easy decision trees in or the Excel user

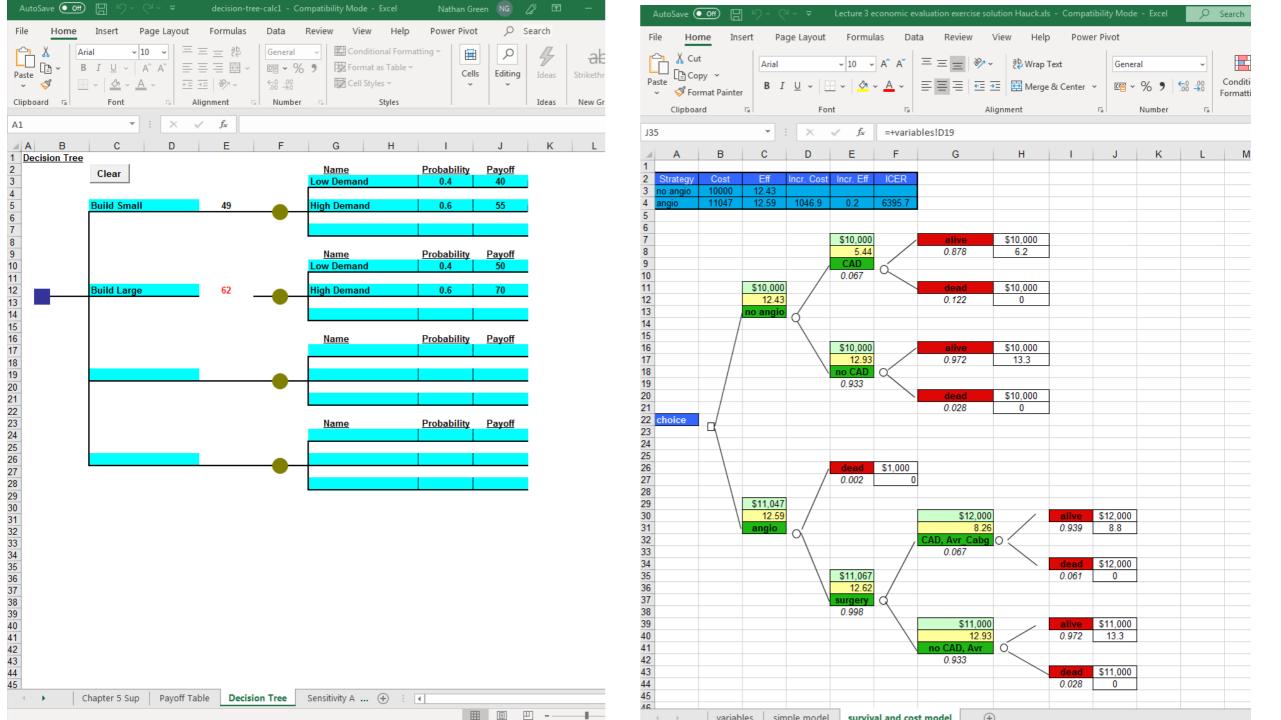
Nathan Green

Imperial College London
9th July 2019

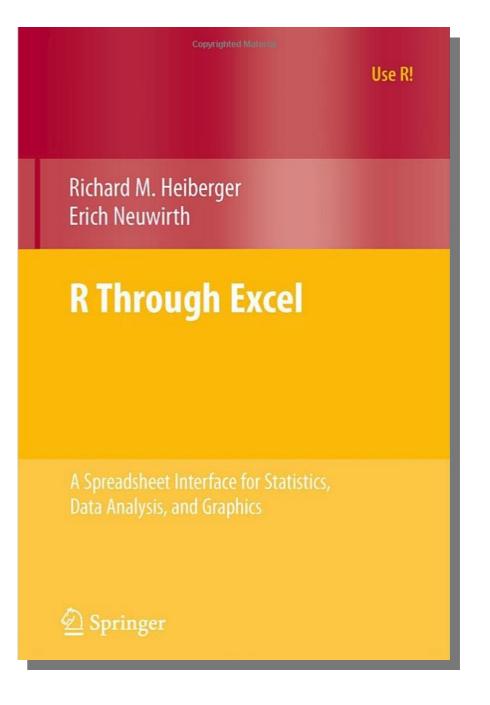
What are decision trees?

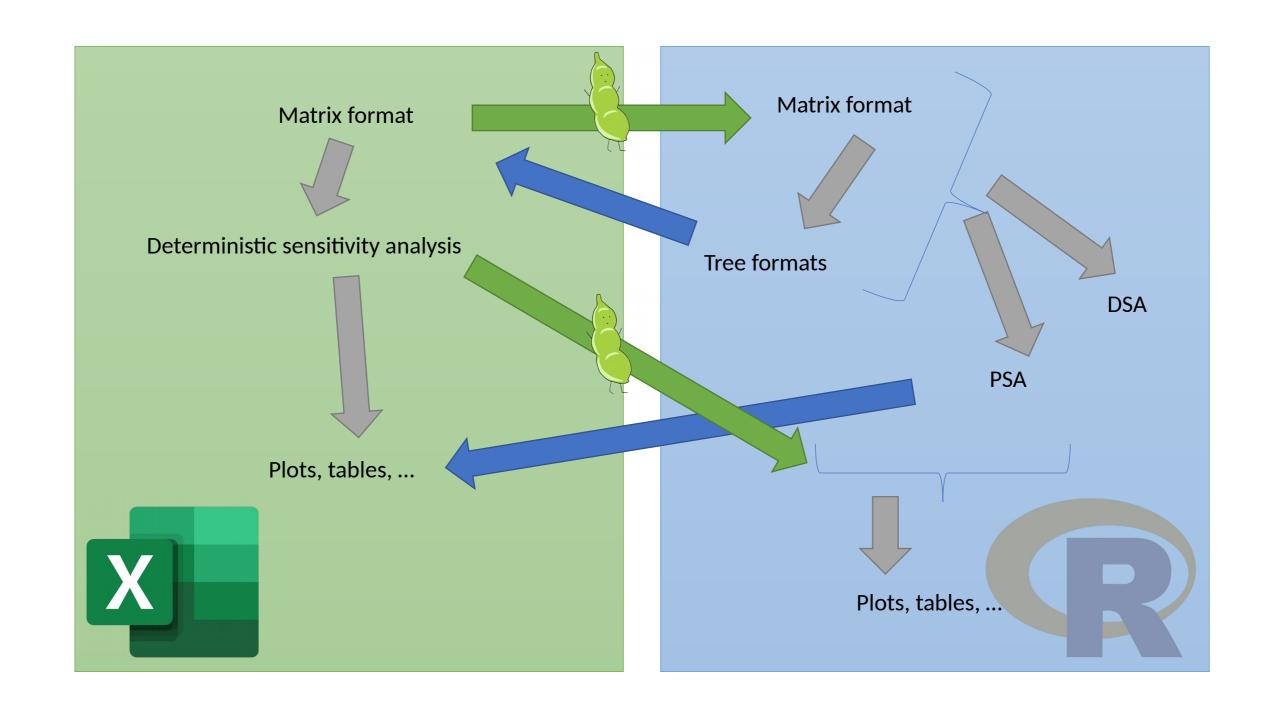
- Can't see the trees for the forest; No, not those decision trees!
- Diagrammatic representations of decision analysis process
- Decisions are square nodes, a point where several alternatives are possible.
- A *chance node*, typically represented by a circle, is a point in a decision tree where chance determines which event will occur.
- The sum of probabilities for all branches emanating from a chance node must equal 1, because one of the events must occur.





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CEdecisiontree



An R package for lightweight cost-effectiveness analysis using decision trees.

Requests and comments welcome; please use Issues.

Installing CEdecisiontree

To install the development version from github:

```
library(devtools)
install_github("Health-Economics-in-R/CEdecisiontree")
```

Then, to load the package, use:

library(CEdecisiontree)

Motivation

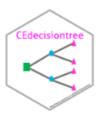
Decisions trees can be modelled as special cases of more general models using available packages in R e.g. heemod, mstate or msm. Further, full probabilty models could be fit using a Bayesian model with e.g. jags or WinBUGS. However, simple decision tree models are often built in Excel, using statistics from literature or expert knowledge. This package is a analogue to these, such that models can be specified in a very similar and simple way.

Calculation

A decision tree is defined by parent-child pairs, i.e. from-to connections, and the probability and associated value (e.g. cost) of traversing each of the connections. Denote the probability of transitioning from node i to j as p_{ij} and the cost attributable to node i as c_i . Where no connection exists between two nodes we shall say that the parent's set of children is the empty set \emptyset . Denote the set of children by $child(\cdot)$. Clearly, there are no p_{ij} or c_j in this case but for computational purposes we will assume that $p_{ij} = NA$ and $c_j = 0$.

The expected value at each node $i \in S$ is calculated by 'folding back' using the recursive formula

$$\hat{c}_i = c_i + \sum_{j \in child(i)} p_{ij}\hat{c}_j$$



Expected cost formula

A decision tree is defined by parent-child pairs, i.e. from-to connections, and the probability and associated value (e.g. cost) of traversing each of the connections. Denote the probability of transitioning from node i to j as p_{ij} and the cost attributable to node i as c_i . Where no connection exists between two nodes we shall say that the parent's set of children is the empty set \emptyset . Denote the set of children by $child(\cdot)$. Clearly, there are no p_{ij} or c_j in this case but for computational purposes we will assume that $p_{ij} = NA$ and $c_j = 0$.

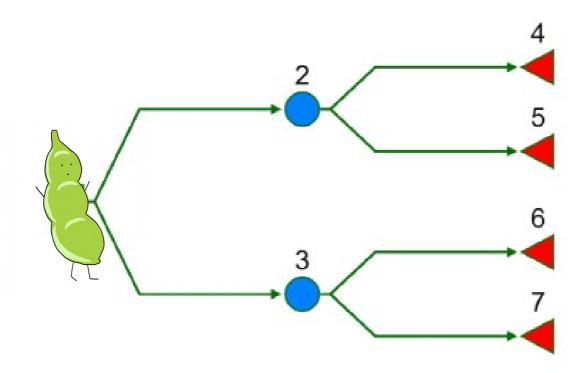
The expected value at each node $i \in S$ is calculated by 'folding back' using the recursive formula

$$\hat{c}_i = c_i + \sum_{j \in child(i)} p_{ij} \hat{c}_j$$

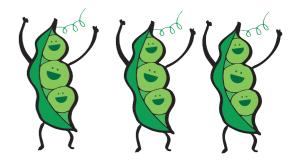
with boundary values at the terminal nodes

$$\hat{c}_i = c_i \text{ for } i = \{S : child(s) = \emptyset\}.$$

Example







9. Smart data structures and dumb code works a lot better than the other way around.

12. Often, the most striking and innovative solutions come from realizing that your concept of the problem was wrong.

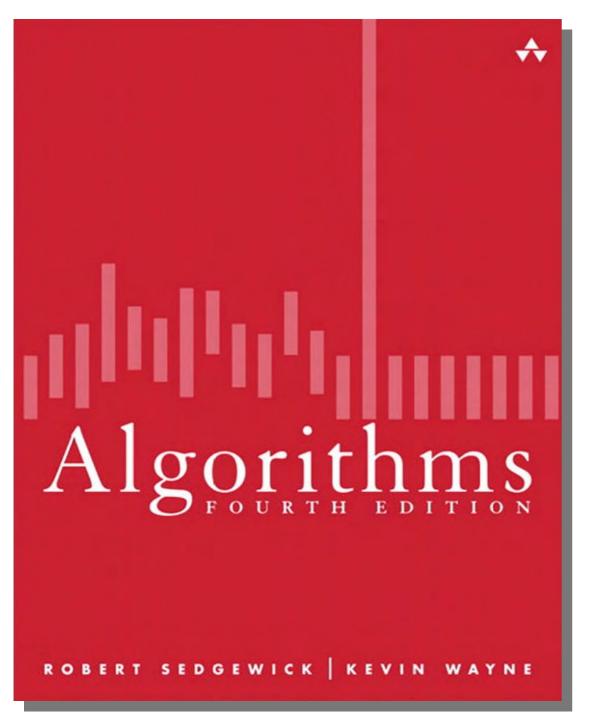
"The most important book about technology today, with implications that go far beyond programming.

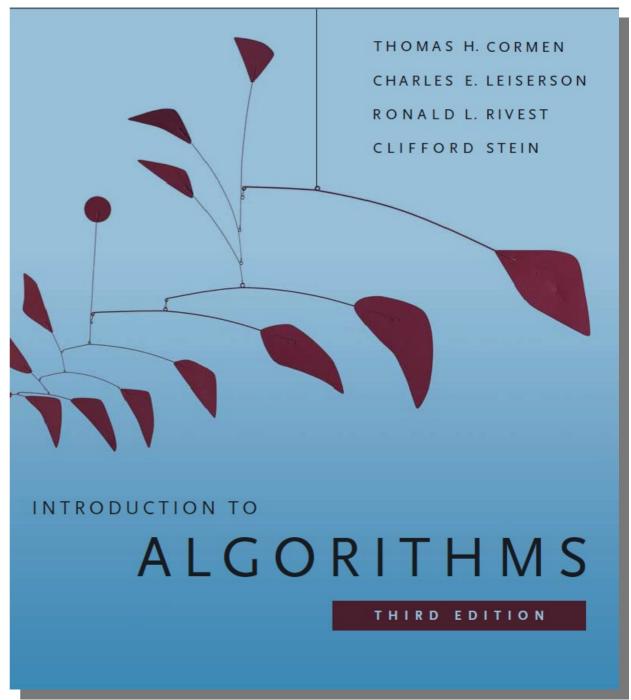
THE CATHEDRAL & THE BAZAAR

MUSINGS ON LINUX AND OPEN SOURCE
BY AN ACCIDENTAL REVOLUTIONARY

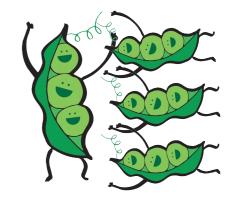


ERIC S. RAYMOND





Data structures



- A way to store and organize data in order to facilitate access and modifications
- No single data structure works well for all purposes, and so it is important to know the strengths and limitations of several of them
- Dynamic programming
 - Allows for divide and conquer recurrence
 - Essentially a trade-off of space for time
 - Repeatedly recomputing a given quantity is harmless unless the time spent doing so becomes a drag on performance then better off storing the results of the initial computation and looking them up instead of recomputing them again.
 - E.g. Fibonacci numbers, Binomial coefficients

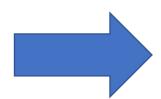
Data formats: long array

```
probs long <-
 probs %>%
 mutate('from' = rownames(.)) %>%
 melt(id.vars = "from",
      variable.name = 'to',
      value.name = 'prob') %>%
 na.omit()
cost long <-
 cost %>%
  mutate('from' = rownames(.)) %>%
 melt(id.vars = "from",
      variable.name = 'to',
      value.name = 'cost') %>%
 na.omit()
dat long <-
 merge(probs_long,
       cost_long)
```



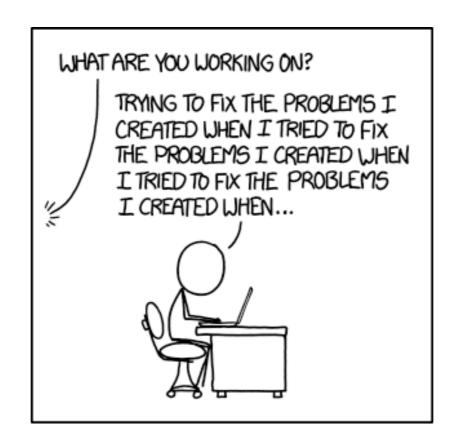


Data format: parent-child str



```
tree
#> $\1\
#> [1] 2 3
#> $^2^
#> [1] 4 5
#> $\3\
#> [1] 6 7
#>
#> $`4`
#> NULL
#>
#> $\^5\
#> NULL
#> $`6`
#> NULL
#> $^7^
#> NULL
dat
    node prob vals
       2 0.2 10
     3 0.8
     4 0.2 10
       6 0.2
#> 7 0.8 1
```

Why tree data structure?



Why tree data structure?

From this

```
for (i in num_from_nodes:1) {
 total <- 0
 for (j in 1:num_to_nodes) {
    if (!is.na(p[i,j])) {
      total <- total + p[i,j]*c_hat[j]
  c_hat[i] <- total + c_hat[i]</pre>
```

Why tree data structi

From this To this:

```
for (i in num_from_nodes:1) {
   total <- 0
   for (j in 1:num_to_nodes) {
      if (!is.na(p[i,j])) {
        total <- total + p[i,j]*c_hat[j] }
      }
      c_hat[i] <- total + c_hat[i]
}</pre>
```

```
if (is.na(node)) {
  return(0)
c_node <- dat$vals[dat$node == node]</pre>
child <- tree[[node]]</pre>
if (is.null(child)) {
  return(c_node)
} else {
  pL <- dat$prob[dat$node == child[1]]
  pR <- dat*prob[dat*node == child[2]]
  if (any(is.na(pL))) pL <- 0
  if (any(is.na(pR))) pR <- 0
  return(c_node +
           pL*dectree_expected_recursive(child[1], tree, dat) +
           pR*dectree expected recursive(child[2], tree, dat))
```

Function dispatch: S3

3 3 NA NA

```
model tree <-
 define model(tree dat =
                list(child = list("1" = c(2, 3),
                                  "2" = NULL,
                                  "3" = NULL),
                     dat = data.frame(node = 1:3,
                                      prob = c(NA, 0.5, 0.5),
                                      vals = c(0, 1, 2)
                ))
model tree
#> $child
#> $child$`1`
#> [1] 2 3
#>
#> $child$`2`
#> NULL
#>
#> $child$'3'
#> NULL
#>
#> $dat
#> node prob vals
      2 0.5 1
      3 0.5 2
#>
#> attr(,"class")
#> [1] "tree_dat" "list"
```

Deterministic sensitivity analysis

```
str(tree_dat_sa, 1)
#> List of 9
#> $ :List of 2
#> ..- attr(*, "class")= chr [1:2] "tree_dat" "list"
#> $ :List of 2
#> ..- attr(*, "class")= chr [1:2] "tree_dat" "list"
#> $ :List of 2
#> ..- attr(*, "class")= chr [1:2] "tree dat" "list"
#> $ :List of 2
#> ..- attr(*, "class")= chr [1:2] "tree dat" "list"
#> $ :List of 2
#> ..- attr(*, "class")= chr [1:2] "tree dat" "list"
#> $ :List of 2
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#> $ :List of 2
#> ..- attr(*, "class")= chr [1:2] "tree_dat" "list"
#> $ :List of 2
#> ..- attr(*, "class")= chr [1:2] "tree_dat" "list"
#> $ :List of 2
#> ..- attr(*, "class")= chr [1:2] "tree dat" "list"
```

Probabilistic sensitivity analysis (PSA)



Probabilistic sensitivity analysis

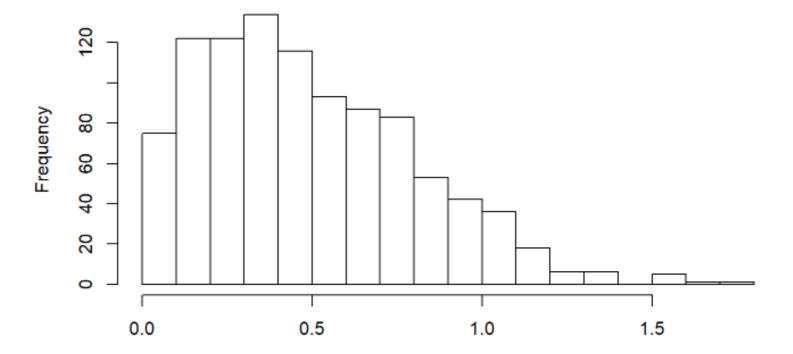


List columns (see Jenny Brian and purrr package)

```
head(tree_dat_sa, 2)
#> [[1]]
#> $child
#> $child$`1`
#> [1] 2 3
#>
#> $child$`2`
#> NULL
#> $child$`3`
#> NULL
#>
#>
#> $dat
#> node
              prob
                      vals
             NA 0.0000000
#> 2 2 0.08081289 0.3373387
#> 3 0.93112888 0.7653589
#>
#> attr(,"class")
#> [1] "tree_dat" "list"
#> [[2]]
#> $child
#> $child$`1`
#> [1] 2 3
#>
#> $child$`2`
#> NULL
#>
#> $child$`3`
#> NULL
#>
#>
#> $dat
#> node
            prob vals
#> 1 1
             NA 0.00000000
     2 0.200610 0.5994206
#> 3 0.219152 0.8655122
#>
#> attr(,"class")
#> [1] "tree dat" "list"
```

```
res <- map_dbl(tree_dat_sa, dectree_expected_values)
head(res)
#> [1] 0.7399091 0.3099285 0.7204631 0.4817292 0.7451696 0.7709943
hist(res, breaks = 20)
```

Histogram of res



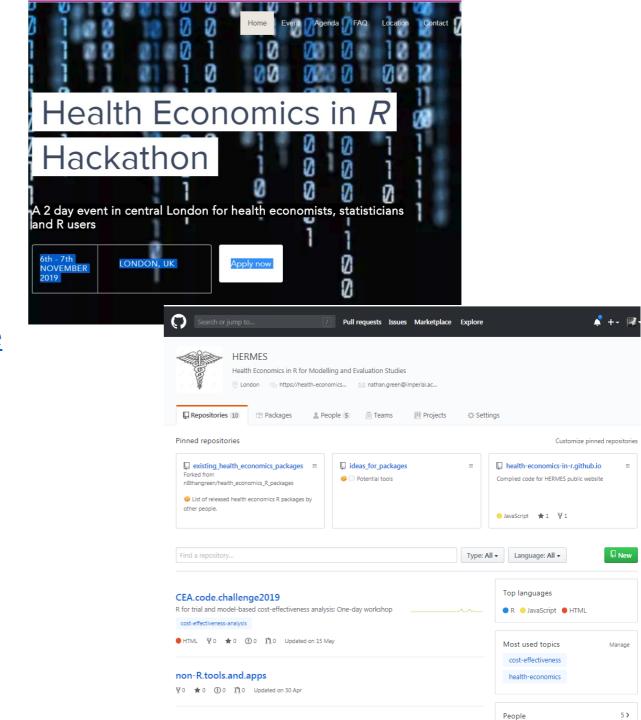
Future

data.tree package

#>	levelNa	me distn	max	min	р	scale	shape	type	
#> 1	LTBI screening cost	unif	0.00		1.00000	NA	NA	logical	
#> 2	¦(0,50]	unif	0.00	0.00	0.00000			chance	
#> 3	LTBI	unif	0.00	0.00	0.03000			chance	
#> 4	Not Agree to Screen	unif	0.00	0.00	0.40000			terminal	
#> 5	°Agree to Screen	unif	106.00	50.00	0.60000			chance	
#> 6	1-Sensitivity	unif	0.00	0.00	0.16000			terminal	
#> 7	°Sensitivity	unif	0.00	0.00	0.84000			chance	
#> 8	Not Start Treatment	unif	0.00	0.00	0.30000			terminal	
#> 9	°Start Treatment	unif	0.00	0.00	0.70000			chance	
#> 10	Symptoms Hepatotoxicity	gamma	NA	NA	0.00245	87.889	6.679	chance	
#> 11	¦ ¦Symptoms Nausea	gamma	NA	NA	0.14300	13	5	chance	
#> 12	Complete Treatment	unif	842.45	511.69	0.80000			chance	
#> 13		unif	0.00	0.00	0.90000			terminal	
#> 14	°Not Effective	unif	0.00	0.00	0.10000		terminal		
#> 15		nt unif	140.41	85.24	0.20000		terminal		
#> 16	°Not Symptoms Nausea	unif	0.00	0.00	0.85700			chance	
#> 17	Complete Treatment	unif	842.45	511.69	0.80000			chance	
#> 18	Effective	unif	0.00	0.00	0.90000			terminal	
#> 19	°Not Effective	unif	0.00	0.00	0.10000			terminal	
#> 20	' °Not Complete Treatme	nt unif	140.41	85.24	0.20000			terminal	
#> 21	' °Not Symptoms Hepatotoxicity	unif	0.00	0.00	0.99755			chance	
#> 22	Symptoms Nausea	gamma	NA	NA	0.14300	13	5	chance	
#> 23	Complete Treatment	unif	842.45	511.69	0.80000			chance	
#> 24	Effective	unif	0.00	0.00	0.90000		terminal		
#> 25	°Not Effective	unif	0.00	0.00	0.10000		terminal		
#> 26	°Not Complete Treatme		140.41	85.24	0.20000		terminal		
#> 27	¦ ¦ °Not Symptoms Nausea	unif	0.00	0.00	0.85700		chance		
#> 28				511.69	0.80000		chance		
#> 29	Effective	unif		0.00	0.90000		terminal		
#> 30	°Not Effective	unif			0.10000			terminal	
#> 31	°Not Complete Treatme	nt unif	140.41	85.24	0.20000			terminal	

Future

- Hackathon!
 - 6th-7th November 2019 @ Imperial College London
 - https://n8thangreen.wixsite.com/he rmes-hack-london
- GitHub organisation (HERMES)



PEAS G

- How to become a Hacker
- The Hacker Attitude
- 1. The world is full of fascinating problems waiting to be solved.
- 2. No problem should ever have to be solved twice.
- 3. Boredom and drudgery are evil.
- 4. Freedom is good.
- 5. Attitude is no substitute for competence.

Comparison with heemod

```
state 1 <- define state(</pre>
  cost total = 0,
  qalv = 0
state 2 <- define state(</pre>
  cost total = 10,
 qaly = 1)
state 3 <- define state(
  cost total = 1,
  qaly = 1)
state 4 <- define state(
  cost total = 10,
  qaly = 1)
state_5 <- define_state(</pre>
  cost_total = 1,
  qaly = 1)
```

```
state 6 <- define state(
 cost total = 10,
 qaly = 1)
state 7 <- define state(
 cost total = 1,
 qaly = 1)
state 8 <- define state(
 cost total = 0,
 qaly = 0
strat base <- define strategy(
 transition = mat base,
 "1" = state 1,
 "2" = state 2,
 "3" = state 3,
 "4" = state 4,
 "5" = state 5,
 "6" = state 6,
 "7" = state 7,
 "8" = state 8
```

```
run model(
 strat base,
 cycles = 100,
 cost = cost total,
 effect = qaly)
#> No named model -> generating names.
#> 1 strategy run for 100 cycles.
#> Initial state counts:
\#>1=1000L
\#>2=0L
\# > 3 = 0L
\#>4=0L
\# > 5 = 0L
#> 6 = 0L
#> 7 = 0L
\# > 8 = 0L
#> Counting method: 'life-table'.
#>
#> Values:
#>
#> cost total galy
#> I
          5600 2000
```