

Machine Learning in Complex Domains:

Assignment 3

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4 Blocked Gibbs Sampler

4.1 Analysis Questions

We have the following equation

$$p(z_{d,i} = k, x_{d,i} = c | \mathbf{z} - z_{d,i}, \mathbf{x} - x_{d,i}, \mathbf{c}, \mathbf{w}; \alpha, \beta, \lambda) = \frac{p(\mathbf{z}, \mathbf{x}, \mathbf{c}, \mathbf{w} | \alpha, \beta, \lambda)}{p(\mathbf{z} - z_{d,i}, \mathbf{x} - x_{d,i}, \mathbf{c}, \mathbf{w}; \alpha, \beta, \lambda)}$$

The full join (numerator) is given to us in the assignment. We can factor this according to the joint and every term that does not involve $z_{d,i}$ or $x_{d,i}$ will cancel. This is basically a union of (15) and (18). This yields the following:

$$p(z_{d,i} = k, x_{d,i} = 0 | \mathbf{z} - z_{d,i}, \mathbf{x} - x_{d,i}, \mathbf{c}, \mathbf{w}; \alpha, \beta, \lambda) = \frac{p(x = 0 | \lambda) \frac{\Gamma(n_{w_{d,i}}^k + 1 + \beta)}{\Gamma(1 + \sum_w n_w^k + \beta)} \frac{\Gamma(n_k^d + 1 + \alpha)}{\Gamma(1 + \sum_{k'} n_{k'}^d + \alpha)}}{\frac{\Gamma(n_{w_{d,i}}^k + \beta)}{\Gamma(\sum_w n_w^k + \beta)} \frac{\Gamma(n_k^d + \alpha)}{\Gamma(\sum_{k'} n_{k'}^d + \alpha)}}$$
$$p(z_{d,i} = k, x_{d,i} = 0 | \mathbf{z} - z_{d,i}, \mathbf{x} - x_{d,i}, \mathbf{c}, \mathbf{w}; \alpha, \beta, \lambda) \propto \frac{(1 - \lambda)(n_{w_{d,i}}^k + \beta)(n_k^d + \alpha)}{(n_*^k + K\beta)(n_*^d + V\alpha)}$$

By analogy, we get the following for the case that $p(x = 1)$.

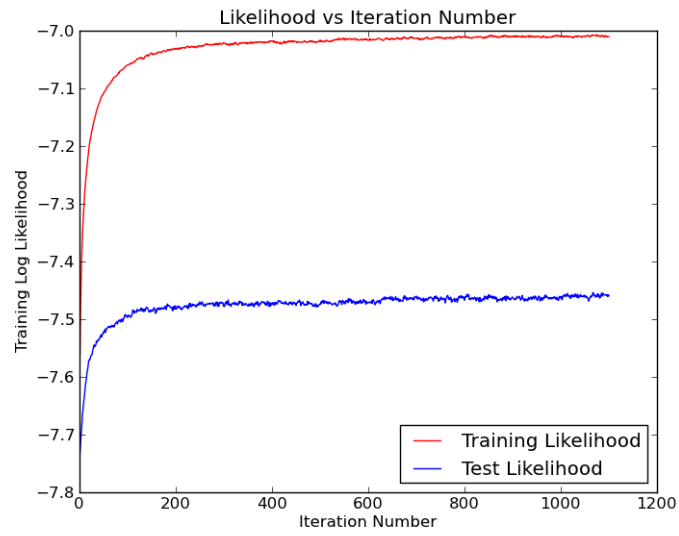
$$p(z_{d,i} = k, x_{d,i} = 1 | \mathbf{z} - z_{d,i}, \mathbf{x} - x_{d,i}, \mathbf{c}, \mathbf{w}; \alpha, \beta, \lambda) \propto \frac{\lambda(n_{w_{d,i}}^k + \beta)(n_k^d + \alpha)}{(n_*^k + K\beta)(n_*^d + V\alpha)}$$

Most of the heavy lifting for this question was done in the appendix so there isn't really any more we can write.

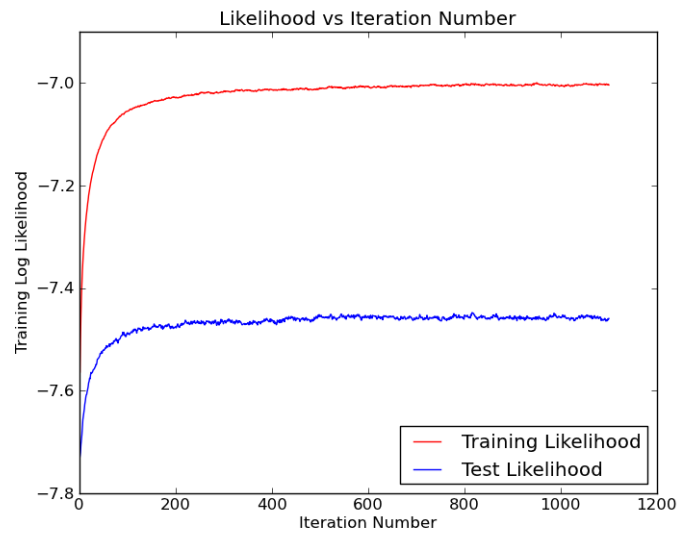
5 Text Analysis with MCLDA

5.1 Empirical Questions

6. (a)
- (b)
- (c)



1.

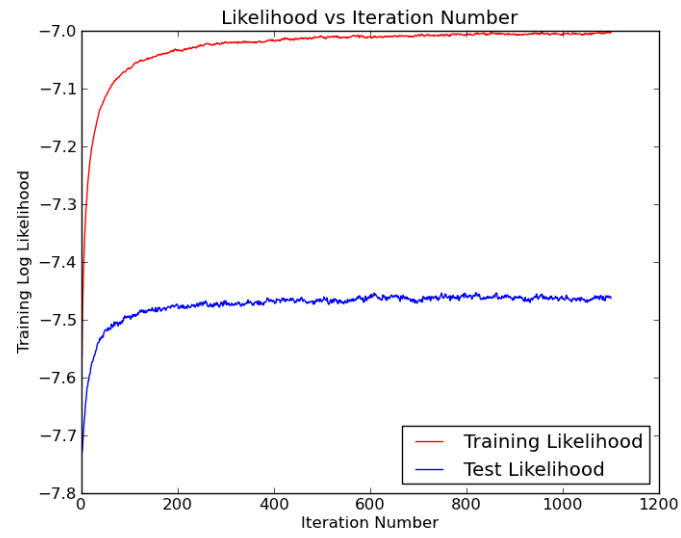


6 Variational Inference

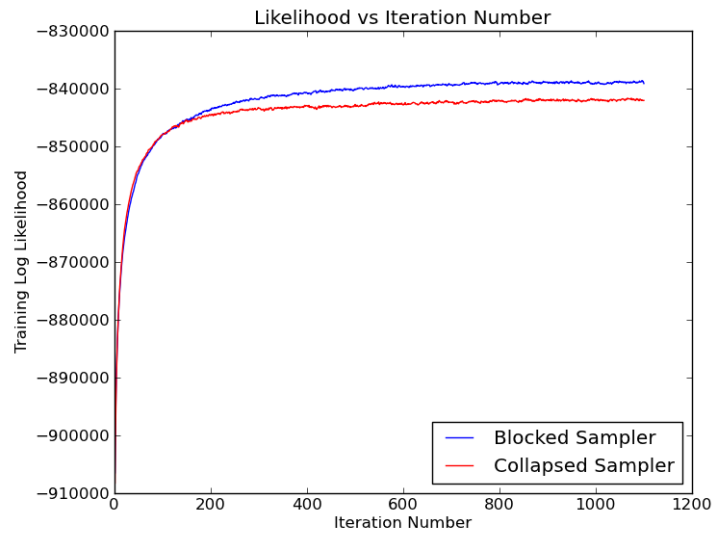
6.1 Analysis Questions

6.3 Empirical Questions

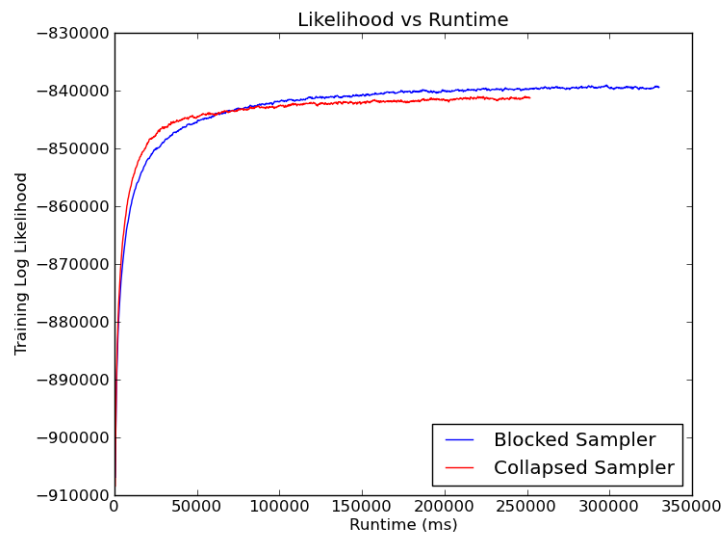
- 1.
- 2.
- 3.
- 4.

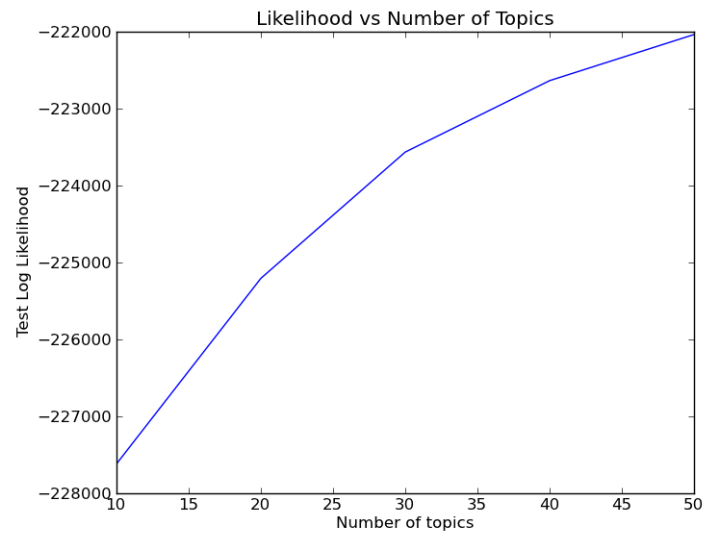


2.

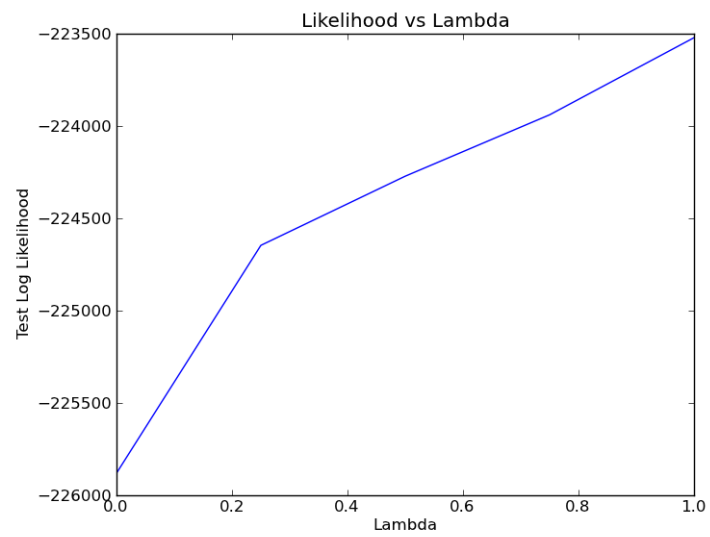


3.





4.



5.