

# Maximum Likelihood Estimator

## Likelihood Functions

$$\text{Single: } P(z|\theta) = \prod_{k=1}^K \theta_k^{z_k}$$

$$\text{Dataset: } P(D|\theta) = \prod_{n=1}^N \prod_{k=1}^K \theta_k^{z_{nk}}$$

## Log-Likelihood

$$\log P(D|\theta) = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \log \theta_k = \sum_{k=1}^K N_k \log \theta_k$$

$$N_k = \sum_{n=1}^N z_{nk} \quad \text{count samples in state } k$$

## Optimization with Constraint

$$\text{Constraint: } \sum_{k=1}^K \theta_k = 1$$

$$\mathcal{L} = \sum_{k=1}^K N_k \log \theta_k + \lambda \left(1 - \sum_{k=1}^K \theta_k\right)$$

## Derivative

$$\frac{N_k}{\theta_k} - \lambda = 0$$

$$\theta_k = \frac{N_k}{\lambda}$$

$$\text{Use constraint: } \sum_k \theta_k = 1$$

$$\sum_{k=1}^K \frac{N_k}{\lambda} = 1 \Rightarrow \lambda = \sum_{k=1}^K N_k = N$$

$$\text{ML Estimator: } \theta_k^{\text{ML}} = \frac{N_k}{N}$$

# Maximum A Posteriori Estimator

## Posterior Distribution

$$\begin{aligned} p(\theta | D, \alpha) &\propto P(D | \theta) \cdot p(\theta | \alpha) \\ &\propto \left[ \prod_{k=1}^K \theta_k^{N_k} \right] \cdot \left[ \prod_{k=1}^K \theta_k^{\alpha_k - 1} \right] \\ &= \prod_{k=1}^K \theta_k^{N_k + \alpha_k - 1} \end{aligned}$$

## Log Posterior

$$\log p(\theta | D, \alpha) = \sum_{k=1}^K (N_k + \alpha_k - 1) \log \theta_k + \text{const}$$

## Optimization with Constraint

Lagrangian  $\mathcal{L} = \sum_{k=1}^K (N_k + \alpha_k - 1) \log \theta_k + \lambda \left( 1 - \sum_{k=1}^K \theta_k \right)$

Derivative:  $\frac{N_k + \alpha_k - 1}{\theta_k} - \lambda = 0$

$$\theta_k = \frac{N_k + \alpha_k - 1}{\lambda}$$

## Using Constraint

$$\lambda = \sum_{k=1}^K (N_k + \alpha_k - 1) = N + \sum_{k=1}^K \alpha_k - K$$

## Result

$$\theta_k^{\text{MAP}} = \frac{N_k + \alpha_k - 1}{N + \sum_{k=1}^K \alpha_k - K}$$

## Special Cases

Case 1: Uniform Prior ( $d_h = 1$  for all  $h$ )

$$\theta_h^{\text{MAP}} = \frac{N_h}{N} = \theta_h^{\text{ML}}$$

MAP reduces to ML

Case 2: General  $d_h > 1$

$$\theta_h^{\text{MAP}} = \frac{N_h + (d_h - 1)}{N + (d_h - 1)}$$