

Stochastic Modelling

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1 Lecture 1

1.1 Practical Information

Two projects

- The projects count 20% and exam 80%.
- Must be done with two people.
- If you want to do statistics is it worth learning R .

Course Overview

- Markov chains for discrete time and discrete outcome.
 - Set of states and discrete time points.
 - Transition between states
 - Future depends on the present, but not the past.
- Continuous time Markov chains. (continuous time and discrete outcome.)
- Brownian motion and Gaussian processes (continuous time and continuous outcome.)

1.2 Mathematical description

Definition 1.1. A *stochastic process* $\{x(t), t \in T\}$ is a family of random variables, where T is a set of indices, and $X(t)$ is a random variable for each value of t .

1.3 Recall from Statistics Course

A random experiment is performed the outcome of the experiment is random.

- The set of possible outcomes is the **sample space** ω
 - An **event** $A \subset \omega$ if the outcome is contained in A
 - The **complement** of an event A is $A^c = \omega \setminus A$
 - The **null event** \emptyset is the empty set $\emptyset = \omega \setminus \omega$

1.3.1 Combining Event

Let A and B be events

- The **union** $A \cup B$ is the event that at least one of A and B occur.
- the **intersection** $A \cap B$ is the event that both A and B occur.

The events A_1, A_2, \dots are called disjoint (or **mutually exclusive**) if $A_i \cap A_j = \emptyset$ for $i \neq j$

1.3.2 Probability

Pr is called a probability on ω if

- $Pr \{ \omega \} = 1$
- $0 \leq P \{ A \} \leq 1$ for all events A
- For A_1, A_2, \dots that are mutually exclusive

$$P \left\{ \bigcup_{i=1}^{\infty} A_i \right\} = \sum_{i=1}^{\infty} P \{ A_i \}$$

We call $P \{ A \}$ the probability of A .

1.3.3 Law of total probability

Let A_1, A_2, \dots be a partition of ω ie

- $\omega = \bigcup_{i=1}^{\infty} A_i$
- A_1, A_2, A_3, \dots are mutually exclusive.

Then for any event B

$$P \{ B \} = \sum_{i=1}^{\infty} P \{ B \cap A_i \}$$

This concept is very important.

1.3.4 Independence

Event A and B are independent of

$$P \{ A \cap B \} = P \{ A \} P \{ B \}$$

Events A_1, \dots, A_n are independent if for any subset

$$P \left\{ \bigcap_{j=1}^k A_{i_j} \right\} = \prod_{j=1}^k P \{ A_{i_j} \}$$

In this case $P \{ \bigcap_{i=1}^n A_i \} = \prod_{i=1}^n P \{ A_i \}$

1.3.5 Random Variables

Definition 1.2. A *random variable* is a real-valued function on the sample space. Informally: A random variable is a real valued variable that takes on its value by chance.

Example.

- Throw two dice. X = sum of the two dice
- Throw a coin. X is 1 for heads and X is 0 for tails.

1.3.6 Notation for random variables

We use

- upper case letters such as X , Y and Z to represent random variables.
- lower case letters as x , y , z to denote the real-valued realized value of a the random variable.

Expression such as $\{X \leq x\}$ denators the event that X assumes a valye less than or earl to the real number x .

1.3.7 Discrete random variables

The random variable X is **discrete** if it has a finite or countablle number of possible outcomes x_1, x_2, \dots

- The **probability mass function** $p_x(x)$ is given by

$$p_x(x) = P\{X = x\}$$

and satisfies

$$\sum_{i=1}^{\infty} p_x(x_i) = 1 \quad \text{and} \quad 0 \leq p_x(x_i) \leq 1$$

- The **cumulative distribution function** (CDF) a of X can be written

$$F_x(x) = P\{X \leq x\} = \sum_{i: x_i \leq x} p_x(x_i)$$

1.3.8 CFD

The CDF of X may also be called the **distribution function** of X

Let $F_x(x)$ be the CDF of X , then

- $F_x(x)$ is monotonally increasing.
- F_x is a stepfunction, which is a piece-wise constant with jumps at x_i .
- $\lim_{x \rightarrow \infty} F_x(x) = 1$
- $\lim_{x \rightarrow -\infty} F_x(x) = 0$

1.3.9 Continuous random variables

A **continuous** random variable takes values on a continuous scale.

- The CDF, $F_x(x) = P(X \leq x)$ is continuous.
- The **probability density function** (PDF) $f_x(x) = F'_x(x)$ can be used to calculate probabilities

$$\begin{aligned} Pr\{a < X < b\} &= Pr\{a \leq X < b\} = Pr\{a < X \leq b\} \\ &= Pr\{a \leq X \leq b\} = \int_a^b f_x(x) dx \end{aligned}$$

1.3.10 Important properties

- CDF:
 - Monotonically increasing
 - continuous
 - $\lim_{x \rightarrow \infty} F_x = 1$ and $\lim_{x \rightarrow -\infty} F_x(x) = 0$
- PDF
 - $f_x(x) \geq 0$ for $x \in \mathbb{R}$
 - $\int_{-\infty}^{\infty} f_x(x) dx = 1$

1.3.11 Expectation

Let $g : \mathbb{R} \rightarrow \mathbb{R}$ be a function and X be a random variable.

- If X is discrete, the expected value of $g(X)$ is

$$E[g(X)] = \sum_{x: p_x(x) > 0} g(x) p_x(x)$$

- If X is continuous, the expected value of $g(X)$ is

$$E[g(X)] = \int_{-\infty}^{\infty} g(x) f_x(x) dx$$

1.3.12 Variance

The variance of the random variable X is

$$\text{Var}[X] = E[(X - E[X])^2] = E[X^2] - E[X]^2$$

Important properties of expectation and variance.

- Expectations is linear

$$E[aX + bY + c] = aE[X] + bE[Y] + c.$$

- Variance scales quadratically and is invariaient to the addition of constants

$$\text{Var}[aX + b] = a^2 \text{Var}[X]$$

- fir independent stochastic variables.

$$\text{Var}[X + Y] = \text{Var}[X] + \text{Var}[Y]$$

1.3.13 Joint CDF

If (X, Y) is a pair for random variables, their **joint comulative distribution function** is given by

$$F_{X,Y} = F(x, y) = \text{Pr}\{X \leq x \cap Y \leq y\}$$

1.3.14 Joint distrubution for discrete random variables

If X and Y are discrete, the **joint probability mass function** $p_{x,y} = \text{Pr}\{X = x, Y = y\}$. can be used to compute probabilities

$$\text{Pr}\{a < X < b, c < Y \leq d\} = \sum_{a < x \leq b} \sum_{c < y \leq d} p_{X,Y}(x, y)$$

1.3.15 Joint distrubution for continous random variables

If X and Y are continous the **joint probability density function**

$$f_{X,Y}(x, y) = f(x, y) = \frac{\partial^2}{\partial x \partial y} F(x, y)$$

can be used to compute probabilities

$$\text{Pr}\{a < X \leq b, c < Y \leq d\} = \int_a^b \int_c^d f(x, y) dx dy$$

1.3.16 Independence

The random variables X and Y are independent if

$$\Pr\{X \leq a, Y \leq b\} = \Pr\{X \leq a\} \cdot \Pr\{Y \leq b\}, \quad \forall a, b \in \mathbb{R}$$

In terms of CDFs: $F_{X,Y}(a, b) = F_X(a) \cdot F_Y(b) \quad \forall a, b \in \mathbb{R}$

Thus we have

- $p_{X,Y}(x, y) = p_X(x) \cdot p_Y(y)$ for discrete random variables
- $f_{X,Y}(x, y) = f_X(x) \cdot f_Y(y)$ for continuous random variables.

2 Lecture 3

2.1 Randoms sum

Building on the hunter example from last week. we can more generally consider random sums

$$X = \begin{cases} 0, & N = 0 \\ \zeta_1 + \zeta_2 + \dots + \zeta_N, & N > 0 \end{cases}$$

where

- N is a discrete random variable with values $0, 1, \dots$
- ζ_1, ζ_2, \dots are independent random variables
- N is independent of $\zeta_1, \zeta_2 + \dots + \zeta_N$
- **Notation** $X = \sum_{i=1}^N \zeta_i = \zeta_1 + \zeta_2 + \dots + \zeta_N$

Example.

1. Insurance company

N : Number of claims.

ζ_1, ζ_2, \dots : Sizes of the claims

Total liability:

$$X = \zeta_1 + \zeta_2 + \dots + \zeta_N$$

2. Be careful!

$$\begin{aligned} \overbrace{E \left[\sum_{i=1}^N \zeta_i \right]}^{\neq \sum_{i=1}^N E[\zeta_i]} &= E \left[E \left[\sum_{i=1}^N \zeta_i \mid N \right] \right] \\ &= E \left[\sum_{i=1}^N E[\zeta_i \mid N] \right] \end{aligned}$$

2.2 Self Study

Section 2.2, 2.3, 2.4

2.3 Stochastic process in discrete time

Definition 2.1. A **discrete-time stochastic process** is a family of random variables $[X_t : t \in T]$ where T is discrete.

- We use $T = \{0, 1, 2, \dots\}$ and write X_n instead of X_t
- we call X_n the **state** at time $n = 0, 1, 2, 3, \dots$
- We call the set of all possible states the **state space**

Table 1: Table for example

Day	$n = 0$	$n = 1$	$n = 2$	\dots
Random Variable	X_0	X_1	X_2	\dots
Realization 1	$x_0 = 0$	$x_1 = 1$	$x_2 = 1$	\dots
Realization 2	$x_0 = 1$	$x_1 = 1$	$x_2 = 1$	\dots

Example.

$$X_n = \begin{cases} 1, & \text{if it rains on day } n \\ 0, & \text{no rain on day } n \end{cases}$$

State space = $\{0, 1\}$

We have a problem. Need

$$Pr \{X_n = x_n \mid X_{n-1} = x_{n-1}, X_{n-2} = x_{n-2}, \dots, X_0 = x_0\}.$$

for all $n = 0, 1, 2, \dots$

2.4 Markov chain

Definition 2.2 (Discrete time Markov Chain). A **Discrete time markoc chain** is a discrete time stochastic process $\{X_n : n = 0, 1, \dots\}$ that statisfied the **markov property** such that

$$\begin{aligned} Pr \{X_{n+1} = j \mid X_n = i, X_{n-1} = i_{n-1}, \dots, X_0 = i_0\} \\ = Pr \{X_{n+1} = j \mid X_n = i\} \end{aligned}$$

for $n = 0, 1, 2, 3, \dots$ and for all states i and j

Definition 2.3 (One-step transition probabilities). We can define it as

- For a discrete Markov chain $\{X_n : n = 0, 1, 2, \dots\}$ we call $P_{ij}^{n,n+1} = Pr \{X_{n+1} = j, X_n = i\}$ the **one step trainisition probabilities**.

- We will assume **stationary transition probabilities** , i.e that

$$P_{ij}^{n,n+1} = P_{ij}$$

for $n = 0, 1, 2, \dots$ and all states i and j .

Some of the properties

1. "You will always go somewhere"

$$\sum_j P_{ij} = 1 \quad \forall i$$

2. The markov chain can be described as follows.

$$\begin{aligned} & Pr \{X_0 = i_0, X_1 = i_1, \dots, X_n = i_n\} \\ &= Pr \{X_0 = i_0\} Pr \{X_1 = i_1 \mid X_0 = i_0\} \dots \\ &\quad Pr \{X_n = i_n \mid X_{n-1} = i_{n-1} \dots X_0 = i_0\} \\ &\quad \vdots \quad \text{Markov step} \\ &= Pr \{X_0 = i_0\} \cdot Pr \{X_1 = i_1 \mid X_0 = i_0\} \dots \\ &\quad Pr \{X_n = i_n \mid X_{n-1} = i_{n-1}\} \\ &= Pr \{X_0 = i_0\} P_{i_0, i_1} \cdot P_{i_1, i_2} \dots P_{i_{n-1}, i_n} \end{aligned}$$

Which is a major simplification.

Definition 2.4 (Transition Probability Matrix). For a discrete time markov-chain with state space $\{0, 1, \dots, N\}$ we call

$$\mathbf{P} = \begin{bmatrix} P_{00} & \dots & P_{0N} \\ P_{10} & \dots & \\ \vdots & & \ddots \\ P_{N0} & \dots & P_{NN} \end{bmatrix}$$

Is the transition matrix. For statespace $\{0, 1, 2, \dots\}$ we envision an infinitely sized matrix.

Example.

- Markoc chain : $\{X_n : n = 0, 1, 2, \dots\}$
- State space = $\{0, 1\}$
- Transition Matrix

$$\mathbf{P} = \begin{bmatrix} 0.9 & 0.1 \\ 0.6 & 0.4 \end{bmatrix}$$

We can compute

$$\begin{aligned} Pr\{X_3 = 1 \mid X_2 = 0\} &= p_{01} \\ &= 0.1 \end{aligned}$$

$$\begin{aligned} Pr\{X_{10} = 0 \mid X_9 = 1\} &= P_{10} \\ &= 0.6 \end{aligned}$$

Definition 2.5 (Transition Diagram). *Let $\{X_n : n = 0, 1, \dots\}$ be a discrete time Markov chain. A **state transtion diagram** visualizes the transition probabilities as a weighted directed graph where the nodes are the states and the edges are the possible transitions marked with the transistion probabilities.*

Example. State space = $\{0, 1, 2\}$ and

$$P = \begin{bmatrix} 0.95 & 0.05 & 9 \\ 0 & 0.9 & 0.1 \\ 0.01 & 0 & 0.99 \end{bmatrix}$$

Transisition diagram

Nice figure of the diagram

2.5 Doing n transitions.

Theorem 2.1. *For a Markoc chain $\{X_n : n = 0, 1, \dots\}$ and any $m \geq 0$ we have*

$$Pr\{X_{m-n} = j \mid X_m = i\} = P_{ij}^{(n)} = \sum_{k=0}^{\infty} P_{ik} P_{kj}^{(n-1)}, \quad n > 0$$

where we define

$$P_{ij}^{(0)} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$

Proof. Set $m = 0$ then is

$$\begin{aligned} P_{ij}^{(n+1)} &= Pr \{X_{n+1} = j \mid X_0 = i\} \\ &= \sum_k Pr \{X_{n+1} = j, X_1 = k \mid X_0 = i\} \\ &= \sum_k Pr \{X_{n+1} = j \mid X_1 = k, X_0 = i\} \cdot Pr \{X_1 = k \mid X_0 = i\} \\ &= \sum_k P_{kj}^{(h)} \cdot P_{ik} = \sum_k P_{ik} P_{kj}^{(h)} \end{aligned}$$

□

Example. $\{X_n : n = 0, 1, 2, \dots\}$ is a markoc chain and

$$P = \begin{bmatrix} 0.1 & 0.9 \\ 0.6 & 0.4 \end{bmatrix}$$

Find $P_{01}^{(4)}$. **Solution.**

$$P^2 = \begin{bmatrix} 0.55 & 0.45 \\ 0.30 & 0.70 \end{bmatrix}$$

So by doing matrix multiplication and we end up with

$$P^4 = P^2 \cdot P^2 = \begin{bmatrix} 0.4375 & 0.5625 \\ 0.3750 & 0.6250 \end{bmatrix}$$

Which therefore ends up with the answer

$$P_{01}^{(4)} = 0.5625$$

3 Lecture 4

3.1 Introduction to first step analysis

Input

- i_0 : starting state
- P : transition probability matrix
- T : number of time steps

Algorithm

1. Set $x_0 = i_0$
2. for $n = 1 \dots T$
3. Simulate x_n from $X_n \mid X_{n-1} = x_{n-1}$
4. end

output : One realization x_0, x_1, \dots, x_T

Example.

$$P = \begin{pmatrix} 0.95 & 0.05 & 0 \\ 0 & 0.90 & 0.10 \\ 0.01 & 0 & 0.99 \end{pmatrix}$$

Let $x_0 = 0$

1. $x_0 = 0$
- 2.

$$\begin{aligned} Pr \{X_1 = 0 \mid X_0 = 0\} &= P_{00} = 0.95 \\ Pr \{X_1 = 1 \mid X_0 = 0\} &= P_{01} = 0.05 \\ Pr \{X_1 = 2 \mid X_0 = 0\} &= P_{02} = 0 \\ &\vdots \end{aligned}$$

Assume we get $x_1 = 1$

3. States

•

$$\begin{aligned} 0 : P_{10} &= 0 \\ 1 : P_{11} &= 0.90 \\ 2 : P_{12} &= 0.10 \\ &\vdots \end{aligned}$$

General notes on simulation

- $Pr\{A\} \approx \frac{\text{times A occur}}{\text{Simulations}}$
- $E[X] \approx \frac{1}{N} \sum_{i=1}^N x_i$

Example. We have $N = 100$ divided into two containers labelled A and b . At each time n , one ball is selected at random and moved to the container. Let Y_n denote the number of balls in container A at time n , and define $X_n = Y_n - 50$. Find the transition probabilities and simulate and plot one realization of

$$\{X_n : n = 0, 1, \dots, 500\}$$

Answer

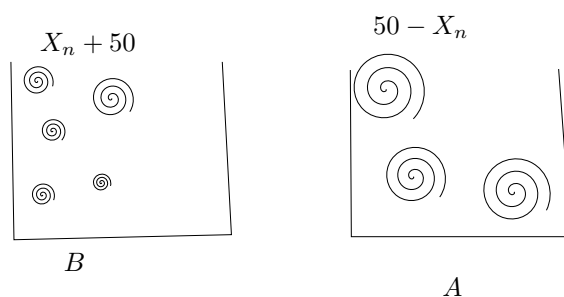


Figure 1: balls

- Only move One ball
- Can move only from i to $j = i - 1$ or $j = i + 1$

$$P_{ij} = \begin{cases} \frac{50-i}{100} & , j = i + 1 \\ \frac{50+i}{100} & , j = i - 1 \\ 0 & , \text{otherwise.} \end{cases}$$

Motivation

Definition 3.1. For a markov chain, a state i such that $P_{ij} = 0 \forall j \neq i$ is called **absorbing**.

Example. Let $\{X_n\}$ be a Markov chain with transition probability matrix

$$\mathbf{P} = \begin{pmatrix} 1 & 0 & 0 \\ \alpha & \beta & \gamma \\ 0 & 0 & 1 \end{pmatrix}$$

where $\alpha, \beta, \gamma > 0$ and $\beta = 1 - \alpha - \gamma$. Assume $x_0 = 1$

1. What is the expected time until absorption ?
2. What is the probability to be absorbed in state 0 ?

Realization .

$$\overbrace{1, 1, 1, 1, 1, 2}^{4 \text{ steps to absorption}}, 2, 2, \dots$$

Mathematically

Let $T = \min \{n \geq 0 : X_n = 0 \text{ or } X_n = 2\}$. Then is

$$Q1 : E[T \mid X_0 = 1]$$

$$Q2 : Pr\{X_T = 0 \mid X_0 = 1\}$$

The idea of first step analysis is to define

- $T^{(n)} = \min \{n \geq 0 : X_{m \times n} = 0 \text{ or } X_{m+b} = 2\}$
- $T = T^{(0)}$
- $v_i^{(m)} = E[T^{(m)} \mid X_m = i]$
- $v_i = v_i^{(0)}$

Table 2: Let m be timesteps

m	0	2	3	4	5
$v_0^{(m)}$	0	0	0	0	0
$v_1^{(m)}$	v_1	v_1	v_1	v_1	v_1
$v_2^{(m)}$	0	0	0	0	0

First step analysis for Q1

$$\begin{aligned}
 v_i &= \sum_{k=0}^2 Pr \{X_1 = k \mid X_0 = i\} (1 + v_k) \\
 &= \sum_{k=0}^2 P_{ik} (1 + v_k) = \sum_{k=0}^2 P_{ik} v_k + 1 \quad \text{which is true for } i = 0, 1, 2
 \end{aligned}$$

Which is reduced to linear algebra. Solving it by

$$\begin{aligned}
 v_0 &= v_2 = 0 \\
 \implies v_1 &= \alpha v_0 + \beta v_1 + \gamma v_2 + 1 \\
 \implies v_1 &= \frac{1}{1 - \beta} \quad [\text{Q1}]
 \end{aligned}$$

$$P_{ij} \implies i = \text{row}, \quad j = \text{column}$$

First step analysis and let

$$\begin{aligned}
 u_i &= Pr \{X_T = 0 \mid X_0 = i\} \\
 &\downarrow \\
 u_i &= \sum_{k=0}^2 P_{ik} u_k, \quad i = 0, 1, 2
 \end{aligned}$$

- Easy: $u_0 = 1, u_2 = 0$
- Harder: $u_1 = \alpha u_0 + \beta u_1 + \gamma u_2$ such that

$$u_1 = \alpha \frac{1}{1 - \beta} = \frac{\alpha}{\alpha - \beta} \quad [\text{Q2}]$$

Example. let $[X_n]$ be a markov chain with transition matrix

$$\mathbf{P} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0.4 & 0.3 & 0.2 & 0.1 \\ 0.1 & 0.3 & 0.3 & 0.3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

The starting state is $x_0 = 1$. Calculate the probability to be absorbed in the state D .

1. Define $u_i = Pr \{ \text{absorbed in state } 0 \mid X_0 = i \}$ for $i = 0, 1, 2, 3$
2. Get the easy ones out of the way. In this case $u_0 = 1$ and $u_3 = 0$
- 3.

$$\begin{aligned} u_1 &= P_{10}u_0 + P_{11}u_1 + P_{12}u_2 + P_{13}u_3 \\ &= 0.4 + 0.3u_1 + 0.2u_2 \\ u_2 &= P_{20}u_0 + P_{21}u_1 + P_{22}u_2 + P_{23}u_3 \\ &= 0.1 + 0.3u_1 + 0.3u_2 \end{aligned}$$

4. Solve for u_1 and u_2

4 Lecture 5

Example. Let P be the matrix

$$P = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0.4 & 0.3 & 0.2 & 0.1 \\ 0.1 & 0.3 & 0.3 & 0.3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

With starting state $x_0 = 1$

1. Define $T = \min_{n \geq 0: X_n = 0} \quad X_n = 3$ and $v_i = E[T \mid X_0 = i]$ for $i = 0, 1, 2, 3$
2. Set $v_0 = v_3 = 0$
- 3.

$$v_1 = P_{10}v_0 + P_{11}v_1 + P_{12}v_2 + P_{13}v_3 = 0.3v_1 + 0.2v_2 + 1$$

and

$$v_2 = P_{20}v_0 + P_{21}v_1 + P_{22}v_2 + P_{23}v_3 + 1 = 0.3v_1 + 0.3v_2 + 1$$

4. Solve the equations and end up with

$$v_1 = \frac{90}{43} \quad \text{and} \quad v_2 = \frac{100}{43}$$

Theorem 4.1. Let $\{X_n\}$ be a discrete time Markov chain with state space $S = \{0, 1, \dots, N\}$ and transition probability matrix \mathbf{P} . Let $A \subset S$ be the set of absorbing state. Then

1. If v_i is the expected time to absorption conditional on $X_0 = i$ then

$$v_i = 0, \quad i \in A$$

$$v_i = 1 + \sum_{i \in \mathbb{R}} P_{ik}v_k \quad i \in A^c$$

Example. A gambler has 10\$ and bets 1\$ If he wins the round, his fortune increases 1\$. The probability of winning each round is $0 < p < 1$ and the probability of losing each round is $q = 1 - p$. The gambler will continue gambling until his fortune is \$ N or 0\$ where $N > 10$. What is the probability the gambler will be ruined.

1. Extract the essential stuff.

$$X_n = \text{Fortune at time } n, \quad n = 0, 1, 2, \dots$$

$$\text{State space} = \{0, 1, \dots, N\}$$

$$\text{Target: } u_k = \Pr \{ \text{Absorption in state 0} \mid X_0 = k \}, \quad k = 0, 1, \dots, N$$

2. Visualize the transitions. Insert figure of transitions.
3. Make the eprobability matrix. The rows are "to" and the columns are "1"

$$P = \begin{bmatrix} 1 & 0 & 0 & 0 & \dots & 0 \\ q & 0 & p & 0 & \dots & 0 \\ 0 & q & 0 & p & \dots & \\ \vdots & & \ddots & & & \\ 0 & 0 & \dots & q & 0 & p \\ & & & & & 1 \end{bmatrix}$$

4. Set up the iteration

$$\begin{aligned} u_0 &= 1, \quad u_N = 0, \quad \text{Easy} \\ u_i &= P_{i,i,1}u_{i-1} + P_{i,i+1}u_{i+1} \\ &= qu_{i-1} + pu_{i+1}, \quad i = 1, 2, \dots, N-1 \end{aligned}$$

5. (a)

$$\begin{aligned} \overbrace{(p+q)}^{=1} u_i &= qu_{i-1} + pu_{i+1} \\ q[u_i - u_{i-1}] &= p[u_{i+1} - u_i] \\ \downarrow \quad \text{Trick} \quad \chi_i &= u_i - u_{i-1} \\ q\chi_1 &= p\chi_{i+1}, \quad \implies \chi_{i+1} = \frac{q}{p}\chi_i \quad i = 1, 2, \dots, N \end{aligned}$$

- (b)

$$\begin{aligned} \chi_1 + \chi_2 + \dots + \chi_k &= [u - u_0] + [u_2 - u_1] \\ &\quad + \dots + [u_k - u_{k-1}] \\ \downarrow \quad \text{Telescoping sum} \\ \chi_1 \left[1 + \frac{q}{p} + \left(\frac{q}{p}\right)^2 + \dots + \left(\frac{q}{p}\right)^{k-1} \right] &= u_k - 1, \\ &\quad k = 1, \dots, N \end{aligned}$$

For $k = N$:

$$\begin{aligned} \chi_1 &= \frac{u_N - 1}{\sum_{k=0}^{N-1} \left(\frac{q}{p}\right)^k} = \frac{-1}{\sum_{k=0}^{N-1} \left(\frac{q}{p}\right)^k} \\ &= \begin{cases} -\frac{1}{N} & , q = p = \frac{1}{2} \\ -\frac{(1-\frac{q}{p})}{(1-(\frac{q}{p})^N)} & q \neq p \end{cases} \end{aligned}$$

(c) From the telescoping sum

$$u_k = 1 + \chi_1 \sum_{i=0}^{k-1} \left(\frac{q}{p}\right)^i$$

$$= \begin{cases} 1 - \frac{1}{N} \cdot k = \frac{N-k}{N}, & p = q = \frac{1}{2} \\ 1 - \frac{1 - \left(\frac{q}{p}\right)^k}{1 - \left(\frac{q}{p}\right)^N} = \frac{\left(\frac{q}{p}\right)^k - \left(\frac{q}{p}\right)^N}{1 - \left(\frac{q}{p}\right)^N}, & p \neq q \end{cases}.$$

where $k = 1, 2, \dots$

6. The final step

$$u_{10} = \begin{cases} \frac{N-10}{N}, & p = q = \frac{1}{2} \\ \frac{\left(\frac{q}{p}\right)^{10} - \left(\frac{q}{p}\right)^N}{1 - \left(\frac{q}{p}\right)^N}, & q \neq p \end{cases}$$

Remark. • When $N \rightarrow \infty$

$q \geq p \implies$ Almost certain you will loose.

$$q < p \implies P(\text{ruined}) = \left(\frac{q}{p}\right)^{10}$$

4.1 Markov Chain in infinitive time

Definition 4.1. Regular Markov Chain . Consider a Markov chain $\{X_n : n = 0, 1, \dots\}$ with finite state space $\{0, 1, 2, \dots\}$ and transition matrix \mathbf{P} . IF there exists an integer $k > 0$ so that all regular elements \mathbf{P}^k are strictly positive, we call \mathbf{P} and $\{X_n\}$ regular.

Remark. 1. P is regular means that it exists an $k > 0$ so that $P_{ij}^{(k)} > 0 \quad \forall i, j$

2. If $P_{ij}^{(k)} > 0 \quad \forall i, j$, then is $P_{ij}^{(K)} > 0 \quad \forall i, j$ and $K \geq k$

5 Lecture 2020-09-14

Find Stationary distributions

(i) $\mathbf{P} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix}$

- Positive recurrent, aperiodic and irreducible.
- \implies Limiting distribution:

$$\pi = \left(\frac{1}{2}, \frac{1}{2} \right)$$

(ii) $\mathbf{P} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

- Positive recurrent and irreducible.
- unique stationary distribution.
- $\pi = \left(\frac{1}{2}, \frac{1}{2} \right)$

(iii) $\mathbf{P} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

- Reducible!
- Part 1:

$$\pi_0 = 1\pi_0 + 0\pi_1 = \pi_0$$

$$\pi_1 = 0\pi_0 + 1\pi_1 = \pi_1$$

$$\implies \pi = 1 - \pi_1$$

$$\implies \pi = (\pi_1, 1 - \pi_1)$$

- Part 2:

Must have

$$\pi_0 \geq 0$$

$$\pi_1 \geq 0$$

$$\implies \pi = (\pi_0, 1 - \pi_0), \quad 0 \leq \pi_0 \leq 1$$

5.1 Section 4.5

Read it yourself .

5.2 Why do we care so much about markov chains?

- (i) Importance goes far beyond statistical modelling of physical phenomena.
- (ii) In the end of the 80s and start of 90s the computational power was growing stronger.
- (iii) We realized that we could sample from difficult distribution by constructing Markov chains whose stationary matched desired target distribution.
- (iv) The theory we have discussed of the theory developed to show that these methods worked.

5.3 Continuous Time Markov Chain

Definition 5.1. The stochastic variable X has a **Poisson distribution** with (mean) parameter $\mu > 0$ if

$$p(x) = \frac{\mu^x}{x!} e^{-\mu}$$

We write $X \sim \text{Poisson}(\mu)$

Remark. $X \sim \text{Poisson}(10)$

- (i) $E[X] = \mu$
- (ii) $\text{Var}[X] = \mu$
- (iii) $SD[X] = \sqrt{\mu}$

Theorem 5.1. If $X \sim \text{Poisson}(\mu)$, $Y \sim (\chi)$ and Y are independent.

Theorem 5.2. If $N \sim \text{Poisson}(\mu)$ and $M | N \sim \text{Binomial}(N, p)$ then

$$M \sim \text{Poisson}(\mu p)$$

Remark. (i) $M = \sum_{k=1}^N I_k$, where $I_1, I_2, \dots \sim \text{Bernoulli}(p)$ and I_1, I_2, \dots and N are independent.

- (ii) This is called **thinning**.

5.3.1 Section 5.1.2

Definition 5.2. A **Possion process** with rate **inensity** $\lambda > 0$ is an integet-valued stochastic process $\{X(t) : t \geq 0\}$ 0 for which.

- For any $n > 0$ and any time point $0 < t_0 < t_1 < \dots < t_n$ the increments

$$X(t_1) - X(t_0), X(t_2) - X(t_1), \dots, X(t_n) - X(t_{n-1})$$

are independent

- For $s \geq 0$ and $t > 0$

$$X(s+t) - X(s) \sim \text{Poission}(\lambda t)$$

- $X(0) = 0$

Remark. • 1. is called independent increments

- In 2, we have

$$X(s + \Delta t) - X(s) \sim \text{Possion}(\lambda \Delta t)$$

- Illustration

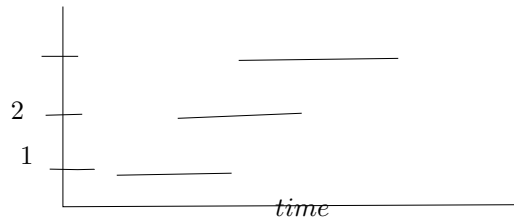


Figure 2: iillustration

- $X(t) = X(t) - X(0) \sim \text{Possion}(\lambda t)$

Example. We assume the arrival of customers to a store follows a Poisson process with rate $\lambda = 4$ customers per hours. The store opens at 09:00. What is the probability that exactly one customer has arrived by 09:30 and exactly five customers have arrived by 11:30.

Answer. Let $X(t)$ = arrivals by time t For $t \geq 0$ (measured in hours). Then is the question

$$\begin{aligned}
 & Pr \left\{ X \left(\frac{1}{2} \right) = 1, X \left(\frac{5}{2} \right) = 5 \right\} \\
 & \downarrow = \text{Rephrase as increments} \\
 & = Pr \left\{ X \left(\frac{1}{2} \right) - X(0) = 1, X \left(\frac{5}{2} \right) - X \left(\frac{1}{2} \right) = 4 \right\} \\
 & \downarrow \text{Independent increments} \\
 & = Pr \left\{ \underbrace{X \left(\frac{1}{2} \right) - X(0) = 1}_{\text{Poisson}(\frac{1}{2}\lambda)} \right\} \\
 & \quad Pr \left\{ \underbrace{X \left(\frac{5}{2} \right) - X \left(\frac{1}{2} \right) = 4}_{\text{Poisson}(2\lambda)} \right\} \\
 & = \frac{2^1}{1!} e^{-2} \cdot \frac{8^4}{4!} e^{-8} \\
 & = 0.0155
 \end{aligned}$$

Example. Assume the arrival of customers to follows an inhomogeneous Poisson process with rate $\lambda(t) = t$, $t \geq 0$. Assume the store opens at 09:00. What is the probability that no-one has arrived at 10:00.

Answer.

$$X(1) - X(0) \sim \text{Poisson} \left(\overbrace{\int_0^1 t dt}^{=\frac{1}{2}} \right)$$

6 Lecture 08/09/20

Equivalent classes and classifications of states in Markov chains.

Things to check

- Understand why regularity fails.
- Extend regularity to infinite spaces.

Example Let $\{X_n : 0, 1, \dots, N\}$ be a markov chain.

- (a) It can go from $0 \rightarrow 0$ and $1 \rightarrow$ with probabilities $p_{00} = p_{11} = 1$, two separate markov chains. Realizations :

0, 0, 0, 0, 0, 0, ...

1, 1, 1, 1, 1, 1, ...

$$P = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \implies P^n = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Definition 6.1. Let $\{X_n : 0, 1, \dots\}$ be a Markov chain with state space $\{0, 1, \dots\}$ then is

- (i) State j is **accessible** from state i if $\exists n \geq 0$ so that $P^{(n)}_{ij} > 0$
- (ii) If states i and j are accessible from each other they are said to **communicate** we write $i \sim j$. If states i and j do not communicate we write $i \not\sim j$

Remark. If $i \not\sim j$, then either (or both)

- (a) (i) $P^{(n)}_{ij} = 0, \quad \forall n \geq 0$
(ii) $P_{ji} = 0, \quad \forall n \geq 0$

- (b) Only the graph matters, not the values of the edges.

(c) $P^{(0)}_{ij} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$

Theorem 6.1. Communication is an **equivalence relation**

- (i) **reflexive**, $i \sim i$
- (ii) **symmetric** $i \sim j \implies j \sim i$
- (iii) **Transitive** $i \sim j$ and $j \sim k$ implies $i \sim k$

A equivalence relation induces **equivalence classes** of sets of states that communicate.

Proof. (i) $P_{ii}^{(0)} = 1 \implies i \sim i$

(ii) By definition is this true.

(iii) (a) $i \sim j \implies \exists n \geq 0 : P_{ij}^{(n)} > 0$

$$j \sim k \implies \exists m \geq 0 : P_{jk}^{(m)} > 0$$

(b) Chapman-kilogram

$$P_{ik}^{(n+m)} = \sum_{r=0}^{\infty} P_{ir}^{(n)} P_{rk}^{(m)} \geq P_{ij}^{(n)} P_{jk}^{(m)}$$

$\implies k$ is accessible from i .

(c) Show yourself

i is accessible from k

□

Definition 6.2. A Markov chain is **irreducible** if \sim (communication) induces exactly one equivalent class. If not, it is called reducible.

Definition 6.3. The **period** of state i , written as $d(i)$ is

$$d(i) = \gcd \left\{ n \geq 1 : P_{ii}^{(n)} > 0 \right\}$$

If $P_{ii}^{(n)} = 0$ for all $n \geq 1$, we define $d(i) = 0$. If $d(i) = 1$, we call the state i is **aperiodic**.

Theorem 6.2. if $i \sim j$, then $d(i) = d(j)$

Remark. The period is a property of the equivalence class.

Notation The state space may be infinite: $\{0, 1, \dots\}$. We introduce

(i) The probability the first return happend after exactly n steps

$$f_{ii}^{(n)} = \Pr \{X_n = i, X_\mu \neq i, \mu = 1, 2, \dots, n-1 \mid X_0 = i\} \quad n > 0$$

We will define $f_{ii}^{(0)} = 0$

(ii) The probability of returning at some time

$$f_{ii} = \sum_{k=0}^{\infty} f_{ii}^{(k)} = \lim_{n \rightarrow \infty} \sum_{k=0}^n f_{ii}^{(k)}.$$

Remark. $f_{ii} < 1 \leftrightarrow$ Positive probability of never returning to i

Definition 6.4. State i is **recurrent** if the probability of returning to state i in a finite number of timesteps is one $f_{ii} = 1$. A state that is not recurrent $f_{ii} < 1$ is called **transient**.

Theorem 6.3. A state i is recurrent if and only if

$$\sum_{n=1}^{\infty} P_{ii}^{(n)} = \infty$$

Equivalently, state i is transient if and only if

$$\sum_{n=1}^{\infty} P_{ii}^{(n)} < \infty$$

Proof. (i)

$$\begin{aligned} \sum_{n=1}^{\infty} P_{ii}^{(n)} &= \sum_{n=1}^{\infty} E[\mathbb{I}\{X_n = i\} \mid X_0 = i] \\ &= E\left[\sum_{n=1}^{\infty} \mathbb{I}\{X_n = i \mid X_0 = i\}\right] \\ &= E[M \mid X_0 = i] \\ M &\rightarrow \text{Returns to state.} \end{aligned}$$

$$(ii) \ E[M \mid X_0 = i] = \begin{cases} f_{ii} \frac{1}{1-f_{ii}}, & f_{ii} < 1 \\ \infty, & f_{ii} = 1 \end{cases}$$

□

7 Lecture 2020-09-18

Read Section 5.1.4 by yourself.

Section 5.2 Motivation

- (a) $\{X(t) : t \geq 0\}$ with rate $\lambda_1 = 5$, $0 \leq t \leq 10$

$$E[X(t)] = \lambda t = 5t,$$

- (b) $\{Y(t) : t \geq 0\}$ with rate $\lambda_2 = t$, $0 \leq t \leq 10$

$$E[Y(t)] = \frac{t^2}{2}$$

Do scatterplot on the project when working on poisson distribution.

Theorem 7.1. Let $p_1, p_2, \dots \in [0, 1]$ be a sequence such that $\lim_{n \rightarrow \infty} np_n = \lambda < \infty$, then

$$\lim_{n \rightarrow \infty} \binom{n}{k} p_n^k (1 - p_n)^{n-k} = \lambda^n \frac{1}{k!} e^{-\lambda}, \quad k = 0, 1, \dots$$

Remark. In TMA4295 Statistical Inference we will say that $\text{Binomial}(n, p_n)$ converges in $\text{Poisson}(\lambda)$ as $n \rightarrow \infty$.

Remark. .

- (i) $p_n \rightarrow 0$, but $n \rightarrow \infty$. $np_n \rightarrow \lambda$ when $n \rightarrow \infty$
- (ii) Many trials ($n \gg 1$) and success is rare ($p \ll 1$) \implies Nr of Successes
Poisson distribution.

Typical examples

- Customers arrivals.
- Car accident.
- Telephone calls.

7.1 Little oh-notation

- (i) You may be familiar with the expressions such as

$$n = o(n^2), \quad \text{as } n \rightarrow \infty$$

May be thought as "n is much smaller than n^2 as $n \rightarrow \infty$ "

(ii) We are going to mostly work with expressions of the form

$$h^2 = o(h), \quad h \rightarrow 0^+$$

May be thought as " h^2 is much smaller than h as $h \rightarrow 0^+$ "

Definition 7.1. Let f and g be real functions. We use *little-oh-notation* in the two following ways

$$(i) \quad f(n) = o(g(n)), \quad n \rightarrow \infty \implies \lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$$

$$(ii) \quad f(h) = o(g(h)) \quad h \rightarrow 0^+ \implies \lim_{h \rightarrow 0^+} \frac{f(h)}{g(h)} = 0$$

Example. Are the following statements false or true?

(i) $h^2 = o(h) \quad h \rightarrow 0^+$

$$\lim_{h \rightarrow 0^+} \frac{h^2}{h} = 0$$

True

(ii) $h^2 = o(h) \quad h \rightarrow \infty$

$$\lim_{h \rightarrow \infty} \frac{h^2}{h} = \lim_{h \rightarrow \infty} h = \infty$$

False

(iii) $\sqrt{h} = o(h) \quad h \rightarrow 0^+$

$$\lim_{h \rightarrow 0^+} \frac{\sqrt{h}}{h} = \infty$$

False

(iv) $h \rightarrow o(1) \quad h \rightarrow 0^+$

$$\lim_{h \rightarrow 0^+} \frac{h}{1} = 0$$

True

Remark.

$$h^p = o(h) \quad h \rightarrow 0^+ \implies p > 1$$

Definition 7.2. A **C process** is a stochastic process $\{N(t) : t \geq 0\}$ so that

- (i) $N(t)$ is a integer for $t \geq 0$
- (ii) $N(t) \geq 0$, for $t \geq 0$
- (iii) If $s \geq t$, then $N(s) \leq N(t)$

We sometimes write

$$N(a, b) = N(b) - N(a) = \text{Number of events in } (a, b], \quad 0 \leq a \leq b$$

However, the notation will not be used in the lecture.

Definition 7.3. Let $\{N(t) : t \geq 0\}$ be a counting process. Then

$$\{N(t) : t \geq 0\}$$

is a **Poisson process** with **rate (intensity)** $\lambda > 0$ if

- (i) For every integer $m > 1$ for any timepoints

$$0 = t_0 < t_1 < \dots < t_m$$

$$N(t_1) - N(t_0), N(t_2) - N(t_1), \dots, N(t_m) - N(t_{m-1})$$

"independent increments"

- (ii) For $t \geq 0$ and $h > 0$, the distribution of $N(t+h) - N(t)$ only depends on h and t . "Stationary Increments"

$$(iii) \Pr\{N(t+h) - N(t) = 1\} = \lambda h + o(h), \quad h \rightarrow 0^+ \quad \forall t \geq 0$$

$$(iv) \Pr\{N(t+h) - N(t) = 0\} = 1 - \lambda h + o(h), \quad h \rightarrow 0^+ \quad \forall t \geq 0$$

$$(v) N(0) = 0$$

For def iii and iv can be described as

$$\begin{aligned} \implies \Pr\{N(t+h) - N(t) \geq 2\} &= 1 - \overbrace{[\lambda h + o(h)]}^{1 \text{ event}} - \overbrace{[1 - \lambda h + o(h)]}^{0 \text{ events}} \\ &= o(h) \\ &\implies \text{Events cannot occur at the same time} \\ &\implies \text{Jumps are of size 1} \end{aligned}$$

Recall

Definition 7.4. (Simplified version.) A **Poission process** with rate **rate** $\lambda > 0$ is an integer valued stochastic process $\{N(t) : t \geq 0\}$ for which

(i) Increments are independent,

(ii) For $s \geq 0$ and $t > 0$

$$N(s+t) - N(s) \sim Poission(\lambda t)$$

(iii) $N(0) = 0$

Theorem 7.2. Definition of simplified and genreal of a Poission process are equivalent.

Proof. Lets call the simplified version P1 and the general version P2, then we need to prove

- Prove that $P1 \implies P2$: i),ii) and v) is proved by definition.

$$\begin{aligned} Pr\{N(t+h) - N(t) = 1\} &= \frac{(\lambda h)^1}{1!} e^{-\lambda h} \\ &= \lambda h (1 - \lambda h o(h)), \quad \text{as } h \rightarrow 0^+ \\ &= \lambda h - \lambda^2 h^2 + \lambda h o(h) \\ &= \lambda h + o(h) \end{aligned}$$

This type of manipulations are importan on the exam.

For iv):

$$\begin{aligned} Pr\{N(t+h) - N(t) = 0\} &= \frac{(\lambda h)^0}{0!} e^{-\lambda h} \\ &= 1 \cdot (1 - \lambda h + o(h)) \\ &= 1 - \lambda h + o(h), \quad \forall t \geq 0 \end{aligned}$$

- Prove that $P2 \implies P1$: i) and iii) are proved by definition.

For ii): Set $s = 0$ Ned to show that

$$N(h) - N(0) \sim Poission(\lambda h)$$

(i) Divide $(0, h]$ into equal size sub-intervals.

$$\implies t_i = \frac{i}{m}, \quad i = 0, 1, \dots, m.$$

(ii) Let

$$\varepsilon = \begin{cases} 1, & \text{at least one event in } (t_{i-1}, t_i] \\ 0, & \text{Otherwise} \end{cases}, \quad i = 1, 2, \dots, m$$

Then we can let $S_m = \sum_{i=1}^m \varepsilon_i$.

(iii) $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_m \sim \text{Bernoulli}(p_m)$ where $p_m = \frac{\lambda h}{m} + o\left(\frac{h}{m}\right)$ as $m \rightarrow \infty$.

Let $S = \lim_{m \rightarrow \infty} S_m$ we get

$$\lim_{m \rightarrow \infty} m o_m = \lim_{m \rightarrow \infty} (\lambda h + o(1)) = \lambda h$$

This is called the "Law of rare events" $S \sim \text{Poisson}(\lambda h)$.

(iv) $Pr\{N(h) - N(0) \neq S_m\} \leq \sum_{i=1}^m Pr\{N(t_i) - N(t_{i-1}) \geq 2\}$

$$\leq \sum_{i=1}^m o\left(\frac{h}{m}\right)$$

$$= m \cdot o\left(\frac{h}{m}\right)$$

$$= h o(1)$$

$$\rightarrow_{m \rightarrow \infty} 0$$

↓

$$N(h) - N(0) = S \sim \text{Poisson}(\lambda h)$$

□

8 Lecture 2020-09-21

Example. Is it reasonable to model the following phenomena as Poisson processes ?

- (a) Cases of a non-infectious rare disease.
 - Independent increments: Yes, people are independent.
 - Stationary increments: Yes. Few people get sick.
 - Many trials, "success" is rare: Yes. many people get sick.
- (b) Calls going through a phone central.
 - Yes. For specific time intervals.
- (c) Goals in football.
 - No. Number of goals are not independent.

8.1 Properties of the Poisson process

Definition 8.1. Let $\{N(t) : t \geq 0\}$ be a Poisson process. The **waiting time** W_n is the time of occurrence of the n -th event. We define $W_0 = 0$

Definition 8.2. The difference $S_n = W_{n+1} - W_n$ are called the **sojourn times** (interarrival times.)

Remark. .

- (i) S_n = Time spent in stationary.
- (ii) Two viewpoints.
 - (a) Poisson process $\{N(t) : t \geq 0\}$
 - (b) Poisson point process. (W_1, W_2, W_3, \dots)

Definition 8.3. The stochastic variable Y has an **exponential distribution** with the rate parameter $\lambda > 0$

$$f(y) = \lambda e^{-\lambda y}, \quad y > 0$$

We write $Y \sim \text{Exp}(\lambda)$.

Remark. • We will always use this parameterization.

- Other: Scale parameter $\beta > 0$:

$$f(y) = \frac{1}{\beta}, \quad y > 0$$

Theorem 8.1. Let $\{N(t) : t \geq 0\}$ be a Poisson process with rate λ . Then $S_0, S_1, \dots, S_{n-1} \sim \text{Exp}(\lambda)$

Proof. For $n = 1$

(i) $\Pr\{S_0 > s_0\} = \Pr\{N(s_0) - N(0) = 0\}$

(ii) $n = 2$

(a) $S_0 \sim \text{Exp}(\lambda)$

(b) $\Pr\{S_1 > s_1 \mid S_0 = s_0\} = \Pr\{N(s_0 + s_1) - N(s_0) = 0 \mid S_0 = s_0\}$

$$\downarrow \text{Independent increments} \implies \text{Markov}$$

$$= \Pr\{N(s_0 + s_1) - N(s_0) = 0\}$$

$$\downarrow \text{Stationary increments}$$

$$= \Pr\{N(s_1) - N(0) = 0\}$$

$$= e^{-\lambda s_1}, \quad s_1 > 0$$

(c) $S \sim \text{Exp}(\lambda)$ and S_0 and S_1 are independent.

(iii) For $n = 3, 4, \dots$

$$\text{Markov property} \implies \text{independence..}$$

$$\text{Exp}(\lambda) \text{ as for } S_0 \text{ and } S_1.$$

□

Remark. Alternative definition of the Poisson process:

(i) Start in 0

(ii) Spend a time $\text{Exp}(\lambda)$ in each state.

Definition 8.4. The stochastic variable Y has a **gamma distribution** with **shape parameter** $\alpha > 0$ and **rate parameter** $\lambda > 0$ if

$$f(y) = \frac{\lambda^\alpha}{\Gamma(\alpha)} y^{\alpha-1} e^{-\lambda y}, \quad y > 0$$

We write $Y \sim \text{Gamma}(\alpha, \lambda)$

Remark. (i) Check which parametrization which is used.

(ii) Scale parameter: $\beta = \frac{1}{\lambda}$ is very common.

(iii) We will use shape and rate.

(iv) $\text{Gamma}(1, \lambda) = \text{Exp}(\lambda)$

Theorem 8.2. For a Poisson process with rate $\lambda > 0$ $W_n \sim \text{Gamma}(n, \lambda)$ for all integers $n > 0$.

Proof. (i) $S_0, S_1, \dots, S_{n-1} \sim \text{Exp}(\lambda)$

(ii) $W_n = S_0 + S_1 + \dots + S_{n-1}$

\downarrow

$$\begin{aligned} &\sim \text{Gamma}\left(\sum_{i=1}^n 1, \lambda\right) \\ &= \text{Gamma}(n, \lambda) \end{aligned}$$

□

Example. Assume the occurrence of a rare disease follows a Poisson process with rate $\lambda = 2$

(a) What is the probability that the first case occurs after 1 month?

(i) Let $S_0 \sim \text{Exp}(2)$

$$\Pr\{S_0 > 1\} = \int_1^\infty 2e^{-2t} dt = e^{-2} \approx 0.135$$

Where $\Pr\{N(1) - N(0)\}$

(b) What is the expected time until the 10th case occurs?

(i) Let $W_{10} \sim \text{Gamma}(10, 2)$

$$E[W_{10}] = \frac{10}{2} = 5, \quad \text{months.}$$

Example. Let $\{X(t) : t \geq 0\}$ is a Poission process with rate $\lambda > 0$.
Determine the distrobution of $W_1 \mid X(t) = 1$

9 Lecture 2020-09-23

Theorem 9.1. Let W_1, W_2, \dots be occurrence in a Poisson process

$$\{(t) : t \geq 0\}$$

with rate $\lambda > 0$. Then is

$$\begin{aligned} (W_1, W_2, \dots, W_n) \mid X(t) = n &\sim f(w_1, w_2, \dots, \mid X(t) = n) \\ &= \frac{n!}{t^n}, \quad 0, w_1 < w_2 < \dots < w_n < t \end{aligned}$$

Discussion

- (i) $X(t) = n$, then exactly n events occur in $(0, t]$. Let V_1, V_2, \dots, V_n be the locations of the events not necessarily ordered.
- (ii) $\{X(t)\}$ can be approximated by a collection of Bernoulli trials on intervals $(\frac{(i-1)}{m}t, \frac{i}{m}t]$, $i = 1, 2, \dots, m$.
- (iii) The m trials are independent. That means any selection of n unique intervals

$$\{i_1, i_2, \dots, i_n\} \subseteq \{1, 2, \dots, m\}$$

locations follow a uniform distribution as $m \rightarrow \infty$, which indicated that

$$V_1, V_2, \dots, V_n \mid X(t) = n \stackrel{iid}{\sim} u(0, t)$$

- (iv) Let sort such that

$$(w_1, w_2, \dots, w_n) = \text{sort}(V_1, V_2, \dots).$$

$$\implies f(w_1, w_2, \dots, w_n \mid X(t) = n) = \left(\frac{1}{t}\right)^n n!$$

$$\text{for } 0 < w_1 < w_2 < \dots < w_n \leq t$$

Remark .

- Conditional on n events occurring in $(0, t]$, the locations of the events are iid uniform distribution on $(0, t]$

Example. Customers arrive according to a Poisson process with rate $\lambda > 0$ per hours. The store opens at 09:00. If 10 people have arrived at 11:00. What is the probability that exactly 5 of the 10 people arrived before 10:00.

Conditional on $X(2) = 10$, arrival times are iid $u(0, 2)$. This implies that

$$\begin{aligned} & Pr \{X(1) = 5 \mid X(2) = 10\} \\ &= Pr \{5 \text{ arrive in } (0, 1] \text{ and } 5 \text{ in } (1, 2]\} \\ &= \binom{10}{5} \end{aligned}$$

Joint simulation

Input

- Time interval $(0, t]$
- Rate, $\lambda > 0$

Algorithm

- Simulate $n \sim Poisson(\lambda t)$
- Simulate $v_1, v_2, \dots, v_n \sim U(0, t)$
- Let $(w_1, w_2, \dots, w_n) = sort(v_1, v_2, \dots, v_n)$

Output

$$x(s) = \begin{cases} 0, & 0 < s \leq w_1 \\ 1, & w_1 < s < w_2 \\ \vdots & \\ n, & w_n \leq s < t \end{cases}$$

9.1 Continuous Markov Chains

We call the stochastic process $\{X(t) : t \geq 0\}$ a continuous-time Markov chain with state space $\{0, 1, \dots\}$ if it satisfies the Markov property

$$\begin{aligned} & Pr \{X(t+s) = j \mid X(s) = i, X(u), 0 \leq u \leq s\} \\ &= Pr \{X(t+s) = j \mid X(s) = i\} \end{aligned}$$

For $i, j = 0, 1, \dots$ for all $s \geq 0$ and $t > 0$.

Remark. • We are only interested in stationary transition probabilities .

$$Pr \{X(s+t) = j \mid X(s) = i\} = Pr \{X(t) = j \mid X(0) = i\}$$

For all $s \geq 0$, $t > 0$ and states i, j .

- Continuous time Markov chain is "random sojourn time + random jumps."

Definition 9.1. Let $\{X(t) : t \geq 0\}$ be a continuous time Markov Chain with state space $\{0, 1, \dots\}$ and stationary probabilities. we call

$$P_{ij}(t) = Pr \{X(t) = j \mid X(0) = i\}, \quad ij, = 0, 1, \dots$$

The *transition probability function* .

9.1.1 Transition probability function

Given

$$\begin{aligned} P_{ij}(t) &= Pr \{X(t) = j \mid X(0) = i\} \\ &= Pr \left\{ \underbrace{X(t) - X(0)}_{\text{Poisson}(\lambda t)} = i - j \right\} \\ &= \begin{cases} \frac{(\lambda t)^{i-j}}{(j-i)!} e^{-\lambda t}, & j \geq 0 \\ 0, & \text{otherwise} \end{cases} \end{aligned}$$

10 References