# IMPLEMENTASI ALGORITMA A\* UNTUK MENENTUKAN LINTASAN TERPENDEK

#### **LAPORAN**

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#### BAB I

#### **TEORI DASAR**

#### 1.1. Algoritma A\*

Algoritma A\* termasuk algoritma *informed search* karena terdapat *heuristic* atau informasi tambahan yang memperkirakan *cost* hingga simpul tujuan. Algoritma ini dapat digunakan untuk menentukan lintasan terpendek dari suatu titik ke titik lain. Ide dari algoritma A\* adalah menghindari melakukan *expand* pada node yang "mahal". *Heuristic* pada algoritma A\* akan melakukan estimasi nilai dari node

Heuristic Search

Adapun fungsi evaluasi *heuristic* pada algoritma A\* dapat dinyatakan dengan

$$f(n) = g(n) + h(n)$$

Keterangan:

g(n) = cost so far to reach n

h(n) = estimated cost from n to goal

f(n) = estimated total cost of path through n to goal

Dalam penentuan rute terpendek, nilai h(n) yang digunakan berdasarkan *straight-line* distance dari n ke goal. Akan dilakukan perhitungan nilai h(n) menggunakan haversine.

#### **BAB II**

# **Kode Program**

#### 2.1. Class Graph

#### 2.1.1. Atribut

```
private Microsoft.Msagl.Drawing.Graph MSAGLform;
private Dictionary<string, Point> nodeLst;
private Dictionary<string, List<string>> adjLst;
private Dictionary<(string, string), Microsoft.Msagl.Drawing.Edge> GUIEdge;
```

#### 2.1.2. Method

#### 2.1.2.1 Method Graph

```
//ctor
public Graph(String filepath)
    /* Kamus */
   file, nodeInfo, edgeInfo : array of string
   numNodes : int
    source, target : string
    edge : var
    */
    /* Algoritma */
    // init Attribute
    nodeLst = new Dictionary<string, Point>();
    MSAGLform = new Microsoft.Msagl.Drawing.Graph();
    adjLst = new Dictionary<string, List<string>>();
   GUIEdge = new Dictionary<(string, string),</pre>
Microsoft.Msagl.Drawing.Edge>();
    // Read file
    string [] file = System.IO.File.ReadAllLines(filepath);
    // get number of nodes
    int numNodes = int.Parse(file[0]);
    // saves all nodes and its point
    for(int i = 1; i < (numNodes + 1); i++)</pre>
        string[] nodeInfo = file[i].Split(' ');
        nodeLst.Add (nodeInfo[2], new Point(Double.Parse(nodeInfo[0]),
Double.Parse(nodeInfo[1])));
        adjLst.Add(nodeInfo[2], new List<string>());
    // Saves edge between node and create MSAGL Graph
    for(int j = nodeLst.Count + 1; j < file.Length; j++)</pre>
        string[] edgeInfo = file[j].Split(' ');
        for(int k = 0; k < numNodes; k++)</pre>
            if(edgeInfo[k].Equals("1"))
                string source = nodeLst.ElementAt(j - numNodes -
1).Key;
```

```
string target = nodeLst.ElementAt(k).Key;

adjLst[source].Add(target);

if(!adjLst[target].Contains(source))
{
    var edge = MSAGLform.AddEdge(source,
Math.Round(haversine(source, target), 5).ToString(), target);
    GUIEdge.Add((source, target), edge);
    edge.Attr.ArrowheadAtTarget =
Microsoft.Msagl.Drawing.ArrowStyle.None;
}
}
}
}
```

#### 2.1.2.2. Method Haversine

```
// Distance by Haversine formula
public double haversine(string source, string target)
    /* KAMUS */
       lon, lat, a, d : double
    /* ALGORITMA */
    // Haversine formula taken from
http://1.bp.blogspot.com/-eIVzIqcs_ik/U4xLXqpgBMI/AAAAAAAQyw/vRrNAYU3
U2E/s1600/Haversine+method+bakhtyiar.png
    double lon = (Math.PI/180) * (nodeLst[target].getLon() -
nodeLst[source].getLon());
    double lat = (Math.PI/180) *(nodeLst[target].getLat() -
nodeLst[source].getLat());
    double a = Math.Pow(Math.Sin(lat / 2), 2) + Math.Cos((Math.PI /
180) * nodeLst[target].getLat()) * Math.Cos((Math.PI / 180) *
nodeLst[source].getLat()) * Math.Pow(Math.Sin(lon / 2), 2);
    double d = Math.Sqrt(a);
    return 2 * 6371 * Math.Asin(d);
```

# 2.1.2.3. Method getMSAGLGraph

```
public Microsoft.Msagl.Drawing.Graph getMSAGLGraph()
{
   return MSAGLform;
}
```

#### 2.1.2.4. Method getNodeLst

```
public Dictionary<string, Point> getNodeLst()
{
   return this.nodeLst;
}
```

## 2.1.2.5. Method getGUIEdge

```
public Dictionary<string, List<string>> getAdjLst()
{
   return this.adjLst;
```

```
}
```

#### 2.1.2.6. Method filterEdge

```
// find edge between prev and next
public Microsoft.Msagl.Drawing.Edge filterEdge(string prev, string
next)
{
    /*KAMUS*/
    /*    edge = Microsoft.MSAGL.Drawing.Edge

    */
    /* ALGORITMA */
    Microsoft.Msagl.Drawing.Edge edge;
    if (GUIEdge.ContainsKey((prev, next)))
    {
        edge = GUIEdge[(prev, next)];
    }
    else
    {
        edge = GUIEdge[(next, prev)];
    }
    return edge;
}
```

#### 2.2. A\*

#### 2.2.1. Atribut

```
private Graph graph;
private Dictionary<string, bool> expanded;
private Dictionary<string, double> visitedCost;
private List<string> path;
private bool found;
private Dictionary<string, string> parentMap;
```

# 2.2.2. Method

#### 2.2.2.1. Method AStar

```
//Ctor
public AStar(Graph graph, string source, string target)
{
    /* KAMUS */
    /*
    end : bool
    currNode : string
    currNodeAdj : Dictionary<string, List<string>>
    */
    /* ALGORTIMA */

    // Init atribbute
    this.expanded = new Dictionary<string, bool>();
    this.visitedCost = new Dictionary<string, double>();
    this.graph = graph;
```

```
this.path = new List<string>();
    this.parentMap = new Dictionary<string, string>();
    //Initialize expanded as false
    initVisit();
    bool end = false;
    string currNode = source;
    double cost;
    Dictionary<string, List<string>> currNodeAdj = graph.getAdjLst();
    this.visitedCost.Add(currNode, 0);
    this.parentMap.Add(currNode, source);
    // while target not found or there are no path found
    while (!end)
        this.path.Add(currNode);
        // Check for all node adjacent with currNode
        foreach (var x in currNodeAdj[currNode])
            // Add parent
            if (!parentMap.ContainsKey(x))
            {
                parentMap.Add(x, currNode);
            }
            // Check if it's target
            if (x.Equals(target))
                this.found = true;
                end = true;
            }
            // Calculate Visited cost using haversine
            \verb|cost| = \verb|getVisitedCost(source, parentMap[x])| +
graph.haversine(parentMap[x], x) + graph.haversine(x, target);
            \textbf{if} \ (!visitedCost.ContainsKey}(x))
                visitedCost.Add(x, cost);
            }
            else
                visitedCost[x] = cost;
        // Check if found
        if (!end)
            expanded[currNode] = true;
            //find lowest cost node to be expanded
            currNode = findLowestCost();
            // Check if there are no node left
            if (currNode == null)
                end = true;
                found = false;
            }
```

```
}
}
this.path = cleanPath(source);
}
```

#### 2.2.2.2. Method initVisit

```
public void initVisit()
{
    /* Assign expanded value false for all node */

    expanded = new Dictionary<string, bool>();
    foreach (var x in this.graph.getNodeLst())
    {
        expanded.Add(x.Key, false);
    }
}
```

#### 2.2.2.3. Method findLowestCost

```
public string findLowestCost()
{
    /* Find nodes with lowest cost */

    /* KAMUS */
    /*
    minNode : string
    min : double
    */

    string minNode = null ;
    double min = Double.MaxValue;
    foreach (var x in visitedCost)
    {
        if (expanded[x.Key] != true && x.Value < min)
        {
            minNode = x.Key;
            min = x.Value;
        }
    }
    return minNode;
}</pre>
```

# 2.2.2.4. Method getStatus

```
public bool getStatus()
{
    return this.found;
}
```

#### 2.2.2.5. Method cleanPath

```
public List<string> cleanPath(string source)
{
    // get lowest path
    /* KAMUS */
```

```
*cleaned : List<string>
    *curr : string
/* ALGORITMA */
List<string> cleaned = new List<string>();
double cost = 0;
// Reverse path
path.Reverse();
string curr = path[0];
string prev = curr;
// While reconstruction have not reached path
while(!curr.Equals(source))
    cost += graph.haversine(prev, curr);
    cleaned.Add(curr);
    prev = curr;
    curr = parentMap[curr];
}
// reverse
cleaned.Reverse();
return cleaned;
```

#### 2.2.2.6. Method getPath

```
// get path
public List<string> getPath()
{
   return this.path;
}
```

#### 2.2.2.7. Method getVisitedCost

```
// Get cost
public double getVisitedCost(string source, string target)
{
    double cost = 0;
    string curr = source;

    // iterate edge and count cost
    foreach (var x in path)
    {
        cost += graph.haversine(curr, x);
        curr = x;
    }

    cost += graph.haversine(curr, target);

    return cost;
}
```

#### 2.3. Main

#### 2.3.1. Atribut

```
private Graph currGraph;
```

#### 2.3.2. Method

#### 2.3.2.1. Method Main

```
public Main()
{
    InitializeComponent();
}
```

#### 2.3.2.2. Method button1 click

```
// Browse Button
private void button1_Click(object sender, EventArgs e)
    /* KAMUS */
        * filename : string
        * x : Graph
        * graf : Microsoft.Msagl.Drawing.Graph
    // get filename
    openFileDialog1.ShowDialog();
    string filename = openFileDialog1.FileName;
    // Construct graph
    currGraph = new Graph(filename);
    // Print Graph
    Microsoft.Msagl.Drawing.Graph graf = currGraph.getMSAGLGraph();
    clear(graf);
    visualizeGraph(graf);
    // Hide first page show second page
    button1.Visible = false;
    label4.Visible = false;
    label5.Visible = false;
    button2.Visible = true;
    button3.Visible = true;
    label1.Visible = true;
    label2.Visible = true;
    comboBox1.Visible = true;
    comboBox2.Visible = true;
    // Add Nodes to Combobox
    addNode(currGraph, 1);
    addNode(currGraph, 2);
```

#### 2.3.2.3. Method visualizeGraph

```
// Print Graph
private void visualizeGraph(Microsoft.Msagl.Drawing.Graph Graf)
    /* Kamus */
    /*
        * renderer : Microsoft.Msagl.GraphViewerGdi.GraphRenderer
        * width, height : int
        * bitmap : Bitmap
        */
    /* ALGORITMA */
    // clear picturebox if there are any image
    if (pictureBox1.Image != null) pictureBox1.Image = null;
    Microsoft.Msagl.GraphViewerGdi.GraphRenderer renderer = new
Microsoft.Msagl.GraphViewerGdi.GraphRenderer(Graf);
    // Calculate layout dimension
    renderer.CalculateLayout();
    int width;
    int height;
    if (Graf.Width > Graf.Height)
        width = 506;
        height = (int)(Graf.Height * (width / Graf.Width));
    }
    else
        height = 600;
        width = (int)(Graf.Width * (height / Graf.Height));
    Graf.Attr.BackgroundColor =
Microsoft.Msagl.Drawing.Color.Transparent;
    // Add graph to picture box
    Bitmap bitmap = new Bitmap(width, height,
PixelFormat.Format32bppPArgb);
    renderer.Render(bitmap);
    pictureBox1.Image = bitmap;
```

#### 2.3.2.4. Method button2 Click

```
/* Reset button*/
private void button2_Click(object sender, EventArgs e)
{
    /* KAMUS */
    /*
        * Main : Form
    */
    /* Algoritma */
    this.Hide();
    Form Main = new Main();
    Main.Show();
}
```

#### 2.3.2.5. Method addNode

```
// Add node to combobox
private void addNode(Graph graph, int y)
    /* ALGORITMA */
    // Check Which combobox to clear
    if(y == 1)
    {
        comboBox1.Items.Clear();
    }
    else
    {
        comboBox2.Items.Clear();
    /* add all node to combobox */
    foreach (var x in graph.getNodeLst())
        if(y == 1)
            comboBox1.Items.Add(x.Key);
        else
        {
            comboBox2.Items.Add(x.Key);
        }
    }
```

#### 2.3.2.6. Method comboBox2\_SelectedIndexChanged

```
/* Change graph visualization based on node choice for combobox1 */
private void comboBox2_SelectedIndexChanged(object sender, EventArgs
e)
{
    /* KAMUS */
        * graf : Microsoft.Msagl.Drawing.Graph
    /* ALGORITMA */
    Microsoft.Msagl.Drawing.Graph graf = currGraph.getMSAGLGraph();
    clear(graf);
    // Check if combobox1 has content to color
    if (comboBox1.GetItemText(comboBox1.SelectedItem).Length > 0)
    {
graf.FindNode(comboBox1.GetItemText(comboBox1.SelectedItem)).Attr.Fill
Color = Microsoft.Msagl.Drawing.Color.Green;
    }
    // color node
graf.FindNode(comboBox2.GetItemText(comboBox2.SelectedItem)).Attr.Fill
Color = Microsoft.Msagl.Drawing.Color.Magenta;
```

```
visualizeGraph(graf);
}
```

## 2.3.2.7. Method comboBox1\_SelectedIndexChanged

```
/* Change graph visualization based on node choice for combobox2 */
private void comboBox1_SelectedIndexChanged(object sender, EventArgs
e)
{
    /* KAMUS */
        * graf : Microsoft.Msagl.Drawing.Graph
        * combo2Content : string
    /* ALGORITMA */
    Microsoft.Msagl.Drawing.Graph graf = currGraph.getMSAGLGraph();
    string combo2Content = "";
    clear(graf);
    // Check if combobox2 has content to color
    if (comboBox2.GetItemText(comboBox2.SelectedItem).Length > 0)
    {
graf.FindNode(comboBox2.GetItemText(comboBox2.SelectedItem)).Attr.Fill
Color = Microsoft.Msagl.Drawing.Color.Magenta;
        cmbo2Content = comboBox2.GetItemText(comboBox2.SelectedItem);
graf.FindNode(comboBox1.GetItemText(comboBox1.SelectedItem)).Attr.Fill
Color = Microsoft.Msagl.Drawing.Color.Green;
    // color node
    comboBox2.Items.Clear();
    addNode(currGraph, 2);
comboBox2.Items.Remove(comboBox1.GetItemText(comboBox1.SelectedItem));
    // Remove selecteditem from combobox1 in combobox2;
    if(combo2Content.Length > 0)
        comboBox2.SelectedItem = combo2Content;
    visualizeGraph(graf);
```

#### 2.3.2.8. Method button3\_Click

```
/* Submit button */
private void button3_Click(object sender, EventArgs e)
{
    /* KAMUS */
    /*
    * source, target : string
    * search : AStar
```

```
* graf : Microsoft.Msagl.Drawing.Graph
        * result : List <string>
        * prev : string
        * edge : Microsoft.Msagl.Drawing.Edge
    /* Algoritma */
    // Check if source and target node has been chosen
    if(comboBox1.GetItemText(comboBox1.SelectedItem).Length > 0 &&
comboBox2.GetItemText(comboBox2.SelectedItem).Length > 0)
        string source = comboBox1.GetItemText(comboBox1.SelectedItem);
        string target = comboBox2.GetItemText(comboBox2.SelectedItem);
        Microsoft.Msagl.Drawing.Edge edge;
        // Init search
        AStar search = new AStar(currGraph, source.ToString(),
target.ToString());
        // Check if there are path
        if (search.getStatus() == true)
            Microsoft.Msagl.Drawing.Graph graf =
currGraph.getMSAGLGraph();
            // Get shortest path
            List<string> result = search.cleanPath(source, target);
            string prev = source;
            // Color node and edges
            for (int i = 0; i < result.Count; i++)</pre>
if(!result[i].Equals(comboBox1.GetItemText(comboBox1.SelectedItem)) &&
!result[i].Equals(comboBox2.GetItemText(comboBox2.SelectedItem)))
                    graf.FindNode(result[i]).Attr.FillColor =
Microsoft.Msagl.Drawing.Color.DodgerBlue;
                edge = currGraph.filterEdge(prev, result[i]);
                edge.Attr.Color = Microsoft.Msagl.Drawing.Color.Red;
                prev = result[i];
            }
            // Print results
            visualizeGraph(graf);
            label3.Visible = true;
            label3.Text = "Cost : " + search.getVisitedCost(source,
target).ToString();
        }
        else
            MessageBox.Show("No Path Found");
        }
    }
   else
    {
        MessageBox.Show("Complete the field first!");
    }
```

#### 2.3.2.9. Method clear

```
/* Clear Msagl Graf from customized attribute */
private void clear(Microsoft.Msagl.Drawing.Graph Graf)
{
    /* ALGORITMA */

    // Color all node to transparent
    foreach (var x in currGraph.getNodeLst())
    {
        Graf.FindNode(x.Key).Attr.FillColor =
Microsoft.Msagl.Drawing.Color.White;
    }

    // Color all edge to black
    foreach(var x in currGraph.getGUIEdge())
    {
        x.Value.Attr.Color = Microsoft.Msagl.Drawing.Color.Black;
    }
}
```

# **BAB III**

# Screenshot Uji

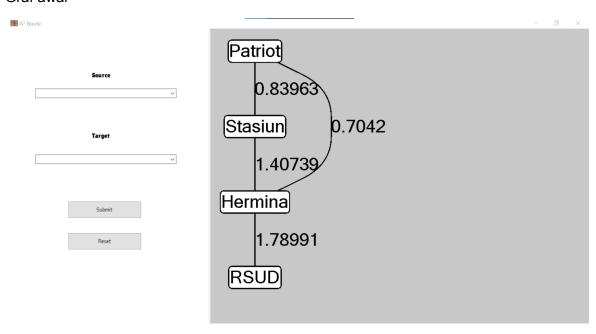
# 3.1. Uji 1

# 3.1.1. Input

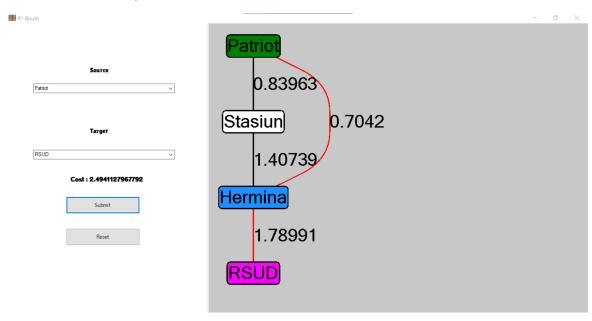
```
4
-6.238393142992205 106.99183138081494 Patriot
-6.23447540694475 106.98682592794263 Hermina
-6.2370137614412675 106.9992995001439 Stasiun
-6.24200511367606 107.00113805383562 RSUD
0 1 1 0 0
1 0 0 1 1
1 1 0 0 0
0 1 0 0 0
```

# 3.1.2. Output

#### Graf awal



# Source: Patriot, Target: RSUD



# 3.2. Uji 2

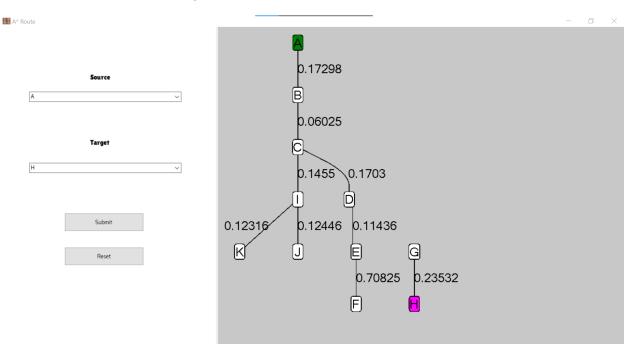
## 3.2.1. Input

11

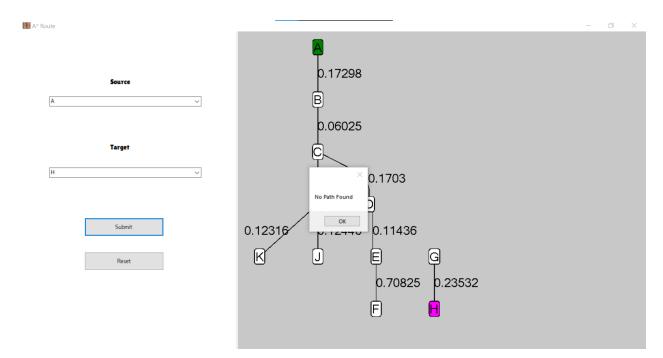
```
-6.893874 107.608454 A
-6.893294 107.609908 B
-6.893230 107.610450 C
-6.893592 107.611949 D
-6.893754 107.612972 E
-6.887412 107.613567 F
-6.887363 107.611469 G
-6.887703 107.609365 H
-6.891923 107.610386 I
-6.891034 107.609701 J
-6.891013 107.611022 K
0 1 0 0 0 0 0 0 0 0 0
10100000000
0 1 0 1 0 0 0 0 1 0 0
00101000000
00010100000
00001000000
0000001000
0000010000
00100000011
0 0 0 0 0 0 0 0 1 0 0
0000000100
```

# 3.2.2. Output

Source Node : A, Source Target : H



#### No Path Found

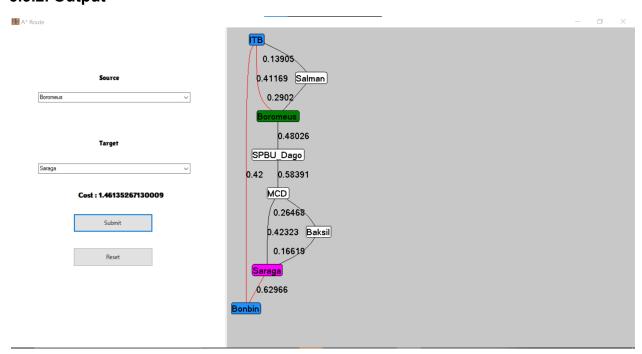


# 3.3. Uji 3

#### 3.3.1. Input

```
8
-6.892674095579858 107.610456766119 ITB
-6.893685967570809 107.61119685795033 Salman
-6.894527417370569 107.6136852826586 Boromeus
-6.890295300177787 107.61281647346945 SPBU_Dago
-6.885090312494578 107.61351686089003 MCD
-6.886144806591044 107.61136736020688 Baksil
-6.886251321000536 107.60986572460708 Saraga
-6.891136755996797 107.60698154656727 Bonbin
0 1 1 0 0 0 0 1
10100000
1 1 0 1 0 0 0 0
0 0 1 0 1 0 0 0
0 0 0 1 0 1 1 0
0 0 0 0 1 0 1 0
00001101
1 0 0 0 0 0 1 0
```

# 3.3.2. Output

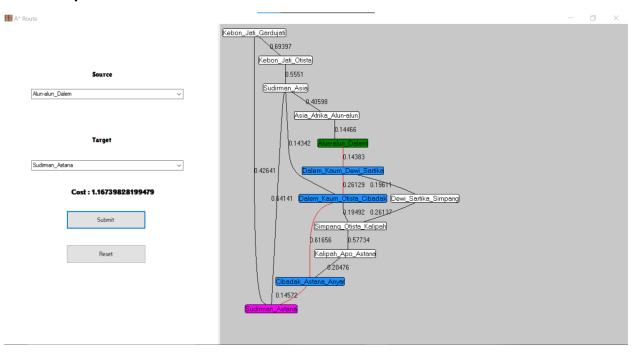


#### 3.4. Uji 4

#### 3.4.1. Input

```
12
-6.916289558795759 107.59823109564569 Kebon_Jati_Gardujati
-6.915799623402846 107.60449846018152 Kebon_Jati_Otista
-6.920773509104472 107.60406918863798 Sudirman_Asia Afrika_Otista
-6.921231487380398 107.60771799675814 Asia_Afrika_Alun-alun
-6.9225308651860935 107.60765360602662 Alun-alun_Dalem Kaum
-6.92241370831757 107.6063559748914 Dalem_Kaum_Dewi_Sartika
-6.9220622375374745 107.60401552969505 Dalem_Kaum_Otista_Cibadak
-6.9241710582913045 107.6062057298512 Dewi_Sartika_Simpang
-6.9238089382260455 107.60386619993885 Simpang_Otista_Kalipah Apo
-6.9232540419560005 107.59866591318783 Kalipah_Apo_Astana Anyar
-6.921423199084892 107.59846719499465 Cibadak_Astana_Anyar
-6.9201238182298335 107.59829548637724 Sudirman_Astana Anyar
010000000001
1010000000000
010100100001
000101000000
000010110000
001001001010
000001001000
00000110100
00000001010
000000100101
101000000010
```

#### 3.4.2. Output



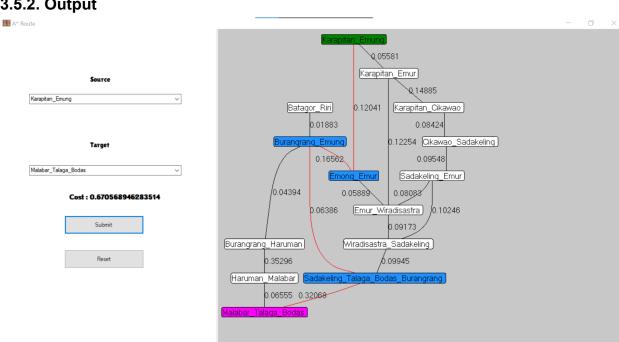
#### 3.5. Uji 5

# 3.5.1. Input

```
14
-6.927562192722218 107.61959799634626 Batagor_Riri
-6.927025406721871 107.61690969806743 Karapitan_Emung
-6.927472728417712 107.61945313196297 Burangrang_Emung
-6.927312970717906 107.61796141334914 Emong_Emur
-6.927504679951173 107.61675945302719 Karapitan_Emur
-6.928793389996319 107.61639457221517 Karapitan_Cikawao
```

```
-6.92914485576096 107.61707067489624 Cikawao_Sadakeling
-6.928537778366568 107.61768238684581 Sadakeling_Emur
-6.927824195166772 107.61782190009745 Emur_Wiradisastra
-6.928217198601289 107.61855260357831 Wiradisastra_Sadakeling
-6.928046790655269 107.61943701951742
Sadakeling_Talaga_Bodas_Burangrang
-6.927077594291167 107.61945311720032 Burangrang_Haruman
-6.927871057396435 107.62254923820818 Haruman_Malabar
-6.928414232712092 107.62231850475352 Malabar_Talaga_Bodas
001000000000000
000110000000000
10010000001100
01100000100000
01001100100000
000010100000000
00000101000000
00000010110000
00011001010000
0000001101000
0010000010001
00100000000010
00000000000101
00000000001010
```

#### 3.5.2. Output



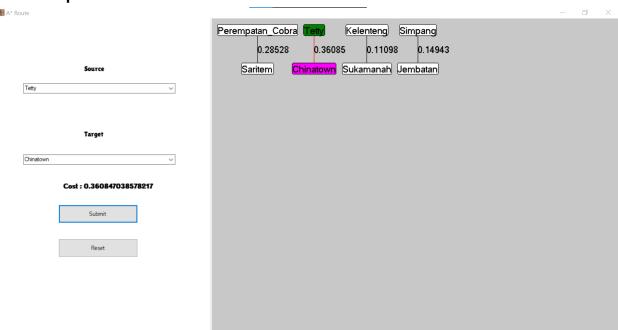
## 3.6. Uji 6

#### 3.6.1. Input

```
-6.918470830235298 107.59625136852266 Tetty
-6.9171075367865145 107.59328484535219 Chinatown
-6.918193911572041 107.59314537048341 Kelenteng
-6.918353672359124 107.59413778781892 Sukamanah
-6.91946134566292 107.5929629802704 Perempatan_Cobra
-6.917192742742358 107.5941699743271 Saritem
-6.9170436323095394 107.59727597236635 Simpang
-6.917459011255302 107.5959885120392 Jembatan
01000000
10000000
00010000
00100000
00000100
00001000
```

0 0 0 0 0 0 1 0 0 0 0 0 1 0

#### 3.6.2. Output



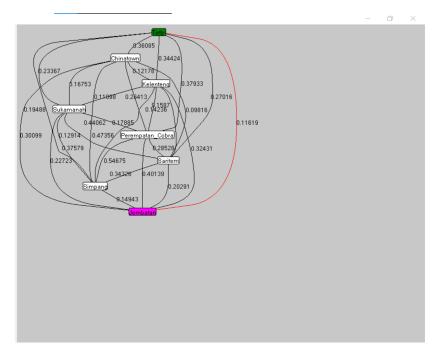
# 3.7. Uji 7

# 3.7.1. Input

```
-6.918470830235298 107.59625136852266 Tetty
-6.9171075367865145 107.59328484535219 Chinatown
-6.918193911572041 107.59314537048341 Kelenteng
-6.918353672359124 107.59413778781892 Sukamanah
-6.91946134566292 107.5929629802704 Perempatan_Cobra
-6.917192742742358 107.5941699743271 Saritem
-6.9170436323095394 107.59727597236635 Simpang
-6.917459011255302 107.5959885120392 Jembatan
0 1 1 1 1 1 1 1
1011111
1 1 0 1 1 1 1 1
1 1 1 0 1 1 1 1
11110111
11111011
11111101
1111110
```

# 3.7.2. Output





# **BAB IV**

# Lampiran

# 4.1. Alamat Repository

https://github.com/isabellahandayani/AStar-Route

# 4.2. Checklist

Poin	Ya	Tidak
Program dapat menerima input graf	1	
Program dapat menghitung lintasan terpendek	1	
3. Program dapat menampilkan lintasan terpendek serta jaraknya	1	
Bonus: Program dapat menerima input peta dengan Google Map     API dan menampilkan peta		1