

VEX CODE VR

Student Name: Me

Assignment: Robotics

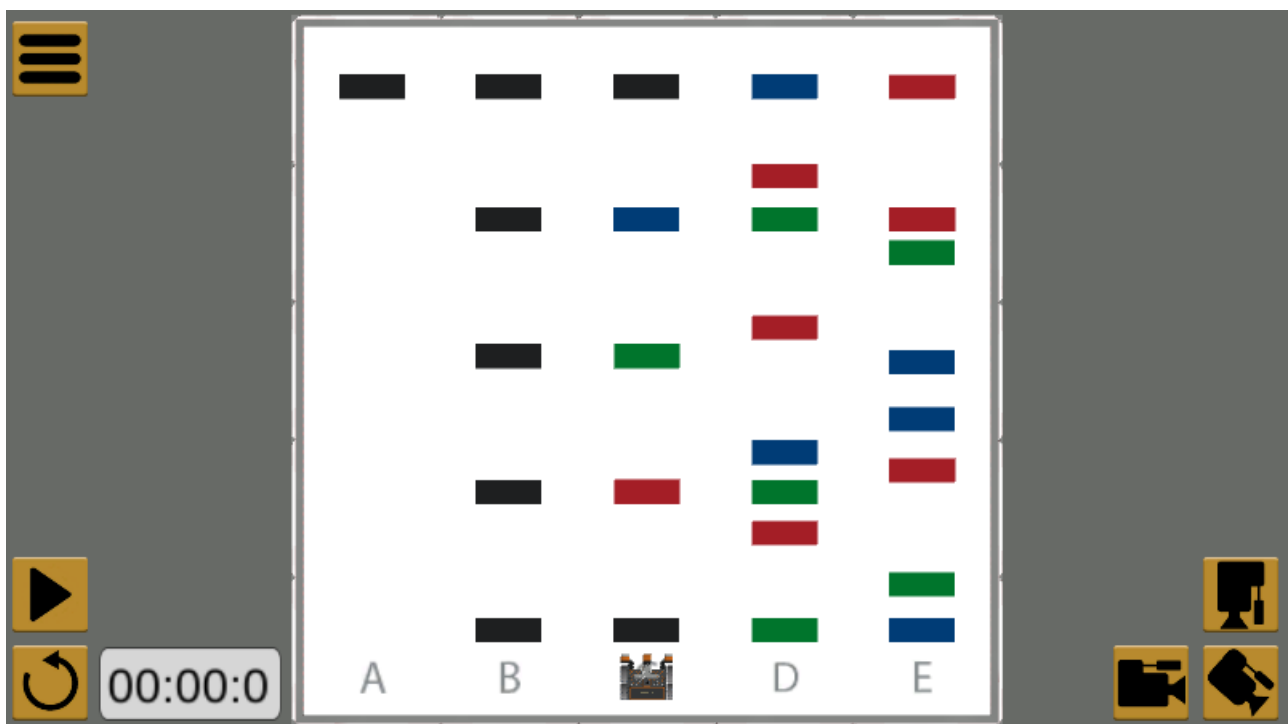
Notes: Line Detector

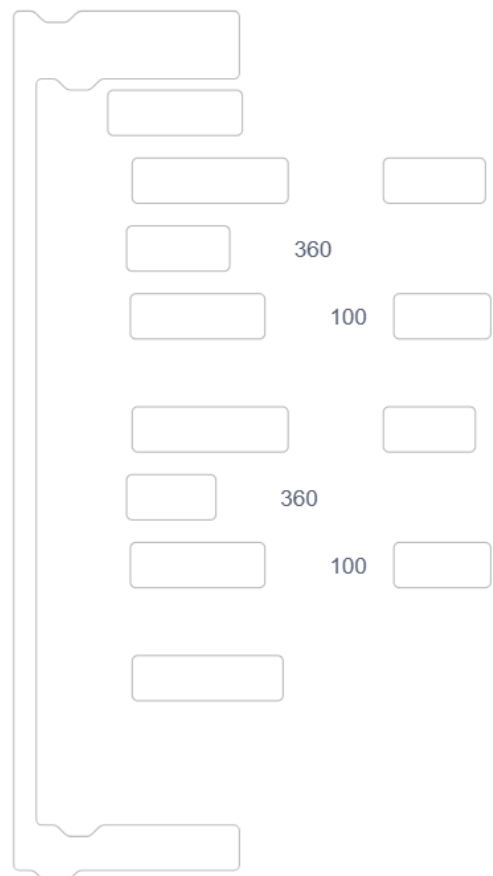
Playground: Line Detector

Project Name: VEXcode Project

Project Type: Blocks

Date: Sat Feb 04 2023





when started

set drive velocity to 100 %

set turn velocity to 100 %

forever

drive forward

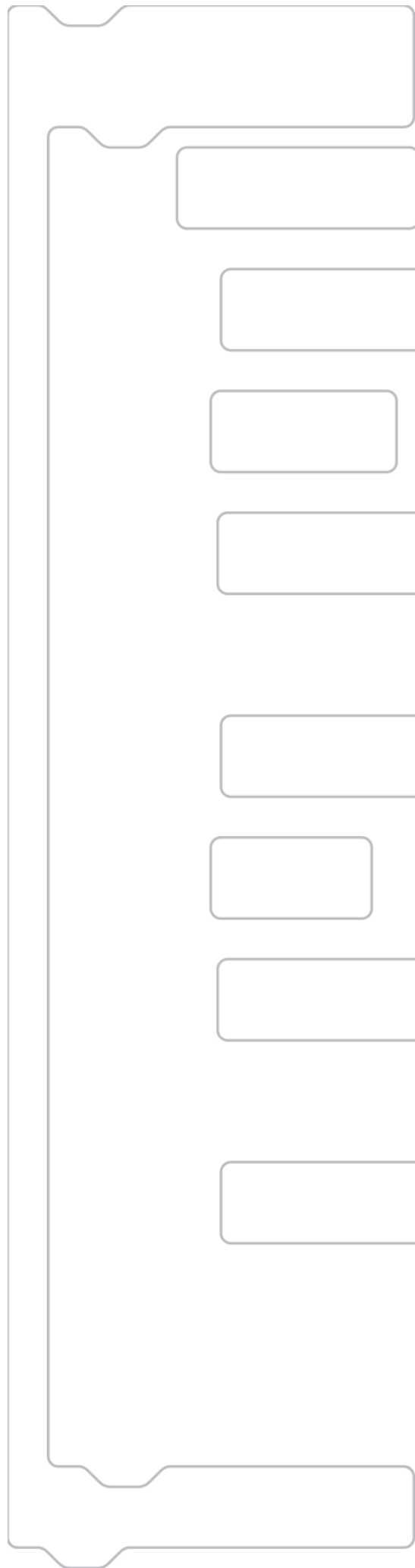
if DownEye brightness in % < 5 then

turn right for 360 degrees ▶

drive forward for 100 mm ▶

if FrontEye is near object? then

stop project



360

100

360

100