



Please justify your answers! The most important part is *how* you arrive at an answer, not the answer itself.

**1** Let

$$z_1 = \sqrt{\frac{2}{3}} \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad z_2 = \sqrt{\frac{2}{3}} \begin{bmatrix} -1/2 \\ \sqrt{3}/2 \end{bmatrix}, \quad z_3 = \sqrt{\frac{2}{3}} \begin{bmatrix} -1/2 \\ -\sqrt{3}/2 \end{bmatrix}.$$

Show that for every  $x \in \mathbb{R}^2$  we have

a)

$$\|x\|^2 = \sum_{i=1}^3 |\langle x, z_i \rangle|^2$$

b)

$$x = \sum_{i=1}^3 \langle x, z_i \rangle z_i$$

*Remark.* The vectors  $z_1, z_2, z_3$  span  $\mathbb{R}^2$ , but they are obviously not an orthonormal basis (they are not even linearly independent). Still, they satisfy a generalization of Parseval's identity and "act like" an orthonormal basis. Such systems appear very naturally in applications (e.g. in signal analysis), and are often called Parseval frames.

**2** Let  $\|\cdot\|_a$  and  $\|\cdot\|_b$  be equivalent norms on a vector space  $X$ . Show that any set  $U \subset X$  is open in  $(X, \|\cdot\|_a)$  if and only if it is open in  $(X, \|\cdot\|_b)$ .

*Remark.* This is in fact a two-way implication; if any set  $U \subset X$  is open in  $(X, \|\cdot\|_a)$  if and only if it is open in  $(X, \|\cdot\|_b)$ , then necessarily the norms  $\|\cdot\|_a$  and  $\|\cdot\|_b$  are equivalent on  $X$ .

**3** Suppose that  $v_1, \dots, v_k$  are non-zero eigenvectors of an operator  $T$  corresponding to distinct eigenvalues  $\lambda_1, \dots, \lambda_k$ . Show that  $\{v_1, \dots, v_k\}$  is a linearly independent set.

**4** Let  $T$  be the shift operator on  $\ell^2$  defined by  $T(x_1, x_2, \dots) = (0, x_1, x_2, \dots)$ .

1. Show that  $T$  has no eigenvalues.
2. Does  $T^*$  have any eigenvalues?

**5** Let  $U$  be a  $n \times n$  matrix with columns  $u_1, \dots, u_n$ . Show that the following statements are equivalent:

1.  $U$  is unitary.
2.  $\{u_1, \dots, u_n\}$  is an orthonormal basis of  $\mathbb{C}^n$ .

**6** Given the matrix

$$A = \begin{pmatrix} 1 & 2 \\ 2 & 2 \\ 2 & 1 \end{pmatrix}.$$

- a) Compute the singular value decomposition of  $A$ .
- b) Use the result of a) to find:
  1. The pseudo-inverse of  $A$ .
  2. The minimal norm solution of  $Ax = b$  for  $b = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ .