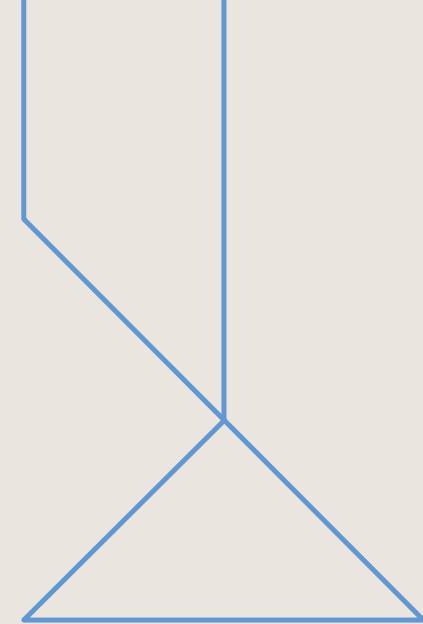
where ℓ is a continuous selection of $t_1, \dots, t_k, -(t_1 + \dots + t_k)$.

Proposition

- Let $Y \subseteq \mathbf{R}^n$ be a smooth submanifold, $\varphi: NY \rightarrow \mathbf{R}^n$ the exponential map, sending (y, v) to $y + v$, and $x \in \mathbf{R}^n$ a regular value of φ .
- Then:
 1. $B(x, \text{dist}_Y(x)) \cap Y$ is a finite set $\{y_0, \dots, y_k\}$; and
 2. $\text{dist}_Y|_{B(x, \delta)}$ is a continuous selection of the functions $\text{dist}_{B(y_i, \varepsilon) \cap Y}|_{B(x, \delta)}$.







Morse theory for distance functions

Between critical values

Proposition [Agrachev-Pallaschke-Scholtes 1997] actually it's Clarke

- Let $f = \text{dist}_Y|_X$ and $[a, b] \subseteq \mathbf{R}$ an interval containing no critical values.
- Then the space $\{f \leq b\}$ deformation retracts to the space $\{f \leq a\}$.

Passing a critical value

Proposition, follows from [Agrachev-Pallaschke-Scholtes 1997]

- Let $X \subseteq \mathbb{R}^n$ be a smooth manifold and $Y \subseteq \mathbb{R}^n$ a closed semialgebraic set.
- Let $c > 0$ be a critical value of $f = \text{dist}_Y|_X$ such that the associated critical points x_1, \dots, x_m are all nondegenerate. Then

$$H^*(\{f \leq c + \varepsilon\}, \{f \leq c - \varepsilon\}) \cong \bigoplus_{i=1}^m \tilde{H}^*\left(S^{k(x_i)+\ell(x_i)}\right).$$

Morse inequalities

Proposition

- Let $X \subseteq \mathbb{R}^n$ be a smooth, compact, semialgebraic manifold and $Y \subseteq \mathbb{R}^n$ a closed semialgebraic set such that all critical points of $\text{dist}_Y|_X$ are nondegenerate.
- Then, for every integer $\lambda \geq 0$,

$$\sum_{i=0}^{\lambda} (-1)^{i+\lambda} b_i(X) \leq \sum_{i=0}^{\lambda} (-1)^{i+\lambda} \left(b_i(X \cap Y) + \sum_{k+\ell=i} \#C_{k,\ell}(X, Y) \right),$$

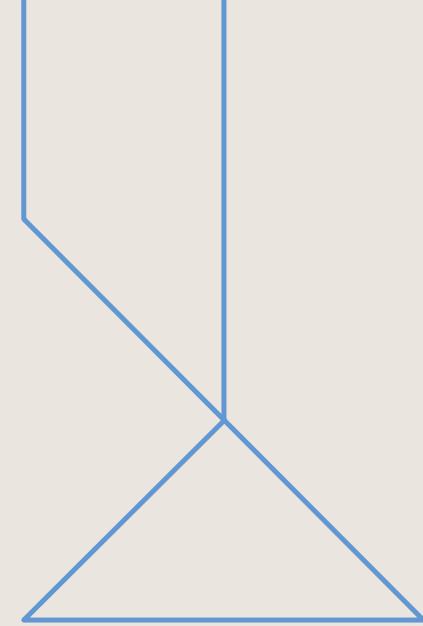
where the b_i are cohomology dimensions.

- Moreover,

$$\chi(X \cap Y) + \sum_{k,\iota \geq 0} (-1)^{k+\iota} \# C_{k,\iota}(X, Y) = \chi(X).$$

- If Y is also smooth and compact, and $\text{dist}_X|_Y$ has only nondegenerate critical points, then

$$\chi(Y) + \sum_{k,\iota \geq 0} (-1)^{k+\iota} \# C_{k,\iota}(X, Y) = \chi(X) + \sum_{k,\iota \geq 0} (-1)^{k+\iota} \# C_{k,\iota}(Y, X).$$



Genericity for algebraic hypersurfaces

Setup

- Let p and q be two real n -variable polynomials, $X := Z(p)$, and $Y := Z(q)$, and consider $\text{dist}_Y|_X$.

Setup

- Let p and q be two real n -variable polynomials, $X := Z(p)$, and $Y := Z(q)$, and consider $\text{dist}_Y|_X$.
- We recover previously studied notions:
 - When $p = 0$ (and so $X = \mathbf{R}^n$), a critical point of piecewise linear index k is a **real geometric $(k+1)$ -bottleneck** [Di Rocco et al. 2023].
 - The **real bottleneck degree** is the number of such geometric 2 -bottlenecks.
 - When $Y = \{y\}$ is a generic point, the number of critical points is (related to) the **Euclidean distance degree**.
- Our bounds on the number of critical points complement and generalize the known bounds on these values.

Theorem (Parametric transversality, Hirsch 1976)

- Let M, N, P be smooth manifolds, $W \subseteq N$ a submanifold of N , and $F: P \times M \rightarrow N$ a smooth map.
- For all p in P , we denote by F_p the map $F(p, -): M \rightarrow N$.
- If F is transverse to W , then the set $\{p \in P \mid F(p, -) \pitchfork W\}$ is residual in P .
 - In other words, for generic $p \in P$, the map F_p is transverse to W .
 - If M and W have small enough dimensions, then F_p misses W entirely.

Theorem (Multijet parametric transversality)

- Now consider $P = \mathcal{P}_d$ the space of polynomials of degree at most d , $M = ((\mathbf{R}^n)^k \setminus \Delta)$ the space of k distinct points in \mathbf{R}^n , $N = {}_k J^r(\mathbf{R}^n, \mathbf{R})$ the space of k -multijets of order r , and

$$F: \begin{cases} \mathcal{P}_d \times ((\mathbf{R}^n)^k \setminus \Delta) & \rightarrow {}_k J^r(\mathbf{R}^n, \mathbf{R}) \\ (p, y_1, \dots, y_k) & \mapsto \left(\frac{\partial^{|\alpha|} p}{\partial x^\alpha}(y_i) \right)_{\substack{\alpha \in \mathbf{N}^n, |\alpha| \leq r, \\ i \in \{1, \dots, k\}}} \end{cases}.$$

- Then there exists a function $d(k, r)$ such that, for all $d \geq d(k, r)$, the map F is a submersion (and so is transverse to every submanifold of N).

Proposition

- For q generic of degree ≥ 2 , for all $x \in \mathbf{R}^n$, the set $B(x, \text{dist}_Y(x)) \cap Y$ is a nondegenerate simplex.

Proposition

- For q generic of degree ≥ 2 , for all $x \in \mathbf{R}^n$, the set $B(x, \text{dist}_Y(x)) \cap Y$ is a nondegenerate simplex.

Idea of proof:

- We follow the strategy of [Yomdin 1981].
- In particular, we use the original parametric transversality theorem.

- For all $k \in \{0, \dots, n+1\}$, define

$$F_k: \begin{cases} \mathcal{P}_d \times \mathbf{R}^n \times (\mathbf{R}^{n(k+1)} \setminus \Delta) & \rightarrow \\ (q, x, \bar{y}) & \mapsto (\bar{y}, \dots, q(y_i), \dots, \|x - y_i\|^2, \dots), \end{cases}$$

$$W_k := \left\{ (\bar{z}, \bar{s}, \bar{t}) \in {}_{k+1}J^0(\mathbf{R}^n, \mathbf{R}^2) \mid \begin{array}{l} \forall i \in \{0, \dots, k\}, s_i = 0, \\ \forall i \in \{1, \dots, k\}, t_i = t_0 \end{array} \right\}.$$

- For all $k \in \{0, \dots, n+1\}$, define

$$F_k: \begin{cases} \mathcal{P}_d \times \mathbf{R}^n \times (\mathbf{R}^{n(k+1)} \setminus \Delta) & \rightarrow \\ (q, x, \bar{y}) & \mapsto (\bar{y}, \dots, q(y_i), \dots, \|x - y_i\|^2, \dots), \end{cases}_{k+1} J^0(\mathbf{R}^n, \mathbf{R}^2)$$

$$W_k := \left\{ (\bar{z}, \bar{s}, \bar{t}) \in {}_{k+1} J^0(\mathbf{R}^n, \mathbf{R}^2) \mid \begin{array}{l} \forall i \in \{0, \dots, k\}, s_i = 0, \\ \forall i \in \{1, \dots, k\}, t_i = t_0 \end{array} \right\}.$$

- We show $F_k \pitchfork W_k$, so $F_k(q, -) \pitchfork W_k$ for generic q by parametric transversality.

- For all $k \in \{0, \dots, n+1\}$, define

$$F_k: \begin{cases} \mathcal{P}_d \times \mathbf{R}^n \times (\mathbf{R}^{n(k+1)} \setminus \Delta) & \rightarrow {}_{k+1}J^0(\mathbf{R}^n, \mathbf{R}^2) \\ (q, x, \bar{y}) & \mapsto (\bar{y}, \dots, q(y_i), \dots, \|x - y_i\|^2, \dots), \end{cases}$$

$$W_k := \left\{ (\bar{z}, \bar{s}, \bar{t}) \in {}_{k+1}J^0(\mathbf{R}^n, \mathbf{R}^2) \mid \begin{array}{l} \forall i \in \{0, \dots, k\}, s_i = 0, \\ \forall i \in \{1, \dots, k\}, t_i = t_0 \end{array} \right\}.$$

- We show $F_k \pitchfork W_k$, so $F_k(q, -) \pitchfork W_k$ for generic q by parametric transversality.
- This implies that $y_0, \dots, y_k \in B(x, \text{dist}_Y(x)) \cap Y$ the $\{y_i - y_0\}_{i=1}^k$ are linearly independent.

- For all $k \in \{0, \dots, n+1\}$, define

$$F_k: \begin{cases} \mathcal{P}_d \times \mathbf{R}^n \times (\mathbf{R}^{n(k+1)} \setminus \Delta) & \rightarrow \\ (q, x, \bar{y}) & \mapsto (\bar{y}, \dots, q(y_i), \dots, \|x - y_i\|^2, \dots), \end{cases}$$

$$W_k := \left\{ (\bar{z}, \bar{s}, \bar{t}) \in {}_{k+1}J^0(\mathbf{R}^n, \mathbf{R}^2) \mid \begin{array}{l} \forall i \in \{0, \dots, k\}, s_i = 0, \\ \forall i \in \{1, \dots, k\}, t_i = t_0 \end{array} \right\}.$$

- We show $F_k \pitchfork W_k$, so $F_k(q, -) \pitchfork W_k$ for generic q by parametric transversality.
- This implies that $y_0, \dots, y_k \in B(x, \text{dist}_Y(x)) \cap Y$ the $\{y_i - y_0\}_{i=1}^k$ are linearly independent.
- The case $k = n+1$ implies that $B(x, \text{dist}_Y(x)) \cap Y$ has at most $n+1$ elements, and these elements thus form a nondegenerate simplex.

Theorem

- For p and q generic of degree ≥ 3 , there are a finite number of critical points.
- The number of critical points with piecewise linear index k is bounded above by $c(k, n) \deg(p)^n \deg(q)^{n(k+1)}$.

Theorem

- For p and q generic of degree ≥ 3 , there are a finite number of critical points.
- The number of critical points with piecewise linear index k is bounded above by $c(k, n) \deg(p)^n \deg(q)^{n(k+1)}$.

Idea of proof:

- We follow a similar approach to [Di Rocco et al. 2023], defining necessary algebraic equations for critical points.
- The set of polynomials and points satisfying these equations is our W , and we apply parametric transversality.
- The upper bound follows from a bound on the Betti numbers of an algebraic set [Basu-Rizzie 2018].

- Specifically, we define

$$F^1 : \left\{ \begin{array}{l} \mathcal{P}_{d_1} \times \mathcal{P}_{d_2} \times \mathbf{R}^n \times (\mathbf{R}^{n(k+1)} \setminus \Delta) \times \mathbf{R}^{k+3} \rightarrow J^1(\mathbf{R}^n, \mathbf{R}) \times {}_{k+1}J^1(\mathbf{R}^n, \mathbf{R}) \times \mathbf{R}^{k+3} \\ (p, q, x, \bar{y}, \bar{\lambda}, \mu, r) \mapsto (x, p(x), \nabla p(x), \bar{y}, q(\bar{y}), \nabla q(\bar{y}), \bar{\lambda}, \mu, r) \end{array} \right.$$

$$W^1 := \left\{ \begin{array}{l} (x, s, u) \in J^1(\mathbf{R}^n, \mathbf{R}), \\ (\bar{y}, \bar{t}, \bar{v}) \in {}_{k+1}J^1(\mathbf{R}^n, \mathbf{R}), \\ \bar{\lambda} \in \mathbf{R}^{k+1}, \\ \mu, r \in \mathbf{R} \end{array} \quad \left| \begin{array}{l} x = \mu u + \sum_{i=0}^k \lambda_i y_i, \\ \sum_{i=0}^k \lambda_i = 1, \\ s = 0, \\ \forall i \in \{0, \dots, k\}, t_i = 0, \\ \forall i \in \{0, \dots, k\}, \|x - y_i\|^2 = r^2, \\ \forall i \in \{0, \dots, k\}, \text{rk}(x - y_i, v_i) \leq 1 \end{array} \right. \right\}.$$

- The intersection $\text{im } F^1(p, q, -) \cap W^1$ defines **algebraic k -critical points**.

Proposition

- For p and q generic of degrees ≥ 3 and ≥ 4 , respectively, the distance function $\text{dist}_Y|_X$ is a continuous selection around each of its critical points.

Proposition

- For p and q generic of degrees ≥ 3 and ≥ 4 , respectively, the distance function $\text{dist}_Y|_X$ is a continuous selection around each of its critical points.

Idea of proof:

- We show that each critical point is a regular value of the exponential map.

- We define

$$F^2: \left\{ \begin{array}{l} \mathcal{P}_{d_1} \times \mathcal{P}_{d_2} \times \mathbf{R}^n \times (\mathbf{R}^{n(k+1)} \setminus \Delta) \times \mathbf{R}^{k+3} \\ (p, q, x, \bar{y}, \bar{\lambda}, \mu, r) \end{array} \right. \rightarrow J^1(\mathbf{R}^n, \mathbf{R}) \times {}_{k+1}J^2(\mathbf{R}^n, \mathbf{R}) \times \mathbf{R}^{k+3}$$

$$\mapsto (x, p(x), \nabla p(x), \bar{y}, q(\bar{y}), \nabla q(\bar{y}), H(q)(\bar{y}), \bar{\lambda}, \mu, r)$$

$$W^2 := \left\{ \begin{array}{l} (x, s, u) \in J^1(\mathbf{R}^n, \mathbf{R}), \\ (\bar{y}, \bar{t}, \bar{v}, \bar{H}) \in {}_{k+1}J^2(\mathbf{R}^n, \mathbf{R}), \\ \bar{\lambda} \in \mathbf{R}^{k+1}, \\ \mu, r \in \mathbf{R} \end{array} \middle| \begin{array}{l} (x, s, u, \bar{y}, \bar{t}, \bar{v}, \bar{\lambda}, \mu, r) \in W^1, \\ \forall i \in \{0, \dots, k\}, \\ \text{rk}[(I_n + rH_i)(I_n - v_i v_i^\top), v_i] < n \end{array} \right\}.$$

- The extra condition on W^2 translates to being a regular value for the exponential map.

Theorem

- For p and q generic of degrees ≥ 4 , the critical points of $\text{dist}_Y|_X$ are all nondegenerate.

Theorem

- For p and q generic of degrees ≥ 4 , the critical points of $\text{dist}_Y|_X$ are all nondegenerate.

Idea of proof:

- We define necessary algebraic equations for degenerateness.
- Fact:** Degenerate critical points satisfy certain algebraic equations related to the second fundamental form of Y , which, at a point $y \in Y$, can be expressed as

$$\text{II}_y : \begin{cases} T_y Y \times T_y Y \rightarrow N_y Y = \mathbf{R}\nabla q(y) \\ (v, w) \mapsto -\frac{\nabla q(y)}{\|\nabla q(y)\|} v^\top H(q)(y) w. \end{cases}$$

- We define

$$F^3 : \left\{ \begin{array}{l} \mathcal{P}_{d_1} \times \mathcal{P}_{d_2} \times \mathbf{R}^n \times (\mathbf{R}^{n(k+1)} \setminus \Delta) \times \mathbf{R}^{k+3} \rightarrow J^2(\mathbf{R}^n, \mathbf{R}) \times {}_{k+1}J^2(\mathbf{R}^n, \mathbf{R}) \times \mathbf{R}^{k+3} \\ (p, q, x, \bar{y}, \bar{\lambda}, \mu, r) \mapsto (x, p(x), \nabla p(x), H(p)(x), \bar{y}, q(\bar{y}), \nabla q(\bar{y}), H(q)(\bar{y}), \bar{\lambda}, \mu, r)' \end{array} \right.$$

$$W^3 := \left\{ \begin{array}{l} (x, s, u, \bar{y}, \bar{t}, \bar{v}, \bar{\lambda}, \mu, r) \in W^1, \\ \forall i \in \{0, \dots, k\}, \nu_i := \frac{\nu_i}{\|\nu_i\|} \in \mathbf{R}^n, \\ \forall i, Q_i := (I_n - \nu_i \nu_i^\top) \frac{H_i}{\|H_i\|} (I_n - \nu_i \nu_i^\top) \in \mathbf{R}^{n \times n}, \\ \forall i, \tilde{H}_i := \frac{-Q_i}{1-rQ_i} \in \mathbf{R}^{n \times n}, \\ V := [\frac{u}{\|u\|}, \nu_0, \dots, \nu_k] \in \mathbf{R}^{n \times (k+2)}, \\ L := I_n - V(V^\top V)^{-1}V^\top \in \mathbf{R}^{n \times n}, \\ \text{rk}(\mu L^\top GL + r \sum_{i=0}^k \lambda_i L^\top \tilde{H}_i L) \leq n - k - 3 \end{array} \right\}.$$

Thank you for your attention :)

Summary

- We (re)develop Morse theory for distance functions between subsets of \mathbb{R}^n using the notion of **continuous selections**.
- We establish that the nondegeneracy of distance functions between algebraic hypersurfaces is generic using a **multijet parametric transversality theorem**.
- We also compute bounds for the number of critical points of such functions, which **generalize bounds** on the bottleneck degree and the Euclidean distance degree.
 - Our results should hold in the complex case as well.

Thank you for your attention :)

References

- Y. Yomdin. *On the local structure of a generic central set*, 1981.
- H. T. Jongen and D. Pallaschke. *On linearization and continuous selections of functions*, 1988.
- A. A. Agrachev, D. Pallaschke, and S. Scholtes. *On Morse theory for piecewise smooth functions*, 1997.
- S. Di Rocco, P. B. Edwards, D. Eklund, O. Gafvert, and J. D. Hauenstein. *Computing Geometric Feature Sizes for Algebraic Manifolds*, 2023.
- A. Song, K. M. Yim, and A. Monod. *Generalized Morse theory of distance functions to surfaces for persistent homology*, 2023.
- **Preprint:** A. Guidolin, A. Lerario, I. Ren, and M. Scolamiero. *Morse theory of Euclidean distance functions and applications to real algebraic geometry*, arXiv:2402.08639.