MAT4400: Notes on Linear analysis

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3 σ-Algebras

Definition 3.0.1 (Borel)**.** The σ-algebra $\sigma(\mathcal{O})$ generated by the open sets $\mathcal{O} = \mathcal{O}_{\mathbb{R}^n}$ of $\mathbb{R}^n$ is called **Borel σ-algebra**, and its members are called **Borel sets** or **Borel measurable sets**.

5 Uniqueness of Measures

Lemma 5.1. *A Dynkin system D is a σ-algebra iff it is stable under finite intersections, i.e. $A, B \in D \Rightarrow A \cap B \in D$.*

Theorem 5.2 (Dynkin)**.** *Assume X is a set, S is a collection of subsets of X closed under finite intersections, that is, if $A, B \in S \Rightarrow A \cap B \in S$. Then $D(S) = \sigma(S)$.*

Theorem 5.3 (uniqueness of measures)**.** *Let (X, B) be a measurable space, and $S \subset P(X)$ be the generator of B, i.e. $B = \sigma(S)$. If S satisfies the following conditions:*

1. *S is stable under finite intersections ($\cap$-stable), i.e. $A, C \in S \Rightarrow A \cap C \in S$.*
2. *There exists an exhausting sequence $(G_n)_{N \in \mathbb{N}} \subset$ with $G_N \uparrow X$. Assume also that there are two measures μ, ν satisfying:*
3. *$\mu(A) = \nu(A),\ \forall A \in S$.*
4. *$\mu(G_n) = \nu(G_n) < \infty$.*

Then $\mu = \nu$.

6 Existence of Measures

Theorem 6.1 (Carathéodory)**.** *Let $S \subset P(X)$ be a semi-ring and $\mu : S \to [0, \infty)$ a pre-measure. Then μ has an extension to a measure μ^* on $\sigma(S)$, i.e. that $\mu(s) = \mu^*(s),\ \forall\ s \in \sigma(S)$.*

Also, if S contains an exhausting sequence, $S_n \uparrow X$, s.t. $\mu(S_n) < \infty$, then the extension is unique.

7 Measurable Mappings

We consider maps $T : X \to X'$ between two measurable spaces $(X, \mathcal{A})$ and $(X', \mathcal{A}')$ which respects the measurable structurs, the σ-algbras on X and X'. These maps are useful as we can transport a measure μ, defined on $(X, \mathcal{A})$, to $(X', \mathcal{A}')$.

Definition 7.0.1. Let $(X, \mathcal{A})$, $(X', \mathcal{A}')$ b measurable spaces. A map $T : X \to X'$ is called $\mathcal{A}/\mathcal{A}'$-measurable if the pre-imag of every measurable set is a measurable set:

$$T^{-1}(A') \in \mathcal{A}, \quad \forall A' \in \mathcal{A}'. \tag{1}$$

- A $\mathcal{B}(\mathbb{R}^n)/\mathcal{B}(\mathbb{R}^m)$ measurable map is often called a Borel map.
- The notation $T : (X, \mathcal{A}) \to (X', \mathcal{A}')$ is often used to indicate measurability of the map T.

Lemma 7.1. *Let $(X, \mathcal{A})$, $(x', \mathcal{A}')$ be measurable spaces and let $\mathcal{A}' = \sigma(\mathcal{G}')$. Then $T : X \to X'$ is $\mathcal{A}/\mathcal{A}'$-measurable iff $T^{-1}(\mathcal{G}') \subset \mathcal{A}$, i.e. if*

$$T^{-1}(G') \in \mathcal{A}, \ \forall G' \in \mathcal{G}'. \tag{2}$$

Theorem 7.2. *Let $(X_i, \mathcal{A}_i)$, $i = 1, 2, 3$, be measurable spaces and $T : X_1 \to X_2$, $S : X_2 \to X_3$ be $\mathcal{A}_1/\mathcal{A}_2$ and $\mathcal{A}_2/\mathcal{A}_3$-measurable maps respectivly. Then $S \circ T : X_1 \to X_3$ is $\mathcal{A}_1/\mathcal{A}_3$-measurable.*

Definition 7.2.1. (and lemma) Let $(T_i)_{i \in I}$, $T_I : X \to X_i$, be arbitrarily many mappings from the same space X into measurable spaces $(X_i, \mathcal{A}_i)$. The smallest σ-algebra on X that makes all T_i simultanously measurable is

$$\sigma(T_i : i \in I) := \sigma\left(\bigcup_{i \in I} T_i^{-1}(\mathcal{A}_i)\right) \tag{3}$$

Theorem 7.3. *Let $(X, \mathcal{A})$, $(X', \mathcal{A}')$ be measurable spaces and $T : X \to X'$ be an $\mathcal{A}/\mathcal{A}'$-measurable map. For every measurable μ on $(X, \mathcal{A})$,*

$$\mu'(A') := \mu(T^{-1}(A')), \quad A' \in \mathcal{A}', \tag{4}$$

defines a measure on $(X', \mathcal{A}')$.

Definition 7.3.1. The measure $\mu'(\cdot)$ in the above theorem is called the push forward or image measure of μ under T and it is denoted as $T(\mu)(\cdot)$, $T_{*\mu}(\cdot)$ or $\mu \circ T^{-1}(\cdot)$.

Theorem 7.4. *If $T \in \mathbb{R}^{n \times n}$ is an orthogonal matrix, then $\lambda^n = T(\lambda^n)$.*

Theorem 7.5. *Let $S \in \mathbb{R}^{n \times n}$ be an invertible matrix. Then*

$$S(\lambda^n) = |\det s^{-1}|\lambda^n = |\det S|^{-1}\lambda^n. \tag{5}$$

Corollary 7.6. *Lebesgue measure is invariant under motions: $\lambda^n = M(\lambda^n)$ for all motions M in $\mathbb{R}^n$. In particular, congruent sets have the same measure. Two sets of points are called congruent if, and only if, one can be transformed into the other by an isometry*

8 Measurable Functions

A *measurable function* is a measurable map $u : X \to \mathbb{R}$ from some measurable space $(X, \mathscr{A})$ to $(\mathbb{R}, \mathscr{B}(\mathbb{R}^1))$. They play central roles in the theory of integration.

We recall that $u : X \to \mathbb{R}$ is $\mathscr{A}/\mathscr{B}(\mathbb{R}^1)$-measurable if

$$u^{-1}(B) \in \mathscr{A}, \quad \forall B \in \mathscr{B}(\mathbb{R}^1). \tag{6}$$

Moreover from a lemma from chapter 7, we actually only need to show that

$$u^{-1}(G) \in \mathscr{A}, \quad \forall G \in \mathcal{G} \text{ where } \mathcal{G} \text{ generates } \mathscr{B}(\mathbb{R}^1). \tag{7}$$

10 Integrals of Measurable Functions

We have defined our integral for positive measurable functions, i.e. functions in $\mathcal{M}^+(\mathscr{A})$. To extend our integral to not only functions in $\mathcal{M}^+(\mathscr{A})$ we first notice that

$$u \in \mathcal{M}_{\overline{\mathbb{R}}}(\mathscr{A}) \Leftrightarrow u = u^+ - u^-, \; u^+, u^- \in \mathcal{M}^+_{\overline{\mathbb{R}}}, \tag{8}$$

i.e. that every measurable function can be written as a sum of **positive** measurable functions.

Definition 10.0.1 (μ-integrable)**.** A function $u : X \to \overline{\mathbb{R}}$ on $(X, \mathscr{A}, \mu)$ is *μ-integrable*, if it is $\mathscr{A}/\mathscr{B}(\overline{\mathbb{R}})$-measurable and if $\int u^+ d\mu, \int u^- d\mu < \infty$ (recall the definition for the integral of positive measurable functions). Then

$$\int u d\mu := \int u^+ d\mu - \int u^- d\mu \in (-\infty, \infty) \tag{9}$$

is the (μ-)*integral* of u. We write $\mathcal{L}^1(\mu)$ for the set of all real-valued μ-integrable functions [1].

Theorem 10.1. *Let $u \in \mathcal{M}_{\overline{\mathbb{R}}}(\mathscr{A})$, then the following conditions are equivalent:*

(i) $u \in \mathcal{L}^1_{\overline{\mathbb{R}}}(\mu)$.

(ii) $u^+, u^- \in \mathcal{L}^1_{\overline{\mathbb{R}}}(\mu)$.

(iii) $|u| \in \mathcal{L}^1_{\overline{\mathbb{R}}}(\mu)$.

(iv) $\exists w \in \mathcal{L}^1_{\overline{\mathbb{R}}}(\mu)$ *with* $w \geq 0$ *s.t.* $|u| \leq w$.

Theorem 10.2 (Properties the μ-integral)**.** *The μ-integral has the following properties:* ***homogeneous, additive****, and:*

[1] In words, we extend our integral to ~~positive~~ measurable functions by noticing that we can write every measurable function as a sum of positive measurable functions, something that we do know how to integrate. We don't want to run into the problem of $\infty - \infty$, thus we require the integral of the positive and negative parts to both (separately) be less than infinity.

(i) $\min\{u,v\}, \max\{u,v\} \in \mathcal{L}^1_{\overline{\mathbb{R}}}(\mu)$ *(lattice property)*

(ii) $u \leq v \Rightarrow \int u d\mu \leq \int v d\mu$ *(monotone)*

(iii) $\left|\int u d\mu\right| \leq \int |u| d\mu$ *(triangle inequality)*

Remark. *If $u(x) \pm v(x)$ is defined in $\overline{\mathbb{R}}$ for all $x \in X$ then we can exclude $\infty - \infty$ and the theorem above just says that the integral is linear:*

$$\int (au + bv) d\mu = a \int u d\mu + b \int v d\mu. \tag{10}$$

This is always true for real-valued $u, v \in \mathcal{L}^1(\mu) = \mathcal{L}^1_{\mathbb{R}}(\mu)$, making $\mathcal{L}^1(\mu)$ a vector space with addition and scalar multiplication defined by

$$(u+v)(x) := u(x) + v(x),\ \ (a \cdot u)(x) := a \cdot u(x), \tag{11}$$

and

$$\int ...d\mu : \mathcal{L}^1(\mu) \to \mathbb{R},\ \ u \mapsto \int u d\mu, \tag{12}$$

is a ***positive linear functional****.*

11 Null sets and the "Almost Everywhere"

Definition 11.0.1. A (μ-)null set $N \in \mathcal{N}_\mu$ is a measurable set $N \in \mathscr{A}$ satisfying

$$N \in \mu \Leftrightarrow N \in \mathscr{A} \text{ and } \mu(N) = 0. \tag{13}$$

This can be used generally about a 'statement' or 'property', but we will be interested in questions like 'when is $u(x)$ equal to $v(x)$', and we answer this by saying

$$u = v \ a.e. \Leftrightarrow \{x : u(x) \neq v(x)\} \text{ is (contained in) a } \mu\text{-null set.}, \tag{14}$$

i.e.

$$u = v \ \ \mu\text{-a.e.} \Leftrightarrow \mu\left(\{x : u(x) \neq v(x)\}\right) = 0. \tag{15}$$

The last phrasing should of course include that the set $\{x : u(x) \neq v(x)\}$ is in $\mathscr{A}$, but this can be trivially seen.

Theorem 11.1. *Let $u \in \mathcal{M}_{\overline{\mathbb{R}}}(\mathscr{A})$, then:*

(i) $\int |u| d\mu = 0 \Leftrightarrow |u| = 0 \ a.e. \ \Leftrightarrow \mu\{u \neq 0\} = 0$,

(ii) $\mathbb{1}_N u \in \mathcal{L}^1_{\overline{\mathbb{R}}}(\mu) \ \ \forall \ N \in \mathcal{N}_\mu$,

(iii) $\int_N u d\mu = 0$.

Corollary 11.2. *Let* $u = v$ *μ-a.e. Then*

(i) $u, v \geq 0 \Rightarrow \int u d\mu = \int v d\mu$,

(ii) $u \in \mathcal{L}^1_{\overline{\mathbb{R}}}(\mu) \Rightarrow v \in \mathcal{L}^1_{\overline{\mathbb{R}}}(\mu)$ *and* $\int u d\mu = \int v d\mu$.

Corollary 11.3. *If* $u \in \mathcal{M}_{\overline{\mathbb{R}}}(\mathscr{A})$, $v \in \mathcal{L}^1_{\overline{\mathbb{R}}}(\mu)$ *and* $v \geq 0$ *then*

$$|u| \leq v \ a.e. \ \Rightarrow u \in \mathcal{L}^1_{\overline{\mathbb{R}}}(\mu). \tag{16}$$

Proposition 11.4 (Markow inequality)**.** *For all* $u \in \mathcal{L}^1_{\overline{\mathbb{R}}}(\mu)$, $A \in \mathscr{A}$ *and* $c > 0$

$$u\left(\{|u| \geq c\} \cap A\right) \leq \frac{1}{c} \int_A |u| d\mu, \tag{17}$$

if $A = X$*, then (obviosly)*

$$u\left\{|u| \geq c\right\} \leq \frac{1}{c} \int |u| d\mu. \tag{18}$$

Corollary 11.5. *If* $u \in \mathcal{L}^1_{\overline{R}}(\mu)$*, then* μ *is a.e.* $\mathbb{R}$*-vaued. In particular, we can find a version* $\tilde{u} \in \mathcal{L}^1(\mu)$ *s.t.* $\tilde{u} = u$ *a.e. and* $\int \tilde{u} d\mu = \int u d\mu$