## Assignment 2

```
//GPS.java
package ccoew.it.businesslogic;
import java.util.ArrayList;
public class GPS
       private int id;
       ArrayList<Track_Route>tr=new ArrayList<Track_Route>();
       public int getId()
              return id;
       }
       public void setId(int id)
              this.id = id;
       }
       public void start_recording()
              System.out.println("ID "+getId()+" START RECORDING");
       }
       public void stop_recording()
              System.out.println("ID "+getId()+" STOP RECORDING");
}
//Track_point.java
package ccoew.it.businesslogic;
public class Track_Point
       private double x;
       private double y;
       private double z;
       private double time;
       public Track_Point(double x, double y, double z, double time)
              super();
              this.x = x;
              this.y = y;
              this.z = z;
              this.time = time;
```

```
}
       public double getX()
              return x;
       public void setX(double x)
              this.x = x;
       public double getY()
              return y;
       public void setY(double y)
              this.y = y;
       public double getZ()
              return z;
       public void setZ(double z)
              this.z = z;
       public double getTime()
              return time;
       public void setTime(double time)
              this.time = time;
}
//Track_Route.java
package ccoew.it.businesslogic;
import java.util.ArrayList;
public class Track_Route
       private String name;
       ArrayList<Track_Point> tp=new ArrayList<Track_Point>();
       int i;
       double total, length,length1,breadth,breadth1,time,velocity;
       double height,height1,total1,total2,total3,final_total,sum=0.0;
       public Track_Route(String name)
```

```
{
       super();
       this.name = name;
}
public String getName()
       return name;
}
public void setName(String name)
       this.name = name;
}
public ArrayList<Track_Point> getTp()
       return tp;
}
public void setTp(ArrayList<Track_Point> tp)
{
       this.tp = tp;
}
public void addTrack(Track_Point track_point)
       tp.add(track_point);
}
public void calculate_length(ArrayList<Track_Point> tp1)
       for(i=0;i<(tp.size()-1);i++)
              length=tp.get(i).getX();
              length1=tp.get(i+1).getX();
              total=length-length1;
              breadth=tp.get(i).getY();
               breadth1=tp.get(i+1).getY();
               total1=breadth-breadth1;
              height=tp.get(i).getZ();
              height1=tp.get(i+1).getZ();
              total2=height-height1;
               final_total=Math.sqrt((total*total)+(total1*total1)+(total2*total2));
              sum=sum+final total;
       int size=tp.size()-1;
       time=tp.get(size).getTime();
       velocity=sum/time;
```

```
System.out.println("Length is "+sum);
              System.out.println("velocity is"+velocity);
       }
}
//Test.java
package ccoew.it.client;
import java.util.ArrayList;
import ccoew.it.businesslogic.*;
public class Test
       public static void main(String[] args)
                     GPS gps =new GPS();
                     gps.start_recording();
                     Track_Route tr=new Track_Route("Track_Route1");
                     System.out.println(tr.getName());
                     ArrayList<Track_Point> tp1=new ArrayList<Track_Point>();
                     Track_Point tp_new=new Track_Point(10,10,10,10);
                     tr.addTrack(tp_new);
                     Track_Point tp_new1=new Track_Point(0,0,0,20);
                     tr.addTrack(tp_new1);
                     Track_Point tp_new2=new Track_Point(10,10,10,30);
                     tr.addTrack(tp_new2);
                     Track_Point tp_new3=new Track_Point(30,30,30,40);
                     tr.addTrack(tp_new3);
                     Track_Point tp_new4=new Track_Point(50,50,50,50);
                     tr.addTrack(tp_new4);
                     Track_Point tp_new5=new Track_Point(60,60,60,60);
                     tr.addTrack(tp_new5);
                     tp1=tr.getTp();
                     tr.calculate_length(tp1);
                     gps.stop_recording();
```

## //OUTPUT

ID 0 START RECORDING Track\_Route1 Length is 121.24355652982142 velocity is2.0207259421636903 ID 0 STOP RECORDING