

## Chapter 5. Cases Study

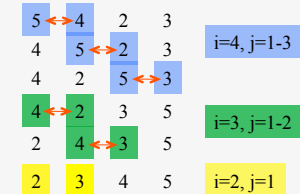
### □ Organization

- Parallel sort
- Matrix – matrix multiplication
- Image processing
- Dynamical system simulation

## Bubble sort odd-even

### • Sequential bubble sort

for  $i=n$  to 2  
 for  $j=1$  to  $i-1$   
 else compare-exchange( $j, j+1$ )



### • Bubble sort odd-even

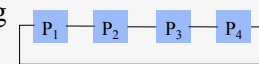
◇ 1 element per processor

for  $k=1$  to  $n/2$

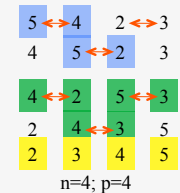
$P_i$ ,  $i$  odd compare-exchange with  $P_{i+1}$

$P_i$ ,  $i$  even compare-exchange with  $P_{i+1}$

◇ on a ring



◇  $n$  stages of comparison



## Bubble sort odd-even

### • Bubble sort odd-even

◇  $n/p$  elements per processor

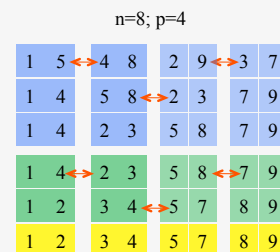
Each processor sorts its elements  
 for  $k=1$  to  $p/2$

$P_i$ ,  $i$  odd with  $P_{i+1}$ :

- exchange of their sub-lists
- gather-sort of 2 sub-lists
- $P_i$  keeps the lower half of the list
- $P_{i+1}$  keeps the upper half of the list

$P_i$ ,  $i$  even with  $P_{i+1}$

- exchange of their sub-lists
- gather-sort of 2 sub-lists
- $P_i$  keeps the lower half of the list
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## Matrix-Matrix Multiplication

### □ Problem

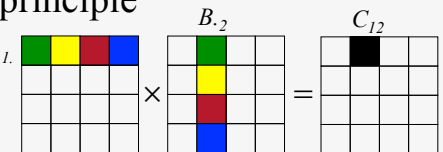
- Compute  $C=A \times B$ ,  $A, B$ : matrix  $n \times n$  on a torus of  $p \times p$  process

$$c_{ij} = \sum_{k=0}^{n-1} a_{ik} b_{kj}$$

### □ Parallel algorithm: principle

Process  $(s, t)$  calculates:  $A_{I_s}$

$$C_{st} = \sum_{k=0}^{p-1} A_{sk} B_{kt}$$



## Matrix-Matrix Multiplication

- Parallel algorithm 1: each process computes one bloc of  $C$  matrix

- **First stage**

1. Cut the matrix  $A$ ,  $B$ ,  $C$  into blocs
2. Distribute the blocs  $A_{ij}$  and  $B_{ij}$  without replication
3. Compute a  $A_{ik} * B_{kj}$

- **Second stage**

1. Circulating of the blocs  $A_{ij}$  and  $B_{ij}$  (For example, send the  $A_{ij}$  to the left, and the  $B_{ij}$  to the upper)
2. Compute a  $A_{ik} * B_{kj}$
3. Repeat  $p-1$  times ( $N=p*p$ )

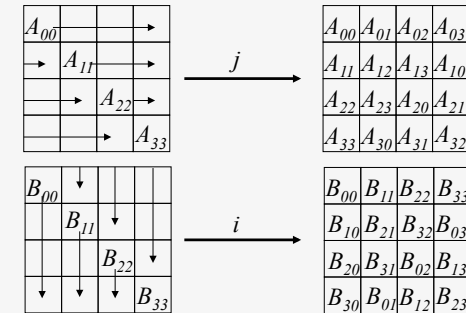
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## Matrix-Matrix Multiplication

- Parallel algorithm 1: example

- Initial distribution of  $A_{ij}$  and  $B_{ij}$



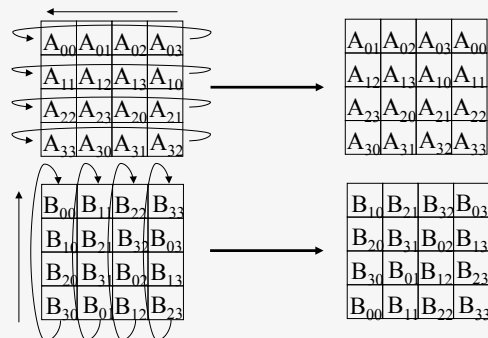
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## Matrix-Matrix Multiplication

- Parallel algorithm 1: example

- Circulating of the blocs  $A_{ij}$  and  $B_{ij}$ :  $p-1$  times



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## Matrix-Matrix Multiplication

- Performance evaluation

- Computation time:

$$Tcomp_{ij}^0 = [t * t(t * t_{multi} + (t-1) * t_{add})], t = \frac{n}{p}$$

$$Tcomp_{ij}^k = [t * t(t * t_{multi} + (t-1) * t_{add})] + [t * t * t_{add}], k = 1, \dots, p-1$$

$$Tcomp_{ij} = p * [t * t(t * t_{multi} + (t-1) * t_{add})] + (p-1) * (t * t * t_{add})$$

- Communication time:

$$Tdist = 2 * [(?)\beta + (?)t * t * sizeof(component)\tau]$$

$$Tcirc = (p-1) * [\beta + t * t * sizeof(component)\tau]$$

$$Tgather = [(?)\beta + (?)t * t * sizeof(component)\tau]$$

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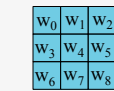
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## Image processing – local linear operations

### □ Problem

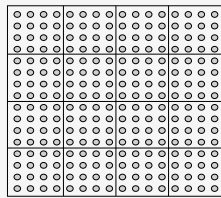
- Replacing each pixel of an image by the average of its neighbors

$$C'(x, y) = w_0 C(x-1, y-1) + w_1 C(x-1, y) + \dots + w_8 C(x+1, y+1)$$



Mask of 3x3

### □ Decomposition

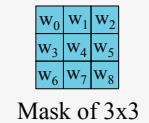
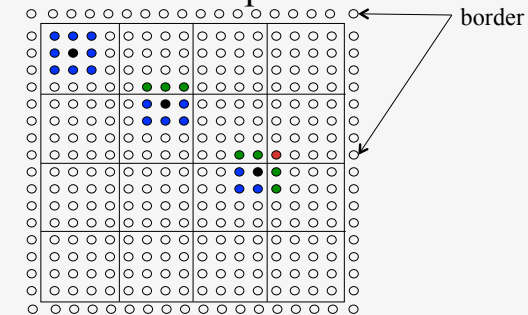


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## Image processing

### □ Communication patterns



Mask of 3x3

### □ Data duplication – No

### □ Communication at each step

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## Case Study: Dynamical system simulation

### □ Dynamical system of particles

- N particles in a square domain
- Interactions between the particles
  - ✧ If the particles are close enough they repel each other
  - ✧ If the particles are far enough they attracted to each other
  - ✧ If the particles are more than some distance,  $r_0$  apart, they do not influence each other

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## Case Study: Dynamical system simulation

### □ Dynamical system simulation

- Given data: masses, initial positions and velocities of the particles
- Simulation: movement of the particles at a series of discrete time steps

### □ Force on particle i

$$F_i = \sum_{j=0}^{n-1} f_{ij} \quad f_{ij} = G \frac{m_i m_j}{r_{ij}^2}$$

- $f_{ij}$ : force exerted on particle i by particle j

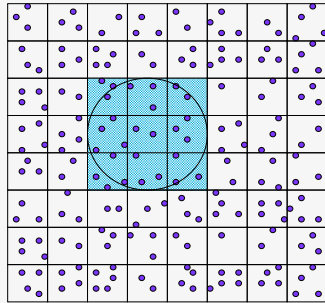
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## Case Study: Dynamical system simulation

### □ Partitioning of the problem

- ♦ Divide the domain into cells of size  $r_0 \times r_0$

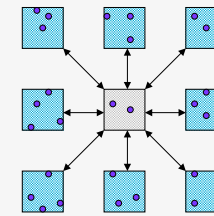


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## Case Study: Dynamical system simulation

### □ Communication pattern

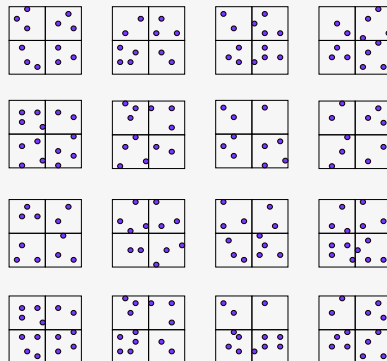


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## Case Study: Dynamical system simulation

### □ Agglomerate and mapping of tasks



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## Case Study: Dynamical system simulation

### □ Data structures

- ♦ Structure for particles
  - ◇ Position
  - ◇ Velocity
- ♦ Structure for cells
  - ◇ List of particles
- ♦ Structure for process
  - ◇ Table/List of cells

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## Case Study: Dynamical system simulation

### □ Sequential code

#### 1. Initialize arrays

- (a) initialize particle's positions and velocities
- (b) initialize the 2D array of cell lists by inserting particles into the linked lists

#### 2. Update loop

For each time step

- (a) find force on each particle, update particle's position and velocity
- (b) move particle under influence of the force exerted on it

## Case Study: Dynamical system simulation

### □ Parallel code

#### 1. Arrays initialization

#### 2. Data Distribution

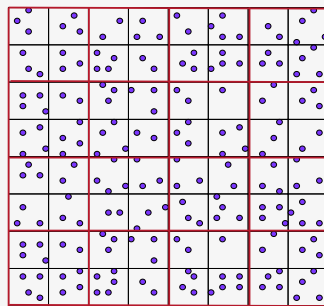
#### 3. Parallel loop:

For each time step

- (a) communicate particle data for boundary cells
- (b) find force on each particle of the process
- (c) update particle's positions and velocities
- (d) migrate particles with communication

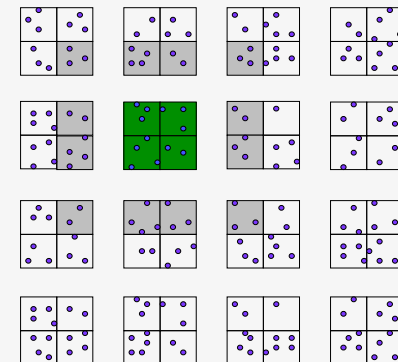
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### □ Data distribution



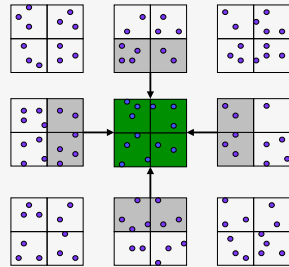
## Case Study: Dynamical system simulation

### □ Data dependencies



## Case Study: Dynamical system simulation

- Communication of boundary cell data
  - ♦ Direct communication with direct neighbors

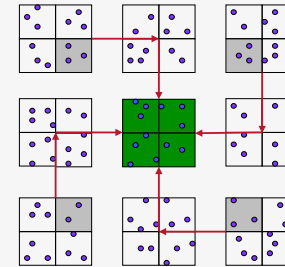


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## Case Study: Dynamical system simulation

- Communication of boundary cell data
  - ♦ Communication with diagonal neighbors



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## Case Study: Dynamical system simulation

- Particles migration
  1. For each particle  $p$ 
    - update position and velocity
    - determine which cell  $p$  is in
    - if  $p$  has moved to new cell
      - delete  $p$  from list of old cell
      - if  $p$  has moved to different process
        - put  $p$  into appropriate communication buffer
        - remove  $p$  from particle array
      - else add  $p$  to list of new cell

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## Case Study: Dynamical system simulation

- Particles migration
  2. Communication of buffers
  3. If the particle received from another process belongs to it
    - add the particle to the list of its new cell
    - else
      - put the particle to appropriate buffer to be passed to another process
- Notes
  - ♦ Irregular communication

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