# Bayesian Neural Networks

ROY team: Ilya Zharikov,

Roman Isachenko, Artem Bochkarev

Skolkovo Institute of Science and Technology Bayesian Methods course

May 25, 2017

# Project goal

#### Goal

Estimate posterior distributions of the model parameters from data

#### Problem

Monte Carlo sampling is very slow for high-dimensional data

## **Probabilistic Programming:**

- Uncertainty in predictions;
- Uncertainty in representations;
- Regularizations with priors;
- Transfer learning;
- Hierarchical Neural Networks.



## Related work

 Salvatier J, Wiecki T. V., Fonnesbeck C. Probabilistic programming in Python using PyMC3. // PeerJ Computer Science. 2016.

- Blundell C. et al. Weight Uncertainty in Neural Network // Proceedings of The 32nd International Conference on Machine Learning. 2015.
- Wucukelbir A. et al. Automatic Differentiation Variational Inference // arXiv preprint arXiv:1603.00788. – 2017.

## Problem Statement

#### Inference problem

Bayes' theorem states: 
$$\mathbb{P}(\theta \mid \mathbf{X}) = \frac{\mathbb{P}(\mathbf{X} \mid \theta)\mathbb{P}(\theta)}{\mathbb{P}(\mathbf{X})}$$

### Maximum A Posteriori (MAP) estimation

$$\boldsymbol{\theta}^* = \arg\max_{\boldsymbol{\theta}} \left[ \ln \mathbb{P}(\boldsymbol{\theta} \,|\, \mathbf{X}) \right] = \arg\max_{\boldsymbol{\theta}} \left[ \ln \mathbb{P}(\mathbf{X} \,|\, \boldsymbol{\theta}) + \ln \mathbb{P}(\boldsymbol{\theta}) \right]$$

### Monte Carlo approach:

- Metropolis-Hastings sampling;
- Gibbs sampling;
- No-U-Turn Sampling (NUTS).



## Variational Inference

#### Goal

Approximate posterior distribution  $p(X, \theta)$  by function  $q(\theta)$  from parametric family.

$$\ln p(\mathbf{X}) = \mathsf{KL}(q||p) + \mathsf{ELBO}(q)$$

$$\updownarrow \qquad \qquad \updownarrow$$

$$\int q(\theta) \ln \frac{q(\theta)}{p(\theta|\mathbf{X})} \mathsf{d}\theta \qquad \int q(\theta) \ln \frac{p(\mathbf{X},\theta)}{q(\theta)} \mathsf{d}\theta$$

Minimization of  $KL(q||p) \Leftrightarrow Maximization of ELBO(q)$ 

# Automatic Differentiation Variational Inference (ADVI)

- Automatic transformation of constrained variables  $\zeta = T(\theta)$ ; Example:  $\theta \in \mathbb{R}_+ \Rightarrow \zeta = T(\theta) = \log \theta$ , then  $\zeta \in \mathbb{R}$ .
- $ullet q(\zeta) = \mathcal{N}(\mu, \Sigma)$ , where  $\Sigma$  is diagonal;

$$oldsymbol{\mu}^*, oldsymbol{\Sigma}^* = rg \max_{oldsymbol{\mu}, oldsymbol{\Sigma}} \mathsf{ELBO}(q)$$

- Stochastic optimization;
- Reparametrization trick to apply automatic differentiation;
- Adaptive step-size.



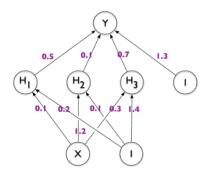
# Deep Learning

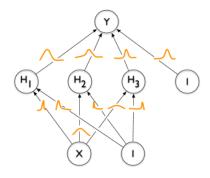
#### **Neural Networks**

Predict values of parameters by fitting complex model on the huge dataset

## **Bayesian Neural Networks**

Predict the parameters of the weights distributions from the dataset





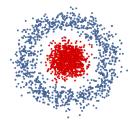
http://bit.ly/2rMQuDq

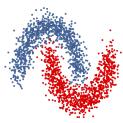
# Experiments

#### Goals:

- investigate influence of different priors on the predictions
- visualize uncertainties in predictions
- analyze the model behaviour

#### Datasets:







## Course of work

**Priors**: Normal, Laplace, Flat, Cauchy **Hyperpriors**:

- fixed values of hyperparameters
- Hierarchical modelling: Half-Normal, Half-Cauchy, Inverse-Gamma

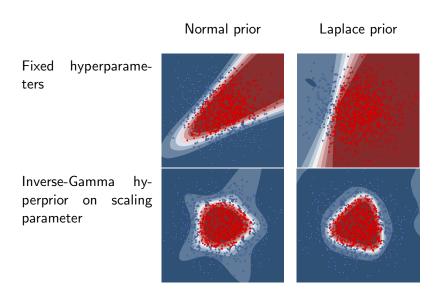
# Synthetic data

**Prior:** Cauchy **Hyperprior:** Inverse-Gamma **Accuracy:** 0.735

Prior: Normal Hyperprior: Inverse-Gamma Accuracy: 0.851

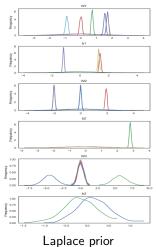
# Posterior Probability Uncertainty

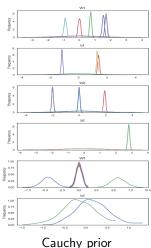
# Synthetic data



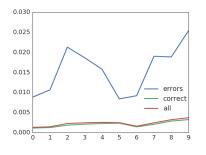
# Synthetic data

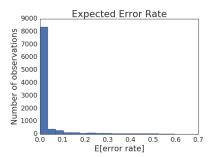
Laplace prior does indeed provide sparser solutions compared to cauchy or gauss.





## **MNIST**





- Accuracy score: 97.7%
- Variance is much higher for misclassified pictures
- Model is not always confident



## **MNIST**

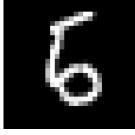
Misclassified pictures with zero expected error rate:

True: 7
Prediction: 0

True: 9 Prediction: 7 True: 5
Prediction: 6







## **MNIST**

#### Pictures with the lowest confidence

True: 4 Prediction: 0

True: 6
Prediction: 8

True: 1 Prediction: 1





