view_frames Result Recorded at time: 12.821 odom Broadcaster: /gazebo Average rate: 10.208 Hz Most recent transform: 12.755 (0.066 sec old) Buffer length: 4.800 sec base_link Broadcaster: /tf_footprint_base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 25.107 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 12.828 (-0.007 sec old) Most recent transform: 12.812 (0.009 sec old) Most recent transform: 12.812 (0.009 sec old) Most recent transform: 12.812 (0.009 sec old) Buffer length: 4.899 sec Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.900 sec base_footprint left_wheel castor_cover right_wheel Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 12.812 (0.009 sec old) Buffer length: 4.900 sec castor_wheel