

## Education

### Carnegie Mellon University

PH.D. IN ELECTRICAL AND COMPUTER ENGINEERING

Pittsburgh, PA, USA

Aug. 2023 – Present

### Tsinghua University

M.S. IN AEROSPACE ENGINEERING

Beijing, China

Aug. 2020 – July 2023

### Tsinghua University

B.E. IN ENGINEERING MECHANICS

Beijing, China

Aug. 2016 – June 2020

- Graduated with honors in the Tsien Excellence in Education Program.

## Research Interest

I am broadly interested in the intersection **learning**, **control**, and optimization. My research focuses on developing **theoretical tools** to deepen our understanding of the connections between learning and control, with the aim of **inspiring new algorithms** that are more applicable to real-world robotic tasks.

## Publications(\* equal contribution, † equal advising)

### PREPRINTS

#### FS-MPC: Stabilizing Sampling-Based MPC with Adaptive Feedback Design

Chaoyi Pan\*, **Zeji Yi**\*, John Zhang, Zachary Manchester, Guannan Qu, Guanya Shi

In Submission to RSS 2025

### CONFERENCE PROCEEDINGS

#### Full-Order Sampling-Based MPC for Torque-Level Locomotion Control via Diffusion-Style Annealing

Haoru Xue\*, Chaoyi Pan\*, **Zeji Yi**, Guannan Qu, Guanya Shi

ICRA2025 [\[Link\]](#)

#### Safe Bayesian Optimization for the Control of High-Dimensional Embodied Systems

Yunyue Wei, **Zeji Yi**, Hongda Li, Saraswati Soedarmadji, Yanan Sui

CoRL 2024, [\[Link\]](#)

#### Model Based Diffusion For Trajectory Optimization

Chaoyi Pan\*, **Zeji Yi**\*, Guanya Shi†, Guannan Qu†

NeurIPS 2024, [\[Link\]](#)

#### CoVO-MPC: Theoretical Analysis of Sampling-based MPC and Optimal Covariance Design

**Zeji Yi**\*, Chaoyi Pan\*, Guanqi He, Guannan Qu†, Guanya Shi†

L4DC 2024, [\[Link\]](#)

#### Improving Sample Efficiency of High Dimensional Bayesian Optimization with MCMC

**Zeji Yi**\*, Yunyue Wei\*, Chuxin Cheng\*, Kaibo He, Yanan Sui

L4DC 2024, [\[Link\]](#)

#### Nonlinear Covariance Control via Differential Dynamic Programming

**Zeji Yi**, Zhefeng Cao, Evangelos Theodorou, Yongxin Chen

ACC 2020, [\[Link\]](#)

#### Adaptive Learning based Upper-Limb Rehabilitation Training System with Collaborative Robot

Jun Hong Lim, Kaibo He, **Zeji Yi**, Chen Hou, Chen Zhang, Yanan Sui, Luming Li

45th Annual International Conference of the IEEE Engineering in Medicine and Biology Society, [\[Link\]](#)

Honors & Awards

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2025	<b>Wei Shen and Xuehong Zhang Presidential Fellowship</b> , College of Engineering, CMU	<i>Pittsburgh, PA</i>
2020	<b>Graduate with Honor</b> , Tsien Excellence in Education Program	<i>Beijing, China</i>
2018-2019	<b>Tsinghua Academic Excellence Scholarship</b> , Top 10%	<i>Beijing, China</i>
2017	<b>Second Class Prize</b> , China Undergraduate Mathematical Contest in Modeling	<i>Beijing, China</i>
2016	<b>First Class Prize</b> , Chinese Physics Olympiad (CPHO), Top 2%	<i>Beijing, China</i>
2016-2018	<b>Tsinghua-Xuetang Scholar</b> , For Excellent Foster Innovative Talent	<i>Beijing, China</i>

Invited Talks

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<b>Caltech FALCON Simnar</b>	<i>Pasadena, USA</i>
CoVO-MPC: THEORETICAL ANALYSIS OF SAMPLING-BASED MPC AND OPTIMAL COVARIANCE DESIGN	<i>Dec. 2023</i>
<b>INFORMS APS 2025</b>	<i>Atlanta, USA</i>
SAMPLING BASED OPTIMAL CONTROL: FROM THEORY TO APPLICATION	<i>Jul. 2025</i>

Skills

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<b>Programming</b>	Python, C++, MATLAB/Simulink, LaTeX
<b>Simulation and Modeling</b>	Mujoco, COMSOL, ABAQUS, SolidWorks
<b>Robotics and Operating Systems</b>	ROS, LINUX
<b>Hardware Platforms</b>	Unitree Go2, Unitree H1, Unitree G1
<b>Languages</b>	Mandarin (Native), English (Fluent)

Academic Services

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<b>Reviewer</b>	ICML, Nuerips, AISTATS, L4DC, CDC, ACC, CoRL, RAL, 2021-Present
<b>Teaching Assistant</b>	CMU: 18-660 Optimization, Tsinghua: Artificial Intelligence and Human Factor Engineering
<b>Organizer</b>	CMU Learning and Control Seminar Link,2024