

Introduction to Software Engineering Methods

System Design

Literature used

- Text Book

Chapters 6 and 7

Content

Overview of System Design Activities:

1. Design Goals

2. Subsystem Decomposition

3. Other activities

Hardware/Software Mapping

Persistent Data Management

Global Resource Handling and Access Control

Software Control

Boundary Conditions

Design

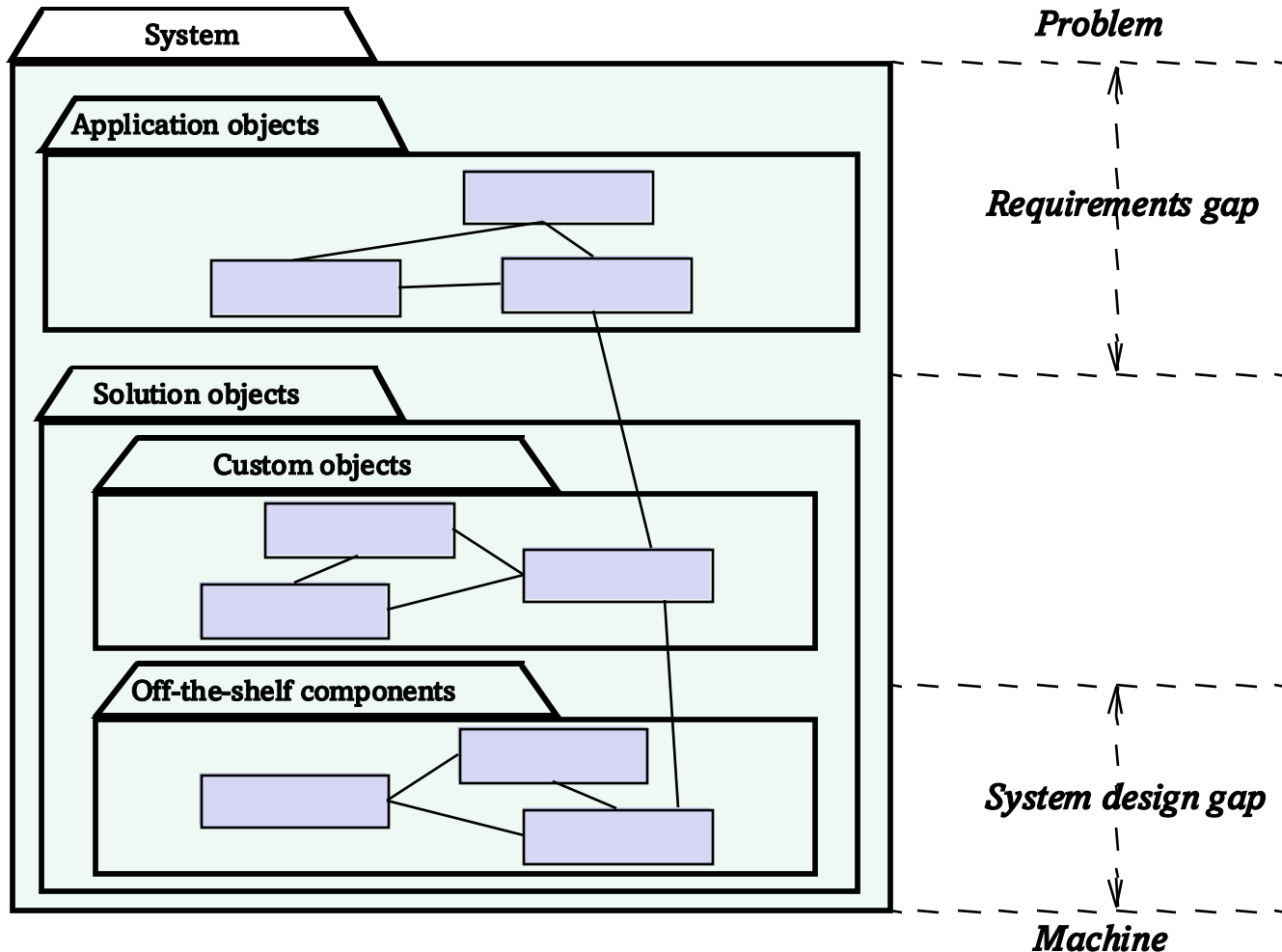
“There are two ways of constructing a software design: One way is to make it so simple that there are obviously no deficiencies, and the other way is to make it so complicated that there are no obvious deficiencies.”

- C.A.R. Hoare

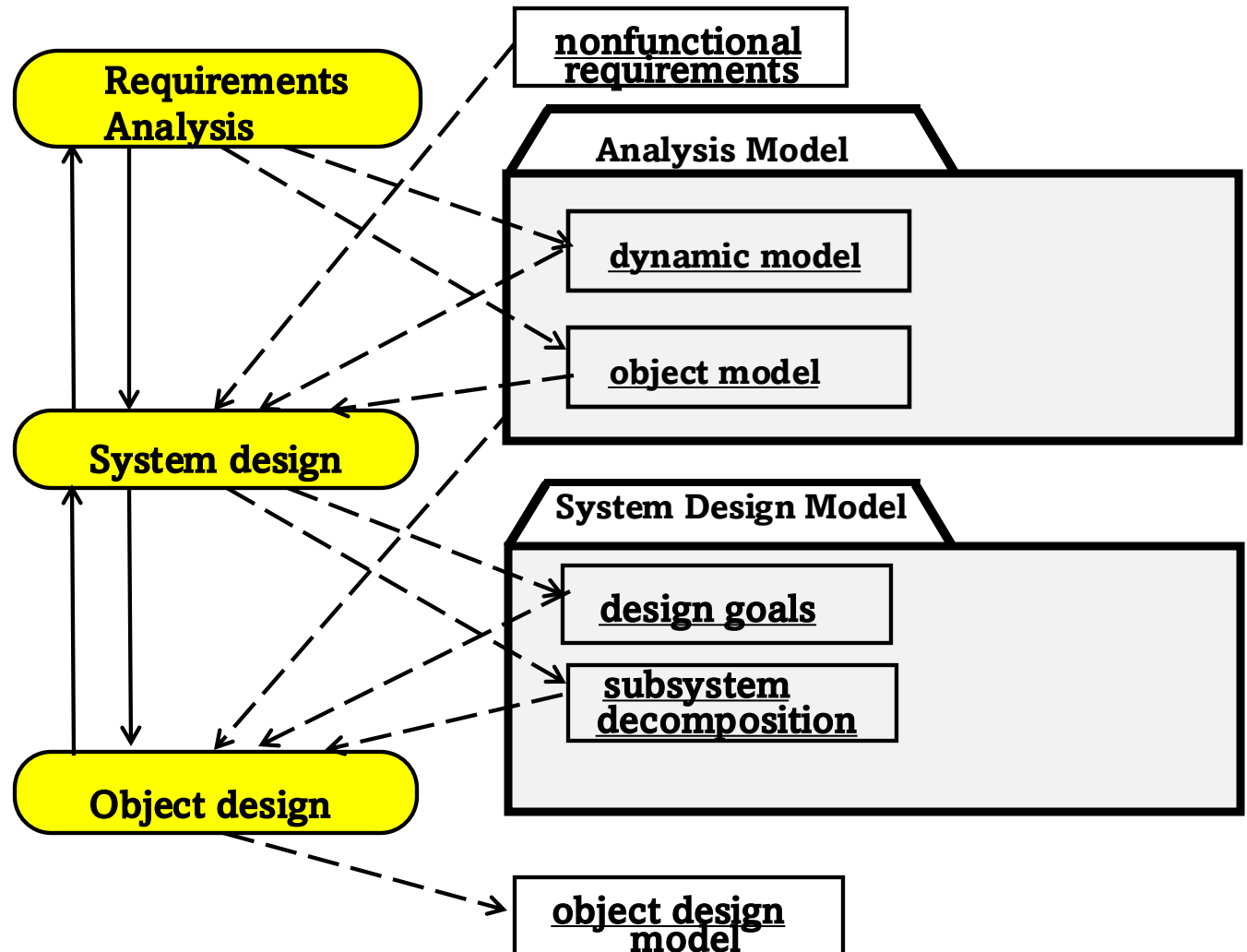
Analysis & Design

- *Analysis*: Focuses on the application domain
- *Design*: Focuses on the solution domain
 - Design knowledge is a moving target
 - Design decisions are changing very rapidly
 - Technology changes rapidly
 - Cost of hardware rapidly sinking
- “*Design window*”:
 - Time window in which design decisions must be made

System Design:



System Design Activities



System Design Activities

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graph TD; A[System Design Activities] --- B[1. Design Goals]; A --- C[2. System Decomposition]; A --- D[3. Concurrency]; A --- E[4. Hardware/Software Mapping]; A --- F[5. Data Management]; A --- G[6. Global Resource Handling]; A --- H[7. Software Control]; A --- I[8. Boundary Conditions]; B --- B1[Definition]; B --- B2[Trade-offs]; C --- C1[Layers/Partitions]; C --- C2[Cohesion/Coupling]; D --- D1[Identification of Threads of control]; E --- E1[Special purpose]; E --- E2[Buy or Build Trade-off]; E --- E3[Allocation]; E --- E4[Connectivity]; F --- F1[Persistent Objects]; F --- F2[Databases]; F --- F3[Data structure]; G --- G1[Access control]; G --- G2[Security]; H --- H1[Monolithic]; H --- H2[Event-Driven]; H --- H3[Threads]; H --- H4[Conc. Processes]; I --- I1[Initialization]; I --- I2[Termination]; I --- I3[Failure];
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1. Design Goals

Definition
Trade-offs

2. System Decomposition

Layers/Partitions
Cohesion/Coupling

3. Concurrency

Identification of
Threads of control

4. Hardware/ Software Mapping

Special purpose
Buy or Build Trade-off
Allocation
Connectivity

5. Data Management

Persistent Objects
Databases
Data structure

6. Global Resource Handling

Access control
Security

8. Boundary Conditions

Initialization
Termination
Failure

7. Software Control

Monolithic
Event-Driven
Threads
Conc. Processes

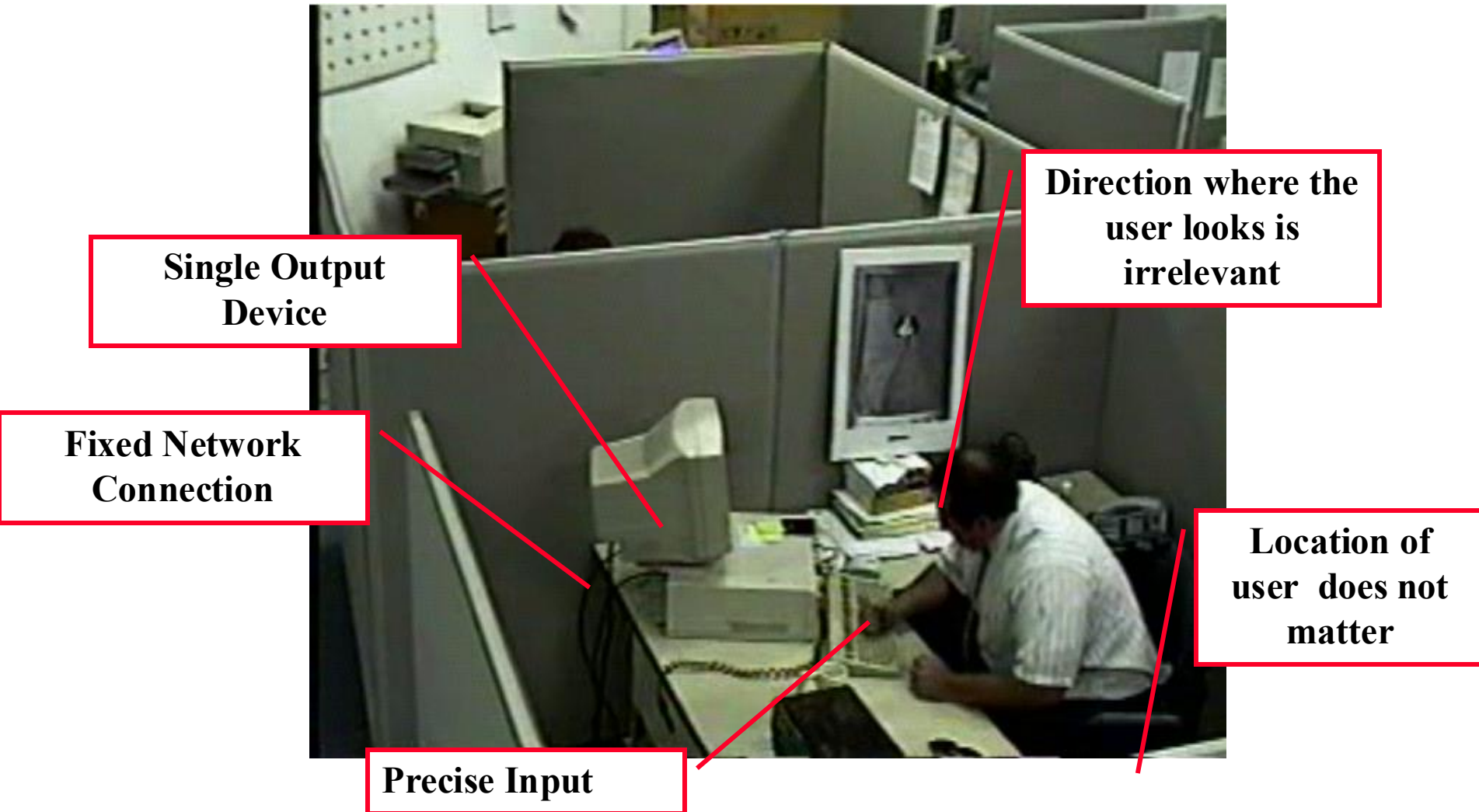
How to use the results from the Requirements Analysis for System Design

- **Nonfunctional requirements =>**
 - Activity 1: Design Goals Definition
- **Functional model =>**
 - Activity 2: System decomposition (Selection of subsystems based on functional requirements, cohesion, and coupling)
- **Object model =>**
 - Activity 4: Hardware/software mapping
 - Activity 5: Persistent data management
- **Dynamic model =>**
 - Activity 3: Concurrency
 - Activity 6: Global resource handling
 - Activity 7: Software control
 - Activity 8: Boundary conditions

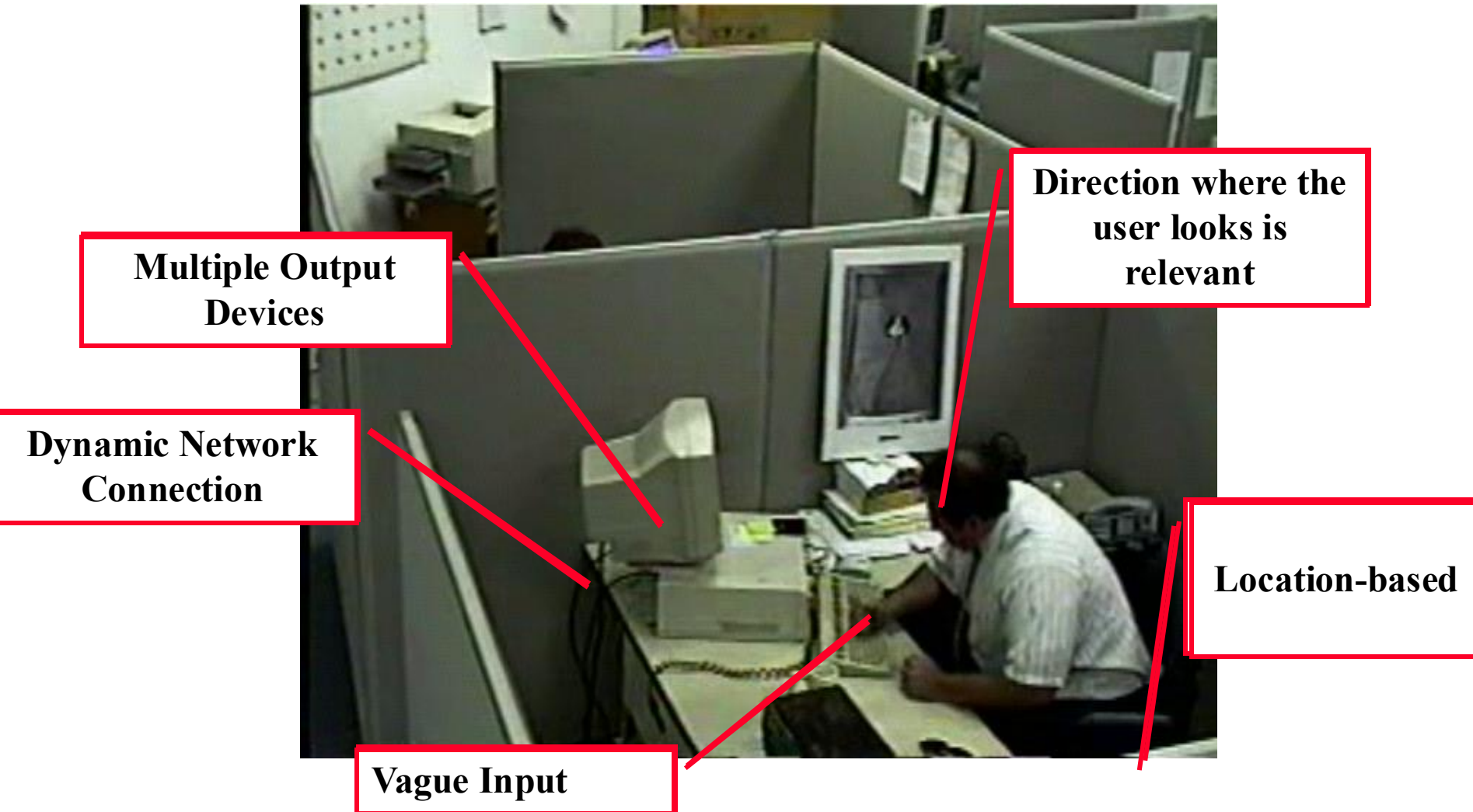
Example: Current Desktop Development



Identify Current Technology Constraints



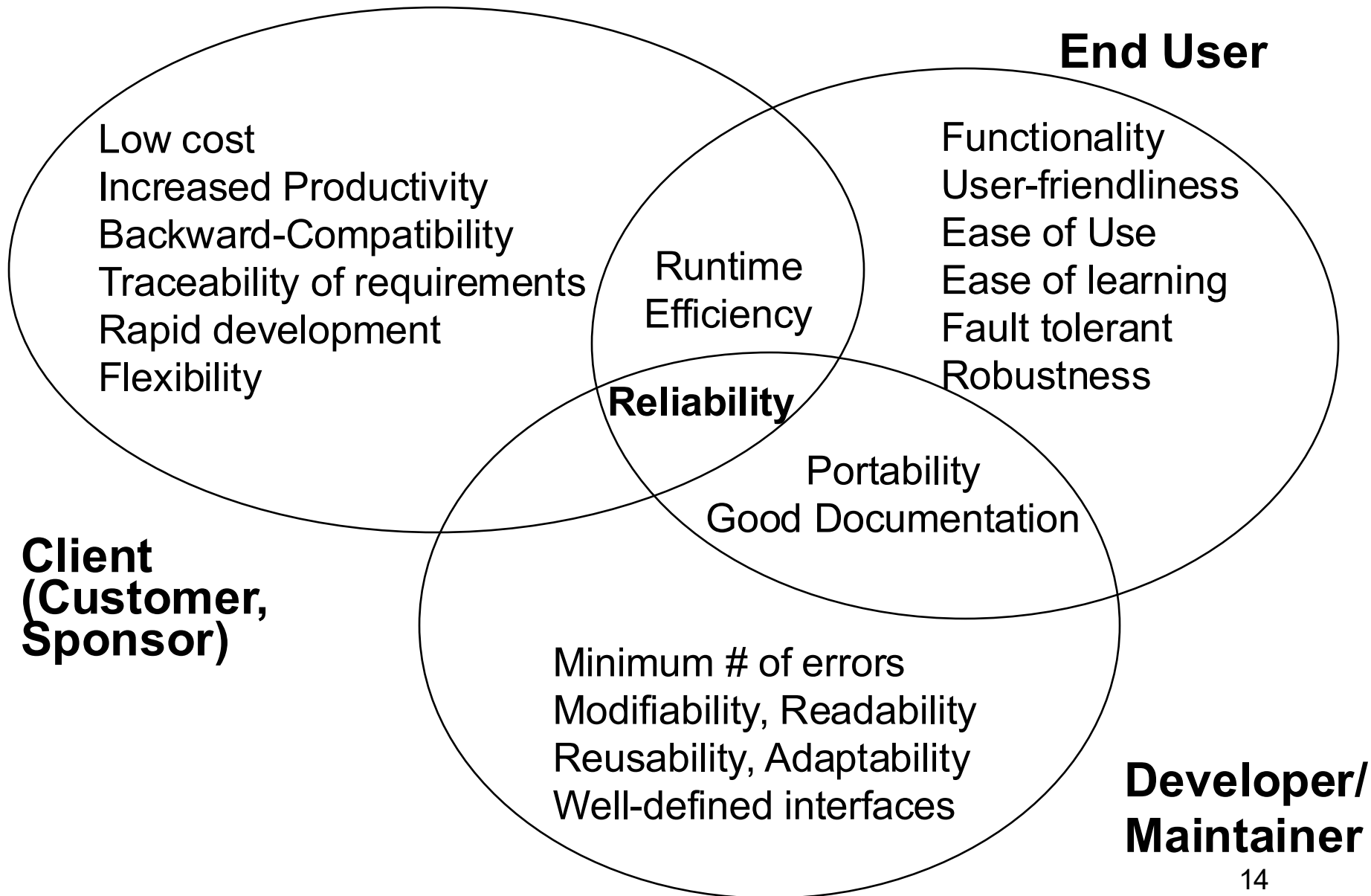
Generalize Constraints using Technology Enablers



Map Generalized Constraints into Design Goals

- Reliability
- Modifiability
- Maintainability
- Understandability
- Adaptability
- Reusability
- Efficiency
- Portability
- Traceability of requirements
- Fault tolerance
- Backward-compatibility
- Cost-effectiveness
- Robustness
- High-performance
- Good documentation
- Well-defined interfaces
- User-friendliness
- Reuse of components
- Rapid development
- Minimum # of errors
- Readability
- Ease of learning
- Ease of remembering
- Ease of use
- Increased productivity
- Low-cost
- Flexibility

Structuring Design Goals



Design goals from non-functional requirements

- **Performance**
 - Response time
 - Throughput
 - Memory
- **Dependability**
 - Robustness
 - Reliability
 - Availability
 - Fault tolerance
 - Security
 - Safety
- **End-user criteria**
 - Utility
 - Usability
- **Cost**
 - Development cost
 - Deployment cost
 - Upgrade cost
 - Maintenance cost
 - Administration cost
- **Maintenance**
 - Extensibility
 - Modifiability
 - Adaptability
 - Portability
 - Readability
 - Traceability of requirements

Design Trade-offs

- Space vs. Speed
- Efficiency vs. Portability
- Rapid development vs. Functionality
- Cost vs. Reusability
- Backward Compatibility vs. Readability
- Delivery time vs. Quality
- Delivery time vs. Functionality
- ...

System Decomposition

- **Subsystem:**

- Collection of classes, associations, operations, events and constraints that are interrelated
- Sources for subsystems: UML Use cases, Objects and Classes.

- **Service:**

- Group of operations provided by the subsystem (a set of related operations that share a common purpose)
- Sources for services: Subsystem use cases

- **Service is specified by Subsystem interface:**

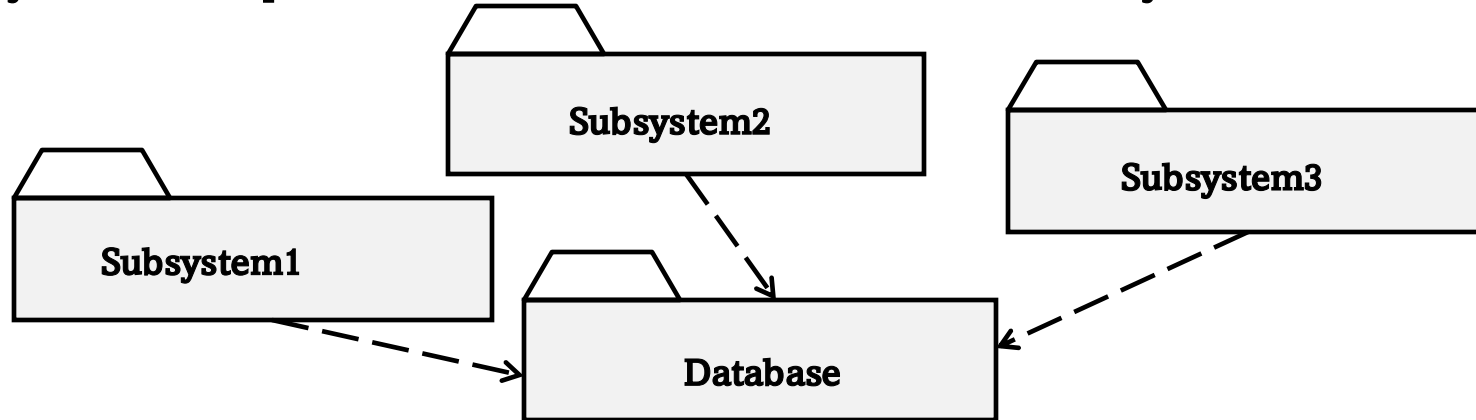
- Specifies interaction and information flow from/to subsystem boundaries, but not inside the subsystem.

Coupling and Cohesion

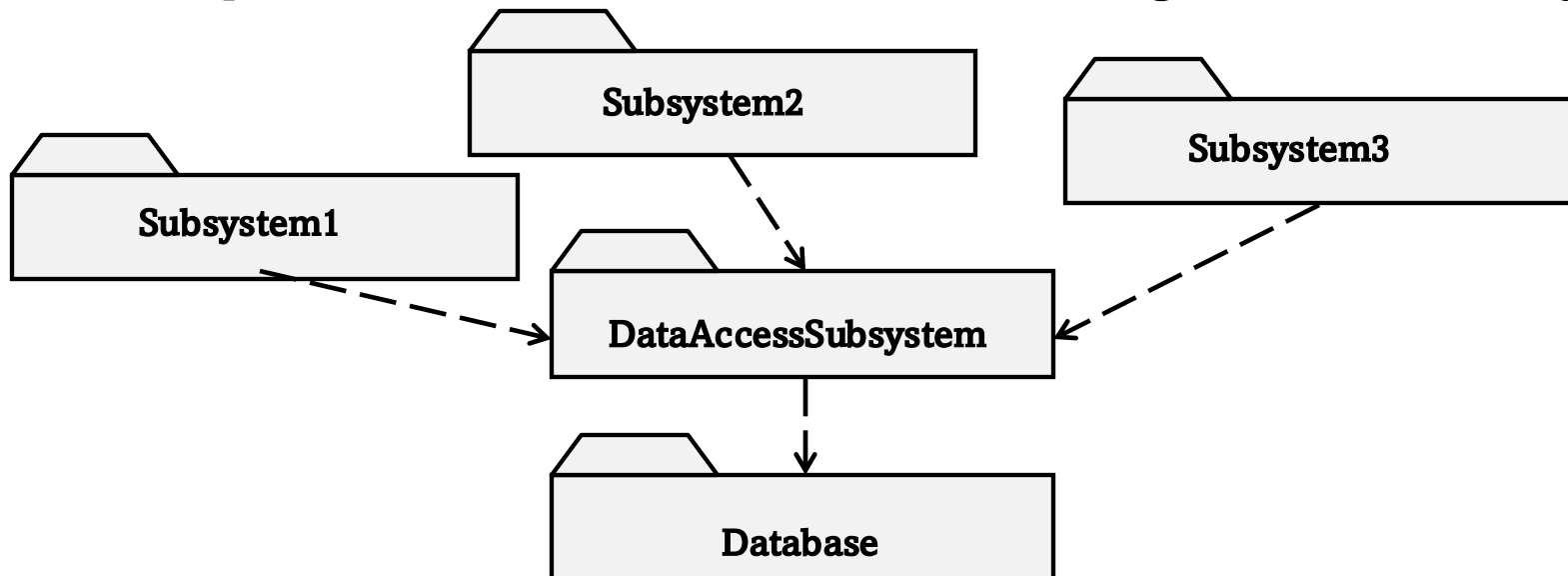
- Goal: Reduction of *complexity while change occurs*
- **Coupling** measures dependencies between subsystems
 - High coupling: Changes to one subsystem will have high impact on the other subsystem (change of model, massive recompilation, etc.)
 - Low coupling: A change in one subsystem does not affect any other subsystem
- **Cohesion** measures the dependence within the system
 - High cohesion: The classes in the subsystem perform similar tasks and are related to each other (via associations)
 - Low cohesion: Lots of miscellaneous and auxiliary classes, no associations
- Subsystems should have as maximum cohesion and minimum coupling as possible:
 - How can we achieve high cohesion?
 - How can we achieve loose coupling?

Reducing coupling

System decomposition 1: Direct access to the Database subsystem

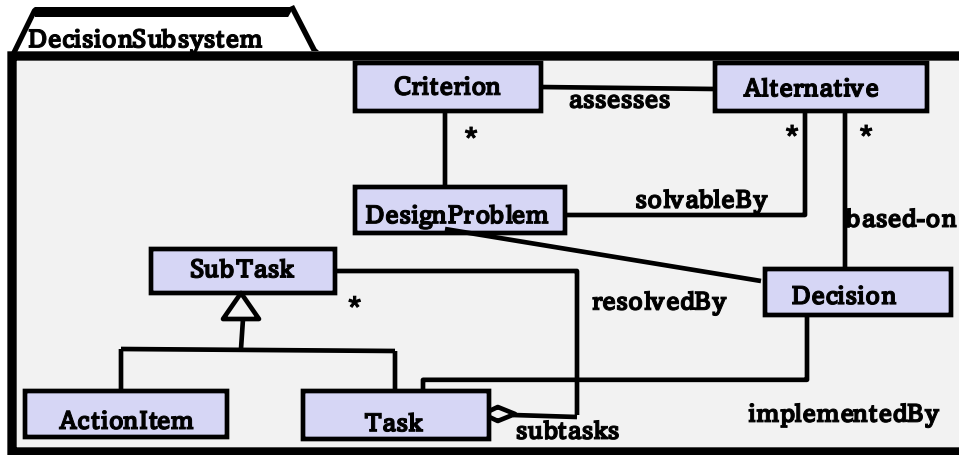


System decomposition 2: Indirect access to the Database through a DataAccessSubsystem

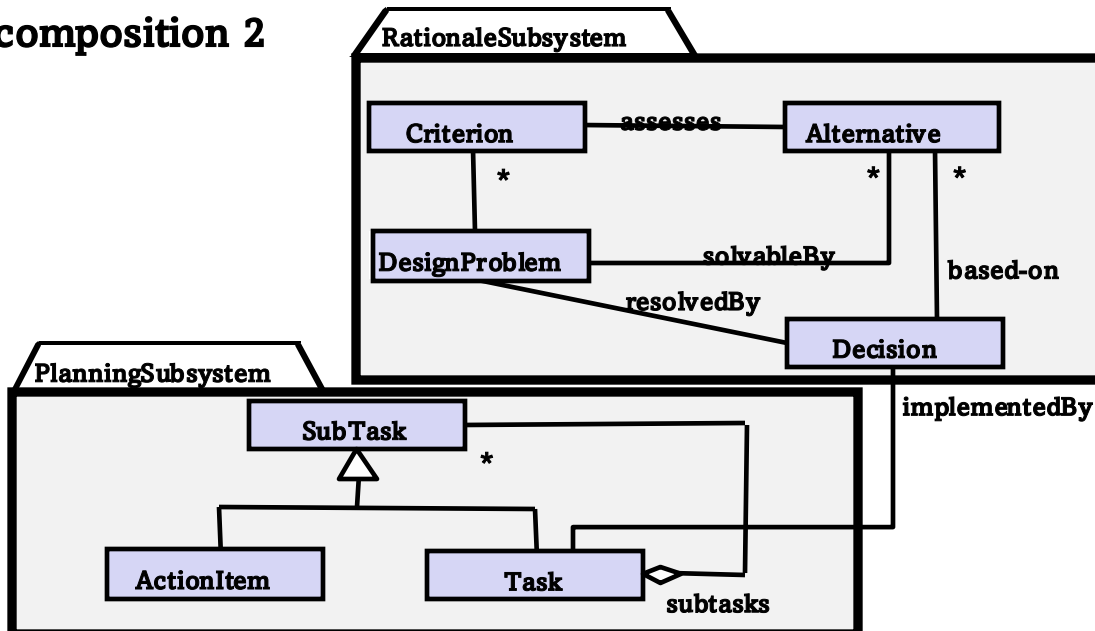


Increasing cohesion

System decomposition 1



System decomposition 2



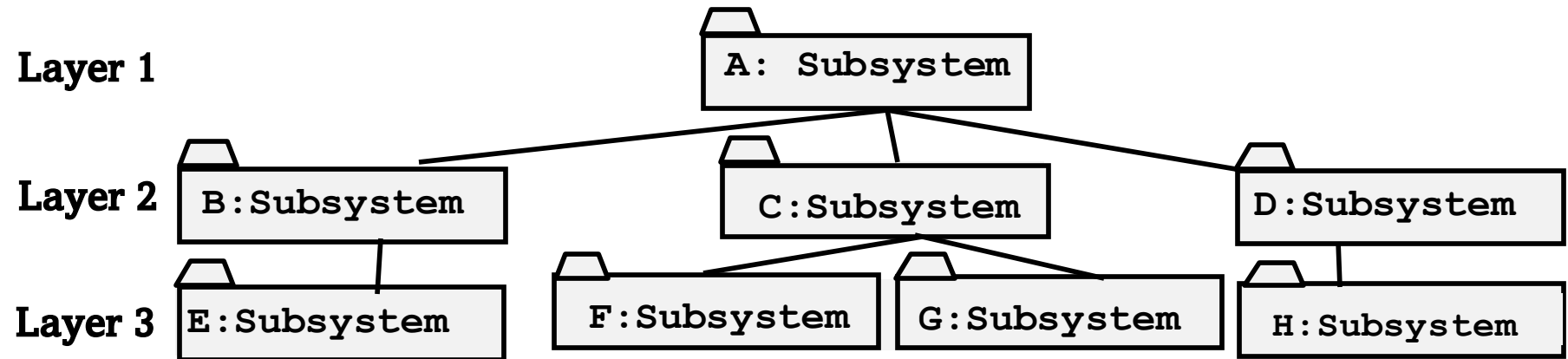
Partitions and Layers

Partitioning and layering are techniques to achieve low coupling.

A large system is usually decomposed into subsystems using both, layers and partitions.

- **Partitions** vertically divide a system into several independent (or weakly-coupled) subsystems that provide services on the same level of abstraction.
- A **layer** is a subsystem that provides subsystem services to a higher layers (level of abstraction)
 - A layer can only depend on lower layers
 - A layer has no knowledge of higher layers

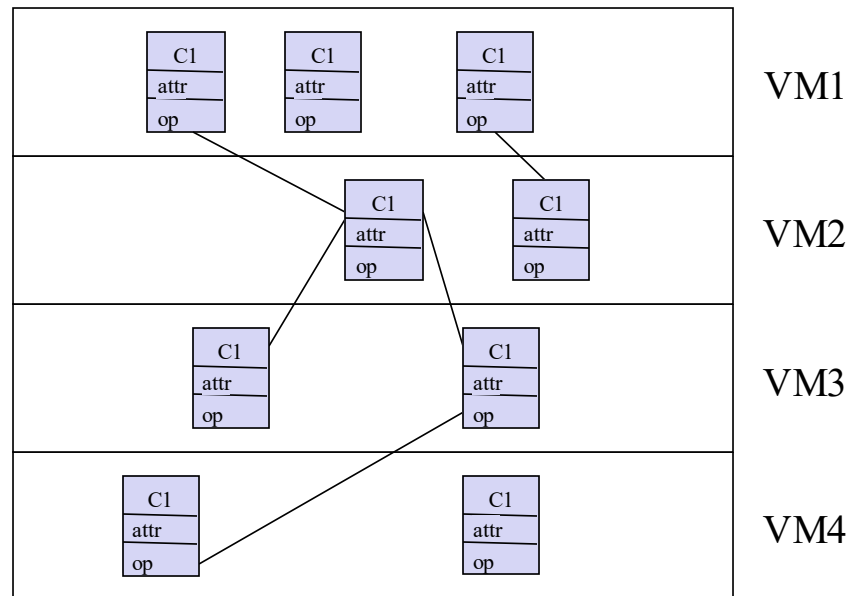
Subsystem Decomposition into Layers



- Subsystem Decomposition Heuristics:
 - No more than 7 ± 2 subsystems at any layer
 - More subsystems increase cohesion but also complexity (more services)
 - No more than 7 ± 2 layers, use 3 layers (good)

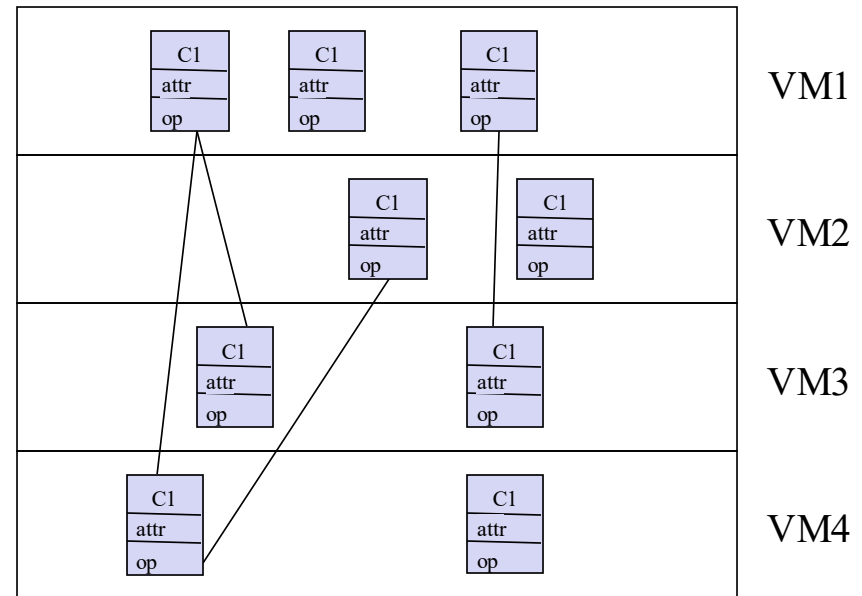
Closed Architecture (Opaque Layering)

- Any layer can only invoke operations from the immediate layer below
- Design goal: **High maintainability, flexibility**



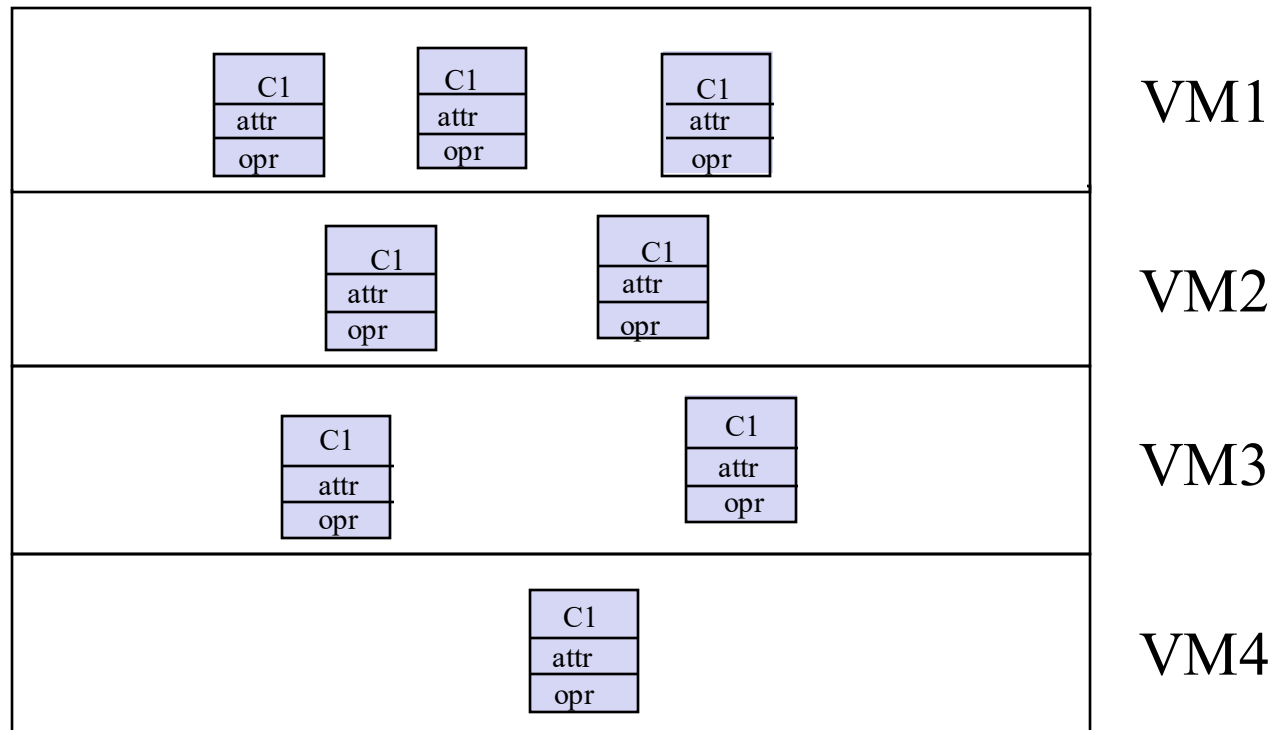
Open Architecture (Transparent Layering)

- Any layer can invoke operations from any layers below
- Design goal: **Runtime efficiency**



Example of layer Architecture: Virtual Machine

Problem



Existing System

Properties of Layered Systems

- Layered systems are ***hierarchical***. They are desirable because hierarchy reduces complexity (by low coupling).
- Closed architectures are more portable.
- Open architectures are more efficient.
- Layered systems often have a chicken-and egg problem
 - Example: Debugger
 - Debugger opening the symbol table when the file system needs to be debugged



Choosing Subsystems

- Criteria for subsystem selection:
 - Most of the interaction should be within subsystems (High cohesion), rather than across subsystem boundaries (Low coupling).

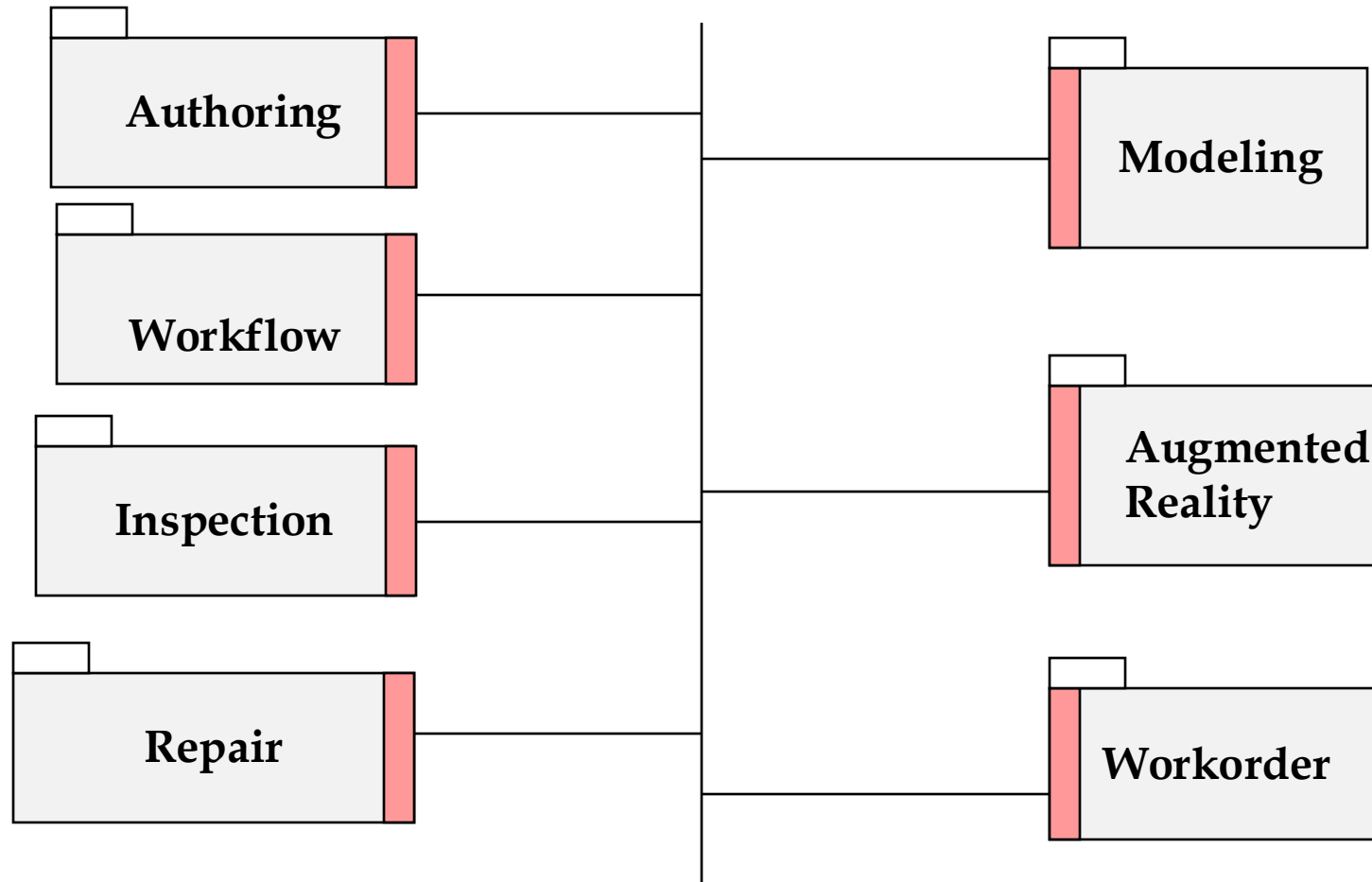
Some heuristics for grouping objects into subsystems

- Assign objects identified in one use case into the same subsystem
- Minimize the number of associations crossing subsystem boundaries
- All objects in the same subsystem should be functionally related
- ...

Software Architectural Styles

- Subsystem decomposition
 - Identification of subsystems, services, and their relationship to each other.
- Specification of the system decomposition is critical.
- Patterns for software architecture
 - Client/Server
 - Peer-To-Peer
 - Repository
 - Model/View/Controller
 - Pipes and Filters
 - ...

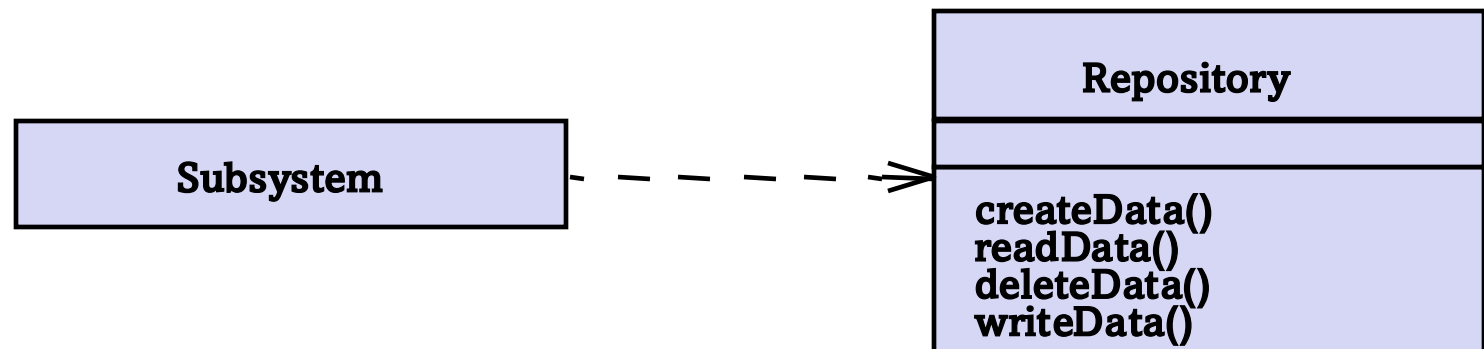
System as a set of subsystems communicating via a software bus



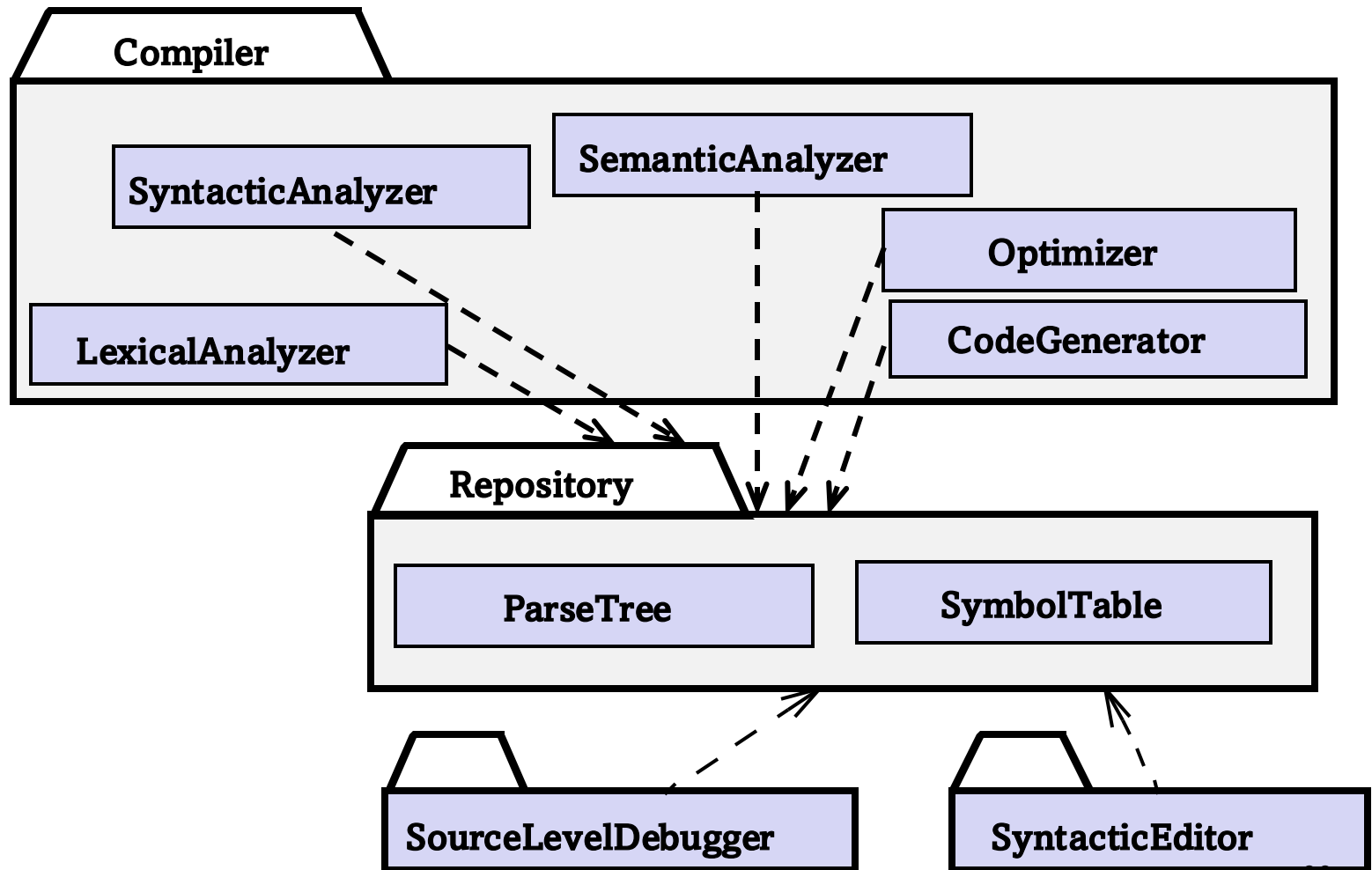
A Subsystem Interface Object publishes the service (= Set of public methods) provided by the subsystem

Repository Architectural Style

- Subsystems access and modify data from a single data structure
- Subsystems are loosely coupled (interact only through the repository)
- Control flow is dictated by central repository (triggers) or by the subsystems (locks, synchronization primitives)

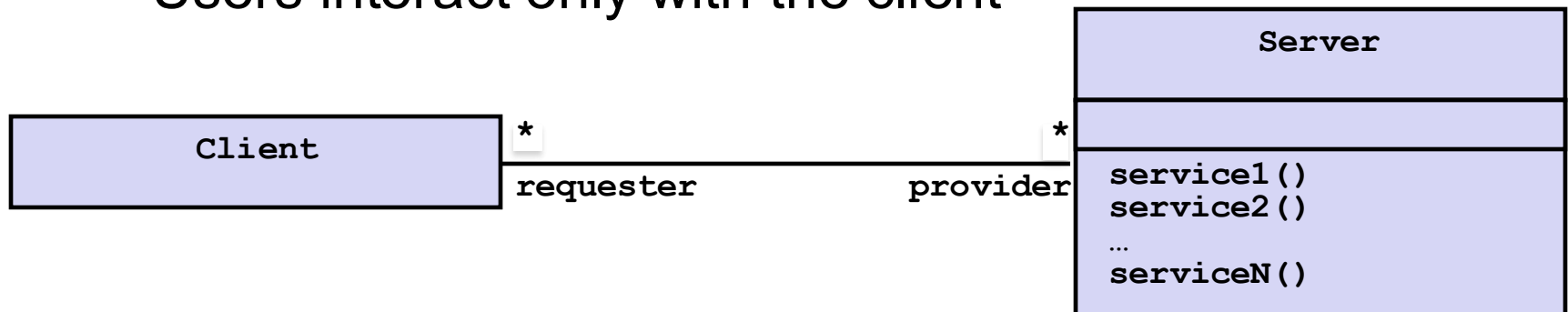


Repository Architectural Style



Client/Server Architectural Style

- One or many servers provide services to instances of subsystems, called clients.
- Client calls on the server, which performs some service and returns the result
 - Client knows the *interface* of the server (*its service*)
 - Server does not need to know the interface of the client
- Response in general immediate
- Users interact only with the client



Example of Client/Server Architectural Style

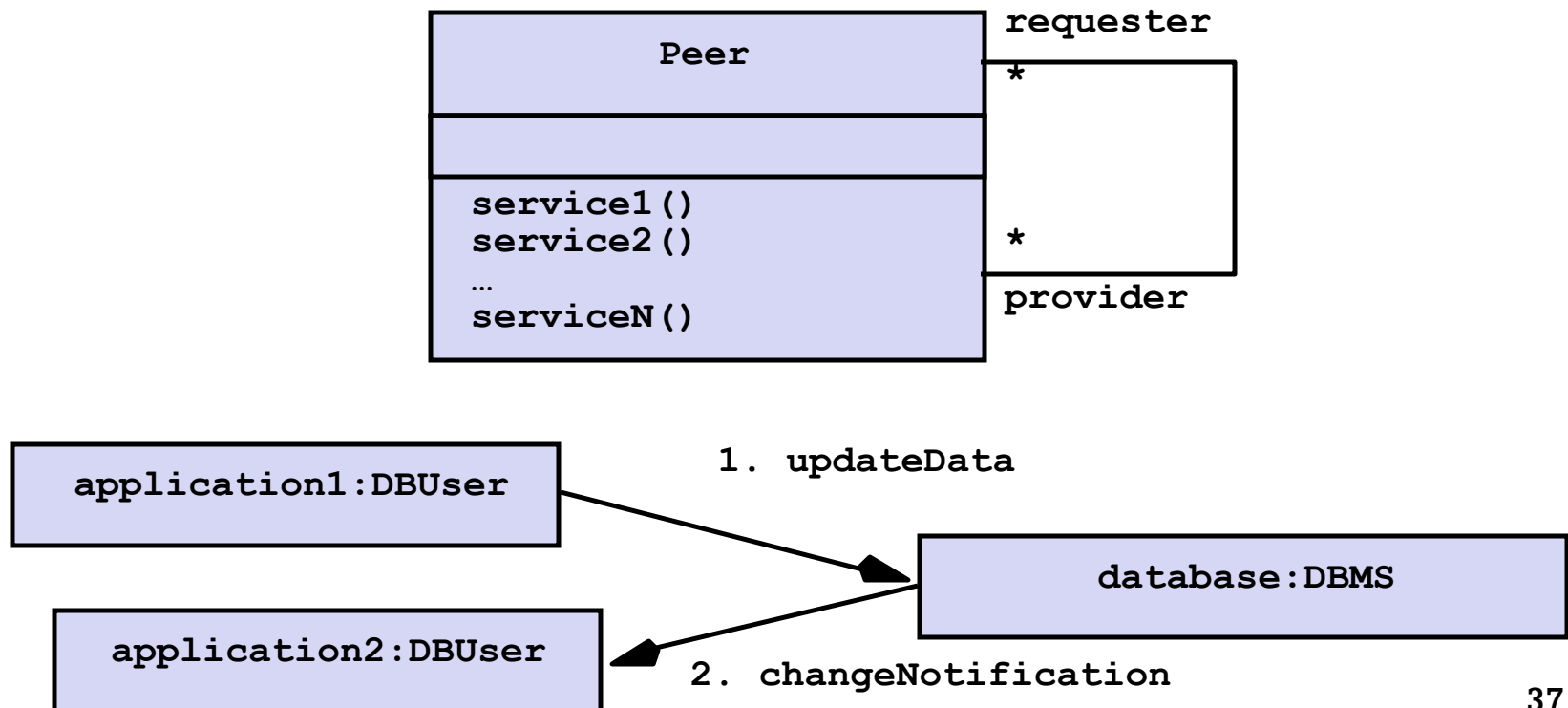
- Often used in database systems:
 - Front-end: User application (client)
 - Back end: Database access and manipulation (server)
- Functions performed by client:
 - Customized user interface
 - Front-end processing of data
 - Initiation of server remote procedure calls
 - Access to database server across the network
- Functions performed by the database server:
 - Centralized data management
 - Data integrity and database consistency
 - Database security
 - Concurrent operations (multiple user access)
 - Centralized processing (for example archiving)

Example of Design Goals for Client/Server Architectural Style

- *Service Portability*
 - Service can be installed on a variety of machines and operating systems and functions in a variety of networking environments
- *Transparency, Location-Transparency*
 - The server might itself be distributed, but should provide a single "logical" service to the user
- *Performance*
 - Client should be customized for interactive display-intensive tasks
 - Server should provide CPU-intensive operations
- *Scalability*
 - Server should have spare capacity to handle larger number of clients
- *Flexibility*
 - The system should be usable for a variety of user interfaces and end devices (eg. wearable computer, desktop)
- *Reliability*
 - System should survive node or communication link problems³⁶

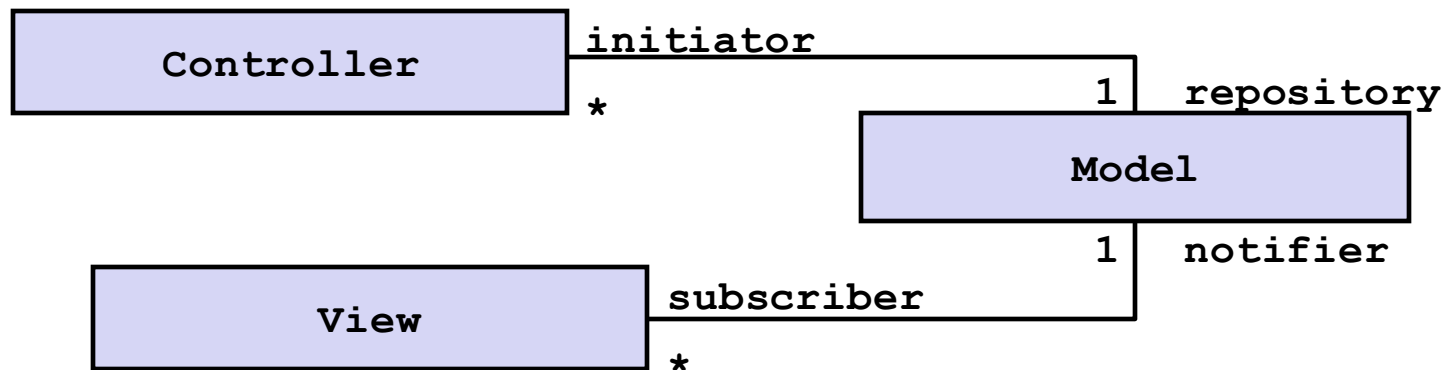
Peer-to-Peer Architectural Style

- Generalization of Client/Server Architecture
- Clients can be servers and servers can be clients
- More difficult because of possibility of deadlocks



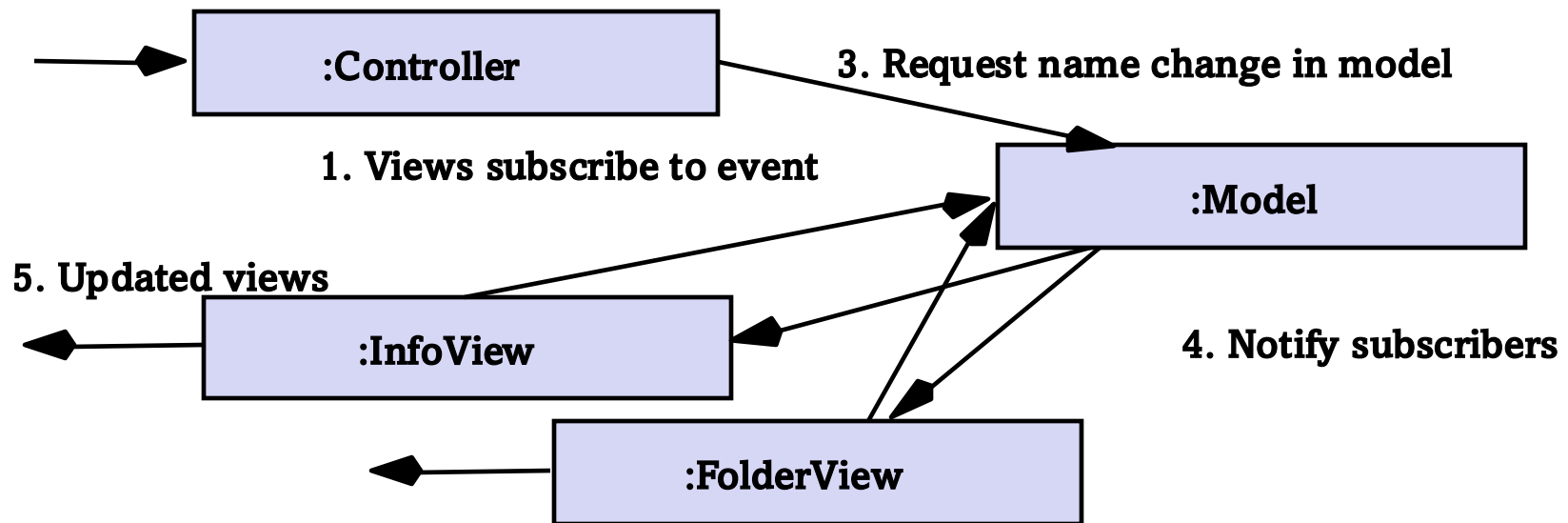
Model/View/Controller

- Subsystems are classified into 3 different types
 - Model subsystem: **Responsible for application domain knowledge**
 - View subsystem: **Responsible for displaying application domain objects to the user**
 - Controller subsystem: **Responsible for sequence of interactions with the user**
- MVC is a special case of a repository architecture:
 - Model subsystem implements the central datastructure, the Controller subsystem explicitly dictate the control flow

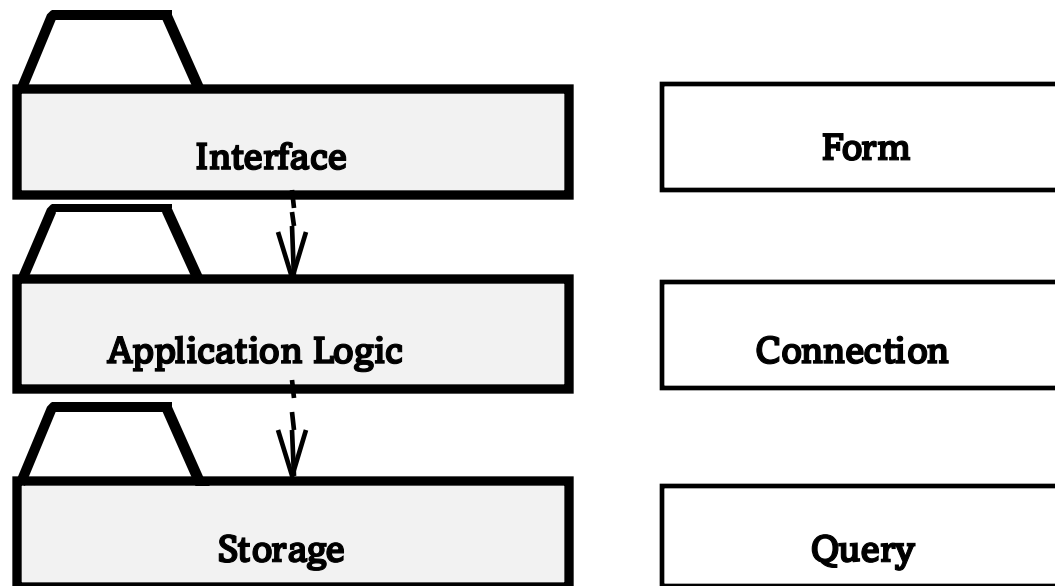


Example of MVC: Sequence of Events

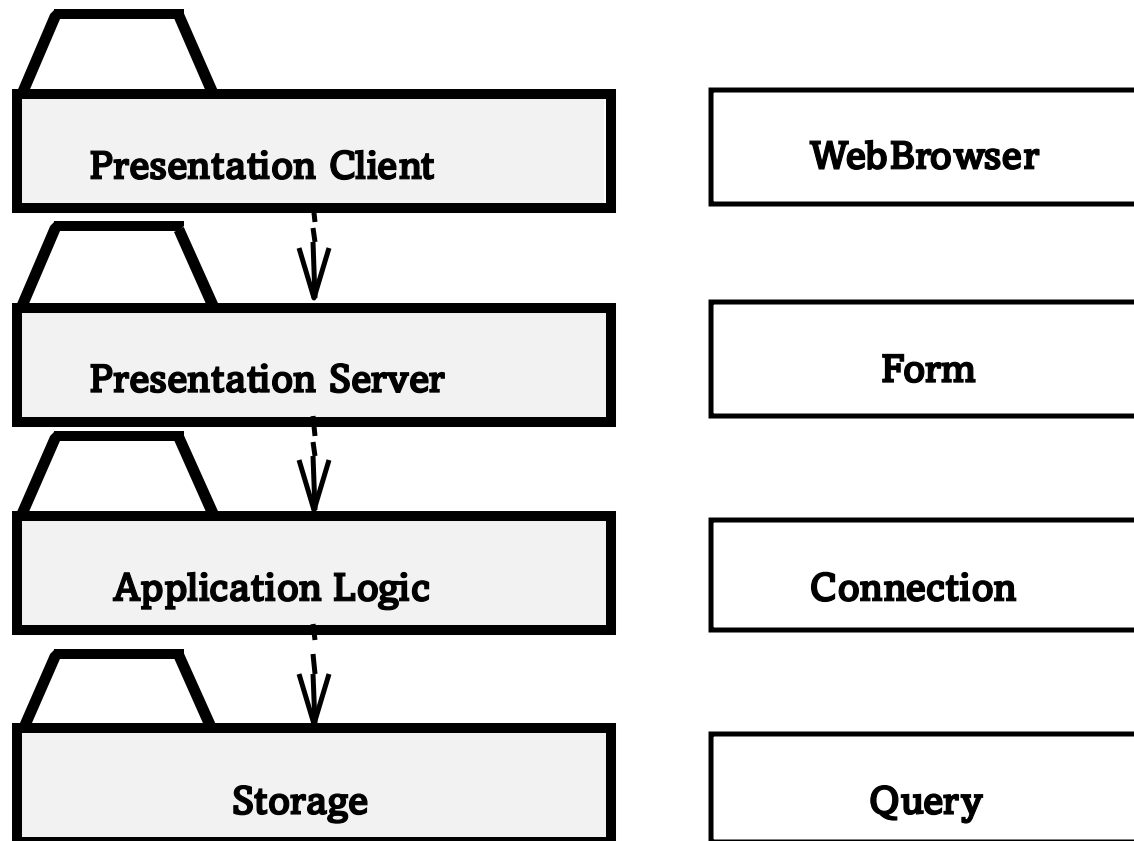
2. User types new filename



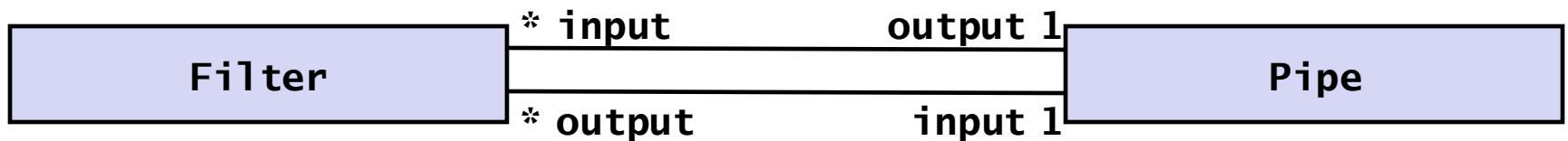
Three-tier architectural style.



Four-tier architectural style.

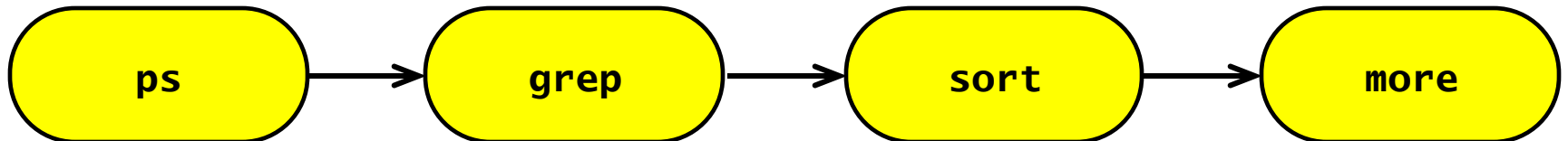


Pipe and filter architectural style.



```
% ps auxwww | grep dutoit | sort | more
```

dutoit	19737	0.2	1.6	1908	1500	pts/6	0	15:24:36	0:00	-tcsh
dutoit	19858	0.2	0.7	816	580	pts/6	S	15:38:46	0:00	grep dutoit
dutoit	19859	0.2	0.6	812	540	pts/6	0	15:38:47	0:00	sort



Intermediate Summary

- System Design
 - Reduces the gap between requirements and the (virtual) machine
 - Decomposes the overall system into manageable parts
- Design Goals Definition
 - Describes and prioritizes the qualities that are important for the system
 - Defines the value system against which options are evaluated
- Subsystem Decomposition
 - Results into a set of loosely dependent parts which make up the system

System Design

```
graph TD; SD[System Design] --- D1[1. Design Goals]; SD --- D2[2. System Decomposition]; SD --- D3[3. Concurrency]; SD --- D4[4. Hardware/Software Mapping]; SD --- D5[5. Data Management]; SD --- D6[6. Global Resource Handling]; SD --- D7[7. Software Control]; SD --- D8[8. Boundary Conditions];
```

1. Design Goals

Definition
Trade-offs

2. System Decomposition

Layers/Partitions
Cohesion/Coupling

3. Concurrency

Identification of
Threads of control

4. Hardware/ Software Mapping

Special purpose
Buy or Build Trade-off
Allocation
Connectivity

5. Data Management

Persistent Objects
Databases
Data structure

6. Global Resource Handling

Access control
Security

8. Boundary Conditions

Initialization
Termination
Failure

7. Software Control

Monolithic
Event-Driven
Threads
Conc. Processes

System Design Activities (continue)

- Hardware/Software Mapping
- Persistent Data Management
- Global Resource Handling and Access Control
- Software Control
- Boundary Conditions

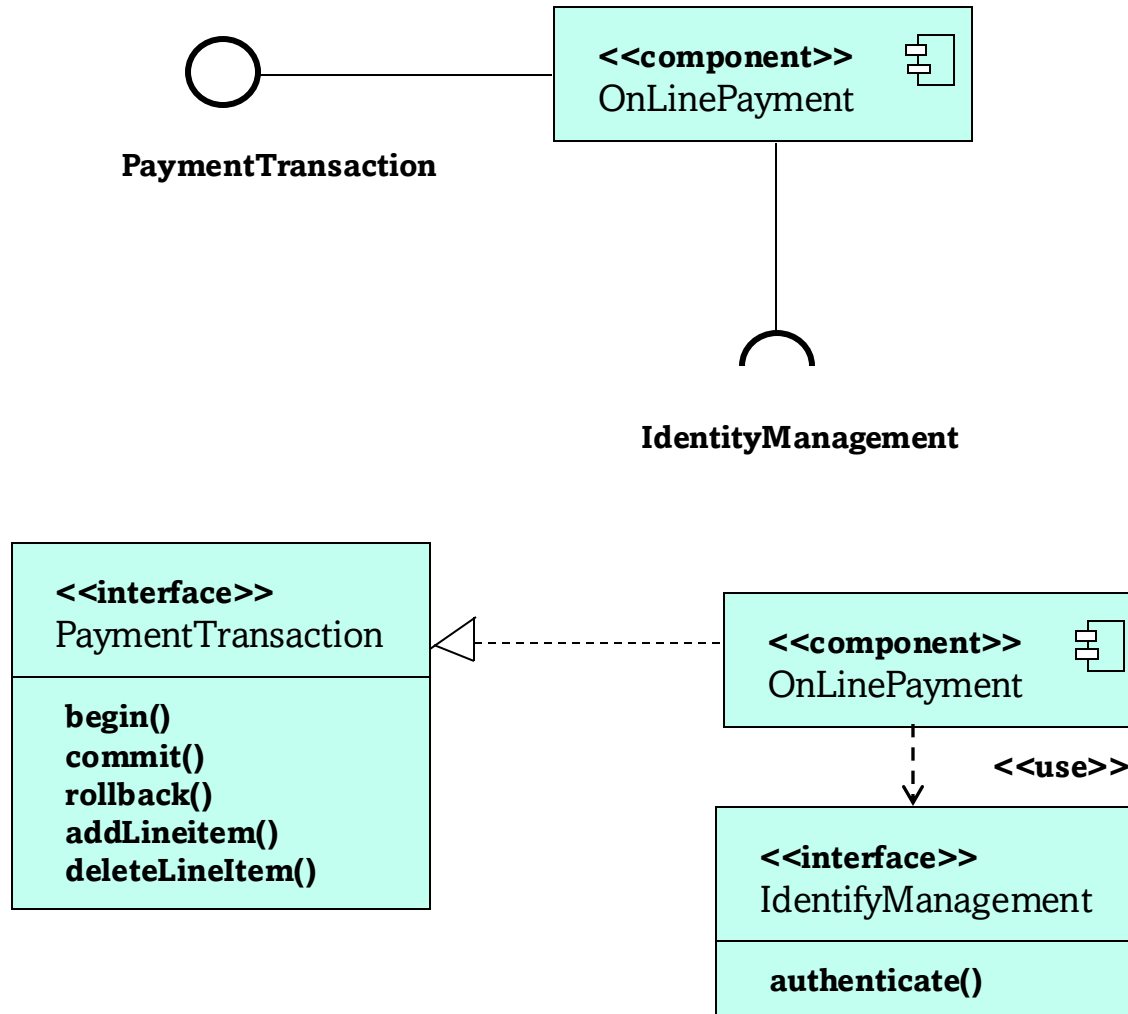
Hardware/Software Mapping

- This activity addresses two questions:
 - How shall we realize the subsystems?
 - Hardware or Software?
 - How is the object model mapped on the chosen hardware & software?
 - Mapping Objects onto Reality: Processor, Memory, Input/Output
 - Mapping Associations onto Reality: Connectivity
- Much of the difficulty of designing a system comes from meeting externally-imposed hardware and software constraints.
 - Certain tasks have to be at specific locations

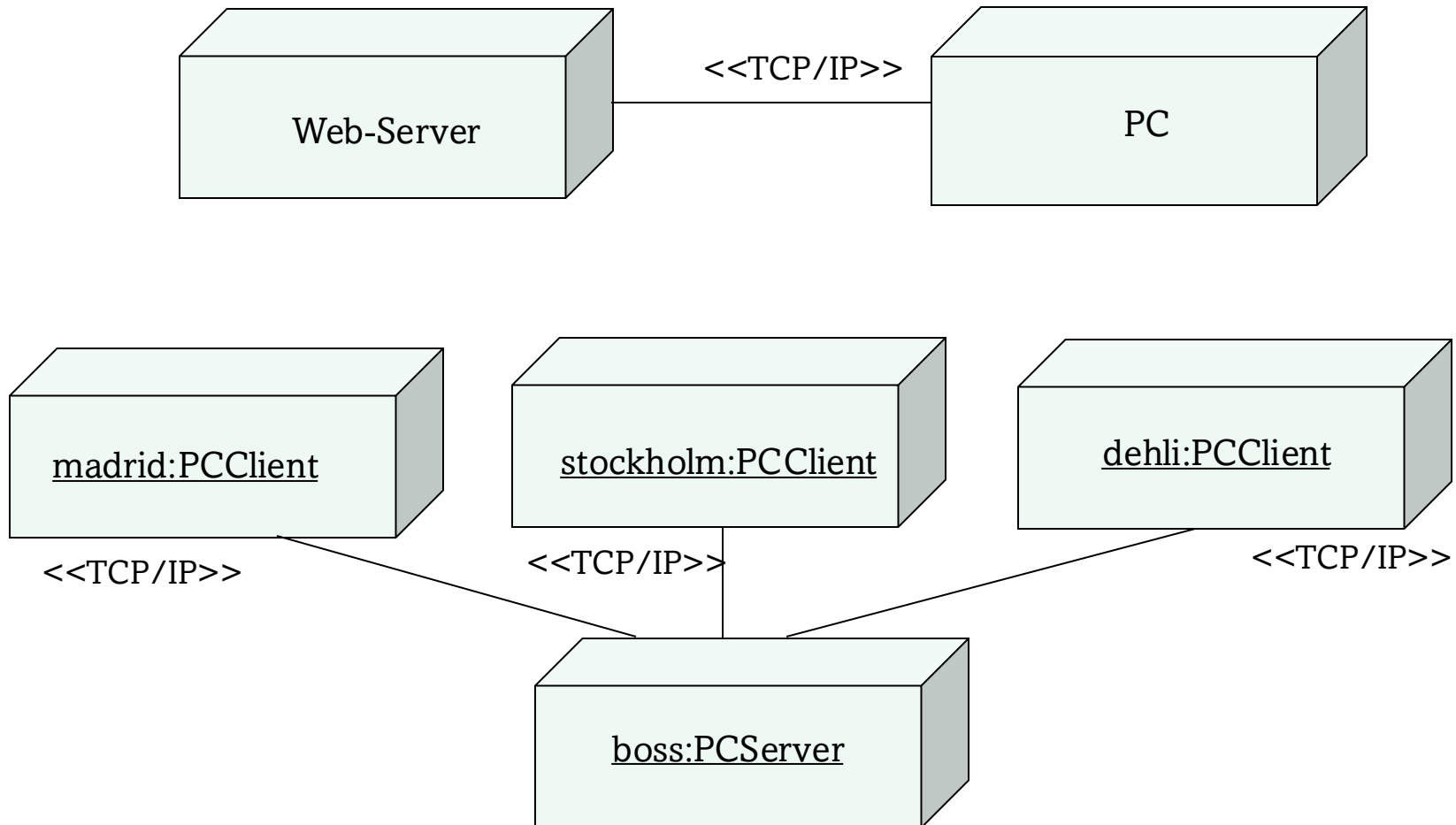
Component and Deployment diagrams

- Models for physical implementation of the system
- Show system components, their structure and dependencies and how they are deployed on computer nodes
- Two kinds of diagrams:
 - component diagrams
 - deployment diagrams
- Component diagrams show structure of components, including their interface and implementation dependencies
- Deployment diagrams show the runtime deployment of the system on computer nodes

Component Diagrams (component interface)



Deployment diagrams

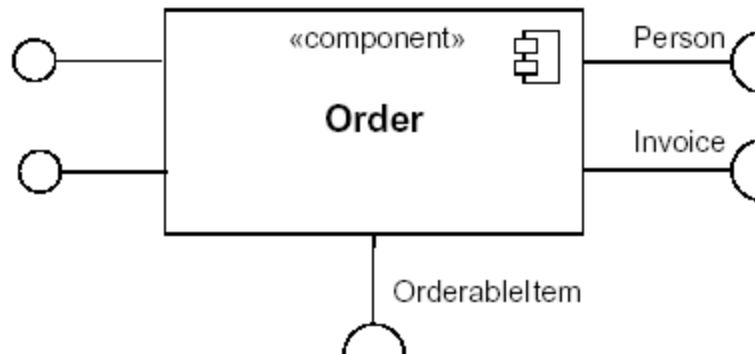


Drawing Hardware/Software Mappings in UML

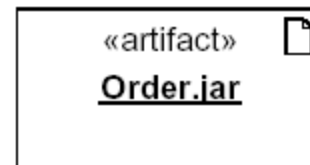
- System design must model static and dynamic structures:
 - Component Diagrams for static structures
 - show the structure at **design time** or **compilation time**
 - Deployment Diagram for dynamic structures
 - show the structure of the **run-time** system

Deployment Diagrams (artifact)

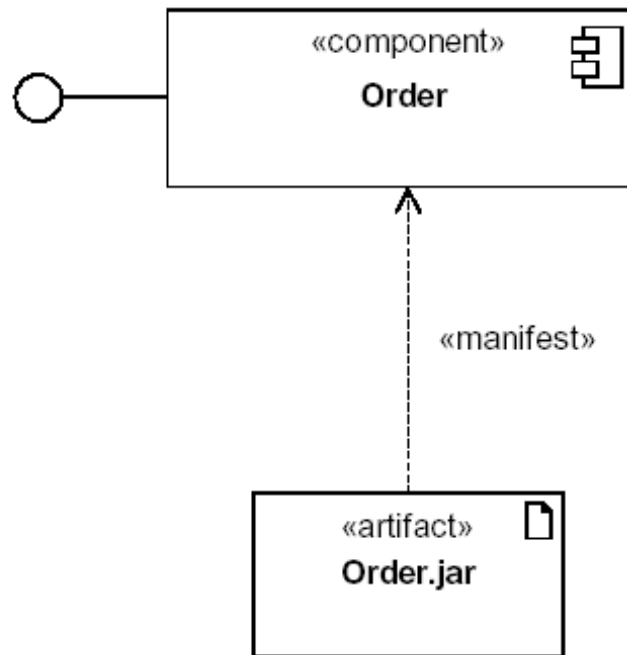
- Component



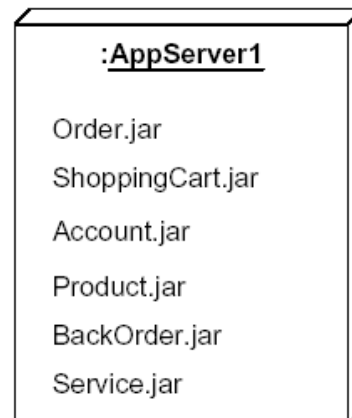
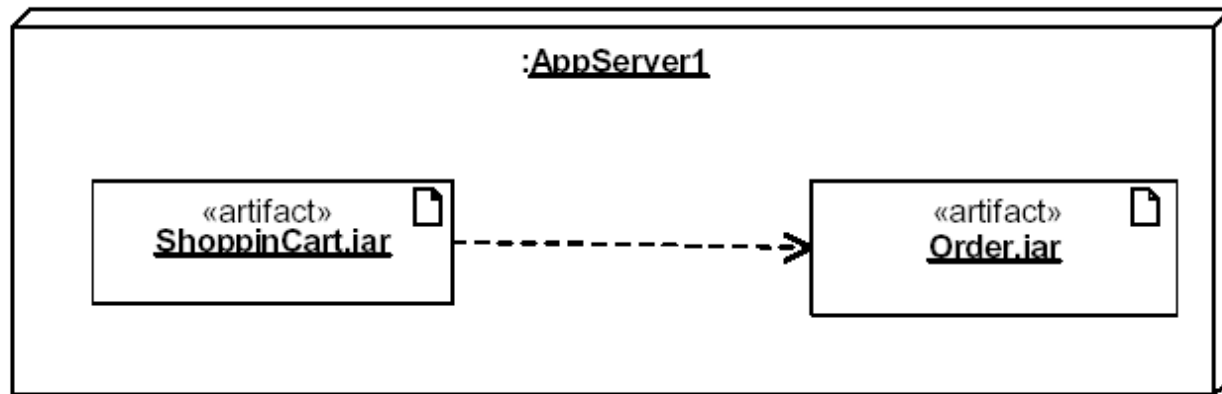
- Artifact - Artifacts represent concrete elements in the physical world (physical piece of information) that are the result of a development process.



Manifestation relationship between artifacts and components



Location of Artifacts on the node



Data Management

- Some objects in the models need to be persistent
- A persistent object can be realized with one of the following
 - Files
 - Cheap, simple, permanent storage
 - Low level (Read, Write)
 - Applications must add code to provide suitable level of abstraction
 - Database
 - Powerful, easy to port
 - Supports multiple writers and readers

File or DB?

When should you choose flat files?

- Voluminous data (e.g., images)
- Temporary data (e.g., core file)
- Low information density (e.g., archival files, history logs)

When should you choose a database?

- Concurrent accesses
- Access at finer levels of detail
- Multiple platforms or applications for the same data

When should you choose a relational database?

- Complex queries over attributes
- Large data set

Global Resource Handling

- Discusses access control
- Describes access rights for different classes of actors
- Describes how object guard against unauthorized access

Access Matrix Implementations

- Global access table: Represents explicitly every cell in the matrix as a (actor, class, operation) tuple.
 - Determining if an actor has access to a specific object requires looking up the corresponding tuple. If no such tuple is found, access is denied.
- Access control list associates a list of (actor, operation) pairs with each class to be accessed.
 - Every time an object is accessed, its access list is checked for the corresponding actor and operation.
 - Example: guest list for a party.
- A capability associates a (class, operation) pair with an actor.
 - A capability provides an actor to gain control access to an object of the class described in the capability.
 - Example: An invitation card for a party.
- Which is the right implementation?

Decide on Software Control

Choose implicit control (non-procedural, declarative languages)

- Rule-based systems
- Logic programming

Choose explicit control (procedural languages):

- Procedure-driven control
 - Control resides within program code. Operations wait for input whenever they need data from an actor.
 - Example: Main program calling procedures of subsystems.
 - Simple, easy to build, hard to maintain (high recompilation costs)
- Event-driven control
 - Control resides within a dispatcher calling functions via callbacks.
 - Very flexible, good for the design of graphical user interfaces, easy to extend

Centralized vs. Decentralized Designs

- Should you use a centralized or decentralized design?
 - Take the sequence diagrams and control objects from the analysis model
 - Check the participation of the control objects in the sequence diagrams
 - If sequence diagram looks more like a fork: Centralized design
 - The sequence diagram looks more like a stair: Decentralized design
- Centralized Design
 - One control object or subsystem ("spider") controls everything
 - Pro: Change in the control structure is very easy
 - Cons: The single control object is a possible performance bottleneck
- Decentralized Design
 - Not a single object is in control, control is distributed, that means, there is more than one control object
 - Cons: The responsibility is spread out – changes are not obvious
 - Pro: Fits nicely into object-oriented development

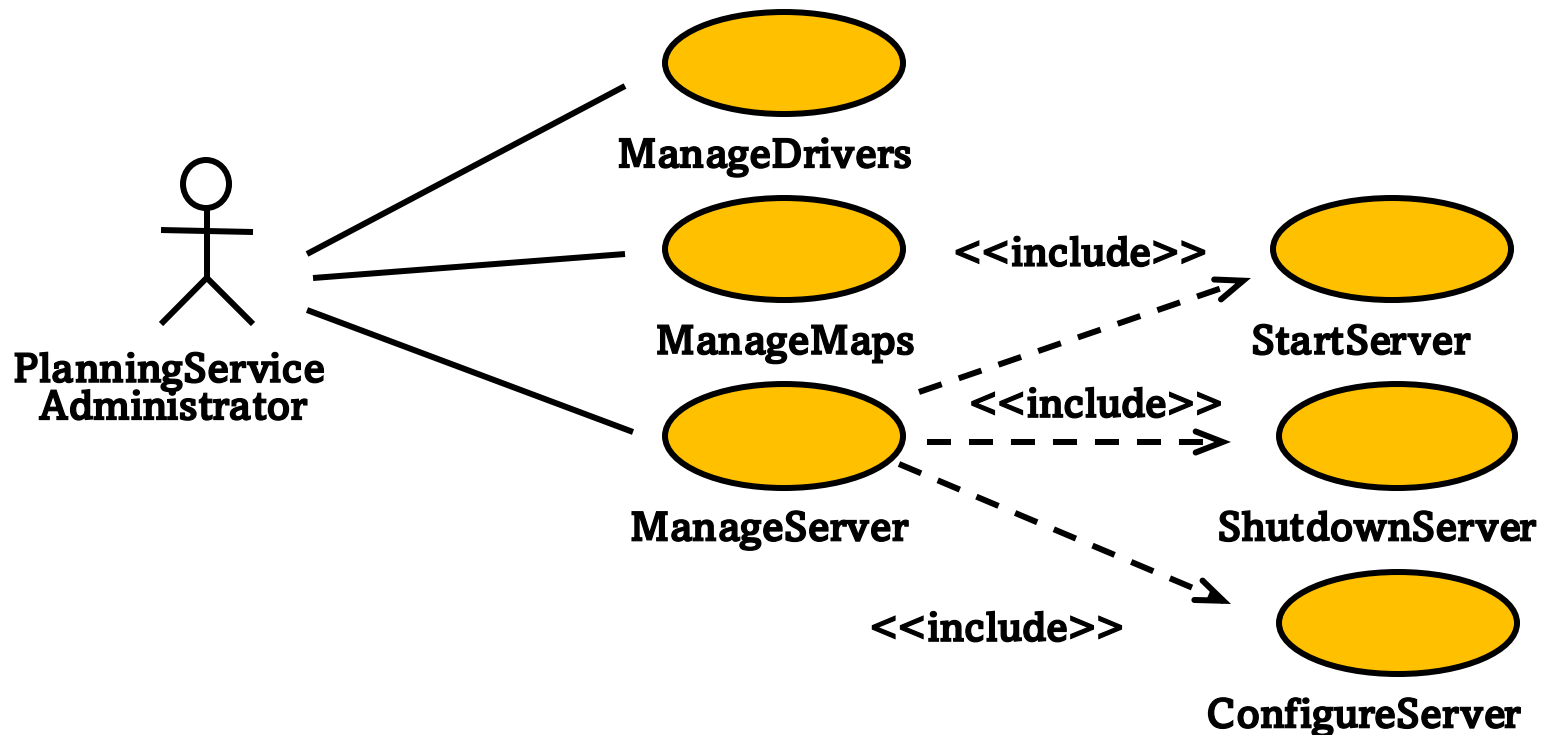
Boundary Condition

- Initialization
 - How does the system start up?
 - What data need to be accessed at startup time?
 - What services have to be registered?
 - What does the user interface do at start up time?
 - How does it present itself to the user?
- Termination
 - Are single subsystems allowed to terminate?
 - Are other subsystems notified if a single subsystem terminates?
 - How are local updates communicated to the database?
- Failure
 - How does the system behave when a node or communication link fails? Are there backup communication links?
 - How does the system recover from failure? Is this different from initialization?

Modeling Boundary Conditions

- Boundary conditions are best modeled as use cases with actors and objects.
- Actor: often the system administrator
- Interesting use cases:
 - Start up of a subsystem
 - Start up of the full system
 - Termination of a subsystem
 - Error in a subsystem or component, failure of a subsystem or component

ManageServer Use Case



Summary

In this lecture, we reviewed the activities of system design :

- Design goals identification
- System decomposition
- Concurrency identification
- Hardware/Software mapping
- Persistent data management
- Global resource handling
- Software control selection
- Boundary conditions

Each of these activities revises the subsystem decomposition to address a specific issue. Once these activities are completed, the interface of the subsystems can be defined.

Next lecture

- Object design

Chapters 8 & 9