# The Ecological Effects of Trait Variation in a u-Predator, v-Prey System (draft)

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## The Model

# Attack Rate as a Function of Predator and Prey Trait Values

Let  $M_i(t)$  be the density of the  $i^{\text{th}}$  predator species, and let  $N_j(t)$  be the density of the  $j^{\text{th}}$  prey species. Let  $\overline{m_i}(t)$  be the mean of a single quantitative trait in the  $i^{\text{th}}$  predator species, and let  $\overline{n_j}(t)$  be the mean of a single quantitative trait in the  $j^{\text{th}}$  prey species. Suppose the traits are normally distributed, and stay normally distributed, with  $\sigma_i^2$  as the constant variance of the  $i^{\text{th}}$  predator species, and with  $\beta_j^2$  as the constant variance of the  $j^{\text{th}}$  prey species. Their distributions are given by:

$$p(m_i, \overline{m_i}) = \frac{1}{\sqrt{2\pi\sigma_i^2}} \exp\left[-\frac{(m_i - \overline{m_i})^2}{2\sigma_i^2}\right]$$
$$p(n_j, \overline{n_j}) = \frac{1}{\sqrt{2\pi\beta_j^2}} \exp\left[-\frac{(n_j - \overline{n_j})^2}{2\beta_j^2}\right]$$

Assume all of the species' phenotypic variances have genetic and environment components:

$$\sigma_i^2 = \sigma_{Gi}^2 + \sigma_{Ei}^2$$
$$\beta_j^2 = \beta_{Gj}^2 + \beta_{Ej}^2$$

Let  $a_{ij}(m_i, n_j)$  be the attack rate of an individual predator from species i on an individual prey from species j. Supposing the attack rate is optimal at  $\alpha_{ij}$  when the predator's trait and prey's trait are at an optimal difference  $\theta_{ij}$ , and decreases in a Gaussian manner as the trait's deviate from that difference, then

$$a_{ij}(m_i, n_j) = \alpha_{ij} \exp \left[ -\frac{((m_i - n_j) - \theta_{ij})^2}{2\tau_{ij}^2} \right]$$

where  $\tau_{ij}$  determines how phenotypically specialized a predator individual of species i must be to use a prey individual of species j. Let  $\overline{a_{ij}}(\overline{m_i}, \overline{n_j})$  be the mean attack rate of predator species i on prey species j. Thus,

$$\overline{a_{ij}}(\overline{m_i}, \overline{n_j}) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} a_{ij}(m_i, n_j) \cdot p(m_i, \overline{m_i}) \cdot p(n_j, \overline{n_j}) dm_i dn_j$$

$$= \frac{\alpha_{ij} \tau_{ij}}{\sqrt{\sigma_i^2 + \beta_j^2 + \tau_{ij}^2}} \exp \left[ -\frac{((\overline{m_i} - \overline{n_j}) - \theta_{ij})^2}{2(\sigma_i^2 + \beta_j^2 + \tau_{ij}^2)} \right]$$

# Fitness Assumptions

Let u be the number of predator species, and let v be the number of prey species. Assuming predators have a linear functional response, convert the consumed prey into offspring with efficiencies  $e_{ij}$ , and experience a per-capita mortality rate  $d_i$ , then the fitness of a predator with phenotype  $m_i$  is

$$W_i(m_i, [N]_1^v, [n]_1^v) = \sum_{i=1}^v (e_{ij}a_{ij}(m_i, n_j)N_j) - d_i$$

and thus the mean fitness of the  $i^{\rm th}$  predator population is

$$\overline{W_i}(\overline{m_i}, [N]_1^v, [\overline{n}]_1^v) = \int_{\mathbb{R}^{v+1}} W_i(m_i, [N]_1^v, [n]_1^v) p(m_i, \overline{m_i}) \prod_{j=1}^v [p(n_j, \overline{n_j})] dm_i \prod_{j=1}^v [dn_j]$$

$$= \sum_{j=1}^v \left( e_{ij} \overline{a_{ij}}(\overline{m_i}, \overline{n_j}) N_j \right) - d_i$$

Suppose prey species j experiences logistic-type growth in the absence of predators with carrying capacity  $K_j$  and intrinsic growth rate  $r_j$ . However, assume the intrinsic growth rate varies as a function of the prey individual's trait value. Assume the contribution of a prey individual to its population decreases in a Gaussian manner as the trait value deviates away from an optimal trait value for that species,  $\phi_j$ . Let  $\rho_j$  be the maximal contribution rate and  $\gamma_j$  be the "cost variance". In other words,

$$r_j(n_j) = \rho_j \exp\left[-\frac{(n_j - \phi_j)^2}{2\gamma_j^2}\right]$$

Thus, the average intrinsic growth rate for the prey population is

$$\overline{r}_{j}(\overline{n}_{j}) = \int_{-\infty}^{\infty} r_{j}(n_{j}) p(n_{j}, \overline{n}_{j}) dn_{j}$$

$$= \frac{\rho_{j} \gamma_{j}}{\sqrt{\beta_{j}^{2} + \gamma_{j}^{2}}} \exp \left[ -\frac{(n_{j} - \phi_{j})^{2}}{2(\beta_{j}^{2} + \gamma_{j}^{2})} \right]$$

Define the fitness of prey individuals with phenotype  $n_i$  as

$$Y_{j}(N_{j}, n_{j}, [M]_{1}^{u}, [m]_{1}^{u}) = r_{j}(n_{j}) \left(1 - \frac{N_{j}}{K_{j}}\right) - \sum_{i=1}^{u} \left(a_{ij}(m_{i}, n_{j})M_{i}\right)$$

$$= \rho_{j} \exp\left[-\frac{(n_{j} - \phi_{j})^{2}}{2\gamma_{j}^{2}}\right] \left(1 - \frac{N_{j}}{K_{j}}\right) - \sum_{i=1}^{u} \left(a_{ij}(m_{i}, n_{j})M_{i}\right)$$

and thus the mean fitness of the  $j^{\text{th}}$  prey population is

$$\overline{Y_j}(N_j, \overline{n_j}, [M]_1^u, [\overline{m}]_1^u) = \int_{\mathbb{R}^{u+1}} Y_j(N_j, n_j, [M]_1^u, [m]_1^u) \prod_{i=1}^u \left[ p(m_i, \overline{m_i}) \right] p(n_j, \overline{n_j}) \prod_{i=1}^u \left[ dm_i \right] dn_j$$

$$= \overline{r_j}(\overline{n_j}) \left( 1 - \frac{N_j}{K_j} \right) - \sum_{i=1}^u \overline{a_{ij}}(\overline{m_i}, \overline{n_j}) M_i$$

## **Ecological Dynamics**

The ecological dynamics of the model (population densities) are given by

$$\begin{cases}
\frac{dM_i}{dt} = M_i \overline{W_i}(\overline{m_i}, [N]_1^v, [\overline{n}]_1^v) \\
\frac{dN_j}{dt} = N_j \overline{Y_j}(N_j, \overline{n_j}, [M]_1^u, [\overline{m}]_1^u)
\end{cases}$$
(1)

# **Evolutionary Dynamics**

Assume the evolution of the mean trait value is always in the direction which increases the mean fitness in the population. Thus the evolutionary dynamics are given by

$$\begin{cases}
\frac{d\overline{m_i}}{dt} = \sigma_{Gi}^2 \frac{\partial \overline{W_i}}{\partial \overline{m_i}} \\
\frac{d\overline{n_j}}{dt} = \beta_{Gj}^2 \frac{\partial \overline{Y_j}}{\partial \overline{n_j}}
\end{cases}$$
(2)

where

$$\begin{split} &\frac{\partial \overline{W_i}}{\partial \overline{m_i}} = \sum_{j=1}^v \left[ \frac{e_{ij} N_j (\theta_{ij} - (\overline{m}_i - \overline{n}_j))}{\sigma_i^2 + \beta_j^2 + \tau_{ij}^2} \cdot \overline{a}_{ij} (\overline{m}_i, \overline{n}_j) \right] \\ &\frac{\partial \overline{Y_j}}{\partial \overline{n_j}} = \overline{r}_j (\overline{n}_j) \left( 1 - \frac{N_j}{K_j} \right) \frac{(\phi_j - \overline{n}_j)}{\beta_j^2 + \gamma_j^2} + \sum_{i=1}^u \left[ \frac{M_i (\theta_{ij} - (\overline{m}_i - \overline{n}_j))}{\sigma_i^2 + \beta_j^2 + \tau_{ij}^2} \cdot \overline{a}_{ij} (\overline{m}_i, \overline{n}_j) \right] \end{split}$$

### The $1 \times 1$ Model

For example, the  $1 \times 1$  model is a four-dimensional system given by

$$\begin{cases} f_1 = \frac{dM}{dt} &= M\overline{W}(\overline{m}, N, \overline{n}) &= M \left[ e\overline{a}(\overline{m}, \overline{n}) N - d \right] \\ f_2 = \frac{dN}{dt} &= N\overline{Y}(N, \overline{n}, M, \overline{m}) &= N \left[ \overline{r}(\overline{n}) \left( 1 - \frac{N}{K} \right) - \overline{a}(\overline{m}, \overline{n}) M \right] \\ f_3 = \frac{d\overline{m}}{dt} &= \sigma_G^2 \frac{\partial \overline{W}}{\partial \overline{m}} &= \sigma_G^2 \left[ \frac{eN(\theta - (\overline{m} - \overline{n}))}{\sigma^2 + \beta^2 + \tau^2} \cdot \overline{a}(\overline{m}, \overline{n}) \right] \\ f_4 = \frac{d\overline{n}}{dt} &= \beta_G^2 \frac{\partial \overline{Y}}{\partial \overline{n}} &= \beta_G^2 \left[ \overline{r}(\overline{n}) \left( 1 - \frac{N}{K} \right) \frac{(\phi - \overline{n})}{\beta^2 + \gamma^2} + \frac{M(\theta - (\overline{m} - \overline{n}))}{\sigma^2 + \beta^2 + \tau^2} \cdot \overline{a}(\overline{m}, \overline{n}) \right] \end{cases}$$

#### Equilibrium Analysis

To find the equilibria of this system, we set each equation to zero, i.e.  $f_1 = f_2 = f_3 = f_4 = 0$ .

$$f_3 = 0 \implies N = 0 \text{ or } \overline{m} - \overline{n} = \theta$$

Let's consider the non-trivial solution, and thus  $\overline{m} - \overline{n} = \theta$ . Then  $\overline{a}(\overline{m}, \overline{n}) = \frac{\alpha \tau}{\sqrt{A}}$  where  $A = \sigma^2 + \beta^2 + \tau^2$ .

$$f_1 = 0 \implies M = 0 \text{ or } N = \frac{d}{e\overline{a}(\overline{m}, \overline{n})} = \frac{d\sqrt{A}}{e\alpha\tau}$$

Again, let's consider the non-trivial solution, and thus  $\frac{d\sqrt{A}}{e\alpha\tau}$ .

$$f_4 = 0 \implies N = K \quad \text{or} \quad \overline{n} = \phi$$

Since  $M \neq 0$ , then  $f_2 = 0 \implies N \neq K$ . Thus  $\overline{n} = \phi$ , and thus  $\overline{m} = \theta + \phi$  and  $\overline{r}(\overline{n}) = \frac{\rho \gamma}{\sqrt{B}}$  where  $B = \beta^2 + \gamma^2$ .

$$f_2 = 0 \implies M = \frac{\rho \gamma \sqrt{A}}{\alpha \tau \sqrt{B}} \left( 1 - \frac{d\sqrt{A}}{e \alpha \tau K} \right)$$

So the coexistence equilibrium solution is

$$C^* = (M^*, N^*, \overline{m}^*, \overline{n}^*) = \left(\frac{\rho \gamma \sqrt{A}}{\alpha \tau \sqrt{B}} \left(1 - \frac{d\sqrt{A}}{e \alpha \tau K}\right), \frac{d\sqrt{A}}{e \alpha \tau}, \theta + \phi, \phi\right)$$

To check for local stability, we find eigenvalues of the Jacobian of the system evaluated at  $C^*$ .

$$\begin{cases} \frac{\partial f_1}{\partial M} &= e\overline{a}(\overline{m}, \overline{n})N - d \\ \frac{\partial f_1}{\partial \overline{m}} &= e\overline{a}(\overline{m}, \overline{n})M \\ \frac{\partial f_1}{\partial \overline{m}} &= \frac{MNe(\theta - (\overline{m} - \overline{n}))}{A} \overline{a}(\overline{m}, \overline{n}) \\ \frac{\partial f_1}{\partial \overline{m}} &= \frac{MNe((\overline{m} - \overline{n}) - \theta)}{A} \overline{a}(\overline{m}, \overline{n}) \\ \frac{\partial f_2}{\partial M} &= -\overline{a}(\overline{m}, \overline{n})N \\ \frac{\partial f_2}{\partial M} &= \overline{r}(\overline{n}) \left(1 - \frac{2N}{K}\right) - \overline{a}(\overline{m}, \overline{n})M \\ \frac{\partial f_2}{\partial \overline{m}} &= -\frac{MN(\theta - (\overline{m} - \overline{n}))}{A} \overline{a}(\overline{m}, \overline{n}) \\ \frac{\partial f_2}{\partial \overline{m}} &= N \left[\frac{\phi - \overline{n}}{B} \overline{r}(\overline{n}) \left(1 - \frac{N}{K}\right) - \frac{M((\overline{m} - \overline{n}) - \theta)}{A} \overline{a}(\overline{m}, \overline{n})\right] \\ \frac{\partial f_3}{\partial M} &= 0 \\ \frac{\partial f_3}{\partial N} &= \frac{\sigma_G^2 e \overline{a}(\overline{m}, \overline{n})(\theta - (\overline{m} - \overline{n})}{A} \\ \frac{\partial f_3}{\partial \overline{m}} &= -\frac{\sigma_G^2 e \overline{a}(\overline{m}, \overline{n})N}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_3}{\partial \overline{m}} &= \frac{\sigma_G^2 e \overline{a}(\overline{m}, \overline{n})N}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial M} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})(\theta - (\overline{m} - \overline{n}))}{A} \\ \frac{\partial f_4}{\partial M} &= -\frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= -\frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= -\frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right] \\ \frac{\partial f_4}{\partial \overline{m}} &= \frac{\beta_G^2 \overline{a}(\overline{m}, \overline{n})M}{A} \left[1 - \frac{(\overline{m} - \overline{n} - \theta)^2}{A}\right]$$

$$\begin{aligned} & \textbf{Special Case:} \ \ M^* = \frac{\rho \gamma \sqrt{A}}{\alpha \tau \sqrt{B}} \left( 1 - \frac{d\sqrt{A}}{Ke\alpha \tau} \right), N = \frac{d\sqrt{A}}{Ke\alpha \tau} \\ & E^* = (\frac{\rho \gamma \sqrt{A}}{\alpha \tau \sqrt{B}} \left( 1 - \frac{d\sqrt{A}}{Ke\alpha \tau} \right), \frac{d\sqrt{A}}{Ke\alpha \tau}, \theta + \phi, \phi). \ \ \text{Then} \ \ J^* = J\big|_{E^*} = \\ & \left( \begin{array}{cccc} 0 & \frac{e\rho \gamma}{\sqrt{B}} \left( 1 - \frac{d\sqrt{A}}{Ke\alpha \tau} \right) & 0 & 0 \\ -\frac{d}{e} & -\frac{d\rho \gamma \sqrt{A}}{Ke\alpha \tau \sqrt{B}} & 0 & 0 \\ 0 & 0 & -\frac{\sigma_G^2 d}{A} & \frac{\sigma_G^2 d}{A} \\ 0 & 0 & -\frac{\beta_G^2 \rho \gamma \left( 1 - \frac{d\sqrt{A}}{Ke\alpha \tau} \right)}{A\sqrt{B}} & \frac{\beta_G^2 \rho \gamma \left( 1 - \frac{d\sqrt{A}}{Ke\alpha \tau} \right)}{\sqrt{B}} \left[ \frac{1}{A} - \frac{1}{B} \right] \\ \end{array} \right) \end{aligned}$$

The characteristic polynomial is

The characteristic polynomial is 
$$P(\lambda) = |\lambda I - J^*| = \begin{vmatrix} \lambda & \frac{e\rho\gamma}{\sqrt{B}} \left(1 - \frac{d\sqrt{A}}{Ke\alpha\tau}\right) & 0 & 0 \\ -\frac{d}{e} & \lambda + \frac{d\rho\gamma\sqrt{A}}{Ke\alpha\tau\sqrt{B}} & 0 & 0 \\ 0 & 0 & \lambda + \frac{\sigma_G^2 d}{A} & \frac{\sigma_G^2 d}{A} \\ 0 & 0 & -\frac{\beta_G^2 \rho\gamma \left(1 - \frac{d\sqrt{A}}{Ke\alpha\tau}\right)}{A\sqrt{B}} & \lambda - \frac{\beta_G^2 \rho\gamma \left(1 - \frac{d\sqrt{A}}{Ke\alpha\tau}\right)}{\sqrt{B}} \left[\frac{1}{A} - \frac{1}{B}\right] \end{vmatrix}$$
 Thus,

Thus,

$$P(\lambda) = \begin{vmatrix} \lambda & \frac{e\rho\gamma}{\sqrt{B}} \left( 1 - \frac{d\sqrt{A}}{Ke\alpha\tau} \right) \\ -\frac{d}{e} & \lambda + \frac{d\rho\gamma\sqrt{A}}{Ke\alpha\tau\sqrt{B}} \end{vmatrix} \cdot \begin{vmatrix} \lambda + \frac{\sigma_G^2 d}{A} & \frac{\sigma_G^2 d}{A} \\ -\frac{\beta_G^2 \rho\gamma \left( 1 - \frac{d\sqrt{A}}{Ke\alpha\tau} \right)}{A\sqrt{B}} & \lambda - \frac{\beta_G^2 \rho\gamma \left( 1 - \frac{d\sqrt{A}}{Ke\alpha\tau} \right)}{\sqrt{B}} \left[ \frac{1}{A} - \frac{1}{B} \right] \end{vmatrix}$$

$$= P_1(\lambda) \cdot P_2(\lambda)$$

Thus the zeros of  $P(\lambda)$  are the zeros of both  $P_1(\lambda)$  and  $P_2(\lambda)$ .

$$P_1(\lambda) = \lambda^2 + \lambda \frac{d\rho\gamma\sqrt{A}}{Ke\alpha\tau\sqrt{B}} + \frac{d\rho\gamma}{\sqrt{B}} \left(1 - \frac{d\sqrt{A}}{Ke\alpha\tau}\right)$$

$$\implies \lambda_{1,2} = \frac{1}{2} \left[ -\frac{d\rho\gamma\sqrt{A}}{Ke\alpha\tau\sqrt{B}} \pm \sqrt{\Delta} \right]$$

Where 
$$\Delta = \left(\frac{d\rho\gamma\sqrt{A}}{Ke\alpha\tau\sqrt{B}}\right)^2 - \frac{4d\rho\gamma}{\sqrt{B}}\left(1 - \frac{d\sqrt{A}}{Ke\alpha\tau}\right)$$
. Since  $N^* = \frac{d\sqrt{A}}{e\alpha\tau} < K$ ,  $\sqrt{\Delta} < \left|\frac{d\rho\gamma\sqrt{A}}{Ke\alpha\tau\sqrt{B}}\right|$ . Thus  $\operatorname{Re}(\lambda_{1,2}) < 0 \iff \left(\frac{d\rho\gamma\sqrt{A}}{Ke\alpha\tau\sqrt{B}}\right)^2 > \frac{4d\rho\gamma}{\sqrt{B}}\left(1 - \frac{d\sqrt{A}}{Ke\alpha\tau}\right)$ . So the coexistence equilibrium is stable if

$$\left(\frac{d\rho\gamma\sqrt{A}}{Ke\alpha\tau\sqrt{B}}\right)^{2} > \frac{4d\rho\gamma}{\sqrt{B}}\left(1 - \frac{d\sqrt{A}}{Ke\alpha\tau}\right)$$
For simplicity, let  $C = \frac{d\sigma_{G}^{2}}{A}$ ,  $D = \frac{\beta_{G}^{2}\rho\gamma\left(1 - \frac{d\sqrt{A}}{Ke\alpha\tau}\right)}{A\sqrt{B}}$ ,  $E = \frac{\beta_{G}^{2}\rho\gamma\left(1 - \frac{d\sqrt{A}}{Ke\alpha\tau}\right)}{B^{3/2}}$ 

$$P_{2}(\lambda) = \lambda^{2} + (C + E - D)\lambda + CE = 0$$

$$\implies \lambda_{3,4} = \frac{1}{2}\left[-(C + E - D) \pm \sqrt{\Delta}\right]$$

Where

$$\Delta = (C + E - D)^2 - 4CE$$

Again, since  $N^* = \frac{d\sqrt{A}}{e\alpha\tau} < K$  and C, D, E > 0,  $\sqrt{\Delta} < |C + E - D|$ . Thus  $\text{Re}(\lambda_{3,4}) < 0 \iff C + E > D$  and  $C^2 + D^2 + E^2 > 2(CD + DE + CE)$ . So the coexistence equilibrium is stable if

$$C + E > D$$
  
 $C^2 + D^2 + E^2 > 2(CD + DE + CE)$