

# NUMCALC

A NUMERICAL CALCULATOR APP

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## FINAL PROJECT

### Second report

*Objective: To specify the methods used for solving roots of polynomials and linear system of equations through their pseudocodes, and to show the preliminary results for the test functions.*

## Numerical Methods

### 1. Incremental search

```
read function, x0, dx, n
xprev=x0
xact=x0+dx
rootCount=0
for i=1 to n do
    if f(xact)*f(xprev)<0
        There is a root for the function in xprev, xact
    end
end
if rootcount==0
    No roots were found for the given number of n iterations and step size
end
end
```

### Results

There's a root for the function in [-2.5, -2]  
There's a root for the function in [-1, -0.5]  
There's a root for the function in [0.5, 1]  
There's a root for the function in [2, 2.5]  
There's a root for the function in [4, 4.5]  
There's a root for the function in [5, 5.5]  
There's a root for the function in [7, 7.5]  
There's a root for the function in [8, 8.5]  
There's a root for the function in [10, 10.5]  
There's a root for the function in [11.5, 12]  
There's a root for the function in [13.5, 14]  
There's a root for the function in [14.5, 15]  
There's a root for the function in [16.5, 17]  
There's a root for the function in [17.5, 18]  
There's a root for the function in [19.5, 20]

There's a root for the function in [21, 21.5]  
There's a root for the function in [22.5, 23]  
There's a root for the function in [24, 24.5]  
There's a root for the function in [26, 26.5]  
There's a root for the function in [27, 27.5]  
There's a root for the function in [29, 29.5]  
There's a root for the function in [30, 30.5]  
There's a root for the function in [32, 32.5]  
There's a root for the function in [33.5, 34]  
There's a root for the function in [35, 35.5]  
There's a root for the function in [36.5, 37]  
There's a root for the function in [38.5, 39]  
There's a root for the function in [39.5, 40]  
There's a root for the function in [41.5, 42]  
There's a root for the function in [43, 43.5]  
There's a root for the function in [44.5, 45]  
There's a root for the function in [46, 46.5]

## 2. Bisection Method

```
read function,xi,xs,tolerance, niter
i <- 1
xm <- (xi + xs)/2
fxm <- f(xm)
error = absolute value of xm
while error > tolerance and i<niter and fxm different to 0
  if f(a)*fxm<0
    b=xm
    xm=(a+b)/2
    error=absolute value of xm-a
  else if f(b)*fxm<0
    a=xm
    xm=(a+b)/2
    error=absolute value of xm-a
  end
  fxm=f(xm)
  i=i+1
end
if fxm=0 then
  the root was found with a value of xm
end
else if error<=tolerance then
  an approximation of the root was found
  with a value of xm
```

```
end
if i==n
    The root was not found in the number
    of iterations given
end
```

## Results

Iteration	a	xn	b	f(xn)	E
22	0.936404	0.936404466	0.9364047	-6.616005e-08	2.3841857e-07
23	0.9364044	0.936404585	0.9364047	2.8715108e-09	1.192092e-07
24	0.9364044	0.93640452	0.93640458	-3.1644283e-08	5.9604644e-08

An approximation of the root was found with a value of 0.9364 and an error of 5.9605e-08

## 3. False position

```
read function, a, b, tolerance,n
i = 1
E = inifnite
fxn = 1
while E>tolerance and i<n and fxn different from 0
    xn=b-f(b)*((b-a)/(f(b)-f(a)))
    fxn=f(xn)
    if f(a)*fxn>0
        E=absolute value of xn-a
        a=xn
    else if f(b)*fxn>0
        E=absolute value of xn-b
        b=xn
    end
    i=i+1
end
if fxn==0
    The root was found with a value of xn
end
if E<= tolerance
    An aproximation of the root was found with a value of xn
end
if i==n
    The root was not found in the number of iterations given
```

```
end  
end
```

## Results

Iteration	a	xn	b	f(xn)	E
3	0.933940380	0.9364047	0.9365060	8.6782541e-08	0.000101320922984094
4	0.933940	0.9364045	0.936404	1.2815393e-10	1.49641e-07
5	0.933940	0.936404	0.9364045	1.8918200e-13	2.209796e-10

An aproximation of the root was found with a value of 0.9364 and an error of 2.2098e-10

## 4. Newton method

```
read function, df, x0, tolerance, n  
if f(x0)=0  
    The inital point given is root  
end  
xn=x0  
fxn=f(xn)  
i=1  
E=infinite  
while E>tolerance and i<n and fxn different from 0  
    xprev = xn  
    xn=xprev-(f(xprev))/df(xprev))  
    E=absolute value of xn-xprev  
    fxn=f(xn)  
    i++  
end  
if fxn=0  
    The root was found with a value of xn  
end  
if E<= tolerance  
    An aproximation of the root was found with a value of xn  
end  
if i=n  
    The root was not found in the number of iterations given  
end  
end
```

## Results

Iteration	xn	f(xn)	E
2	0.936366741267331	-2.19126198827135e-05	0.00797475135475945
3	0.93640458001899	-4.98339092214195e-10	3.78387516588585e-05
4	0.936404580879562	-1.11022302462516e-16	8.60571947036703e-10

An aproximation of the root was found with a value of 0.9364 and an error of 8.6057e-10

## 5. Fixed point

```
read function, g, x0, tolerance, n
if f(x0)=0
    The initial point given is the root
end
xn=x0
fxn=f(xn)
gxn=g(xn)
i=1
E=infinite
while E>tolerance and i<n and fxn different from 0
    xprev=xn
    xn=gxn
    E=absolute value of xn-xprev
    fxn=f(xn)
    gxn=g(xn)
    i++
end
if fxn=0
    The root was found with a value of xn
end
if E<= tolerance
    An aproximation of the root was found with a value of xn
end
if i=n
    The root was not found in the number of iterations given
end
end
```

## Results

Iteration	xn	g(xn)	f(xn)	E
28	-0.3744451043623	-0.3744449757003	1.286620382457e-07	2.142604523803e-07
29	-0.3744449757003	-0.3744450529611	-7.726074024994e-08	1.286620382456e-07
30	-0.3744450529611	-0.3744450065665	4.639458395239e-08	7.726074024994e-08

An approximation of the root was found with a value of -0.37445 and an error of 7.7261e-08

## 6. Secant method

```

read function,x0,x1, tolerance,
if f(x0)=0
The initial point x0 given is the root
end
if f(x1)=0
The initial point x1 given is the root
end
xn=x0
xnext=x1
fxn=f(xnext)
i=2
e=infinite
while e>tolerance and i<n and fxn different from 0
    xprev=xn
    xn=xnext
    xnext=xn-(f(xn)/((f(xn)-f(xprev))/(xn-xprev)))
    e=absolute value of xnext-xn
    fxn=f(xnext)
    i++
end
if fxn=0
    The root was found with a value of xn
end
if E<= tolerance
    An aproximation of the root was found with a value of xn
end
if i=n
    The root was not found in the number of iterations given
end
end

```

## Results

Iteration	xn	f(xn)	E
4	0.936407002376704	1.40223589106814e-06	0.000410421585531284
5	0.93640458147312	3.43716499706659e-10	2.42090358437697e-06
6	0.936404580879561	-4.9960036108132e-16	5.93558091566138e-10

An aproximation of the root was found with a value of 0.9364 and an error of 5.9356e-10

## 7. Simple Gauss Elimination

```
read A,b
Ab=[A b]
[f,c]=size of Ab
for j=1 to c-2
  for i=j to f-1
    Ab(i+1,j to c)=Ab(i+1,j to c)-(Ab(i+1,j)/Ab(j,j))*Ab(j,j to c)
  end
end
end
```

## Regresive Sustitution function

```
read A,b
[f,c]<-size of A
x(f)<-b(f)/A(f,f)
for i=f-1 reducing 1 each step to 1
  sum=0
  for j=i+1 to f
    sum=sum+A(i,j)*x(j)
  end
  x(i)=(b(i)-sum)/A(i,i)
end
end
\\
\\
```

## Main function

```
read A,b
[U,B]<-Elimination with parameters A,b
x<-Regresive sustitution function with parameters U,B
The solution of the equation is x
```



## Results

Stage 2:

2.0000	-1.0000	0	3.0000	1.0000
0	1.0000	3.0000	6.5000	0.5000
0	0	-41.0000	-73.5000	-5.5000
0	0	-38.000	-96.0000	-12.0000

Stage 3:

2.0000	-1.0000	0	3.0000	1.0000
0	1.0000	3.0000	6.5000	0.5000
0	0	-41.0000	-73.5000	-5.5000
0	0	0	-27.878048780487802	-6.902439024390244

Solution:

0.038495188101487 -0.180227471566054 -0.309711286089239 0.247594050743657

## 8. Gauss elimination with partial pivot

### Function of Gaussian elimination with partial pivot (ElimPivPar)

```
read A,b
[f,c]<-size of Ab
for j=1 to c-2
  col<-absolute value of j to f, j
  m<- find maximum in col
  temp<- Ab in row j
  Ab in row j <- Ab in row m+j-1
  Ab in rom m+j-1<- temp
  for i=j to f-1
    Ab in row i+1 and column j to c<-Ab(i+1,j:c)-(Ab(i+1,j)/Ab(j,j))*Ab(j,j:c)
  end
end
end
```

### Regresive Sustitution function

```
read A,b
[f,c]<-size of A
x(f)<-b(f)/A(f,f)
for i=f-1 reducing 1 each step to 1
  sum=0
  for j=i+1 to f
    sum=sum+A(i,j)*x(j)
  end
```

```
x(i)=(b(i)-sum)/A(i,i)
end
end
```

### Main function

```
read A,b
[U,B]<-function ElimPivPar with parameters A,b
x<-Regresive substitution function with parameters U,B
The solution of the equation is x
```

### Results

Stage 2:

14.000	5.000	-2.000	3.000	1.000
0	13.000	-2.000	11.000	1.000
0	0	3.164835164835165	7.664835164835164	0.917582417582418
0	0	0.021978021978022	4.021978021978022	0.989010989010989

Stage 3:

14.000	5.000	-2.000	3.000	1.000
0	13.000	-2.000	11.000	1.000
0	0	3.164835164835165	7.664835164835164	0.917582417582418
0	0	0	3.96875000	0.982638888888889

Solution:

0.038495188101487	-0.180227471566054	-0.309711286089239	0.247594050743657
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## 9. Gauss method with total pivot

### Elimination Gauss method with total pivot (ElimPivTot)

```
read A,b
A,b=[A b]
[f c]= size of Ab
tags<-1 to c-1
for j=1 to c-2
  subm <- submatrix of Ab(j to f,j to c-1)
  [mi,mj]<-find maximum between subm,[]
  temp<-Ab(j,j to end)
  Ab(j, j to end)<-Ab(mi+j,j to end)
  Ab(mi+j-1,j to end)<-temp
  temp<-Ab in column j
  Ab in column mj+j-1<-temp
  temp<-tags(j)
  tags(j)<-tags(mj+j-1)
```

```

        tags(mj+j-1)=temp
        for i=j to f-1
            Ab(i+1,j to c)=Ab(i+1,j to c)-(Ab(i+1,j)/Ab(j,j))*Ab(j,j to c)
        end
    end
end

```

### Regressive Substitution function (solve)

```

read A,b
[f,c]<-size of A
x(f)<-b(f)/A(f,f)
for i=f-1 reducing 1 each step to 1
    sum=0
    for j=i+1 to f
        sum=sum+A(i,j)*x(j)
    end
    x(i)=(b(i)-sum)/A(i,i)
end
end
\\
\\

```

### Main function

```

read A,b
[U,B,tags]<-ElimPivTot(A,b)
x<-solve(U,B)
f<-size of x,2
xtemp<-[]
for i=1 to f
    ind<-tags in position i
    xtemp(ind)<-x(i)
end
x=xtemp
end

```

### Results

Stage 2:

14.0000	5.0000	-2.0000	3.0000	1.0000
0	13.0000	-2.0000	11.0000	1.0000
0	0	3.1648	7.6648	0.9176
0	0.0000	0.0220	4.0220	0.9890

Stage 3:

14.0000	5.0000	3.0000	-2.0000	1.0000
0	13.0000	11.0000	-2.0000	1.0000
0	0	7.6648	3.1648	0.9176
0	0.0000	0	-1.6387	0.5075

Solution:

0.0385 -0.1802 -0.3097 0.2476

## 10. Multiple roots

```
read f, df, d2f, x0, tolerance, n
if f(x0)=0
    The initial point given is the root
end
xn=x0
Fxn=f(xn)
i=1;
E=infinite
while E>tolerance and i<N and Fxn different from 0
    xprev<-xn
    F<-f(xprev);
    dF<-df(xprev)
    d2F<-d2f(xprev)
    xn<-xprev-(F*dF)/((dF^2)-F*d2F)
    Fxn<-f(xn)
    E=absolute value of xn-xant
    i=i++;
end
if Fxn=0
    The root was found with a value of xn
    return
end
if E<=Tol
    An approximation of the root was found with a value of xn and an error of E
    return
end
if i=N
    The root was not found in the number of iterations given
    return
end
end
```

## Results

Iteration	xn	f(xn)	E
2	-0.0084583	3.5671e-05	0.22575
3	-1.189e-05	7.0688e-11	0.0084464
4	-4.2186e-11	0	1.189e-05

The root was found with a value of -4.2186e-11

## 11. Müller's algorithm

```

read f, x0, x1, x2, tolerance, N

h1 = x1 - x0
h2 = x2 - x1
d1 = (f(x1) - f(x0))/h1
d2 = (f(x2) - f(x1))/h2
d = (d2 - d1)/(h2 + h1)
i = 2

while i < N:
    b = d2 + h2*d
    D = (b^2 - 4*f(x2)*d)^1/2 ----- from the quadratic formula

    if |b-D| < |b+D|:
        E = b + d
    else:
        E = b - d

    h = -2*f(x2)/E

    if |h| < tolerance:
        return p, E, i -----p is the x coordinate for the root and E the
                                i-th iteration error

        break
    else:
        x0 = x1
        x1 = x2
        x2 = p
        h1 = x1 - x0
        h2 = x2 - x1
        d1 = ((f(x1) - f(x2))/h1
        d2 = ((f(x2) - f(x1))/h2
        d = (d2 - d1)/(h2 + h1)

```

```

        i = i + 1
    end

    print: "The method failed after " + N + " iterations"

```

## Results

Iteration	xn	f(xn)	E
6	1.8393	-1.3324e-05	0.001417
7	1.8393	2.0229e-10	2.4357e-06
8	1.8393	2.2204e-16	3.6978e-11

An aproximation of the root was found with a value of 1.8393 and an error of 3.6978e-11

## 12. Steffensen's algorithm

```

read g (function), p0 (initial value), tolerance, N

i = 1

while i < N:
    p1 = g(p0)
    p2 = g(p1)
    p = p0 - (p1-p0)^2/(p2-2*p1+p0)

    if |p-p0| < tolerance:
        return p ----- p is the x coordinate for the root and E the
                           i-th iteration error
    else:
        i = i + 1
        p0 = p
end

```

The method failed after N iterations

## Results

Iteration	xn	f(xn)	E
3	0.93634	-3.6044e-05	0.0081341
4	0.9364	-2.1289e-09	6.2238e-05
5	0.9364	-2.2204e-16	3.6764e-09

An aproximation of the root was found with a value of 0.9364 and an error of 3.6764e-09

### 13. Aitken's process for accelerating convergence

```
read f, g, x0, tolerance, N

% Initial assignments
xn=x0
Fxn=f(xn)
Gxn=g(xn)
i=1;
E=inf;

while E > tolerance and i < N and Fxn different to 0
    AitkenMod = false
    xant = xn
    xn = Gxn

    % Check mod3 families until we obtain a multiple of 3
    if mod(i,3) == 1
        x1 = xn;
    else if mod(i,3) = 2
        x2 = xn;
    else if mod(i,3) = 0
        xn = x0 - ((x1-x0)^2/(x2-2*x1+x0))
        x0 = xn;
        AitkenMod = true

    E = abs(xn-xant)
    Fxn = f(xn)
    Gxn = g(xn)
    i=i+1
end

if Fxn == 0
    print: "The root was found with a value of " + xn
    return
if E <= tolerance
    print: "An aproximation of the root was found with a value of " + xn + " and
        an error of " + E
    return
if i == N
    print: "The root was not found in the number of iterations given"
```

return

## Results

Iteration	xn	Aitken	g(xn)	f(xn)	E
8	-0.37444	0	-0.37445	-7.641e-07	1.2724e-06
9	-0.37445	1	-0.37445	-4.9033e-13	4.7741e-07
10	-0.37445	0	-0.37445	2.9454e-13	4.9033e-13

An approximation of the root was found with a value of -0.37445 and an error of 4.9033e-13

## 14. Tridiagonal Gaussian Elimination

```

read A,b ----- % Ax = b system
n = length(b)

% Check if matrix is tridiagonal
for i=1 : n
    for j=1 : n
        aij = A(i,j);
        if i = j or i-1 = j or i+1 = j
            if aij = 0
                "The given matrix is not tridiagonal"
                return
            else
                if aij != 0
                    "The given matrix is not tridiagonal"
                    return
                end
            end
        end
    end
end

Ab = [A b] ----- % Augmented A|b matrix
diagp = zeros(n,1)
diagu = zeros(n-1,1)
diagl = zeros(n-1,1)
diagp(1) = A(1,1)

for i=2 : n
    % Extract the elmenents from each diagonal
    diagl(i-1) = Ab(i,i-1)
    diagp(i) = Ab(i,i)
    diagu(i-1) = Ab(i-1,i)

```



```
% Making the diagonal below zeros
M = diagl(i-1)/diagp(i-1) ----- % Multiplier
diagp(i) = diagp(i)-M*diagu(i-1)
diagl(i-1) = diagl(i-1)-M*diagp(i-1)
b(i) =b(i)-M*b(i-1)
Ab(i,i-1:i+1) = [diagl(i-1) diagp(i) diagu(i-1)]
Ab(i,end) = b(i)
end

% Substitution
x(n) = b(n)/diagp(n)
for i=n-1 : -1 : 1
    x(i) = (b(i)-diagu(i)*x(i+1))/diagp(i);
end
print: x
```

## Results

Stage 0:

2.0400	-1.0000	0	48.8000
-1.0000	2.0400	-1.0000	0.8000
0	-1.0000	2.0400	0.8000

Stage 2:

2.0400	-1.0000	0	48.8000
0	1.5498	-1.0000	24.7216
0	-1.0000	2.0400	0.8000

Stage 3:

2.0400	-1.0000	0	48.8000
0	1.5498	-1.0000	24.7216
0	0	1.3948	16.7514

Solution:

35.5397	23.7010	12.0103
---------	---------	---------

The matrix given in Microsoft Teams to test Elimination Methods came out as not Tridiagonal.

## 15. Trisection

```
read f,a,b,Tol,N
```

```
if a>=b
    The given interval is not valid, a is greater or equal to b
    return
end
if f(a) is 0
    The root is the given value for a
    return
end
if f(b) is 0
    The root is the given value for b
    return
end
if f(a)*f(b)>0
    There is no root in the given interval
    return
end
i=1;
xm1=(2*a+b)/3; %mid point 1
xm2=(2*b+a)/3; %mid point 2
Fxm1=f(xm1);
Fxm2=f(xm2);
if absolute value of Fxm1<= absolute value of Fxm2
    xm=xm1;
    Fxm=Fxm1;
else
    xm=xm2;
    Fxm=Fxm2;
end
E=absolute value of xm;
while E>Tol and i<N and Fxm1 different to 0
    if f(a)*Fxm1<0
        b=xm1;
    elseif Fxm1*Fxm2<0
        a=xm1;
        b=xm2;
    else
        a=xm2;
    end
    xm1=(2*a+b)/3
    xm2=(2*b+a)/3
    Fxm1=f(xm1)
    Fxm2=f(xm2)
    xant=xm
```

```

        if absolute value of Fxm1<= absolute value of Fxm2
            xm=xm1
            Fxm=Fxm1
        else
            xm=xm2
            Fxm=Fxm2
        end
        E=absolute value of xm-xant
        i=i+1
    end
    if Fxm==0
        The root was found with a value of xm
        return
    end
    if E<=Tol
        An approximation of the root was found with a value of xm and an error of E
        return
    end
    if i==N
        The root was not found in the number of iterations given
        return
    end
end
end

```

## Results

Iteration	a	xn	b	f(xn)	E
13	0.93640310025	0.9364043547	0.9364049819	-1.3098e-07	6.2723e-07
14	0.93640435470	0.9364045637	0.9364049819	-9.9042e-09	2.0908e-07
15	0.93640456377	0.93640463346	0.9364047728	3.0453e-08	6.9692e-08

An aproximation of the root was found with a value of 0.9364 and an error of 6.9692e-08

## 16. Jacobi

```

function read A,b,x0,p,Tol,N
if det(A)==0
    error
D<- diagonal of A
L<- -lower triangular part of A +D
U<- -upper triangular part of A +D
T<- inverse matrix of D *(L+U)

```

```

C<-inverse matrix of D *b
ro<- maximum of |eigenvalues of T| %spectral radius of iteration matrix
x<-x0
i<-0
E<-infinite
while E>Tol and i<N
    xprev<-x
    x<-T*xprev+C
    E=p_norm of x-xprev
    i<-i+1
end
end

```

## Results

Iteration	Error	x1	x2	x3	x4
50	1.5846e-07	0.52511	0.25546	-0.41048	-0.28166
51	1.1941e-07	0.52511	0.25546	-0.41048	-0.28166
52	8.9974e-08	0.52511	0.25546	-0.41048	-0.28166

Answer  
0.5251  
0.2555  
-0.4105  
-0.2817

## 17. Crout Factorization

```

function read A
[f,c]=size of A
L=matrix of zeros with dimensions f,c
U=identity matrix of f dimension
L(:,1)=A(:,1)
U(1,2 to end)=A(1,2 to end)/L(1,1)
for j=2 to c
    for i=2 to f
        if i>=j
            L(i,j)= A(i,j)- [(L(i,1 to i-1) x
            transpose matrix of U(1 to i-1,j))]
        else
            U(i,j)=(A(i,j)- [(L(i,1:j-1) x U(1:j-1,j)')))/L(i,i)]
        end
    end
end

```

```
end
end
end
```

## Results

Lower Triangular Matrix L

4.0000	0.0000	0.0000	0.0000
1.0000	15.7500	0.0000	0.0000
0.0000	-1.3000	-3.7524	0.0000
14.0000	8.5000	-3.6190	13.9492

Upper Triangular Matrix U

1.0000	-0.2500	0.0000	0.7500
0.0000	1.0000	0.1905	0.4603
0.0000	0.0000	1.0000	-0.4526
0.0000	0.0000	0.0000	1.0000

Progressive substitution  $Lz=b$

0.2500 0.0476 -0.2830 -0.2817

Regresive substitution  $Ux=z$ , solution

0.5251 0.2555 -0.4105 -0.2817

## 18. Gauss Seidel Method

```
function read A,b,x0,p,Tol,N
if det(A)==0
    error
D<- diagonal of A
L<- -lower triangular part of A +D
U<- -upper triangular part of A +D
T<- inverse matrix of D *(L+U)
C<-inverse matrix of D *b
ro<- maximum of |eigenvalues of T| %spectral radius of iteration matrix
x<-x0
i<-0
E<-infinite
while E>Tol and i<N
    xprev<-x
    x<-T*xprev+C
    E<-p_norm of x-xprev
    i<-i+1
end
```

end

## Results

Iteration	Error	x1	x2	x3	x4
28	2.7736e-07	0.52511	0.25546	-0.41048	-0.28166
29	1.6628e-07	0.52511	0.25546	-0.41048	-0.28166
30	9.968e-08	0.52511	0.25546	-0.41048	-0.28166

Answer

0.5251

0.2555

-0.4105

-0.2817

## 19. Doolittle Factorization

```
function read A
[f,c]=size of A
L= identity matrix of dimension f
U=zero matrix of dimensions f,c
for j=1 to c
    for i=1 to f
        if i<=j
            U(i,j)=A(i,j)
            U(i,j)=U(i,j)-[(L(i,1:i-1) x Transpose matrix of U(1:i-1,j))]
        else
            L(i,j)=A(i,j)
            L(i,j)=L(i,j)-[(L(i,1:j-1) x Transpose matrix of U(1:j-1,j))]
            L(i,j)=L(i,j)/U(j,j)
        end
    end
end
end
```

## Results

Lower Triangular Matrix L

1.0000	0.0000	0.0000	0.0000
0.2500	1.0000	0.0000	0.0000
0.0000	-0.0825	1.0000	0.0000
3.5000	0.5397	0.9645	1.0000

Upper Triangular Matrix U

4.0000	-1.0000	0.0000	3.0000
0.0000	15.7500	3.0000	7.2500
0.0000	0.0000	-3.7500	1.6984
0.0000	0.0000	0.0000	13.9492

Progressive substitution  $Lz=b$

1.0000 0.7500 1.0619 -3.9289

Regressive substitution  $Ux=z$ , solution

0.5251 0.2555 -0.4105 -0.2817

## 20. Cholesky Factorization

```
function read A
[f,c]<-size of A
L<-zero matrix of dimensions f,c
U<-zero matrix of dimensions f,c
L(1,1)<-square root of A(1,1)
U(1,1)<-L(1,1);
L(2 to end,1)<-A(2 to end,1)/L(1,1)
U(1,2:end)<-A(1,2:end)/L(1,1)
for j=2 to c
  for i=2 to f
    if i>j
      L(i,j)<-(A(i,j)-[(L(i,1:j-1) x transpose matrix of U(1:j-1,j))]/L(j,j)
    else if i=j
      L(i,i)<-square root of (A(i,i)-[(L(i,1:j-1) x transpose matrix of U(1:j-1,i)
      U(i,i)<-L(i,i)
    else
      U(i,j)<-(A(i,j)-[(L(i,1:j-1) x transpose matrix of U(1:j-1,j))]/L(i,i)
    end
  end
end
end
```

## Results

Lower Triangular Matrix L

$2.0000 + 0.0000i$	$0.0000 + 0.0000i$	$0.0000 + 0.0000i$	$0.0000 + 0.0000i$
$0.5000 + 0.0000i$	$3.9686 + 0.0000i$	$0.0000 + 0.0000i$	$0.0000 + 0.0000i$
$0.0000 + 0.0000i$	$-0.3276 + 0.0000i$	$0.0000 + 1.9371i$	$0.0000 + 0.0000i$
$7.0000 + 0.0000i$	$2.1418 + 0.0000i$	$0.0000 + 1.8683i$	$3.7349 + 0.0000i$

Upper Triangular Matrix U

$2.0000 + 0.0000i$	$-0.5000 + 0.0000i$	$0.0000 + 0.0000i$	$1.5000 + 0.0000i$
$0.0000 + 0.0000i$	$3.9686 + 0.0000i$	$0.7559 + 0.0000i$	$1.8268 + 0.0000i$
$0.0000 + 0.0000i$	$0.0000 + 0.0000i$	$0.0000 + 1.9371i$	$0.0000 - 0.8768i$
$0.0000 + 0.0000i$	$0.0000 + 0.0000i$	$0.0000 + 0.0000i$	$3.7349 + 0.0000i$

Progressive substitution  $Lz=b$

$0.5000 + 0.0000i$   $0.1890 + 0.0000i$   $0.0000 - 0.5482i$   $-1.0520 + 0.0000i$

Regresive substitution  $Ux=z$ , solution

$0.4982$   $0.1477$   $0.1555$   $-0.2817$

## 21. SOR

```
function read A,b,x0,p,w,Tol,N
if determinant of A=0
    error
D<-diagonal of A
L<- -lower triangular part of A +D
U<- -upper triangular part of A +D
T<-inverse matrix of (D-w*L) * ((1-w)*D+w*U)
C<-w*inverse matrix of (D-w*L)*b
ro<-spectral radius of t
x<-x0
i<-0
E<-inf
while E>Tol and i<N
    xprev<-x
    x<-T*xprev+C;
    E<-p_norm x-xprev
    i<-i+1
end
```



end

## Results

Iteration	Error	x1	x2	x3	x4
33	1.8071e-07	0.52511	0.25546	-0.41048	-0.28166
34	1.106e-07	0.52511	0.25546	-0.41048	-0.28166
35	5.9459e-08	0.52511	0.25546	-0.41048	-0.28166

Answer

0.5251  
0.2555  
-0.4105  
-0.2817

## Progressive Substitution

```
function read L,B
f=rows of L
x=zero matrix of dimensions 1,f
x(1)=B(1)/L(1,1)
for i=2 to f
    sum=0
    for j=1 to i
        sum=sum+L(i,j)*x(j)
    end
    x(i)=(B(i)-sum)/L(i,i)
end
end
```

## 22. LU Factorization Partial Pivot

```
function read A
[f,c]<-size of A
L<-identity matrix of dimension f
P<- identity matrix of dimension f
for j=1 to c-1
    col<-|A(j:f,j)|
    m<- maximum of col
    m<-m(1)
    row change of A and P
    if j>1
        rows and columns change of L
    end
end
```

```
        end
        for i=j to f-1
            Mi<-A(i+1,j)/A(j,j)
            A(i+1,j:c)<-A(i+1,j:c)-(Mij)*A(j,j to c);
            L(i+1,j)=Mij
        end
    end
    U<-A
end
```

## Results

Lower Triangular Matrix L

1.0000	0.0000	0.0000	0.0000
0.2500	1.0000	0.0000	0.0000
0.0000	-0.0825	1.0000	0.0000
3.5000	0.5397	0.9645	1.0000

Upper Triangular Matrix U

4.0000	-1.0000	0.0000	3.0000
0.0000	15.7500	3.0000	7.2500
0.0000	0.0000	-3.7500	1.6984
0.0000	0.0000	0.0000	13.9492

Vector Pb

1.0000
1.0000
1.0000
1.0000

Progressive substitution  $Lz=Pb$

1.0000	0.9286	1.0797	1.1745
--------	--------	--------	--------

Regressive substitution  $Ux=z$ , solution

0.5251	0.2555	-0.4105	-0.2817
--------	--------	---------	---------

## 23. LU Factorization

```
function read A
[f,c]=size of A
L=identity matrix of dimension f
for j=1 to c-1
    for i=j to f-1
        Mij=A(i+1,j)/A(j,j)
        A(i+1,j to c)=A(i+1,j to c)-(Mij)*A(j,j to c)
        L(i+1,j)=Mij
    end
end
U=A
end
```

## Results

Lower Triangular Matrix L

1.0000	0.0000	0.0000	0.0000
0.2500	1.0000	0.0000	0.0000
0.0000	-0.0825	1.0000	0.0000
3.5000	0.5397	0.9645	1.0000

Upper Triangular Matrix U

4.0000	-1.0000	0.0000	3.0000
0.0000	15.7500	3.0000	7.2500
0.0000	0.0000	-3.7500	1.6984
0.0000	0.0000	0.0000	13.9492

Progressive substitution  $Lz=b$

1.0000 0.7500 1.0619 -3.9289

Regressive substitution  $Ux=z$ , solution

0.5251 0.2555 -0.4105 -0.2817

## 24. Lagrange Interpolation Method

begin

```

Read the number of points (n)

for i = 1 to n
    Read (x_i, y_i) pairs ----- y_i = f(x_i)
end

Read xp
Initialize: yp = 0 ----- yp = f(xp)

For i = 1 to n
    p = 1
    For j =1 to n
        If i < j
            p = p * (x_p - x_j)/(x_i - x_j)
        End If
    Next j
    yp = yp + p*y_i
End

print yp ----- Lagrange polynomial at xp
end

```

For the Lagrange polynomial, the output would be the expression,

$$\sum_{i=0}^n L_i(x_i) \quad (1)$$

where, for each iteration,

$$L_i(x) = \prod_p \frac{x - x_p}{x_i - x_p} \quad (2)$$

## Results

Iteration	Li(x)
0	-0.05000*(x) (x - 3.00000) (x - 4.00000)
1	0.08333*(x + 1.00000) (x - 3.00000) (x - 4.00000)
2	-0.08333*(x + 1.00000) (x) (x - 4.00000)
3	0.05000*(x + 1.00000) (x) (x - 3.00000)

Polynomial Coefficients

-0.77500  
0.25000  
-0.66667  
0.05000

Polynomial

$$-0.775*(x)*(x - 3.00000)*(x - 4.00000) + 0.25*(x + 1.00000) (x - 3.00000) (x - 4.00000) - 0.66667*(x + 1.00000) (x) (x - 4.00000)$$

## 25. Vandermonde's matrix method

```
begin
    input X, b ----- X = (x1, x2, ..., xn), and Y = (f(x1), f(x2), ..., f(xn))

    initialize deg = length(X)
    initialize a_i = zeros(deg, 1) ---- The vector of the coefficients

    For i = 0 < degree, i++
        For j = 0; j < degree; j++
            A[i][j] = x[i]^(j+1) ----- Vandermonde's Matrix
        end
    end

    output A, b

    Use this output to solve the system of equations A*a_1 = b with whatever
    method you prefer.

    sol = GaussianElimination (A, b)
end
```

## Results

Polynomial Coefficients

-1.14167  
5.82500  
-5.53333  
3.00000

Polynomial

$$-1.14167x^3 + 5.82500x^2 - 5.53333x^1 + 3.00000$$

## Newton's Method Divided differences method

26.

```
begin
    input (x0, f(x0)), (x1, f(x1)), ..., (xn, f(xn))

    For i = 0, 1, ..., n
        F_i,0 = f(xi)
    end

    For i = 1, ..., n
        For j = 1, ..., i
            set F_i,j = (F_i,j-1 - F_i-1,j-1)/(xi - xi-j)
        end
    end

    output F_0,0 , ..., F_i,i, ..., F_n,n
end
```

The output  $F_{0,0}, \dots, F_{i,i}, \dots, F_{n,n}$  can be translated into the expression,

$$P(x) = \sum_{x=0}^n F_{i,i} * \prod_{j=0}^{i-1} (x - x_j) \quad (3)$$

where  $P(x)$  is the Newton's polynomial.

## Results

Xi	f(Xi)	1	2	3
-1	15.5	0	0	0
0	3	-12.5	0	0
3	8	1.6667	3.5417	0
4	1	-7	-2.1667	-1.1417

Polynomial Coefficients

15.50000  
 -12.50000  
 3.54167  
 -1.14167

Polynomial

15.50000 - 12.50000(x + 1.00000) + 3.54167(x + 1.00000)(x) - 1.14167(x + 1.00000)(x)(x - 3.00000)

## Splines 1st, 2nd, and 3rd degree

```
begin
    input (X0, f(X0)), (X1, f(X1)), ..., (Xn, f(Xn))
    input degree

    if degree == 1
        for i = 0, i = n-1
            M_i = (f(X_{i+1}) - f(X_i))/(X_{i+1} - X_i)
            return p(X) = f(X_{i+1}) - f(X_i) = M_i * (X - X_i)
        end
    end

    if degree == 2
        for i = 1, i = n
            p(X) = A_i*X_i^2 - B_i*X_i + C_i
        end
        for i = 2, i = n
            p(X) = 2*A_{i-1}*X_{i-1} - B_{i-1}
        end
        To be natural spline both p(X) must be equal to 0 in both cases
        return p(X)
    end

    if degree == 3
        for i = 1, i < n
            p(X) = A_i*X_i^3 + B_i*X_i^2 + C_i*X_i + D_i
        end
        for i = 2, i = n
            p(X) = 3*A_{i-1}*X_{i-1}^2 + 2*B_{i-1}*X_{i-1} + C_{i-1}
        end
        for i = 3, i = n
            p(X) = 6*A_{i-1}*X_0 + 2*B_{i-1} = 0
        end
        To be natural spline, it must follow that
            - 6*A_{i-1}*X_0 + B_{i-1} = 0
            - 6*A_i*X_n + B_i = 0
        return p(X)
    end
end
```

## Results

### Lineal

Iteration	Coefficient a	Coefficient b
0	-12.5	3
1	1.6667	3
2	-7	29

Iteration	Spline
0	$-12.50000x + 3.00000$
1	$1.66667x + 3.00000$
2	$-7.00000x + 29.00000$

### Cuadratic

Iteration	Coefficient a	Coefficient b	Coefficient c
0	0	-12.5	3
1	4.7222	-12.5	3
2	-22.833	152.83	-245

Iteration	Spline
0	$0.00000x^2 - 12.50000x + 3.00000$
1	$4.72222x^2 - 12.50000x + 3.00000$
2	$-22.83333x^2 + 152.83333x - 245.00000$

### Cubic

Iteration	Coefficient a	Coefficient b	Coefficient c	Coefficient d
0	2.5333	7.6	-7.4333	3
1	-1.5222	7.6	-7.4333	3
2	2.0333	-24.4	88.567	-93

Iteration	Spline
0	$2.53333x^3 + 7.60000x^2 - 7.43333x + 3.00000$
1	$-1.52222x^3 + 7.60000x^2 - 7.43333x + 3.00000$
2	$2.03333x^3 - 24.40000x^2 + 88.56667x - 93.00000$