$$A = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 3 & 0 \\ 2 & -4 & 2 \end{pmatrix}$$

(host: find determinant of transpose)

finding eigenvalues:

finding eigenvalues:

$$0 = \det (A - \lambda I) = \det \begin{pmatrix} 0 & 3-\lambda & 0 \\ 2 & -4 & 2-\lambda \end{pmatrix} = (2-\lambda)(1-\lambda)(3-\lambda)$$

finding eigenvectors: (vertors in ker $(A - \lambda I)$)

$$\begin{pmatrix} 0 & 2 & 0 \\ 0 & 2 & 0 \\ 2 & -4 & 1 \end{pmatrix} V_1 = 0 \longrightarrow V_1 = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} \text{ is an eigenvector}$$

$$\lambda = 2$$

$$\begin{pmatrix} -1 & 2 & 0 \\ 0 & 1 & 0 \\ 2 & -4 & 0 \end{pmatrix} \quad V_2 = \underbrace{0} \quad \rightarrow \quad V_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad \text{is an eigen vector}$$

$$\lambda = 3$$

$$\begin{pmatrix} -2 & 2 & 0 \\ 0 & 0 & 0 \\ 0 & -4 & 1 \end{pmatrix} \quad \forall 3 = 0 \quad \longrightarrow \quad \forall 3 = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} \quad \text{is an eigenvector}$$

And we find that setting $P = (V_1, V_2, V_3) = \begin{pmatrix} -1 & 0 & 1 \\ 0 & 0 & 1 \\ 2 & 1 & -2 \end{pmatrix}$ $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix} = P^{-1} A P.$

$$\exp(At) = \sum_{n=0}^{\infty} \frac{A^n t^n}{n!} = P \sum_{n=0}^{\infty} \frac{d^n ag(1, 2, 3)^n t^n}{n!} P^{-1}$$

$$= P \frac{d^n ag(e^t, e^{2t}, e^{3t})}{e^t} P^{-1}$$

$$= \int e^t e^{3t} e^{t} = 0$$

$$= \begin{pmatrix} e^{t} & e^{3t} - e^{t} & 0 \\ 0 & e^{3t} & 0 \\ 2(e^{2t} - e^{t}) & 2(e^{t} - e^{3t}) & e^{2t} \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 1 & 0 & 2 & 0 \\ 1 & 1 & 0 & 2 \end{pmatrix}$$

finding ergenvalues:

$$0 = \det (A - \lambda I) = (1 - \lambda)(2 - \lambda)^3$$
.

-> eigenvalues are $\lambda=1$ and $\lambda=2$ with multiplicity 3. algebraic

and eigenvectors:

however, these span the entire eigenspace

is greater than (the geometric multiplicity of $\lambda=2$) = 2.

By the Jordan chain proceedure, we can find a final Inearly independent vector V4 in ker (A-2I)2 by setting

$$(A-2I)V_4 = V_2$$
 \rightarrow $V_4 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ is a generalized eigenvector

diagonalization: let P = (V₁, V₂, V₄, V₃)

t v₄ vant v₂ Le cause V₂ was

$$J = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix} = P^{-1} A P, \quad \text{which is the}$$

Jordan normal form of A