Isabel Moore

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SUMMARY

Computer Engineering graduate student specializing in robotics, autonomy, networking, and controls. Seeking Summer 2025 internship with plans for full-time employment upon May 2026 graduation.

EDUCATION

Texas A&M University

Master of Science in Computer Engineering, Focus on Robotics/Autonomy Bachelor of Science in Mechanical Engineering Aug 2024 - May 2026

Aug 2019 - May 2024

EXPERIENCE

Texas A&M Engineering Experiment Station (TEES), Texas A&M

Aug 2024 - Jan 2025

Graduate Researcher

- Enabled seamless cross-operation between Texas A&M and UMich's Mcity autonomous vehicle track of testing ground truth data, simulation, and machine learning model prediction.
- Streamlined data pipelines for data preparation, model training, data augmentation, and model refinement.

Bush Combat Development Complex, Byran, TX

May 2024 - Sep 2024

Graduate Researcher | Air-Ground Cooperative Autonomy Team & Resilient, Real-time Networking Team

- Led development of differential drive control using reinforcement learning and neural network policies for Jackal robots, integrating Gazebo simulation results with real-world data testing.
- Diagnosed and corrected system errors by optimizing neural network weights and model parameters using TensorBoard, leading to 25% reduction in critic loss for better prediction precision.

Connected Autonomous Safe Technologies (CAST) Laboratory, Texas A&M

Sep 2023 - May 2024

Undergraduate Researcher

- Designed and validated recovery algorithms to counter GPS spoofing attacks, enhancing GPS security and advancing autonomous vehicle technology, achieving path error to less than 3% in spoofing conditions.
- Authored undergraduate thesis on resilient fusion for localization under GPS spoofing attacks, accepted for publication at IEEE Cyber Security and Resilience Conference 2024.

Southwest Research Institute, San Antonio, TX

May 2023 - Aug 2023

Fellow for UTSR Gas Turbine Industrial Fellowship Program

- Redesigned microturbine for hybrid/electric UAV fuel system, aligning CFD analysis with physical test results from previous year to enhance design accuracy, achieving prediction alignment within 98.9%.
- Presented findings at conference of 200 attendees using combustion pressure distribution and fuel system analytics to develop and propose future design modifications.

IT Security Operations, Texas A&M

Jan 2023 - May 2023

Cybersecurity Student Analyst

- Monitored and analyzed around a dozen security alerts daily to identify and address potential incidents.
- Performed security assessments and vulnerability scans on university systems, identifying risks and implementing mitigation strategies.

PROJECTS

US Army Moving Object Trajectory Estimation (MOTE)

May 2024 - Sep 2024

- Engineered autonomous navigation system to optimize yaw control through live trajectory adjustments.
- Acheived significant reduction in yaw error from 180° to within 2-5° (97% reduction), improving off-road testing.

GM-SAE AutoDrive ChallengeTM II

Aug 2023 - Jun 2024

- Led team of 6 on Vehicle Dynamics & CANBUS team, steering efforts as Technical Analysis Lead to refine vehicle path planning and securing 2nd place overall.
- Focused on optimizing lateral controller settings, enhancing vehicle stability and maneuverability by 70%.

PUBLICATIONS

• Using Sensor-Health-Aware Resilient Fusion for Localization in Presence of GPS Spoofing Attacks. IEEE International Conference on Cyber Security and Resilience (CSR), London, UK, 2024.

PROFESSIONAL SKILLS

- Programming: Python, C++/C/C#, Java, SQLite, Git, LabVIEW, MATLAB/Simulink
- Software: ROS, RViz, Gazebo, Linux, Docker, ANSYS Fluent, SolidWorks, AutoCAD