



# Simplex Control and Message/ACK Exchange

- Module 6 Final Presentation

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# Outline

- Purpose
- Data Transmission in the MAC Layer
  - Building the MAC Frame
  - State Machine for the Frame Transmission
  - ACK Timeout
  - Other Features Considered
- Implementation
- Interfacing with the other Modules
- ‘End-to-End’ Simulation of Data Transmission and ACK Response
- Lessons Learned

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# Purpose

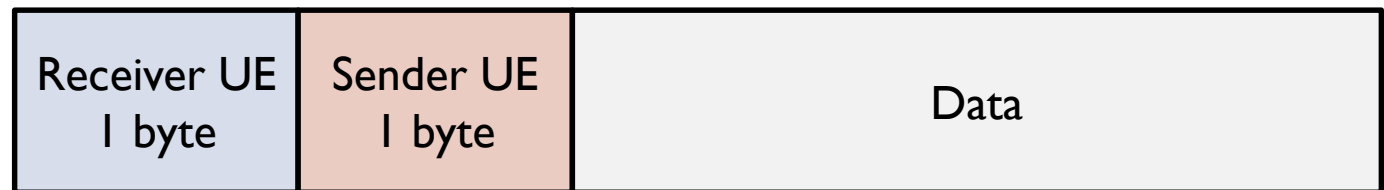
- Establishing end-to-end network resource allocation management in simplex mode.
- Exchanging of control information and message/ACK forwarding between the UEs and the BS units.

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# Building the MAC Frame

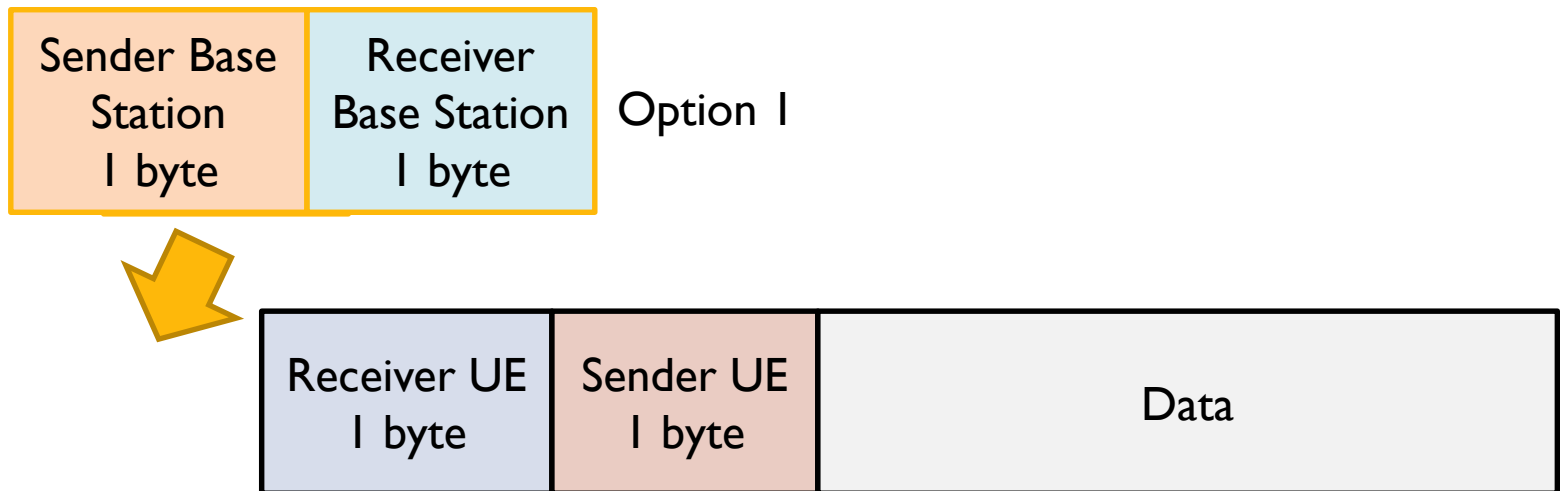
- The package format must be small enough that it is easy to handle
- It must also convey useful information
  - Receiver UE
  - Sender UE
  - Data



# Building the MAC Frame

## The Routing between Base Stations:

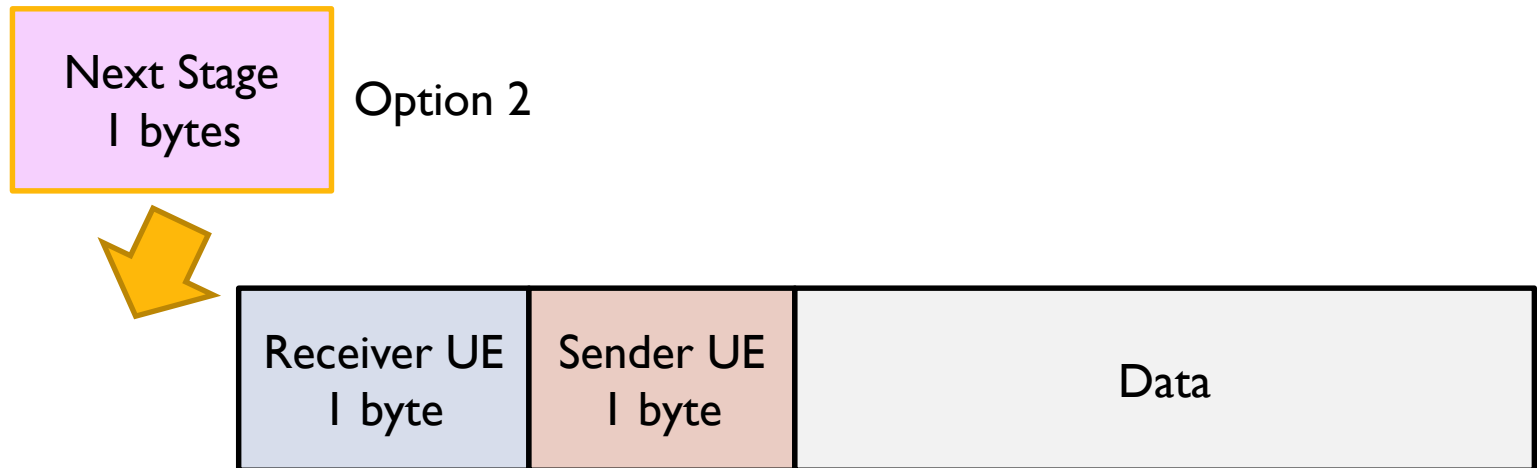
- Transmit the entire routing path
  - This is very long
  - It requires additional processing at the Base Station



# Building the MAC Frame

## The Routing between Base Stations:

- Transmit the next stage in the path
  - The Base Station must change the value of this field every time

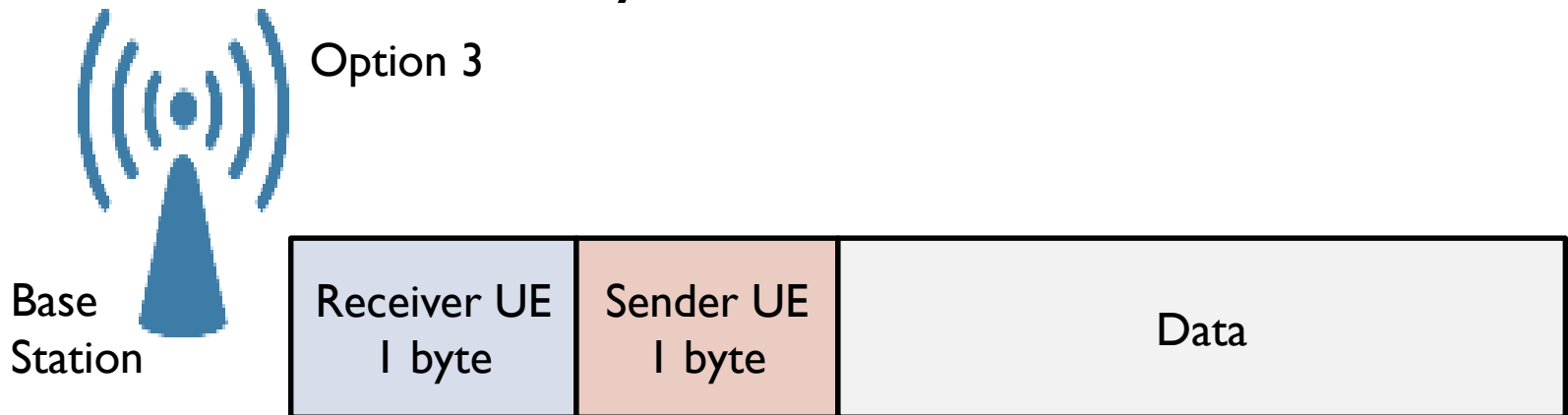




# Building the MAC Frame

## The Routing between Base Stations:

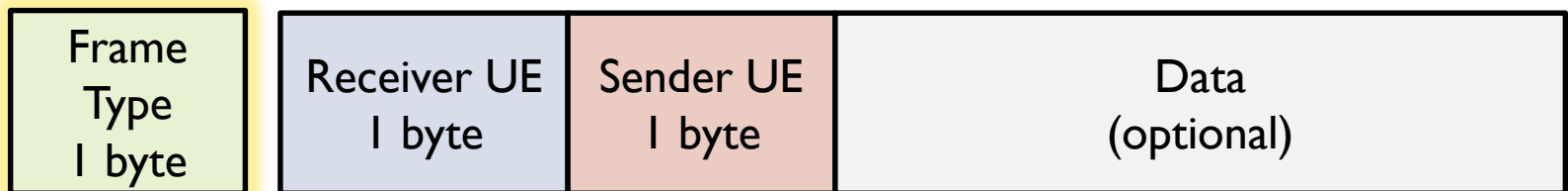
- Read the receiver at the Base Station and determine the routing to destination
  - Easy to understand
  - The header stays small



# Building the MAC Frame

## Frame Type:

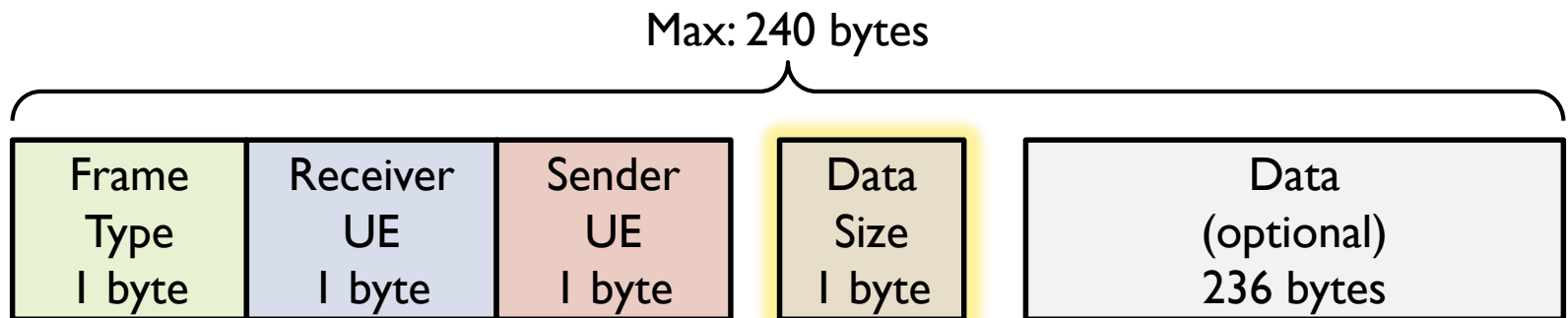
- Differentiates between the uses of the MAC frames
- The INVALID frame type is used to drop corrupt frames
- Also helps with error detection through hamming distance
  - DATA      1111 0000 = 240
  - ACK        1111 1111 = 255
  - INVALID 0000 0000 = 0



# Building the MAC Frame

## Data Size:

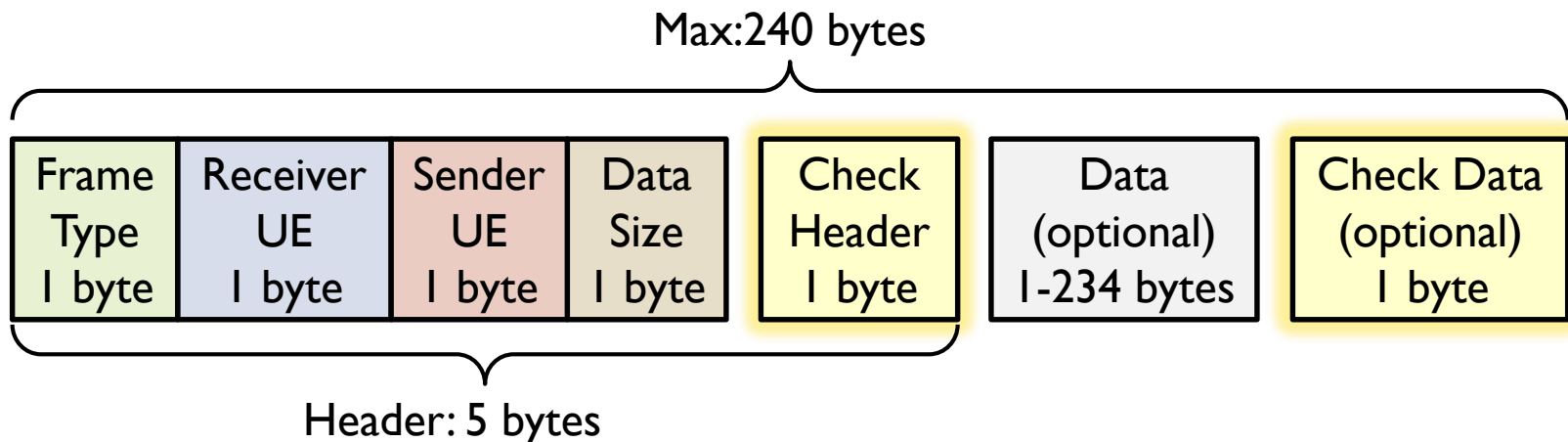
- Set a maximum size for all MAC frames of 240 bytes or 1920 bits
- Transmitting the data size allows us to cut off padding added by the physical layers



# Building the MAC Frame

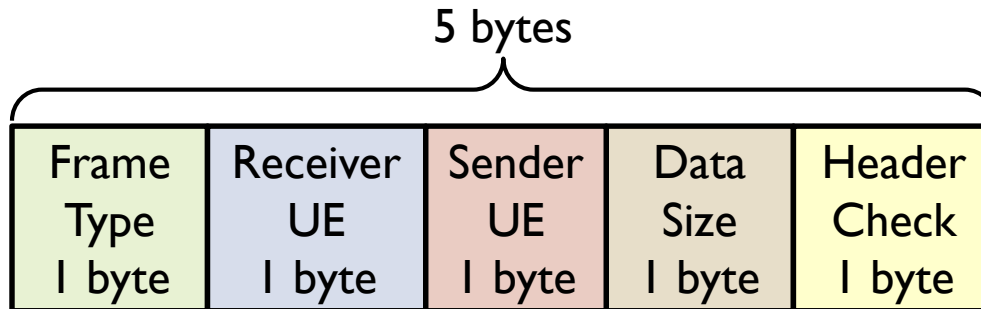
## CRC:

- We must be sure that the Data is transmitted without errors
- CRC-8 to check the integrity of the bits
  - simple and fast but does not correct errors.
- Team 4 needs to be sure that the header is correct

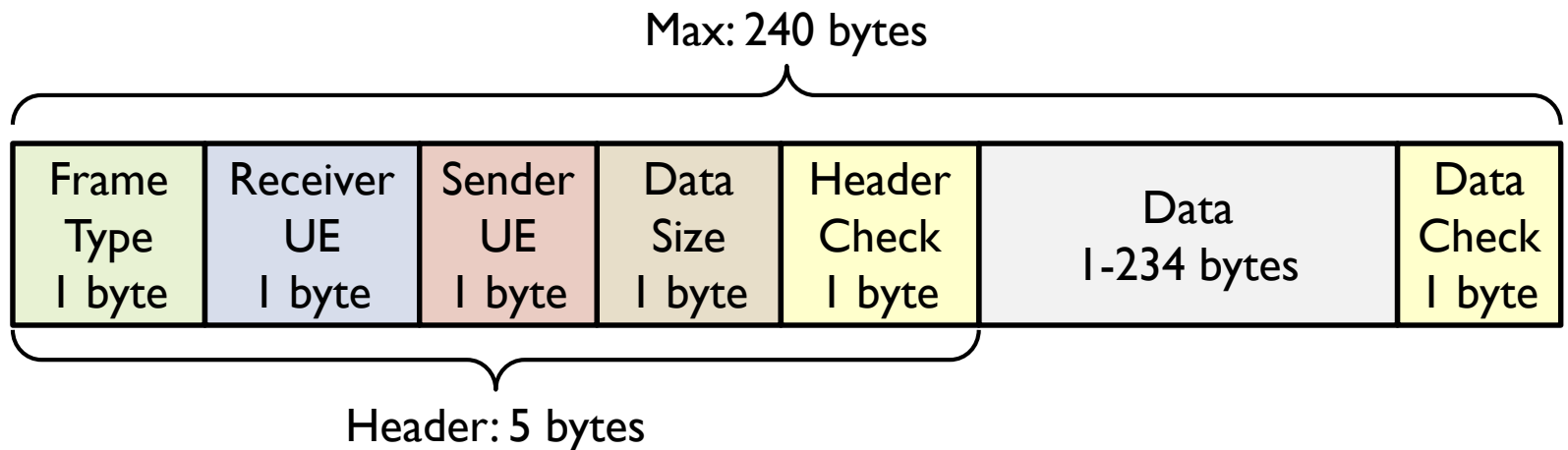


# Building the MAC Frame

## ACK Frame:



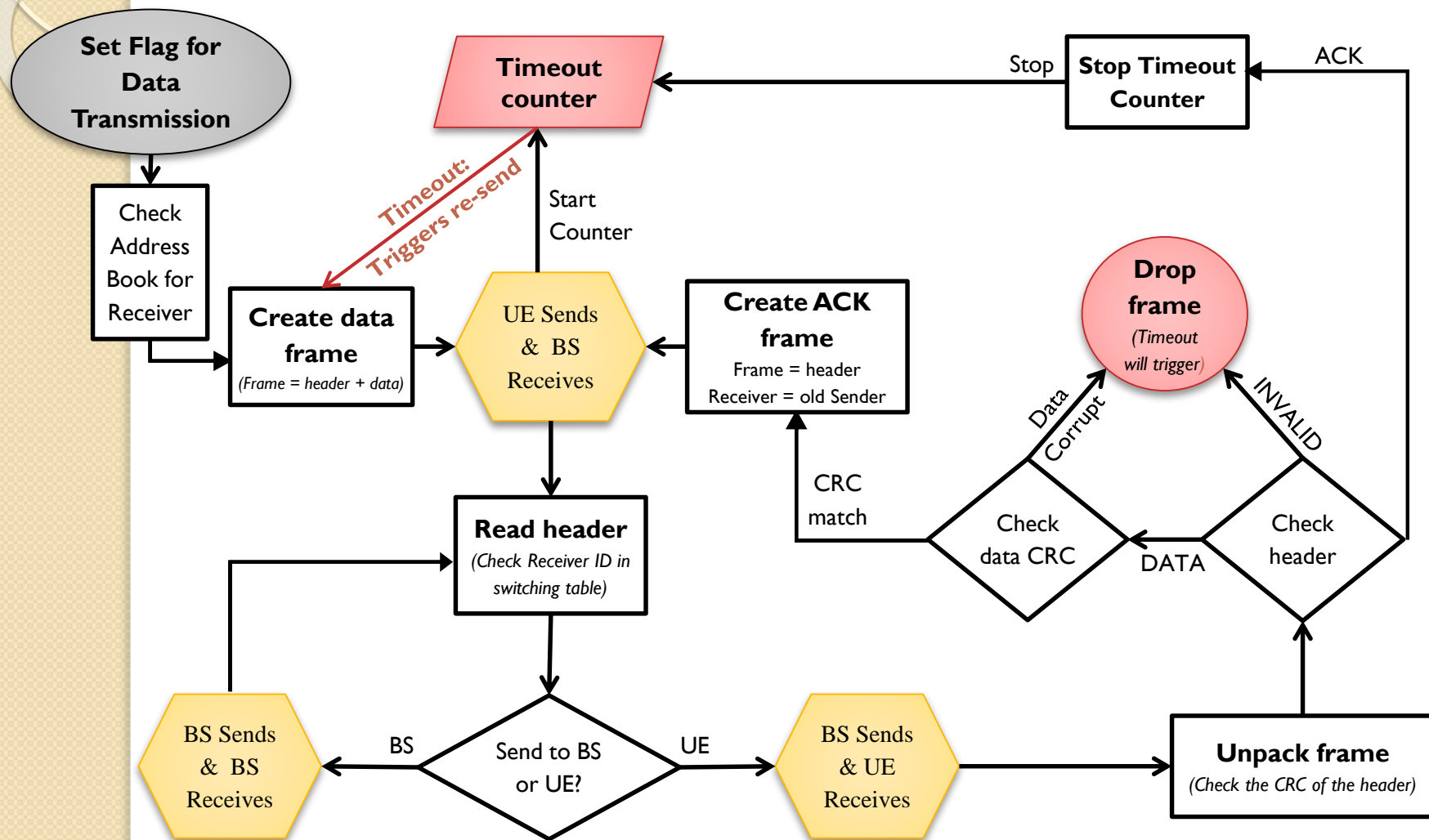
## Data Frame:



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# State Machine for Frame Transmission



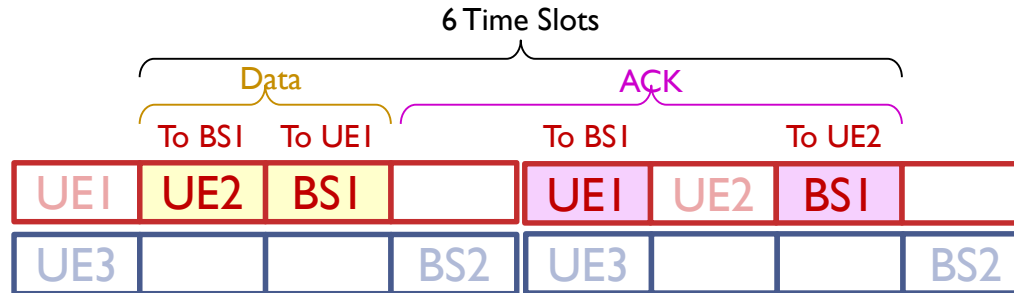
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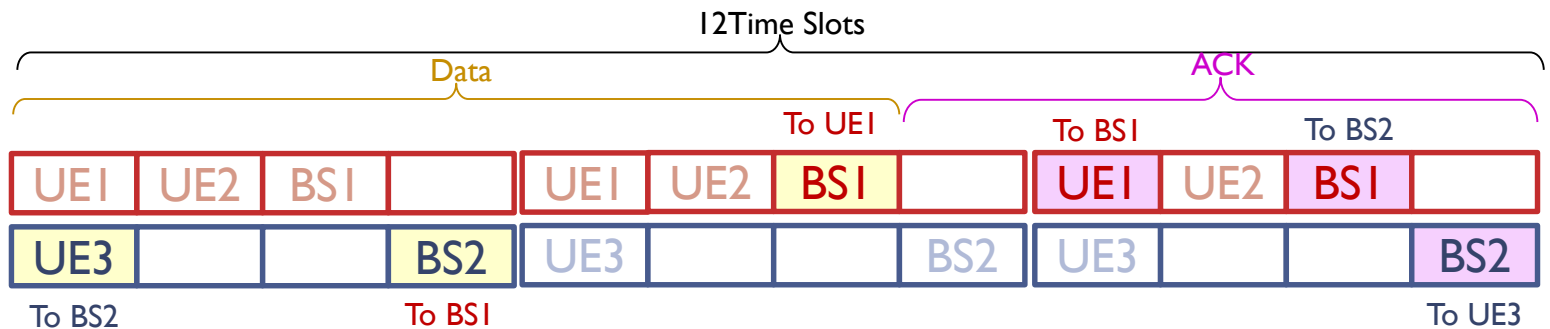


# ACK Time Out

Shortest message  
UE2 to UE1



Longest message  
UE3 to UE1



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# Other Features Considered

- Sequence number
  - Sliding window
  - Group ACK
- NACK

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# Implementation Constructor

Constructor  
method

```
function obj = FrameObj(inputType,inputrcvID,inputsndID,inputData)

    % create a FrameObj with 4 inputs from the frame requirements
    if nargin == 4
        obj.classUse = inputType;
        %test if the frame type is valid
        obj.frameType = inputType;
        obj.rcvID = inputrcvID;
        obj.sndID = inputsndID;
        obj.data = inputData;

    %create a FrameObj with 1 array of bits
    elseif nargin == 1
```

Verification of the  
number of inputs

# Implementation Constructor

Check for the  
minimum size

CRC check the  
header.

Failed checks result  
in INVALID frame  
types

```
elseif nargin == 1
    %Not sure if we need to do this. It might just be a
    %reminder that inputType is not the data that is being used
    %by the class properties in this case.
    bitwise = inputType;

    %size check
    [size_in, ~] = size(bitwise);
    if (size_in >= 40)
        % hCRC check

        % needed for the crc calculation
        hDetect = comm.CRCDetector([8 7 6 4 2 0]);
        % detects if there is an error in the CRC of the header
        [~, err] = step(hDetect, bitwise(1:5*8,1));

        if (err ==0)
            obj.classUse = bitwise;

            %We are actually converting the array of bits here
            %and then passing the pretty decimal numbers we get
            %to the propertyfunctions.
            obj.frameType = bi2de(bitwise(1:8,1)', 'left-msb');
            obj.rcvID = bi2de(bitwise(1+8:2*8,1)', 'left-msb');
            obj.sndID = bi2de(bitwise(1+2*8:3*8,1)', 'left-msb');

            %Whether there is data or not depends on frameType.
            %The location of data in the frame is dependent on
            %dataSize so we pass the unaltered FrameObj input
            %to obj.data
            obj.data = bitwise;
        else
            % the crc does not match and the header is junk
            obj.frameType = FrameObj.INVALID;
        end
    else
        % the data we recdived is not long enough to check the
        % header crc
        obj.frameType = FrameObj.INVALID ;
    end
end
```

# Implementation

## Data field

Maximum size of  
data field

Mapping chars to  
bits

Creation of CRC

```
function obj = set.data(obj,datainput)
    %These variables mean we can vary the size of MAXBYTES or the
    %header without and data will still be functional.
    header_bits = (FrameObj.MAXBYTES-(FrameObj.MAXDATA+1))*8;
    max_data_bits = FrameObj.MAXDATA*8;
    switch obj.frameType
        case FrameObj.DATAFRAME %DATA
            if obj.classUse == FrameObj.ENCODE;
                %This converts the datainput into an array of bits
                temp_bin = reshape(dec2bin(datainput,8)',1,[]);

                %Define the length of temp_data for speed
                % the length of temp_data is limited by MAXBYTES
                if size(temp_bin,2)>=max_data_bits
                    temp_data = zeros(1,max_data_bits);
                else
                    temp_data = zeros(1,size(temp_bin,2));
                end

                for j=1:size(temp_data,2)
                    temp_data(1,j) = str2num(temp_bin(1,j));
                end

                crcGen = comm.CRCGenerator([8 7 6 4 2 0]);

                %Calculates the CRC and adds it to the end of data
                obj.data = step(crcGen, temp_data');

            elseif obj.classUse == FrameObj.DECODE;
```

# Implementation

## Data field

Extract the data size

The dimensions of the input limit the data size

Maximum size of data field

```
elseif obj.classUse == FrameObj.DECODE;
    data_bits = size(datainput, 1)-header_bits -8;
    %This separates the data from the rest of the array
    %using dataSize.

    %First separate dataSize then convert to decimal
    %Cast to double and convert from bytes to bits
    Temp = bi2de(datainput(1+3*8:4*8,1),'left-msb');
    ds = double(Temp*8);

    %This allows FrameObj to not exceed the dimensions
    %of inputdata in case the dataSize was corrupted to
    %be or larger than the length of the input array
    %and passed the hCRC.
    if ds >= data_bits
        ds = data_bits
    end
    % or larger than MAXDATA
    if ds >= max_data_bits
        ds = max_data_bits
    end

    %Separate data using the start of the data and the
    %length+crc
    bits = datainput(header_bits+1:header_bits+ds+8,1);
    %cast to double
    obj.data = double(bits);
end
```



# Implementation

## Receiving a Frame

Check the  
FrameType

Verify the data CRC

Create only one  
ACK to send back

Drop INVALID  
Frame

```
receivedFrame = FrameObj(frame_array');
if(receivedFrame.frameType == FrameObj.DATAFRAME)
    Numdata=Numdata+1;
    hDetect = comm.CRCDetector([8 7 6 4 2 0]);
    receivedFrame.sndID;
    [~, err] = step(hDetect, receivedFrame.data);
    if(err == 0)
        %create ACK package
        %switch the role of send and received of the received package
        % the received ID is now the send ID
        if(ackToTransmit == 0)

            frameOut = FrameObj(FrameObj.ACKFRAME,receivedFrame.sndID,receivedFrame.rcvID,0);
            ackToTransmit = 1;
            status = FrameObj.CRCOK;

        end

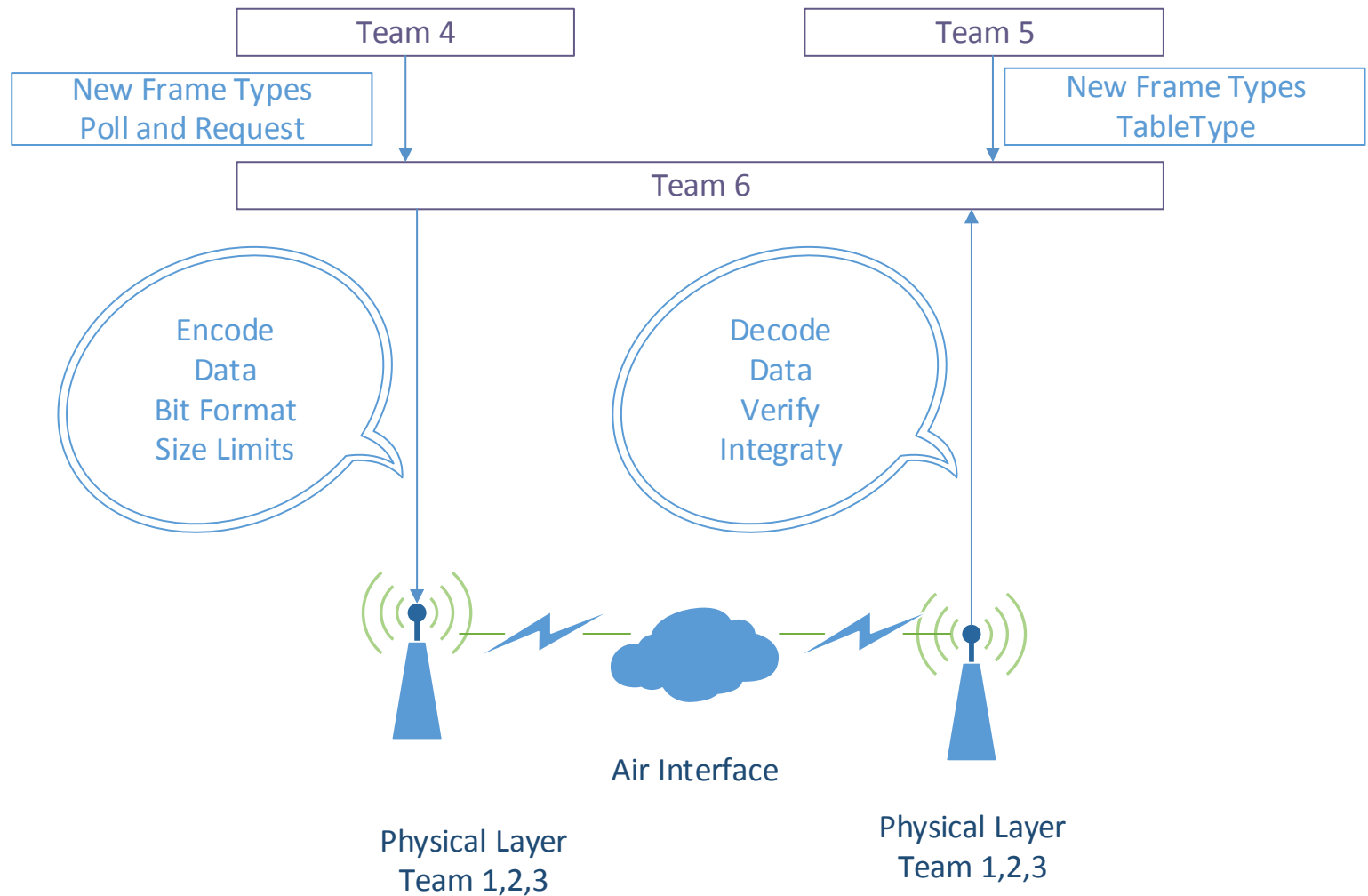
        Numrightdata=Numrightdata+1;
    else
        frameOut = 0;
        status = FrameObj.CRCFAIL;
        Numwrongdata=Numwrongdata+1;
    end
elseif (receivedFrame.frameType == FrameObj.ACKFRAME)

    frameOut = 0 ;
    status = FrameObj.ACKRECEIVED ;
    Numack=Numack+1;
elseif (receivedFrame.frameType == FrameObj.INVALID)
    Numinvalidframe=Numinvalidframe+1;
end
```

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# Interfacing Diagram



# Interfacing with the Physical Modules

- Teams 1, 2 & 3
  - Format of the bits that are generated by FrameObj
    - Length of the frame
    - Order of the bits
  - How to exchange data between the layers
    - Flags to indicate new messages
    - Callbacks
- Team 3
  - Additional processing to route the message

# Interfacing with the Network Modules

- Team 4
  - The ACK frame is reused
  - The same basic frame construction is used
    - Polling Frame
    - Request Frame
- Team 5
  - The address table determines which physical resource will route the frames.
  - The same basic frame construction is used
    - Table Frame

# FrameType Functionality

## Data Transmission with Transceiver from Lab 2

Frame Type	Number Received
ACKFRAME	2
DATAFRAME	102 <ul style="list-style-type: none"><li>• Correct CRC</li><li>• Corrupt CRC</li></ul>
INVALID	3466



False Detection of ACK frame because similar frameType numeric representation.

Frame Type	Number Received
ACKFRAME	0
DATAFRAME	165 <ul style="list-style-type: none"><li>• Correct CRC</li><li>• Corrupt CRC</li></ul>
INVALID	3559

We increased the hamming distance between the values of the types of frames to avoid false detection

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# ‘End-to-End’ Simulation of Data Transmission and ACK Response Using Team 4’s Transceiver



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# Lessons Learned

- The Physical layer is very important, we cannot compensate for unreliable data transmission.
- We can accommodate erroneous data through verifying the data range and considering possible received values
- Hamming distance of the frame type are very important
- More data types are needed for the control messages in the system than for transmitting data.