

# Stochastic Modelling

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# 1 Lecture 1

## 1.1 Practical Information

Two projects

- The projects count 20% and exam 80%.
- Must be done with two people.
- If you want to do statistics is it worth learning  $R$ .

### Course Overview

- Markov chains for discrete time and discrete outcome.
  - Set of states and discrete time points.
  - Transition between states
  - Future depends on the present, but not the past.
- Continuous time Markov chains. (continuous time and discrete outcome.)
- Brownian motion and Gaussian processes (continuous time and continuous outcome.)

## 1.2 Mathematical description

**Definition 1.1.** A *stochastic process*  $\{x(t), t \in T\}$  is a family of random variables, where  $T$  is a set of indices, and  $X(t)$  is a random variable for each value of  $t$ .

## 1.3 Recall from Statistics Course

A random experiment is performed the outcome of the experiment is random.

- The set of possible outcomes is the **sample space**  $\omega$ 
  - An **event**  $A \subset \omega$  if the outcome is contained in  $A$
  - The **complement** of an event  $A$  is  $A^c = \omega \setminus A$
  - The **null event**  $\emptyset$  is the empty set  $\emptyset = \omega \setminus \omega$

### 1.3.1 Combining Event

Let  $A$  and  $B$  be events

- The **union**  $A \cup B$  is the event that at least one of  $A$  and  $B$  occur.
- the **intersection**  $A \cap B$  is the event that both  $A$  and  $B$  occur.

The events  $A_1, A_2, \dots$  are called disjoint (or **mutually exclusive**) if  $A_i \cap A_j = \emptyset$  for  $i \neq j$

### 1.3.2 Probability

$Pr$  is called a probability on  $\omega$  if

- $Pr \{\omega\} = 1$
- $0 \leq P\{A\} \leq 1$  for all events  $A$
- For  $A_1, A_2, \dots$  that are mutually exclusive

$$P\left\{\bigcup_{i=1}^{\infty} A_i\right\} = \sum_{i=1}^{\infty} P\{A_i\}$$

We call  $P\{A\}$  the probability of  $A$ .

### 1.3.3 Law of total probability

Let  $A_1, A_2, \dots$  be a partition of  $\omega$  ie

- $\omega = \bigcup_{i=1}^{\infty} A_i$
- $A_1, A_2, A_3, \dots$  are mutually exclusive.

Then for any event  $B$

$$P\{B\} = \sum_{i=1}^{\infty} P\{B \cap A_i\}$$

**This concept is very important.**

### 1.3.4 Independence

Event  $A$  and  $B$  are independent of

$$P\{A \cap B\} = P\{A\} P\{B\}$$

Events  $A_1, \dots, A_n$  are independent if for any subset

$$P\left\{\bigcap_{j=1}^k A_{i_j}\right\} = \prod_{j=1}^k P\{A_{i_j}\}$$

In this case  $P\{\bigcap_{i=1}^n A_i\} = \prod_{i=1}^n P\{A_i\}$

### 1.3.5 Random Variables

**Definition 1.2.** A *random variable* is a real-valued function on the sample space. Informally: A random variable is a real valued variable that takes on its value by chance.

**Example.**

- Throw two dice.  $X$  = sum of the two dice
- Throw a coin.  $X$  is 1 for heads and  $X$  is 0 for tails.

### 1.3.6 Notation for random variables

We use

- upper case letters such as  $X$ ,  $Y$  and  $Z$  to represent random variables.
- lower case letters as  $x$ ,  $y$ ,  $z$  to denote the real-valued realized value of a the random variable.

Expression such as  $\{X \leq x\}$  denators the event that  $X$  assumes a valye less than or earl to the real number  $x$ .

### 1.3.7 Discrete random variables

The random variable  $X$  is **discrete** if it has a finite or countablle number of possible outcomes  $x_1, x_2, \dots$

- The **probability mass function**  $p_x(x)$  is given by

$$p_x(x) = P\{X = x\}$$

and satisfies

$$\sum_{i=1}^{\infty} p_x(x_i) = 1 \quad \text{and} \quad 0 \leq p_x(x_i) \leq 1$$

- The **cumulative distribution function** (CDF) a of  $X$  can be written

$$F_x(x) = P\{X \leq x\} = \sum_{i: x_i \leq x} p_x(x_i)$$

### 1.3.8 CDF

The CDF of  $X$  may also be called the **distribution function** of  $X$

Let  $F_x(x)$  be the CDF of  $X$ , then

- $F_x(x)$  is monotonally increasing.
- $F_x$  is a stepfunction, which is a piece-wise constant with jumps at  $x_i$ .
- $\lim_{x \rightarrow \infty} F_x(x) = 1$
- $\lim_{x \rightarrow -\infty} F_x(x) = 0$

### 1.3.9 Continuous random variables

A **continuous** random variable takes values on a continuous scale.

- The CDF,  $F_x(x) = P(X \leq x)$  is continuous.
- The **probability density function** (PDF)  $f_x(x) = F'_x(x)$  can be used to calculate probabilities

$$\begin{aligned} Pr\{a < X < b\} &= Pr\{a \leq X < b\} = Pr\{a < X \leq b\} \\ &= Pr\{a \leq X \leq b\} = \int_a^b f_x(x) dx \end{aligned}$$

### 1.3.10 Important properties

- CDF:
  - Monotonically increasing
  - continuous
  - $\lim_{x \rightarrow \infty} F_x = 1$  and  $\lim_{x \rightarrow -\infty} F_x(x) = 0$
- PDF
  - $f_x(x) \geq 0$  for  $x \in \mathbb{R}$
  - $\int_{-\infty}^{\infty} f_x(x) dx = 1$

### 1.3.11 Expectation

Let  $g : \mathbb{R} \rightarrow \mathbb{R}$  be a function and  $X$  be a random variable.

- If  $X$  is discrete, the expected value of  $g(X)$  is

$$E[g(X)] = \sum_{x: p_x(x) > 0} g(x) p_x(x)$$

- If  $X$  is continuous, the expected value of  $g(X)$  is

$$E[g(X)] = \int_{-\infty}^{\infty} g(x) f_x(x) dx$$

### 1.3.12 Variance

The variance of the random variable  $X$  is

$$\text{Var}[X] = E[(X - E[X])^2] = E[X^2] - E[X]^2$$

Important properties of expectation and variance.

- Expectations is linear

$$E[aX + bY + c] = aE[X] + bE[Y] + c.$$

- Variance scales quadratically and is invariaient to the addition of constants

$$\text{Var}[aX + b] = a^2 \text{Var}[X]$$

- fir independent stochastic variables.

$$\text{Var}[X + Y] = \text{Var}[X] + \text{Var}[Y]$$

### 1.3.13 Joint CDF

If  $(X, Y)$  is a pair for random variables, their **joint comulative distribution function** is given by

$$F_{X,Y} = F(x, y) = \text{Pr}\{X \leq x \cap Y \leq y\}$$

### 1.3.14 Joint distrubution for discrete random variables

If  $X$  and  $Y$  are discrete, the **joint probability mass function**  $p_{x,y} = \text{Pr}\{X = x, Y = y\}$ . can be used to compute probabilities

$$\text{Pr}\{a < X < b, c < Y \leq d\} = \sum_{a < x \leq b} \sum_{c < y \leq d} p_{X,Y}(x, y)$$

### 1.3.15 Joint distrubution for continous random variables

If  $X$  and  $Y$  are continous the **joint probability density function**

$$f_{X,Y}(x, y) = f(x, y) = \frac{\partial^2}{\partial x \partial y} F(x, y)$$

can be used to compute probabilities

$$\text{Pr}\{a < X \leq b, c < Y \leq d\} = \int_a^b \int_c^d f(x, y) dx dy$$

### 1.3.16 Independence

The random variables  $X$  and  $Y$  are independent if

$$Pr\{X \leq a, Y \leq b\} = Pr\{X \leq a\} \cdot Pr\{Y \leq b\}, \quad \forall a, b \in \mathbb{R}$$

In terms of CDFs:  $F_{X,Y}(a, b) = F_X(a) \cdot F_Y(b) \quad \forall a, b \in \mathbb{R}$

Thus we have

- $p_{X,Y}(x, y) = p_X(x) \cdot p_Y(y)$  for discrete random variables
- $f_{X,Y}(x, y) = f_X(x) \cdot f_Y(y)$  for continuous random variables.



## 2 Lecture 2

**Definition 2.1.** Let  $A$  and  $B$  be events. The conditionally probability of  $A$  given  $B$  is defined by

$$Pr\{A | B\} = \begin{cases} \frac{Pr\{A \cap B\}}{Pr\{B\}}, & Pr\{B\} > 0, \\ \text{Not defined} & Pr\{B\} = 0 \end{cases}$$

**Example.** Throw one die and let  $X$  denote the number of eyes. Find  $Pr\{X \geq 5 | X \geq 3\}$ .

$$\begin{aligned} Pr\{X \geq 5 | X \geq 3\} &= \frac{Pr\{X \geq 5\}}{Pr\{X \geq 3\}} \\ &= \frac{\frac{2}{6}}{\frac{4}{6}} = \frac{1}{2} \end{aligned}$$

**Definition 2.2. Conditional PMF** (Conditionally probability mass function PMF). Assume  $X$  and  $Y$  are jointly distributed random variables. The Conditional PMF.  $p_{x|y}$  of  $X$  given  $Y$  given by

$$p_{X|Y}(x | y) = \frac{Pr\{X = x, Y = y\}}{Pr\{Y = y\}} = \frac{p_{X,Y}(x, y)}{p_Y(y)}, \quad p_Y(y) > 0$$

*Remark.*  $\{X = x, Y = y\}$  is shorthand for  $\{(X = x) \cap (Y = y)\}$

*Remark.* •  $p_{X|Y}(x | y)$  is a pmf for

$$x \implies \sum_x p_{X|Y}(x | y) = 1 \quad \forall y$$

•  $P_{X|Y}(x|y)$  is not a pmf for

$$y \implies \sum_{x|Y} \neq 1 \quad \text{In General}$$

Check if  
Lecture two  
is in google  
cal

**Example.** Throw die and let

$X = \text{Number of eyes}$

$$Y = \begin{cases} 0, & \text{if } X \geq 2 \\ 1, & \text{if } X \geq 3 \end{cases}$$

Find the conditionally **PMF**  $p_{X|Y}$

**Solution.** For  $y = 0$

$$p_{x|y}(x | y) = \begin{cases} \frac{1}{2}, & x = 1, 2 \\ 0, & x = 3, 4, 5, 6 \end{cases}$$

For  $y = 1$

$$p_{x|y}(x | y) = \begin{cases} 0, & x = 1, 2 \\ \frac{1}{4}, & x = 3, 4, 5, 6 \end{cases}$$

Didnt quite understand this example

- $\sum_x p_{X|Y}(X | 0) = 1$

- **Noob mistake**

$$p_{X|Y} = (1 | 0) + p_{X|Y}(1 | 1) = \frac{1}{2} + 0 \neq 1$$

## 2.1 Joint Distrobution

The conditional **PMF** is essential to us because we can siplify the joint **PMF** as

$$\begin{aligned} p_{X|Y}(x, y) &= Pr\{X = x, Y = y\} \\ &= Pr\{U = y\} Pr\{X = x | Y = y\} \\ &= p_Y(y) p_{X|Y}(x | y) \end{aligned}$$

*Remark.* if  $X$  and  $Y$  are independent then is

$$\begin{aligned} p_{X|Y}(x | y) &= p_X(x) \quad \text{if } p_Y(y) > 0 \\ \implies p_{X|Y}(x | y) &= p_X(x) \cdot p_Y(Y) \end{aligned}$$

## 2.2 Simplified Notation

Unless it will cause confusion, we typically write

- $p(x)$  instead of  $p_X(x)$

- $p(y)$  instead of  $p_Y(y)$
- $p(x, y)$  instead of  $p_{X,Y}(x, y)$
- $p(x \mid Y = y)$  instead of  $p_{X|Y}(X \mid y)$

## 2.3 Marginalization

The law of total probability gives

$$\begin{aligned} \Pr\{X = x\} &= \sum_y \Pr\{X = x, Y = y\} \\ &= \sum_y \Pr\{Y = y\} \Pr\{X = x \mid Y = y\} \end{aligned}$$

**Example.** A hunter encounters  $N$  birds. For each bird, he gets one shot and either hits or misses. Assume the probability of hitting is  $p$  for each bird and that the shots are independent. Additionally, assume that the number of birds encountered is Poisson distributed with mean  $\lambda$  i.e.  $N \sim \text{Poisson}(\lambda)$ . Find the **EMF** of the number of birds hit.

**Solution.**

i Notation.

$$\text{Let } I_i = \begin{cases} 0, & \text{Miss bird } i \\ 1, & \text{Hit bird } i \end{cases} \quad \text{for } i = 1, 2, 3, 4, \dots$$

Let  $X$  = Number of birds hit Target is  $p(x), x = 0, 1, 2, \dots$

i Condition on  $N$

$$(X|N = n) = \begin{cases} 0, & n = 0 \\ \sum_{i=1}^n I_i, & n > 0 \end{cases}$$

. We know

$$\begin{aligned} (X | N = n) &\sim \text{Binomial}(n, p) \\ \implies \Pr\{X = x | N = n\} \\ &= \binom{n}{x} p^x (1-p)^{n-x} \quad x = 0, 1, \dots, n \end{aligned}$$

iii)

$$\begin{aligned} \Pr\{X = x\} &= \sum_{n=0}^{\infty} \Pr\{X = x, N = n\} \\ &= \sum_{n=x}^{\infty} \Pr\{N = n\} \Pr\{X = x | N = n\} \\ &= \sum_{n=x}^{\infty} \frac{\lambda^n e^{-\lambda}}{n!} \frac{p^x (1-p)^{n-x} n!}{x! (n-x)!} \\ &= \lambda^x \frac{e^{-\lambda} p^x}{x!} \sum_{n=x}^{\infty} \frac{(1-p)^{n-x}}{(n-x)!} \lambda^{n-x}, \\ &\quad \text{hint } \sum_{k=0}^{\infty} \frac{a^k}{k!} = e^a \\ &= (\lambda p)^x e^{-\lambda} \frac{1}{x!} \sum_{n=x}^{\infty} \frac{[\lambda(1-p)]^{n-x}}{(n-x)!} \\ &= (\lambda p)^x e^{-\lambda p} \frac{1}{x!}, \quad x = 0, 1, 2, 3, \dots \\ &\implies \sim \text{Poisson}(\lambda p) \end{aligned}$$

## 2.4 Conditional Expectation

Let  $X$  and  $Y$  be random variables and  $g$  a real function. The **Conditional expected value** of  $g(X)$  given  $Y = y$  is

$$E[g(X) | Y = y] = \sum_x g(x) Pr\{X = x | Y = y\}, \quad \text{if } Pr\{Y = y\} > 0$$

*Remark.* • Note that  $E[g(X) | Y]$  is a stochastic variable!

- $E[g(X) | Y = y]$  has probability  $Pr\{Y = y\}$

**Theorem 2.1** (Law of iterated expectations). *Let  $X$  and  $Y$  be random variables such that  $E[|g(X)|] < \infty$ , and let  $g$  be a real function. then*

$$E[g(X)] = E[E[g(X) | Y]].$$

*Proof.*

$$\begin{aligned} E[E[g(X) | Y]] &= \sum_y E[g(X) | Y = y] \\ &= \sum_y \left\{ \sum_x g(x) \cdot Pr\{X = x | Y = y\} \right\} y Pr\{Y = y\} \\ &= \sum_y \sum_x g(x) \cdot Pr\{X = x, Y = y\} \\ &= \sum_x g(x) \sum_y Pr\{X = x, Y = y\} \\ &= \sum_x g(x) Pr\{X = x\} \\ &= E[g(X)] \end{aligned}$$

□

**Theorem 2.2** (Law of total variance). *Let  $X$  and  $Y$  be random variables such that  $E[X^2] < \infty$ , then*

$$Var[X] = E[Var[X | Y]] + Var[E[X | Y]]$$

**Revisited Example.** A hunter encounters  $N$  birds. For each bird, he gets one shot and either hits or misses. Assume the probability of hitting is  $p$  for each bird and that the shots are independent. Additionally, assume that the number of birds encountered is Poisson distributed with mean  $\lambda$  i.e.  $N \sim \text{Poisson}(\lambda)$ . Find the expected value and the variance of the number of birds hit.

$$E[X] = E[E[X | Y]]$$

$$\text{Var}[X] = E[\text{var}[X | Y]] + \text{Var}[E[X | Y]]$$

**Solution .**

$$E[X | N = n] = np$$

$$\text{Var}[X | N = n] = np(1 - p)$$

$$\implies \text{Var}[X | N] = Np(1 - p)$$

We get

•

$$E[X] = E[E[X | N]]$$

$$= E[Np] = pE[N]$$

$$= p\lambda$$

•

$$\text{Var}[X] = E[\text{Var}[X | N]] + \text{Var}[E[X | N]]$$

$$= E[Np(1 - p)] + \text{Var}[Np]$$

$$= p(1 - p)\lambda + p^2\text{Var}[N]$$

$$= p(1 - p)\lambda + p^2\lambda$$

$$= \lambda p$$

### 3 Lecture 3

#### 3.1 Randoms sum

Building on the hunter example from last week. we can more generally consider random sums

$$X = \begin{cases} 0, & N = 0 \\ \zeta_1 + \zeta_2 + \dots + \zeta_N, & N > 0 \end{cases}$$

where

- $N$  is a discrete random variable with values  $0, 1, \dots$
- $\zeta_1, \zeta_2, \dots$  are independent random variables
- $N$  is independent of  $\zeta_1, \zeta_2 + \dots + \zeta_N$
- **Notation**  $X = \sum_{i=1}^N \zeta_i = \zeta_1 + \zeta_2 + \dots + \zeta_N$

#### Example.

1. Insurance company

$N$  : Number of claims.

$\zeta_1, \zeta_2, \dots$  : Sizes of the claims

Total liability:

$$X = \zeta_1 + \zeta_2 + \dots + \zeta_N$$

2. Be careful!

$$\begin{aligned} \overbrace{E \left[ \sum_{i=1}^N \zeta_i \right]}^{\neq \sum_{i=1}^N E[\zeta_i]} &= E \left[ E \left[ \sum_{i=1}^N \zeta_i \mid N \right] \right] \\ &= E \left[ \sum_{i=1}^N E[\zeta_i \mid N] \right] \end{aligned}$$

#### 3.2 Self Study

Section 2.2, 2.3, 2.4

#### 3.3 Stochastic process in discrete time

**Definition 3.1.** A **discrete-time stochastic process** is a family of random variables  $[X_t : t \in T]$  where  $T$  is discrete.

- We use  $T = \{0, 1, 2, \dots\}$  and write  $X_n$  instead of  $X_t$
- we call  $X_n$  the **state** at time  $n = 0, 1, 2, 3, \dots$
- We call the set of all possible states the **state space**

Table 1: Table for example

| Day             | $n = 0$   | $n = 1$   | $n = 2$   | $\dots$ |
|-----------------|-----------|-----------|-----------|---------|
| Random Variable | $X_0$     | $X_1$     | $X_2$     | $\dots$ |
| Realization 1   | $x_0 = 0$ | $x_1 = 1$ | $x_2 = 1$ | $\dots$ |
| Realization 2   | $x_0 = 1$ | $x_1 = 1$ | $x_2 = 1$ | $\dots$ |

**Example.**

$$X_n = \begin{cases} 1, & \text{if it rains on day } n \\ 0, & \text{no rain on day } n \end{cases}$$

State space =  $\{0, 1\}$

**We have a problem.** Need

$$Pr \{X_n = x_n \mid X_{n-1} = x_{n-1}, X_{n-2} = x_{n-2}, \dots, X_0 = x_0\}.$$

for all  $n = 0, 1, 2, \dots$

### 3.4 Markov chain

**Definition 3.2** (Discrete time Markov Chain). A **Discrete time markoc chain** is a discrete time stochastic process  $\{X_n : n = 0, 1, \dots\}$  that statisfied the **markov property** such that

$$\begin{aligned} Pr \{X_{n+1} = j \mid X_n = i, X_{n-1} = i_{n-1}, \dots, X_0 = i_0\} \\ = Pr \{X_{n+1} = j \mid X_n = i\} \end{aligned}$$

for  $n = 0, 1, 2, 3, \dots$  and for all states  $i$  and  $j$

**Definition 3.3** (One-step transition probabilities). We can define it as

- For a discrete Markov chain  $\{X_n : n = 0, 1, 2, \dots\}$  we call  $P_{ij}^{n,n+1} = Pr \{X_{n+1} = j, X_n = i\}$  the **one step trainstition probabilities**.



- We will assume **stationary transition probabilities** , i.e that

$$P_{ij}^{n,n+1} = P_{ij}$$

for  $n = 0, 1, 2, \dots$  and all states  $i$  and  $j$  .

Some of the properties

1. "You will always go somewhere"

$$\sum_j P_{ij} = 1 \quad \forall i$$

2. The markov chain can be described as follows.

$$\begin{aligned} & Pr \{X_0 = i_0, X_1 = i_1, \dots, X_n = i_n\} \\ &= Pr \{X_0 = i_0\} Pr \{X_1 = i_1 \mid X_0 = i_0\} \dots \\ &\quad Pr \{X_n = i_n \mid X_{n-1} = i_{n-1} \dots X_0 = i_0\} \\ &\quad \vdots \quad \text{Markov step} \\ &= Pr \{X_0 = i_0\} \cdot Pr \{X_1 = i_1 \mid X_0 = i_0\} \dots \\ &\quad Pr \{X_n = i_n \mid X_{n-1} = i_{n-1}\} \\ &= Pr \{X_0 = i_0\} P_{i_0, i_1} \cdot P_{i_1, i_2} \dots P_{i_{n-1}, i_n} \end{aligned}$$

Which is a major simplification.

**Definition 3.4** (Transition Probability Matrix). For a discrete time markov-chain with state space  $\{0, 1, \dots, N\}$  we call

$$\mathbf{P} = \begin{bmatrix} P_{00} & \dots & P_{0N} \\ P_{10} & \dots & \\ \vdots & & \ddots \\ P_{N0} & \dots & P_{NN} \end{bmatrix}$$

Is the transition matrix. For statespace  $\{0, 1, 2, \dots\}$  we envision an infinitely sized matrix.

**Example.**

- Markov chain :  $\{X_n : n = 0, 1, 2, \dots\}$
- State space =  $\{0, 1\}$
- Transition Matrix

$$\mathbf{P} = \begin{bmatrix} 0.9 & 0.1 \\ 0.6 & 0.4 \end{bmatrix}$$

We can compute

$$\begin{aligned} \Pr\{X_3 = 1 \mid X_2 = 0\} &= p_{01} \\ &= 0.1 \end{aligned}$$

$$\begin{aligned} \Pr\{X_{10} = 0 \mid X_9 = 1\} &= P_{10} \\ &= 0.6 \end{aligned}$$

**Definition 3.5** (Transition Diagram). *Let  $\{X_n : n = 0, 1, \dots\}$  be a discrete time Markov chain. A **state transition diagram** visualizes the transition probabilities as a weighted directed graph where the nodes are the states and the edges are the possible transitions marked with the transition probabilities.*

**Example.** State space =  $\{0, 1, 2\}$  and

$$P = \begin{bmatrix} 0.95 & 0.05 & 0 \\ 0 & 0.9 & 0.1 \\ 0.01 & 0 & 0.99 \end{bmatrix}$$

Transition diagram

Nice figure of the diagram

### 3.5 Doing n transitions.

**Theorem 3.1.** *For a Markov chain  $\{X_n : n = 0, 1, \dots\}$  and any  $m \geq 0$  we have*

$$\Pr\{X_{m+n} = j \mid X_m = i\} = P_{ij}^{(n)} = \sum_{k=0}^{\infty} P_{ik} P_{kj}^{(n-1)}, \quad n > 0$$

where we define

$$P_{ij}^{(0)} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$

*Proof.* Set  $m = 0$  then is

$$\begin{aligned} P_{ij}^{(n+1)} &= Pr \{X_{n+1} = j \mid X_0 = i\} \\ &= \sum_k Pr \{X_{n+1} = j, X_1 = k \mid X_0 = i\} \\ &= \sum_k Pr \{X_{n+1} = j \mid X_1 = k, X_0 = i\} \cdot Pr \{X_1 = k \mid X_0 = i\} \\ &= \sum_k P_{kj}^{(h)} \cdot P_{ik} = \sum_k P_{ik} P_{kj}^{(h)} \end{aligned}$$

□

**Example.**  $\{X_n : n = 0, 1, 2, \dots\}$  is a markoc chain and

$$P = \begin{bmatrix} 0.1 & 0.9 \\ 0.6 & 0.4 \end{bmatrix}$$

Find  $P_{01}^{(4)}$ . **Solution.**

$$P^2 = \begin{bmatrix} 0.55 & 0.45 \\ 0.30 & 0.70 \end{bmatrix}$$

So by doing matrix multiplication and we end up with

$$P^4 = P^2 \cdot P^2 = \begin{bmatrix} 0.4375 & 0.5625 \\ 0.3750 & 0.6250 \end{bmatrix}$$

Which therefore ends up with the answer

$$P_{01}^{(4)} = 0.5625$$

## 4 References