

# Repetition

## Theorem

Assume  $\mathbf{X} \sim \mathcal{N}_n(\boldsymbol{\mu}, \Sigma)$  and  $\mathbf{L}$  is the Cholesky factor of  $\Sigma$  (i.e.,  $\Sigma = \mathbf{L}\mathbf{L}^T$ ). Then

- 1)  $\mathbf{X} \sim \mathcal{N}_n(\boldsymbol{\mu}, \Sigma)$  implies  $\mathbf{Z} = \mathbf{L}^{-1}(\mathbf{X} - \boldsymbol{\mu}) \sim \mathcal{N}_n(\mathbf{0}, \mathbf{I})$ .
- 2)  $\mathbf{Z} \sim \mathcal{N}_n(\mathbf{0}, \mathbf{I})$  implies  $\mathbf{X} = \mathbf{L}\mathbf{Z} + \boldsymbol{\mu} \sim \mathcal{N}_n(\boldsymbol{\mu}, \Sigma)$ .

**Note:** This states that all  $n$ -dimensional multivariate Gaussian distributions are linear transformations of each other.

## Theorem

If

$$\mathbf{X} = (\mathbf{X}_A, \mathbf{X}_B) \sim \mathcal{N}_{n_A+n_B} \left( \begin{bmatrix} \boldsymbol{\mu}_A \\ \boldsymbol{\mu}_B \end{bmatrix}, \begin{bmatrix} \Sigma_{AA} & \Sigma_{AB} \\ \Sigma_{BA} & \Sigma_{BB} \end{bmatrix} \right),$$

where  $\mathbf{X}_A$  is  $n_A$ -dimensional and  $\mathbf{X}_B$  is  $n_B$ -dimensional, then

$$\mathbf{X}_A | \mathbf{X}_B = \mathbf{x}_B \sim \mathcal{N}_{n_A}(\boldsymbol{\mu}_C, \Sigma_C),$$

where

$$\begin{aligned} \boldsymbol{\mu}_C &= \boldsymbol{\mu}_A + \Sigma_{AB}\Sigma_{BB}^{-1}(\mathbf{x}_B - \boldsymbol{\mu}_B) \\ \Sigma_C &= \Sigma_{AA} - \Sigma_{AB}\Sigma_{BB}^{-1}\Sigma_{BA}. \end{aligned}$$

**Note:** Calculating conditional distributions is just linear algebra.

**Note 2:** Used **a lot** in everything from simple to complex models, but, in practice, computations are done by computers.

## Simulation from $\mathcal{N}_n(\boldsymbol{\mu}, \Sigma)$

### Input:

$n$ : dimension

$\boldsymbol{\mu}$ : mean vector

$\Sigma$ : covariance matrix

### Algorithm:

1. calculate Cholesky factorization  $\Sigma = \mathbf{L}\mathbf{L}^T$ .
2. for  $i = 1 \dots n$
3.     draw  $z_i \sim \mathcal{N}(0, 1)$
4. end
5. set  $\mathbf{x} = \mathbf{L}\mathbf{z} + \boldsymbol{\mu}$

**Output:**  $\mathbf{x}$  is a simulation from  $\mathcal{N}_n(\boldsymbol{\mu}, \Sigma)$ .

## Definition

The stochastic process  $\{B(t) : t \geq 0\}$  with state space  $\mathbb{R}$  is called **Brownian motion** with **variance parameter**  $\sigma^2 > 0$  if

- 1)  $B(s+t) - B(s) \sim \mathcal{N}(0, t\sigma^2)$  for  $s \geq 0$  and  $t > 0$ .
- 2) for  $0 \leq t_1 < t_2 \leq t_3 < t_4$ ,

$$B(t_2) - B(t_1) \quad \text{and} \quad B(t_4) - B(t_3)$$

are independent.

- 3)  $B(0) = 0$  (and the realizations are continuous).

**Note:** Point 2) is equivalent to independent increments when increments follow Gaussian distributions.