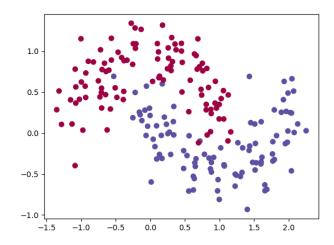
Comp 576 HW 1

Jingyu Fu (NetID: jf70)

1 Backpropagation in Simple Neural Network

1-a



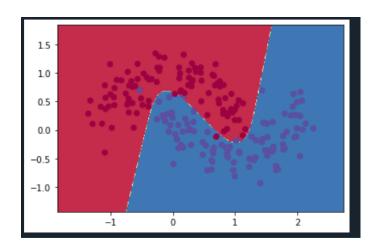
1-e-1 Train with three hidden units for three different functions

Observations:

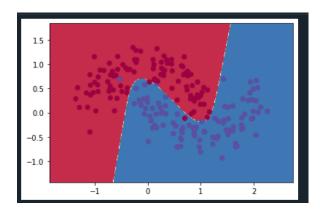
Three functions all have very similar decision boundary and loss after iteration 19000. Although ReLU has a sharper decision boundary comparing to other two functions, the general trend and shape is still very similar to others.

Tanh

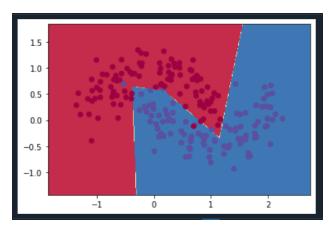
Loss after iteration 19000: 0.070758



Sigmoid
Loss after iteration 19000: 0.078155



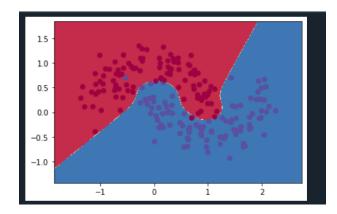
Relu
Loss after iteration 19000: 0.071219



1-e-2. Train with increased hidden units

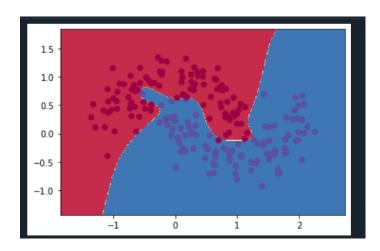
I tried with 4 hidden and 10 hidden, comparing to previous tests, we could see that higher the hidden units, smaller the loss. But there should be a threshold between 4 hidden and 10 hidden, because the 10 hidden is overfitted.

Tanh with 4 hidden
Loss after iteration 19000: 0.050689



Tanh with 10 hidden

Loss after iteration 19000: 0.030565

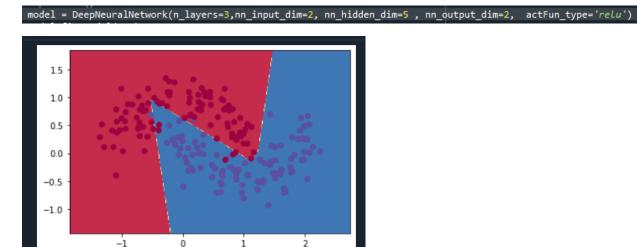


1-f Deeper network:

1-f-1: Make Moons dataset

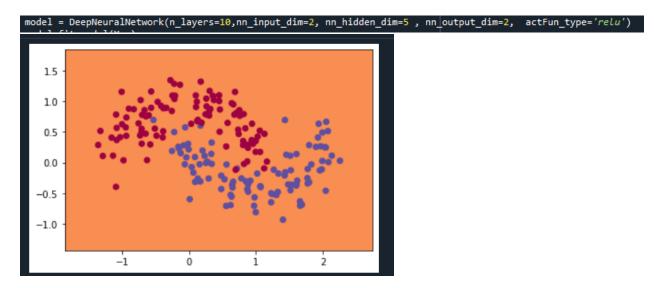
Decision boundary changes as the number of layers and size of layers change. When the number and size of layers increases, the boundary becomes smoother and the loss decreases. But there is a threshold, once passed this threshold, there comes the problem of overfitting. Therefore it is necessary to find a point where it is appropriate, and neither overfitting nor underfitting.

Model 1: 3 layers, relu



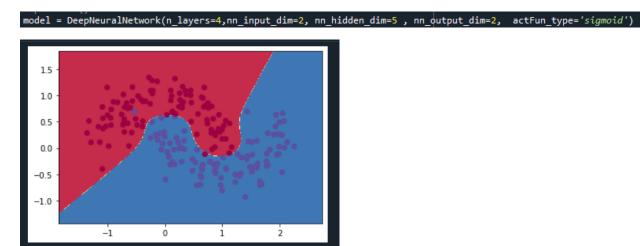
Loss after iteration 19000: 0.108509

Model 2: 10 layers, relu



Loss after iteration 19000: 0.693200

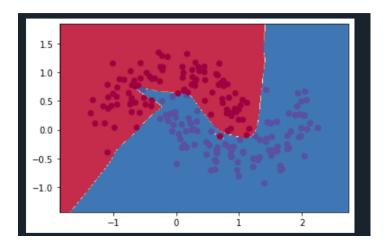
Model 3: 4 layers, sigmoid



Loss after iteration 19000: 0.058388

Model 4: 5 layers, tanh

model = DeepNeuralNetwork(n_layers=5,nn_input_dim=2, nn_hidden_dim=10 , nn_output_dim=2, actFun_type='tanh')



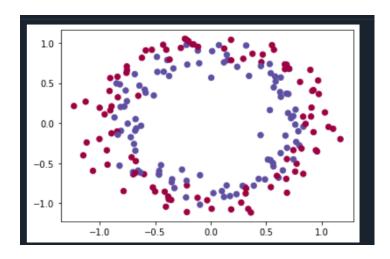
Loss after iteration 19000: 0.079216

1-f-2: Another dataset

Dataset overview:

The dataset I used is make_circles. This dataset has 200 samples and 0.1 noise, whose ideal result is a circle. It is easy to find that this dataset has a much higher loss comparing to make_moons, which is probably because of the closely clustered data points in this dataset.

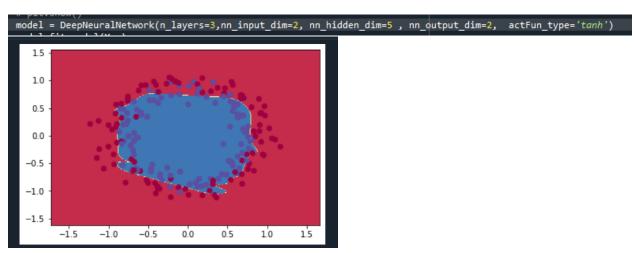
X, y = datasets.make_circles(200,noise = 0.1)



Observations:

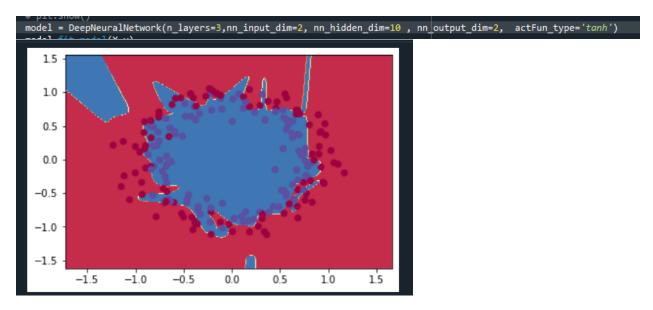
Three layers with activation function of tanh has a very high loss, which is 0.86. When I increased the hidden dim, the loss decreased and boundary became little bit smoother. Activation function sigmoid with 5 layers has a lossvalue between those previous two models and a more reasonable boundary shape.

Model 1:



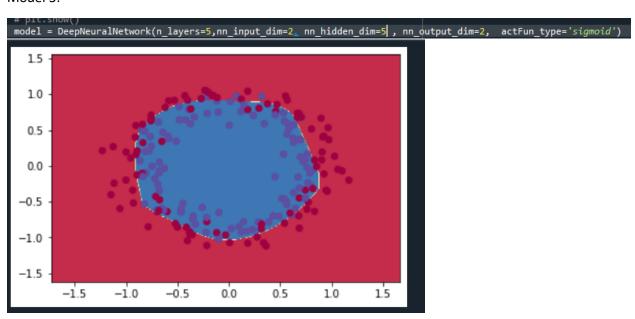
Loss after iteration 19000: 0.861026

Model 2:



Loss after iteration 19000: 0.299084

Model 3:



Loss after iteration 19000: 0.414022

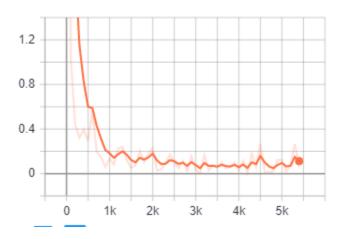
2 Training a Simple Deep Convolutional Network on MNIST

2-a-5

Final test accuracy: 0.9866

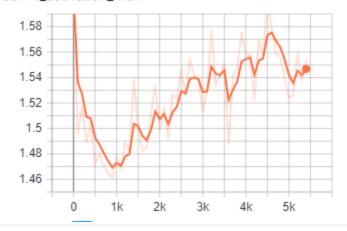
Training time: 391.691699

2-a-6:

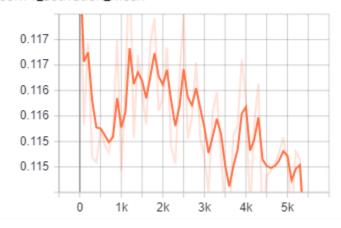


2-b

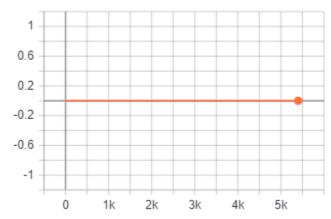
conv1_activation_max



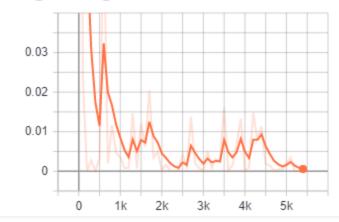
conv1_activation_mean



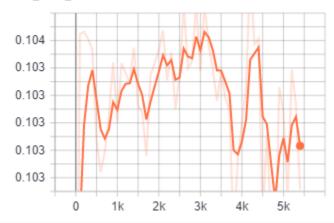
conv1_activation_min



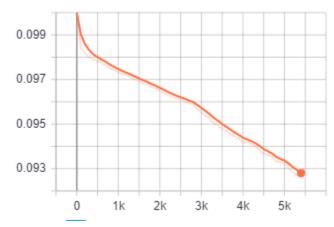
conv1_activation_std



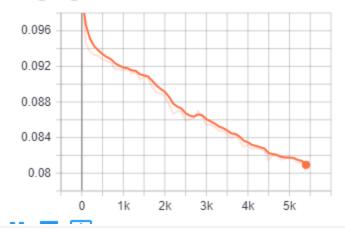
conv1_bias_max



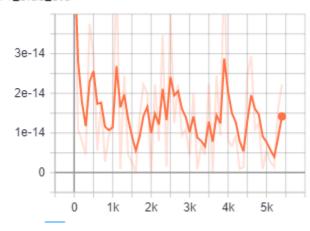
conv1_bias_mean



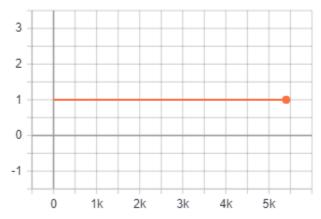
conv1_bias_min



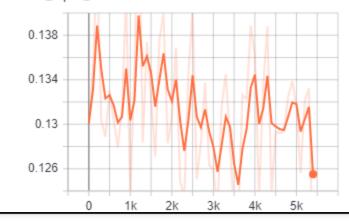
conv1_bias_std



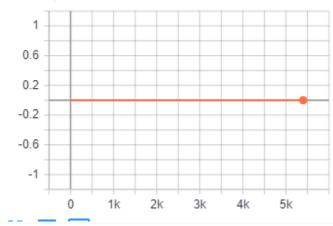
conv1_input_max



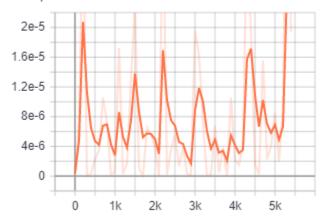
conv1_input_mean



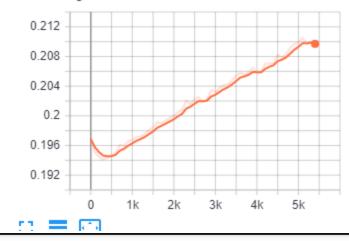
conv1_input_min



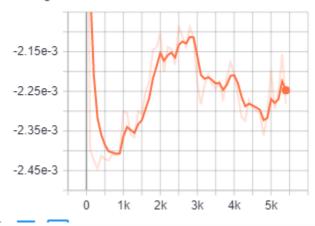
conv1_input_std



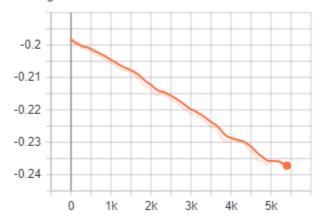
conv1_weight_max



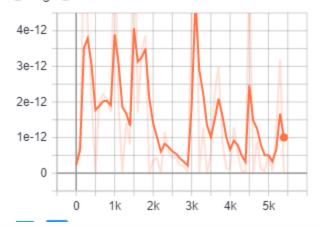
conv1_weight_mean



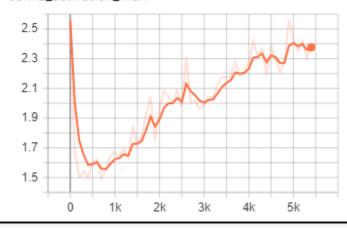
conv1_weight_min



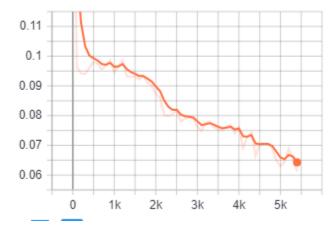
conv1_weight_std



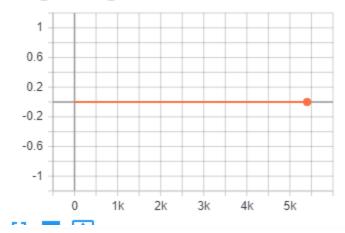
conv2_activation_max



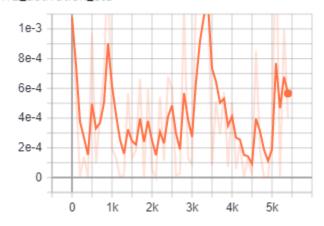
conv2_activation_mean



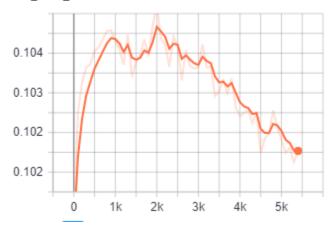
conv2_activation_min



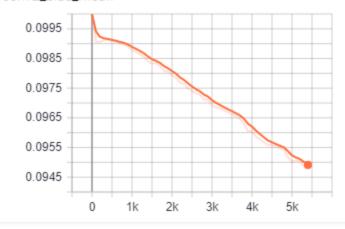
conv2_activation_std



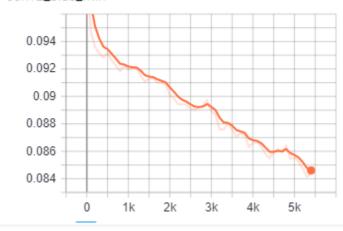
conv2_bias_max



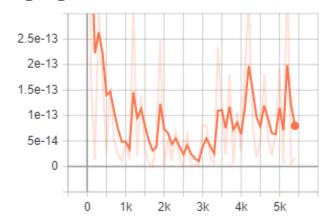
conv2_bias_mean



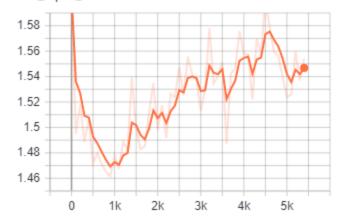
conv2_bias_min



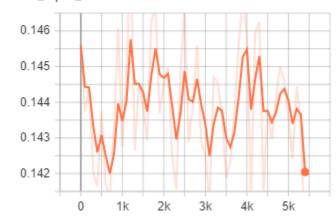
conv2_bias_std



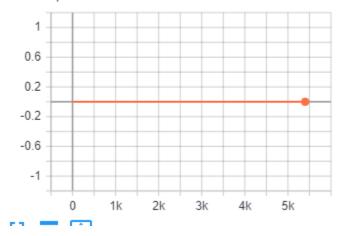
conv2_input_max



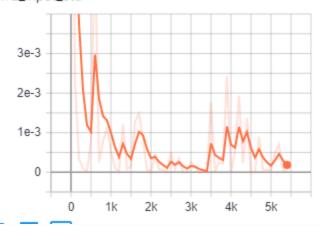
conv2_input_mean



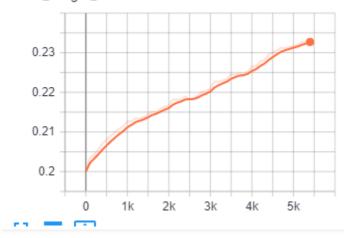
conv2_input_min



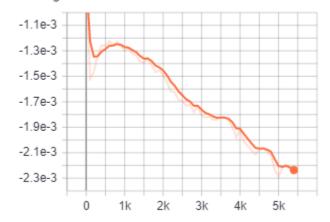
conv2_input_std



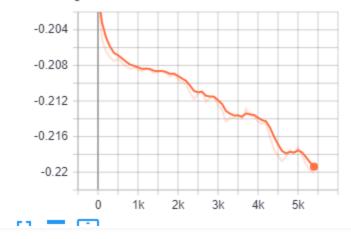
conv2_weight_max



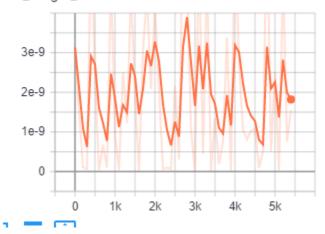
conv2_weight_mean



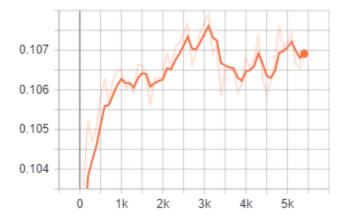
conv2_weight_min

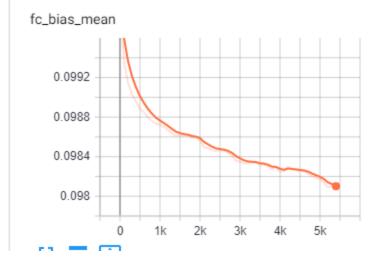


conv2_weight_std

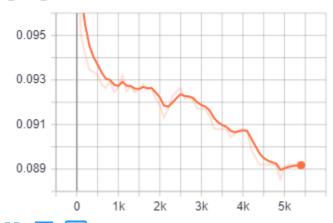


fc_bias_max

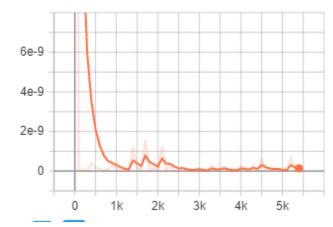






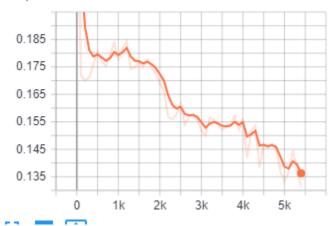




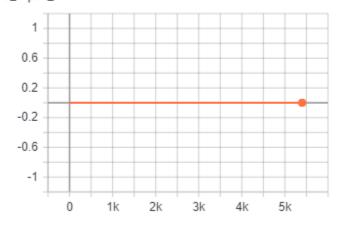


fc_input_max 2.5 2.3 2.1 1.9 1.7 1.5 0 1k 2k 3k 4k 5k

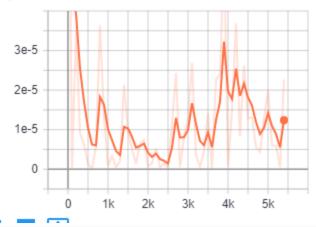
fc_input_mean



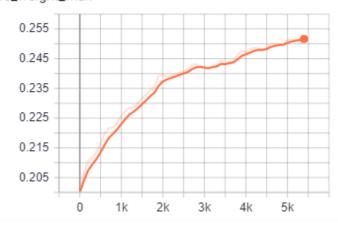
fc_input_min



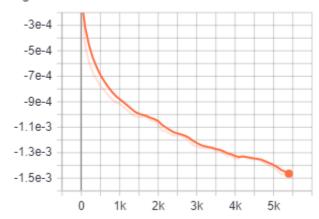
fc_input_std



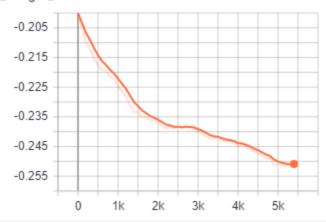
fc_weight_max

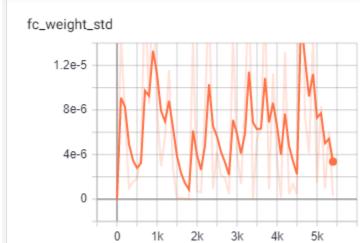


fc_weight_mean

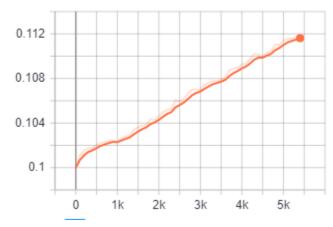


fc_weight_min

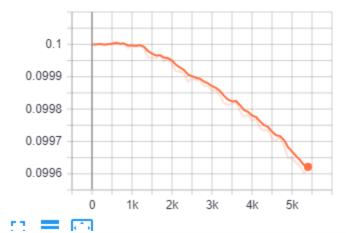




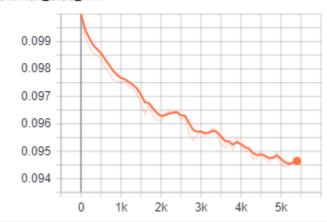
softmax_bias_max



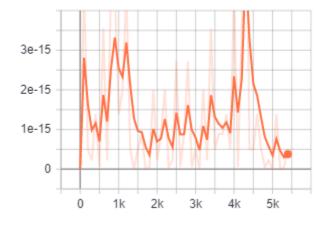
softmax_bias_mean



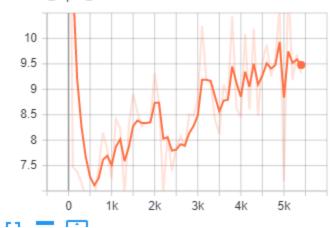
softmax_bias_min



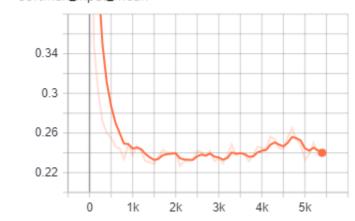
softmax_bias_std



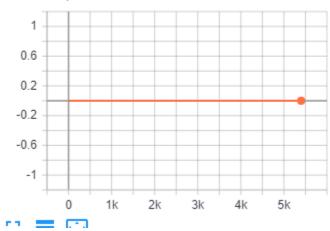
softmax_input_max

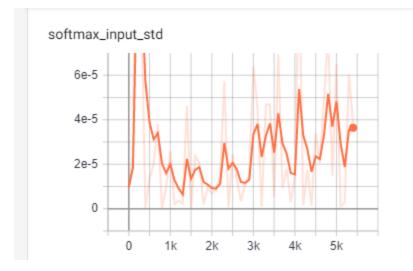


softmax_input_mean

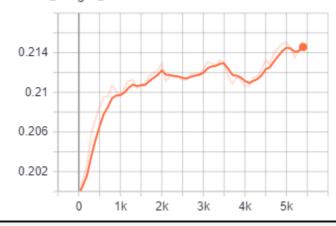


softmax_input_min

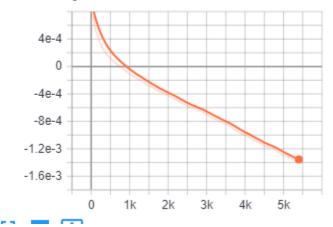




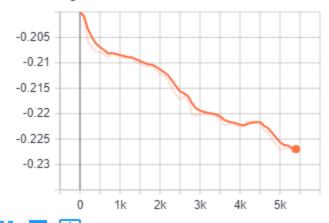
softmax_weight_max



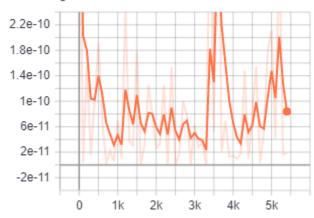
softmax_weight_mean

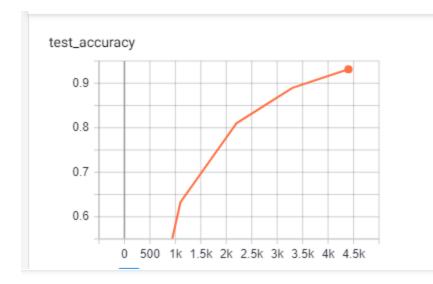


softmax_weight_min

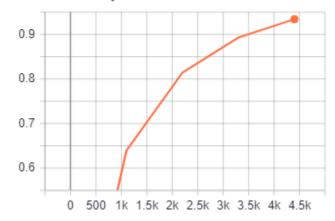


softmax_weight_std

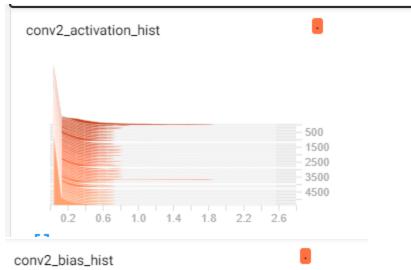




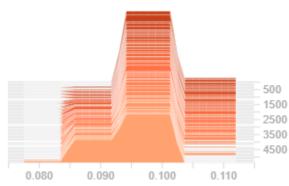
validation_accuracy

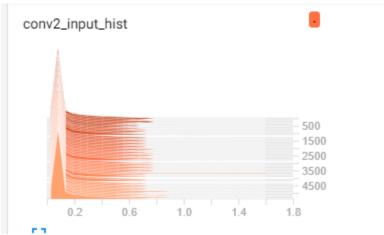


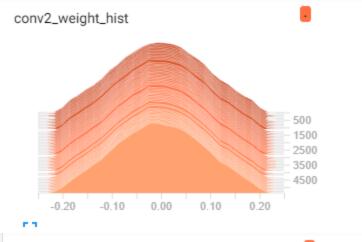


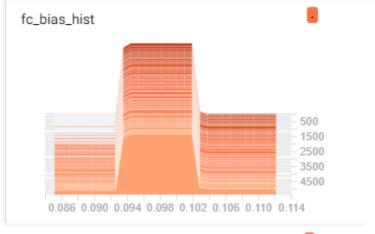




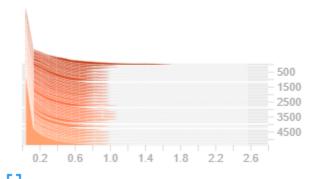


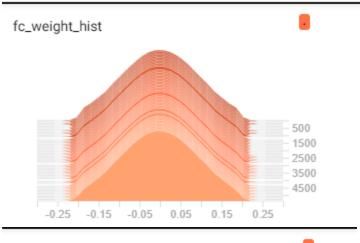


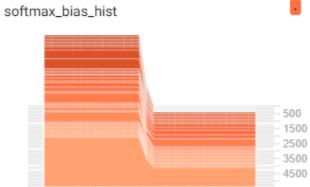












0.102

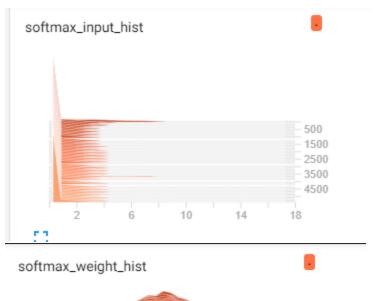
0.106

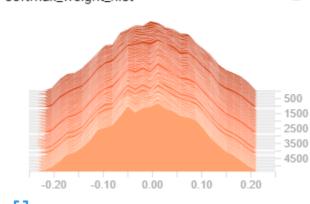
0.110

0.094

0.098

0.114



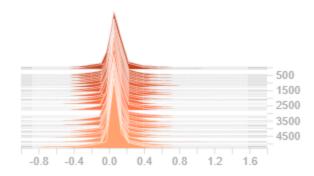


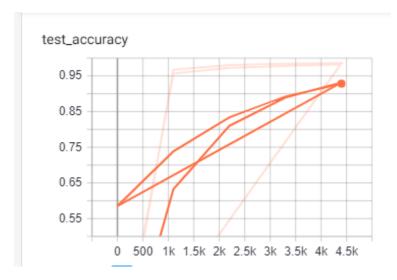
2-c:

Using tanh as activation function, test accuracy increases faster and network learns faster.

with tanh:

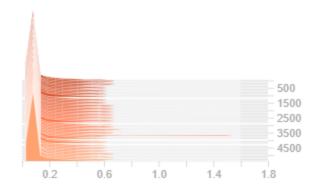






With relu:





test_accuracy

