

Symmetry Teleportation for Accelerated Optimization

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<https://arxiv.org/pdf/2205.10637.pdf>

Symmetry Teleportation

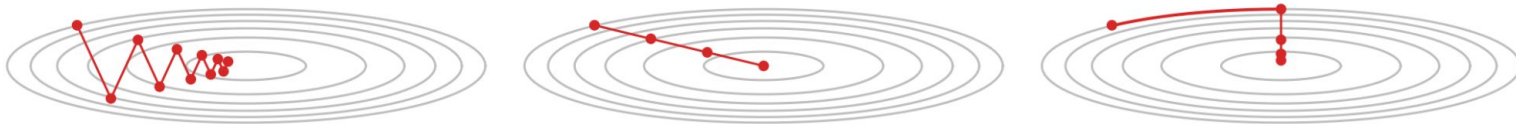


Figure 1: Left to right: gradient descent, second-order methods, proposed method.

Algorithm 1: Symmetry Teleportation

Input: Loss function $\mathcal{L}(w)$, learning rate η , number of epochs t_{max} , initialized parameters w_0 , symmetry group G , teleportation schedule K .

Output: $w_{t_{max}}$.

```

1 for  $t \leftarrow 0$  to  $t_{max} - 1$  do
2   if  $t \in K$  then
3      $g \leftarrow \operatorname{argmax}_{g \in G} \|(\nabla \mathcal{L})|_{g \cdot w_t}\|^2$ 
4      $w_t \leftarrow g \cdot w_t$ 
5   end if
6    $w_{t+1} \leftarrow w_t - \eta(\nabla \mathcal{L})|_{w_t}$ 
7 end for
8 return  $w_{t_{max}}$ 

```

$$G = \left\{ g : \mathcal{L}(w) = \mathcal{L}(g \cdot w) \right\}$$

Example: Booth function

$$\mathcal{L}_b(x_1, x_2) = (x_1 + 2x_2 - 7)^2 + (2x_1 + x_2 - 5)^2 \qquad \mathcal{L}_b(u, v) = u^2 + v^2$$

**Bijective change
of variables**

$$(u, v) = h(x_1, x_2) = (x_1 + 2x_2 - 7, 2x_1 + x_2 - 5)$$
$$(x_1, x_2) = h^{-1}(u, v) = \left(-\frac{1}{3}u + \frac{2}{3}v + 1, \frac{2}{3}u - \frac{1}{3}v + 3\right)$$

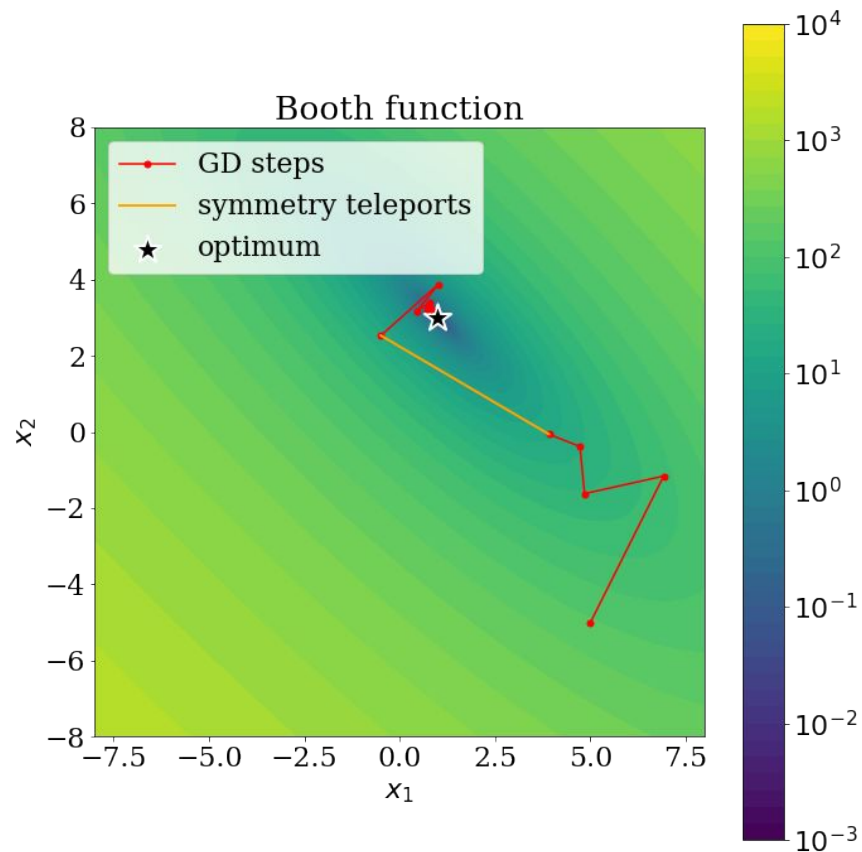
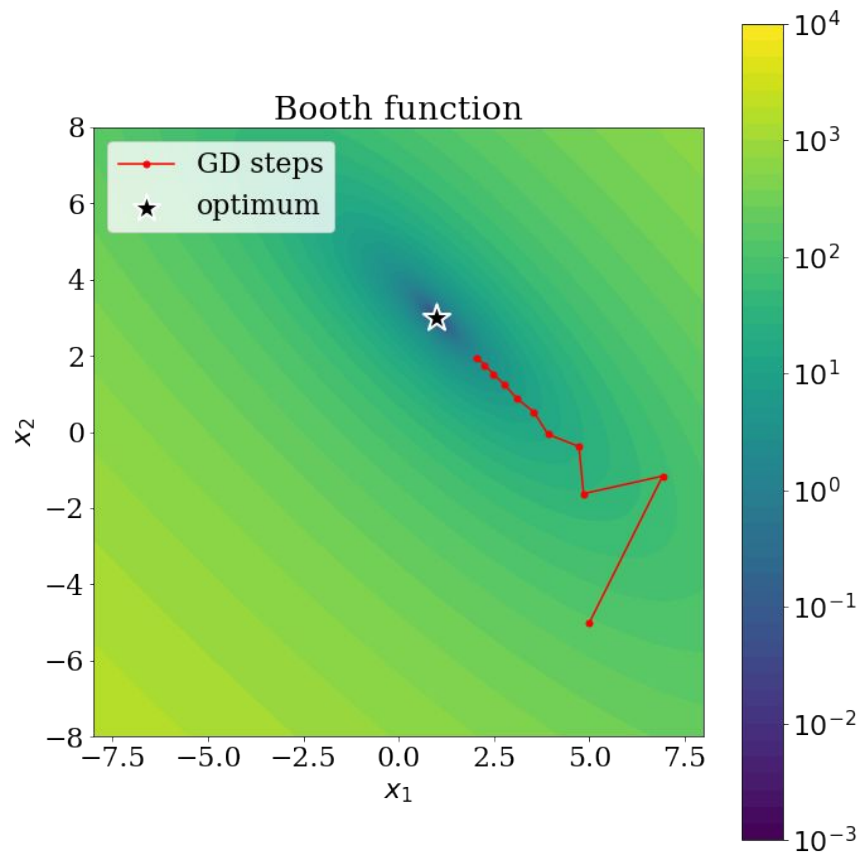
$$g_\theta \cdot (x_1, x_2) = h^{-1}(R_\theta h(x_1, x_2))$$

$$\mathcal{L}_b(x_1, x_2) = \mathcal{L}_b(g_\theta \cdot (x_1, x_2))$$

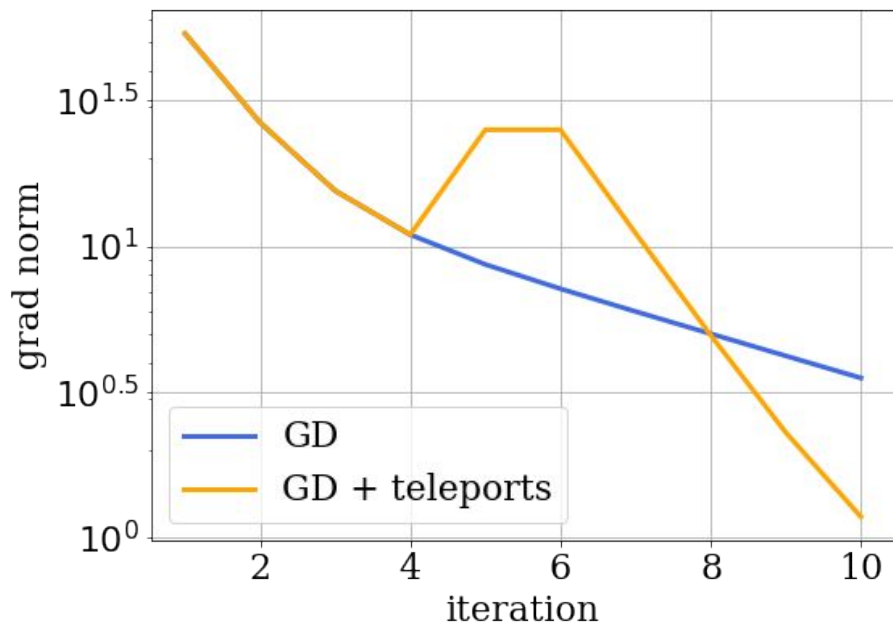
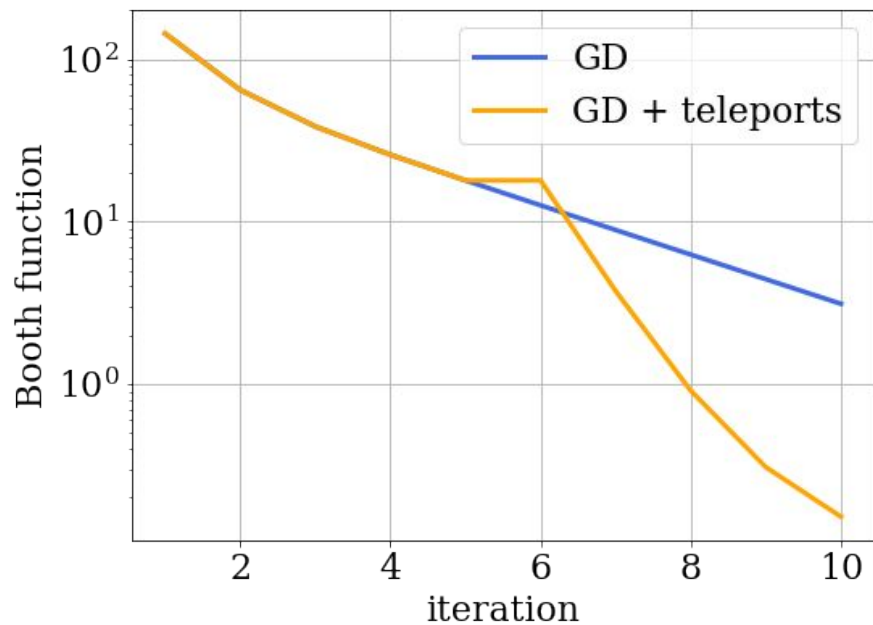
Arbitrary rotation matrix



Example: Booth function



Example: Booth function



Example: Rosenbrock function

$$\mathcal{L}_r(x_1, x_2) = 100(x_1^2 - x_2)^2 + (x_1 - 1)^2 \quad \mathcal{L}_r(u, v) = u^2 + v^2$$

**Bijective change
of variables**

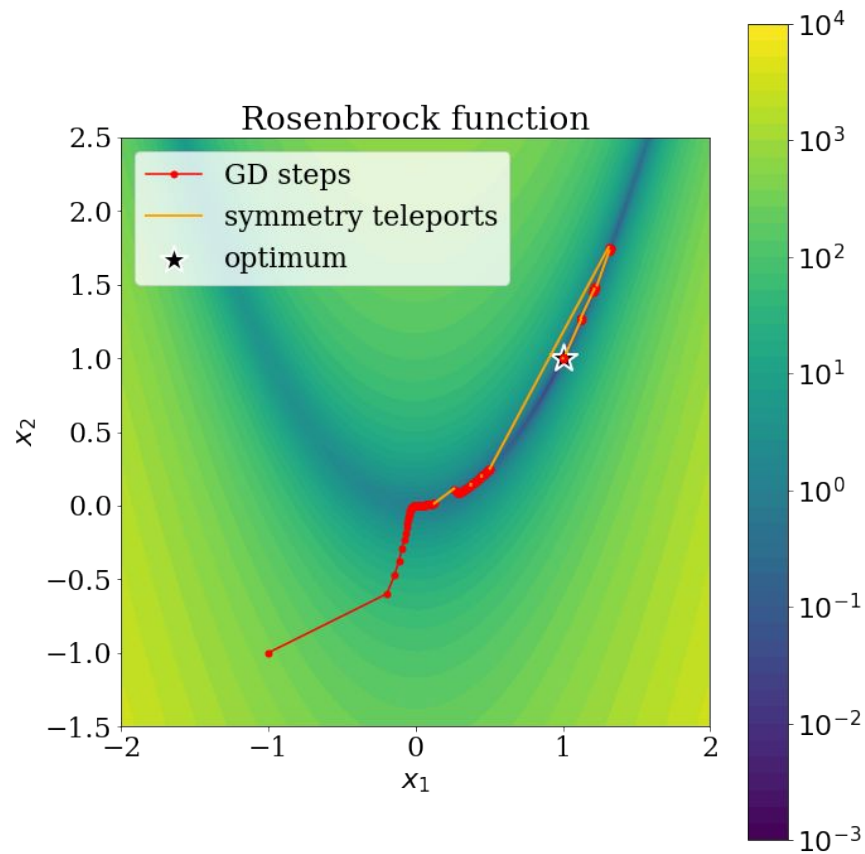
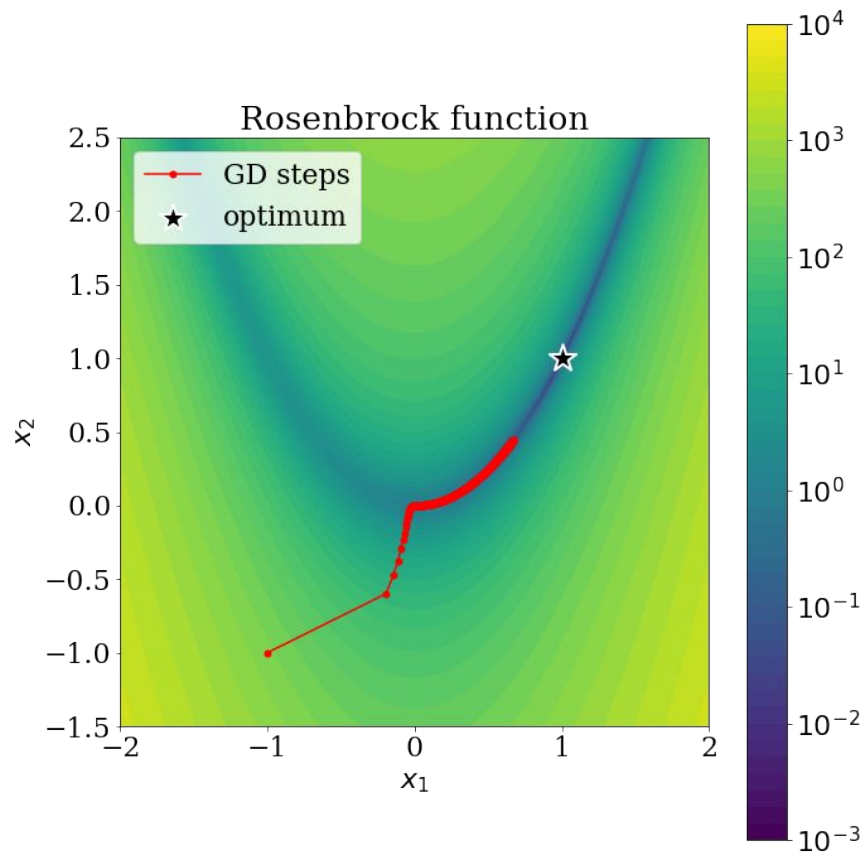
$$(u, v) = h(x_1, x_2) = (10(x_1^2 - x_2), x_1 - 1)$$
$$(x_1, x_2) = h^{-1}(u, v) = (v + 1, (v + 1)^2 - 0.1u)$$

$$g_\theta \cdot (x_1, x_2) = h^{-1}(R_\theta h(x_1, x_2)) \quad \mathcal{L}_r(x_1, x_2) = \mathcal{L}_r(g_\theta \cdot (x_1, x_2))$$

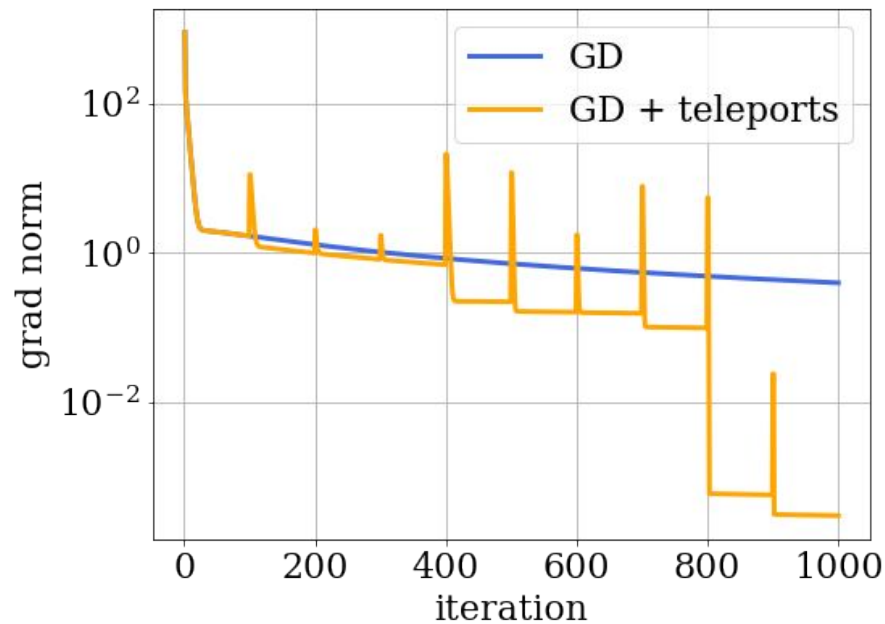
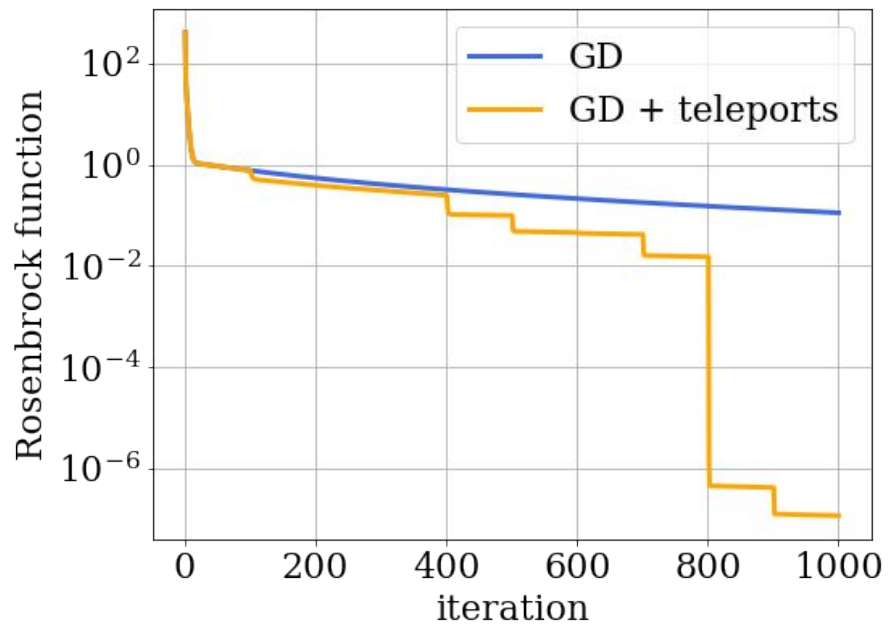
Arbitrary rotation matrix



Example: Rosenbrock function



Example: Rosenbrock function



Example: MNIST

$$MLP(x) = W_3 \sigma(W_2 \sigma(W_1 x))$$

$$g_m \cdot W_k = \begin{cases} W_m g_m^{-1} & k = m \\ \sigma^{-1}(g_m \sigma(W_{m-1} h_{m-2})) h_{m-2}^{-1} & k = m - 1 \\ W_k & k \notin \{m, m - 1\} \end{cases}$$

$$MLP(x) = \underbrace{W_3 g_3^{-1}}_{W'_3} \sigma \left(\underbrace{\sigma^{-1}(g_3 \sigma(W_2 h_1)) h_1^{-1}}_{W'_2} \underbrace{\sigma(W_1 x)}_{h_1} \right) =$$

Example: MNIST

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Example: MNIST

$$MLP(x) = W_3 \sigma(W_2 \sigma(W_1 x))$$

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$$\begin{aligned} MLP(x) &= \underbrace{W_3 g_3^{-1}}_{W'_3} \sigma \left(\underbrace{\sigma^{-1}(g_3 \sigma(W_2 h_1))}_{W'_2} \underbrace{\cancel{\sigma(W_1 x)}}_{h_1} \right) = \underbrace{W_3 g_3^{-1}}_{W'_3} \cancel{\sigma} \left(\cancel{\sigma^{-1}}(g_3 \sigma(W_2 h_1)) \right) = \\ &= W_3 g_3^{-1} (g_3 \sigma(W_2 h_1)) = W_3 \sigma(W_2 h_1) \end{aligned}$$

Example: MNIST

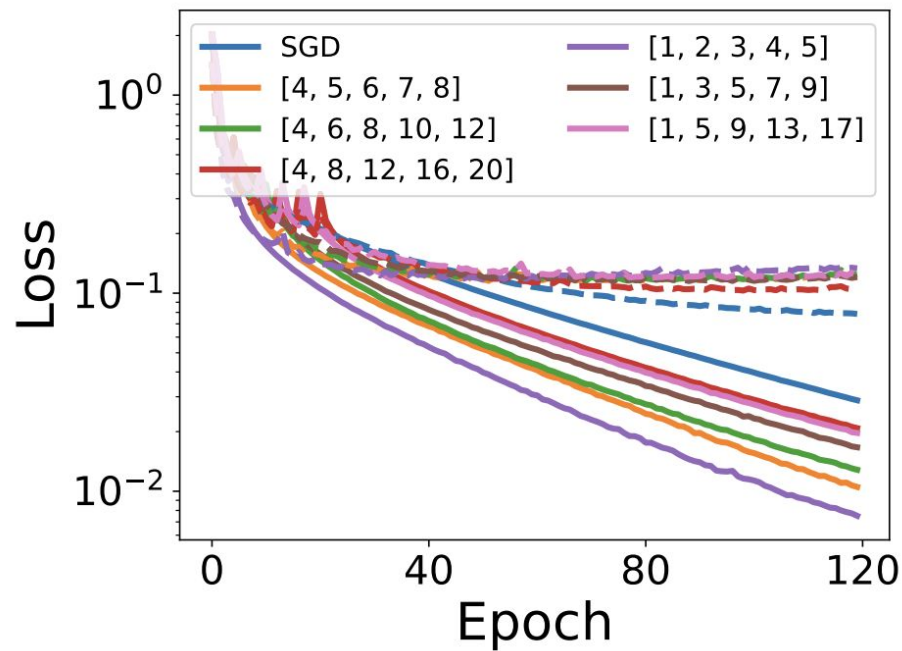
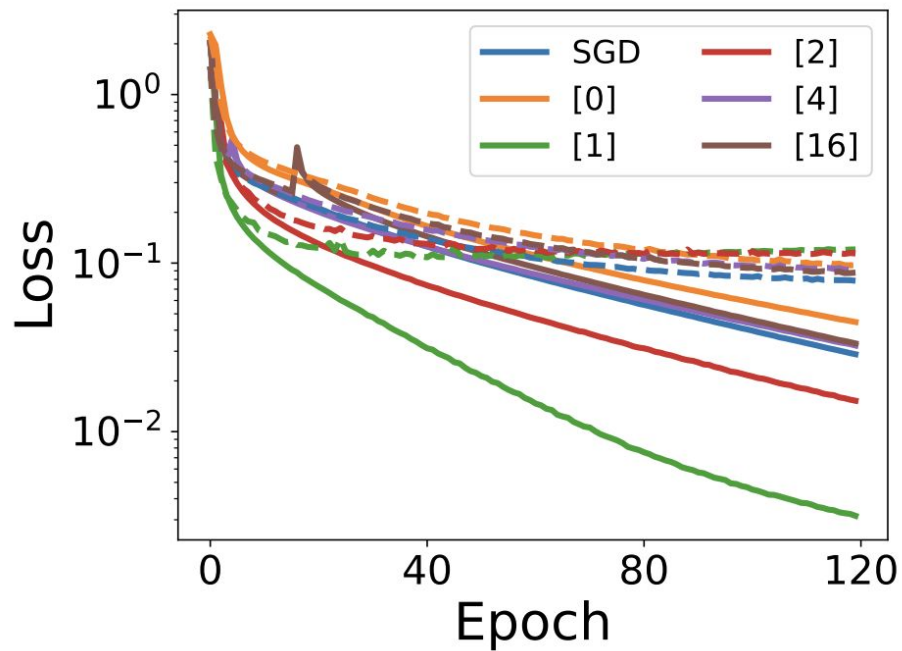
$$MLP(x) = W_3 \sigma(W_2 \sigma(W_1 x))$$

$$g_m \cdot W_k = \begin{cases} W_m g_m^{-1} & k = m \\ \sigma^{-1}(g_m \sigma(W_{m-1} h_{m-2})) h_{m-2}^{-1} & k = m - 1 \\ W_k & k \notin \{m, m - 1\} \end{cases}$$

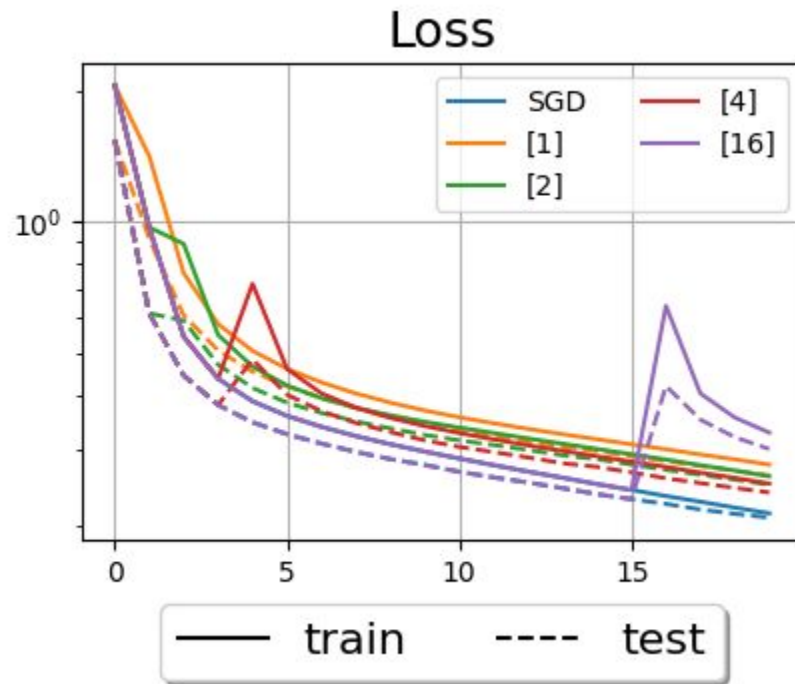
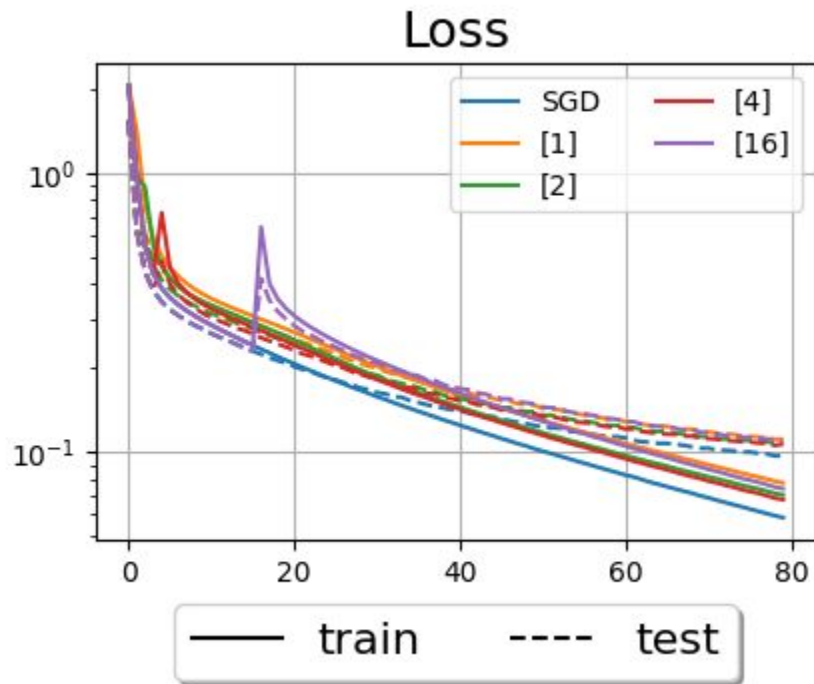
$$\begin{aligned} MLP(x) &= \underbrace{W_3 g_3^{-1}}_{W'_3} \sigma \left(\underbrace{\sigma^{-1}(g_3 \sigma(W_2 h_1))}_{W'_2} \underbrace{\cancel{\sigma(W_1 x)}}_{h_1} \right) = \underbrace{W_3 g_3^{-1}}_{W'_3} \cancel{\sigma} \left(\cancel{\sigma^{-1}}(g_3 \sigma(W_2 h_1)) \right) = \\ &= W_3 g_3^{-1} (g_3 \sigma(W_2 h_1)) = W_3 \sigma(W_2 h_1) \end{aligned}$$

$$g \approx I + \epsilon T, \quad g^{-1} \approx I - \epsilon T, \quad gg^{-1} = I - \epsilon^2 T^2 \xrightarrow{\epsilon \rightarrow 0} I$$

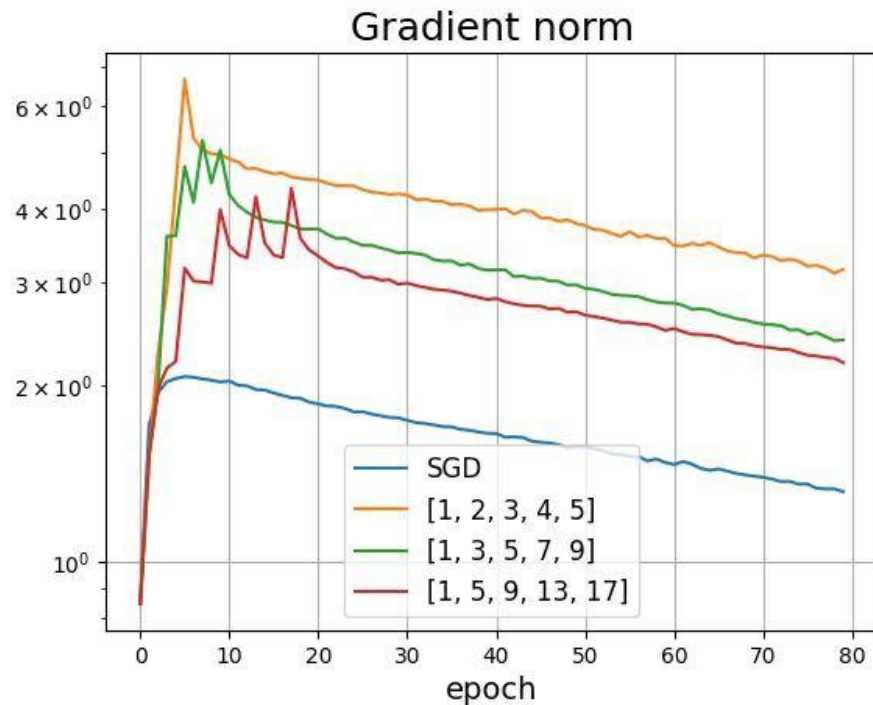
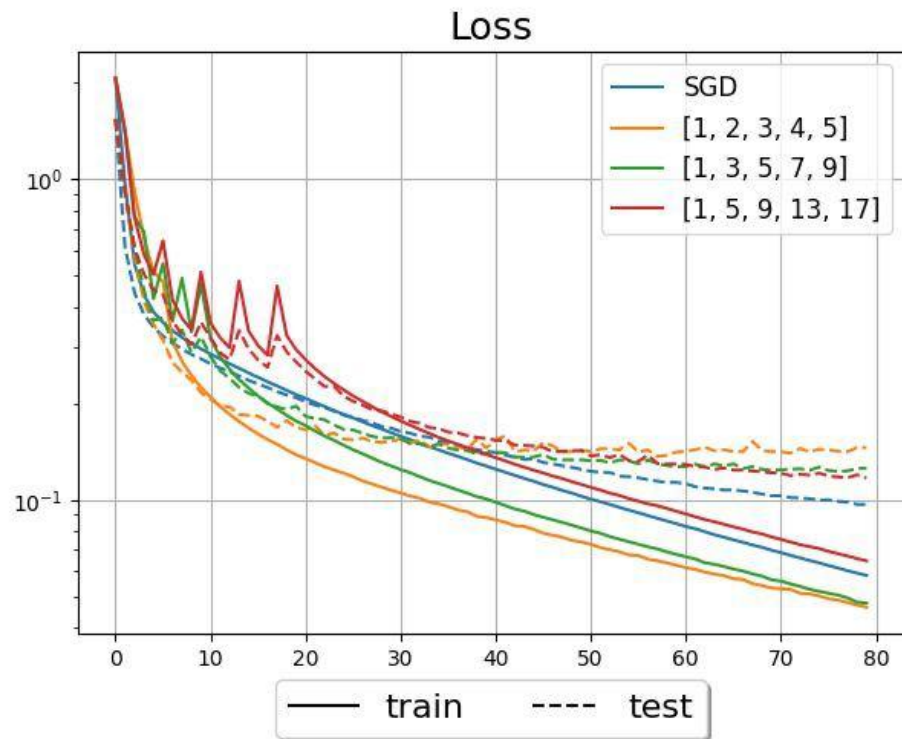
Example: MNIST (Paper results)



Example: MNIST (One Teleportation)

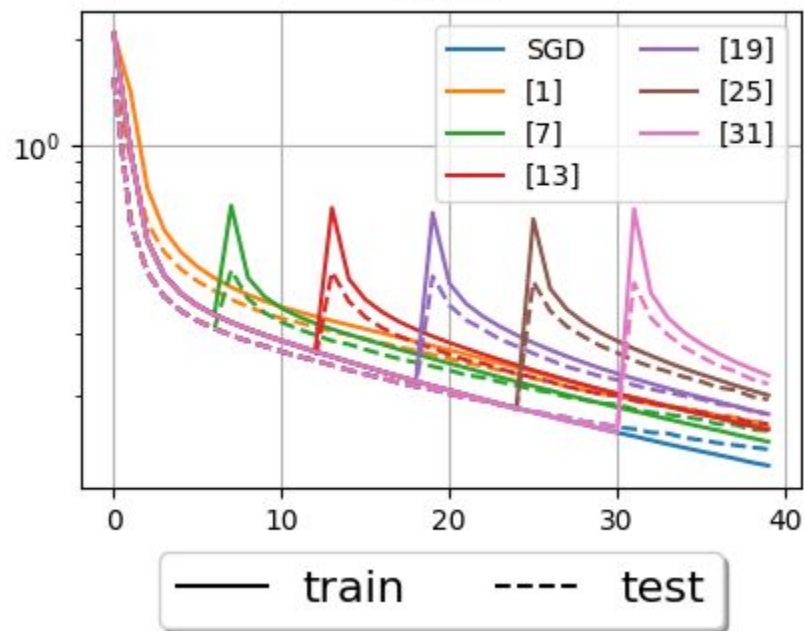


Example: MNIST (Several Teleportations)

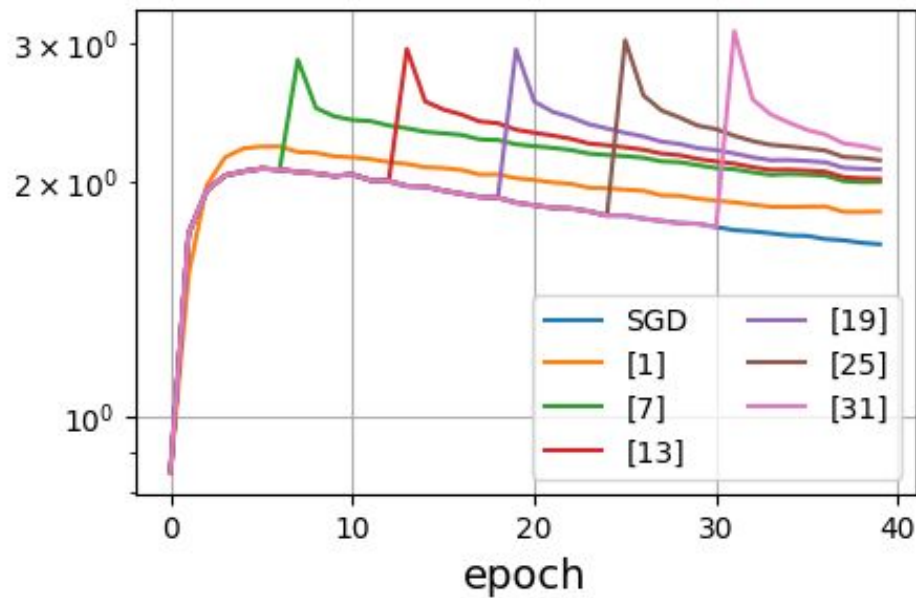


Example: MNIST

Loss



Gradient norm



Example: MNIST (Batch Size 200)

