

SYLLABUS
CIRCUITS AND SYSTEMS (EEC-213/EEC-208)
Applicable from the Academic Session 2021-22

Marking Scheme:

1. Teachers Continuous Evaluation: 25 marks
2. Term end Theory Examinations: 75 marks

Instructions for paper setter:

1. There should be 9 questions in the term end examinations question paper.
2. The first (1st) question should be compulsory and cover the entire syllabus. This question should be objective, single line answers or short answer type question of total 15 marks.
3. Apart from question 1 which is compulsory, rest of the paper shall consist of 4 units as per the syllabus. Every unit shall have two questions covering the corresponding unit of the syllabus. However, the student shall be asked to attempt only one of the two questions in the unit. Individual questions may contain upto 5 sub-parts / sub-questions. Each Unit shall have 1 marks weightage of 15.

UNIT I

Signals, Classification of Signals, Systems, Classification of Systems, Linear Time Invariant (LTI) Systems; Laplace Transform, z-Transform, Fourier Series and Transform (Continuous and Discrete) and their properties. Laplace Transform and Continuous Time LTI systems, z-Transform and Discrete Time LTI systems, Fourier analysis of signals and systems, State Space Analysis. [T1]

UNIT II

System modeling in terms of differential equations and transient response of R, L, C, series and parallel circuits for impulse, step, ramp, sinusoidal and exponential signals by classical method and using Laplace transform. [T2]

UNIT III

AC Circuits: Circuits containing Capacitors and Inductors, Transient Response, Alternating Current and Voltages, Phasors, Impedances and Admittance, Mesh Analysis, Loop Analysis, Nodal Analysis, Thevenin's and Norton's Theorem, Y - D and D-Y Transformation, Bridge Circuits. Resonant Circuits, Complex Frequency and Network Function, Two port Networks. Passive Filters. [T3]

UNIT IV

Graph theory: Concept of tree, tie set matrix, cut set matrix and application to solve electric networks-Two port networks - Introduction of two port parameters and their interconversion, interconnection of two 2-port networks, open circuit and short circuit impedances and ABCD constants, relation between image impedances and short circuit and open circuit impedances. Network functions, their properties and concept of transform impedance, Hurwitz polynomial. [T2]

NEW TOPICS ADDED FROM ACADEMIC SESSION (2021-22)

SYLLABUS (ACADEMIC SESSION 2014-15)

CIRCUIT & SYSTEMS (ETEE-207)

INSTRUCTIONS TO PAPER SETTERS

Maximum Marks: 7

- Question No. 1 should be compulsory and cover the entire syllabus. This question should have objective or short answer type questions. It should be of 25 marks.
- Apart from Question No. 1, the rest of the paper shall consist of four units as per the syllabus. Every unit should have two questions. However, the student may be asked to attempt only 1 question from each unit. Each question should be 12.5 marks.

UNIT-I

Introduction to signals, their classification and types, different types of systems, LTI system and their properties, periodic waveforms and signal synthesis, properties and applications Laplace transform of complex waveform. [T1,T2][No. of Hours: 1]

UNIT-II

System modeling in terms of differential equations and transient response of R, L, C, series and parallel circuits for impulse, step, ramp, sinusoidal and exponential signals by classical method and using Laplace transform. [T1,T2][No. of Hours: 1]

UNIT-III

Graph theory: concept of tree, tie set matrix, cut set matrix and application to solve electrical networks.

Two port networks - Introduction of two port parameters and their interconversion, interconnection of two 2-port networks, open circuit and short circuit impedances and ABCD constants relation between image impedances and short circuit and open circuit impedances. Network functions, their properties and concept of transform impedance, Hurwitz polynomial

[T1,T2][No. of Hours: 1]

UNIT-IV

Positive real function and synthesis of LC, RC, RL Networks in Foster's I and II, Cauer's II forms, Introduction of passive filter and their classification, frequency response, characteristic impedance of low pass, high pass, Band Pass and Band reject prototype section. [T1,T2][No. of Hours: 1]

Q.1 State and explain Norton theorem. (IPU-2014)

Ans. Statement: "Any two terminal, linear, bilateral network can be replaced by an equivalent circuit consisting of a current source parallel with the resistance (impedance) seen from that terminals. The equivalent current source, I_N is the short circuit between the terminals and equivalent resistance, R_N , is the ratio of the open circuit voltage to the short circuit current at these terminals."

Explanation:

- Consider a network of fig (a)
- Short circuit terminals AB: To find out short circuited current

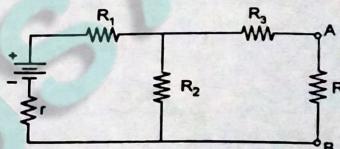


fig. (a)

I_{sc} (By replacing resistance R_L with a zero resistance thick wire) fig (b)

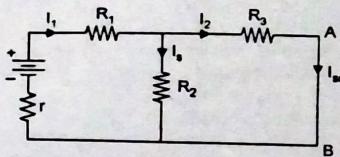


Fig. (b)

- Equivalent resistance of the fig. (c) network, $R_N = ((R_1 + r) \parallel R_2) + R_3$

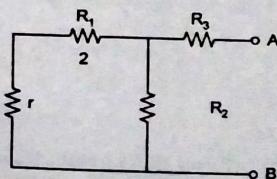


Fig. (c)

- Nortons equivalent circuit will be as per fig (d)

$$I_L = \frac{I_{sc} R_N}{R_N + R_L}$$

(applying current dimension in fig. (d))

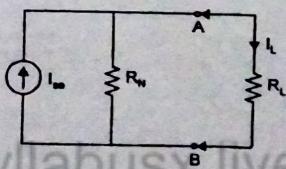
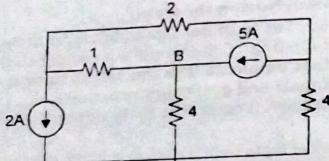


Fig. (d)

Q.2 Using the nodal analysis, find the different branch current in the circuit of figure shown. All Branch conductances are in Siemens. (6)(IPU-2014)



Ans. At node A, apply KCL/nodal analysis

$$\begin{aligned} 2 + I_1 + I_2 &= 0 \\ \Rightarrow 2 + (V_A - V_B) 1 + (V_A - V_C) 2 &= 0 \\ \Rightarrow 2 + V_A - V_B + 2V_A - 2V_C &= 0 \\ \Rightarrow 2 + 3V_A - V_B - 2V_C &= 0 \\ \Rightarrow 3V_A - V_B - 2V_C &= -2 \dots (1) \end{aligned}$$

at node B, apply KCL/nodal analysis

$$\begin{aligned} I_1 + 5 &= I_3 \\ \Rightarrow (V_A - V_B) 1 + 5 &= V_B 4 \\ \Rightarrow V_A - V_B + 5 &= 4V_B \\ \Rightarrow V_A - V_B - 4V_B &= -5 \\ \Rightarrow V_A - 5V_B &= -5 \end{aligned} \quad (2)$$

at node C, apply KCL/nodal analysis

$$\begin{aligned} I_2 &= 5 + I_4 \\ \Rightarrow (V_A - V_C) 2 &= 5 + V_C 4 \\ \Rightarrow 2V_A - 2V_C - 4V_C &= 5 \\ \Rightarrow 2V_A - 2V_C - 4V_C &= 5 \\ \Rightarrow 2V_A - 6V_C &= 5 \end{aligned} \quad (3)$$

we solve equation (1), (2) & equation (3), then we get

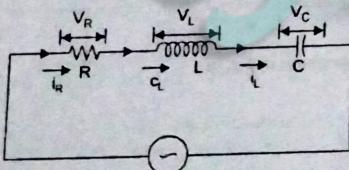
$$V_A = -5/4, V_B = 3/4, V_C = -5/4$$

$$I_1 = (V_A - V_B) 1 = \left(-\frac{5}{4} - \frac{3}{4} \right) 1 = \frac{-8}{4} = -2 \text{ Amp.} \quad I_3 = V_B 4 = \frac{3}{4} \times 4 = 3 \text{ amp}$$

$$I_2 = (V_A - V_C) 2 = \left(-\frac{5}{4} - \left(-\frac{5}{4} \right) \right) 2 = 0 \text{ Amp; } \quad I_4 = 4V_C = 4 \times \left(-\frac{5}{4} \right) = -5 \text{ amp Ans.}$$

Q.3 Discuss resonance the Series RLC circuits. How the resonant frequency is calculate. Give graphical representation of resonance. (IPU-2014)

Ans. Consider an ac circuit containing a resistance R, an inductance L and capacitance C connected in series, as shown in figure.



Impedance of the circuit

$$Z = \sqrt{R^2 + (x_L - x_c)^2} = \sqrt{R^2 + \left(\omega L - \frac{1}{\omega C} \right)^2}$$

if for some frequency of applied voltage $x_L = x_c$ in magnitude then

- (i) Net reactance is zero ie. $X = 0$
- (ii) Impedance of the circuit $Z = R$
- (iii) The current flowing through the circuit is maximum and in phase with the applied voltage. The magnitude of the current will be equal to V/R .
- (iv) $I x_L = I x_c$

when the above condition exists, the circuit is said to be in resonance and the frequency at which it occurs is known as resonant frequency.

If resonant frequency is denoted by f_r ,

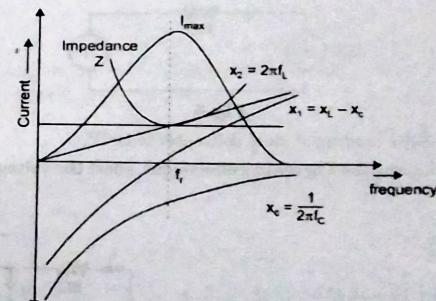
If, then

$$x_L = \omega L = 2\pi f_r L \quad x_c = \frac{1}{2\pi f_r C}$$

$$x_L = x_c \Rightarrow 2\pi f_r L = \frac{1}{2\pi f_r C}$$

$$\Rightarrow f_r = \frac{1}{2\pi\sqrt{LC}} \Rightarrow \omega_r = \frac{1}{\sqrt{LC}}$$

graphical representation of resonance.



→ The circuit can be made resonant in two different ways namely,

- (i) by varying L & C parameter at a constant supply or frequency.
- (ii) by varying the supply frequency & with Parameters L and C constant.

→ In the above graphical representation, Resistance R is independent of supply frequency, therefore, remains constant. It has been represented by a straight line, i.e. parallel to the X-axis.

$$\begin{aligned} \rightarrow x_L &= \omega L \\ \Rightarrow x_L &= 2\pi f_r L \\ \Rightarrow f_r &\propto x_L \end{aligned}$$

Due $x_L \propto f_r$, so it is represented by a straight line passing through the origin, and it

lies on the first quadrant. Similary

$$x_c = \frac{1}{2\pi f C}$$

$$x_c \propto (1/f)$$

→ So x_c inversely proportional to the resonant frequency and it is represented by a rectangular hyperbola. It lies in the fourth quadrant.

→ The net reactance is the difference of inductive reactance x_L and capacitive reactance x_c , and the curve drawn between the net reactance ($x_L - x_c$) and frequency will be a hyperbola. The frequency at which the reactance curve crosses the frequency axis is called the resonant frequency. (f_r)

→ The impedance of the circuit, Z being equal to $\sqrt{R^2 + (x_L - x_c)^2}$ is minimum at resonant frequency f_r .

→ At frequencies lower than resonant frequency f_r , the impedance Z is large and capacitive as $x_C > x_L$ and the power factor is leading. and at frequencies higher than resonant frequency f_r , the impedance Z is large but $x_L > x_C$ and power factor is lagging. The power factor has the maximum value of unity at resonant frequency.

Q.4 (i) For a circuit shown in Fig. A, the reading of ideal voltmeter is....

(ii) For a network in Fig. B, if we find the Thevenin's Equivalent Circuit at terminal X & Y then Thevenin's Voltage will be (IPU-2015)

Ans. (i)

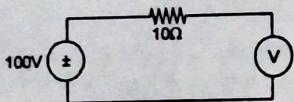


Fig. A

From the Fig. A the reading of ideal voltmeter is 100V.

Ans. (ii) For finding the Thevenin's equivalent, short the voltage source and open current source.

$$\text{Now, } i_4 = \frac{V_0}{10}$$

$$R_{XY} = 5 + 10 = 15 \Omega$$

$$6i_4 - 2V_0 = 0$$

$$\frac{6V_0}{10} - 2V_0 = 0$$

$$6V_0 - 20V_0 = 0$$

$$V_0 = 0$$

Because there is no independent source.

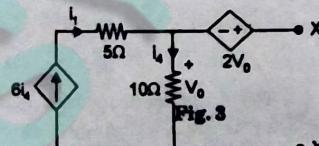


Fig. B

Q.5 For a series RL circuit shown in Fig A. Draw a phasor diagram showing all the electrical quantities (Voltage and Current) marked in the circuit. Also write the impedance of circuit in j notation. (IPU-2015)

Ans.

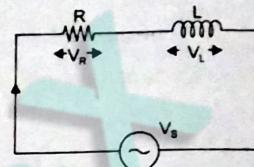
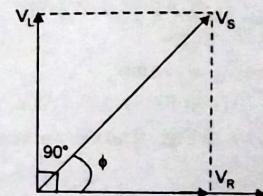


Fig. A

From the above circuit

$$V_s = \sqrt{V_R^2 + V_L^2} \quad \dots(1)$$

Phasor diagram of RL circuit



and impedance of RL circuit is given by

$$Z = R + jX_L \quad \dots(2)$$

Q.6 For a network shown in Fig. A, find all the marked mesh currents. (IPU-2015)

Ans

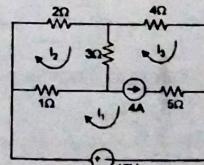
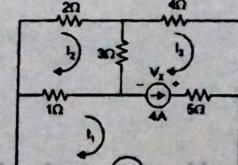


Fig. A

$$I_1 = ?$$

$$I_2 = ?$$

$$I_3 = ?$$



(Applying Mesh Analysis)

$$12 + V_s = 6I_1 - I_2 - 5I_3 \quad \dots(1)$$

$$0 = -I_1 + 6I_2 - 3I_3 \quad \dots(2)$$

$$-V_s = -5I_1 - 3I_2 + 12I_3 \quad \dots(3)$$

Adding equation (1) to (3), we get

$$12 = I_1 - 4I_2 + 7I_3 \quad \dots(4)$$

- The relation between the source current and mesh currents is given by

$$I_s = I_1 - I_3$$

$$4 = I_1 - I_3 \quad \dots(5)$$

→ Now from equation (3), (4), (5) the value of I_1 , I_2 and I_3 can be obtained.

→ Multiply equation (3) by 2, equation (4) by 3, and adding the results to eliminate I_2 .

We get

$$I_1 + 15I_3 = 36 \quad \dots(6)$$

$$I_1 - I_3 = 4 \quad \dots(7)$$

- From above equation $I_1 = 6$ Amp, $I_3 = 2$ Amp

Put the value in equation (3), we get

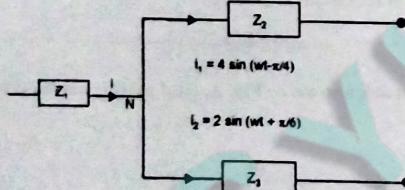
$$I_2 = 2 \text{ Amp}$$

So,

$$I_1 = 6 \text{ Amp}, I_2 = 2 \text{ Amp}, I_3 = 2 \text{ Amp} \text{ Ans.}$$

Q.7 For a network shown in Fig., find the current 'T' entering the node 'N'. Express 'T' in polar form. (IPU-2015)

Ans.



- From the above, T is the phasor sum of currents

$$\text{i.e. } I = i_1 + i_2 \quad \dots(1)$$

$$I = 4 \sin (\omega t - \pi/4) + 2 \sin (\omega t + \pi/6)$$

$$= 4 \sin \omega t \cos \frac{\pi}{4} - 4 \cos \omega t \sin \frac{\pi}{4} + 2 \sin \omega t \cos \pi/6 + 2 \cos \omega t \sin \pi/6$$

$$= \frac{4}{\sqrt{2}} \sin \omega t - \frac{4}{\sqrt{2}} \cos \omega t + 2 \cdot \frac{\sqrt{3}}{2} + 2 \cdot \frac{1}{2} \cos \omega t$$

$$I = 4.560 \sin \omega t - 1.828 \cos \omega t \quad \dots(2)$$

Standard form of equation is. $i = I_m \sin(\omega t + \alpha)$

$$i = (I_m \cos \alpha) \sin \omega t + (I_m \sin \alpha) \cos \omega t \quad \dots(3)$$

By comparing, we find $I_m \cos \alpha = 4.560$

$$I_m \sin \alpha = 1.828$$

- Squaring and adding these quantities we get

$$I_m^2 \cos^2 \alpha + I_m^2 \sin^2 \alpha = (4.560)^2 + (-1.828)^2$$

$$I_m^2 (\cos^2 \alpha + \sin^2 \alpha) = 20.79 + 3.34$$

$$I_m^2 = 24.13$$

⇒

$$I_m = 4.91 \text{ Amp.}$$

$$\Rightarrow \frac{I_m \sin \alpha}{I_m \cos \alpha} = \frac{-1.828}{4.560} \Rightarrow \tan \alpha = -0.400$$

$$\alpha = -21.8^\circ$$

⇒ Now standard current equation $-i = I_m \sin(\omega t + \alpha)$

$$i = 4.91 \sin(\omega t - 21.8^\circ) \text{ Ans.}$$

Q.8 Find the current through R_L in the network shown in Fig.A using Norton Theorem. (IPU-2015)

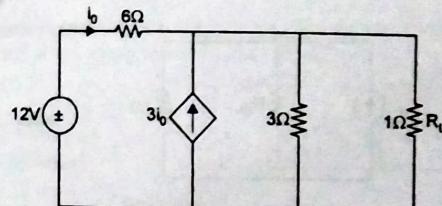
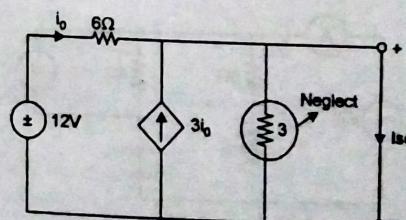


Fig.A

Ans. First remove R_L and short terminals



$$I_{sc} = 3i_o + i_o = 4i_o$$

But

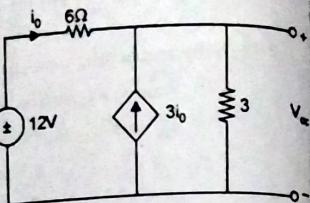
$$i_o = \frac{12}{6} = 2 \text{ Amp}$$

$$I_{sc} = 4 \times 2 = 8 \text{ Amp}$$

=
Now open the terminals

Nodal Analysis

$$i_o + 3i_o - \frac{V_{\infty}}{3} = 0$$



$$4i_o = \frac{V_{\infty}}{3}$$

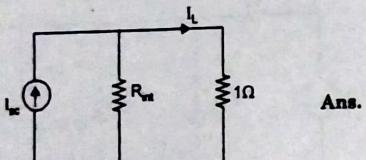
$$= 0$$

$$4 \left[\frac{12 - V_{\infty}}{8} \right] \frac{V_{\infty}}{3} - \frac{V_{\infty}}{3} = 0$$

$$V_{\infty} = 8V$$

Now

$$R_{in} = \frac{V_{\infty}}{I_{sc}} = \frac{8}{8} = 1W$$



Ans.

Q.9 For a AC network shown in Fig. A, if the reading of voltmeter (indicating RMS value) is 60V then find the reading of Ammeter. Note Ammeter is also indicating the RMS value. (IPU-2015)

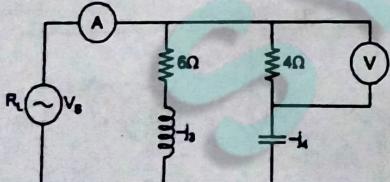


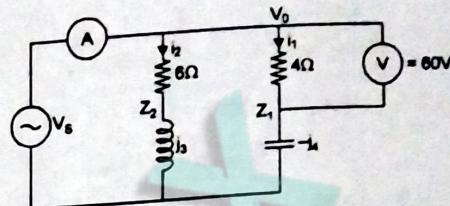
Fig.A

Ans. $V = 60V$ (rms) Ammeter reading ; $i_1 = 60/4 = 15$ Amp

$$Z_1 = (4 - j_4) Z_2 = (6 + j_8)$$

$$V_0 \Rightarrow 15(4 - j_4)$$

$$V_1 = (60 - j 60) \text{ volt}$$



$$i_2 = \frac{V_1}{Z_2}$$

Now
Because in parallel voltage is same so it directly appears to Z_2 .

$$i_2 = \frac{60 - j 60}{6 + j_3} = (10 - j 20)$$

Now

$$i = i_1 + i_2 = (15 + j0) + (10 - j 20)$$

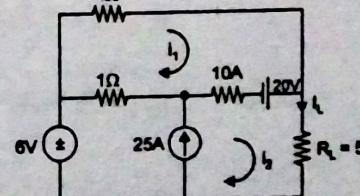
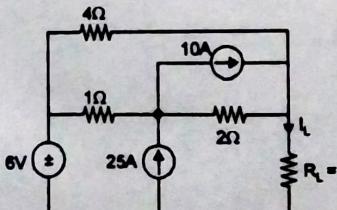
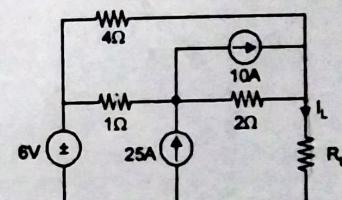
$$i = (25 - j20) \text{ Amp}$$

Now Ammeter reads $i = 25$ Amp Ans.

Q.10. For a network shown in Fig. A, if R_L is load resistance & I_L is current flowing through it then complete the table given below. (IPU-2015)

S.No.	R_L	I_L
1		5 Ohm
2		10 Ohm
3		15 Ohm

Ans.



$$\Rightarrow 4i_1 + 20 + 10(i_1 - i_2) + 1(i_1 - i_2) = 0$$

$$\Rightarrow 15i_1 - 11i_2 = -20 \quad \dots(1)$$

$$i_2 - i_1 + 10(i_2 - i_1) - 20 + 5i_2 = 0$$

$$-11i_1 + 16i_2 = 20 \quad \dots(2)$$

\Rightarrow

$$\begin{aligned} 15i_1 - 11i_2 &= -20 \times 16 \\ 11i_1 - 16i_2 &= -20 \times 11 \\ 240i_1 - 121i_2 &= -320 + 220 \end{aligned}$$

$$119i_1 = -100$$

$$i_1 = -0.840 \text{ Amp.}$$

$$-(15 \times 0.840) = 11i_2 = -20$$

$$-12.6 - 11i_2 = -20$$

$$-11i_2 = -20 + 12.6$$

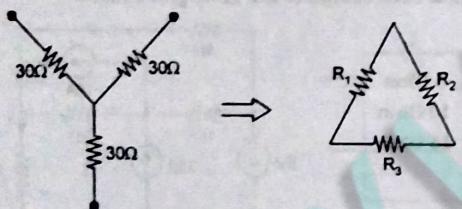
$$-11i_2 = -7.4$$

$$i_2 = 0.672$$

$$I_1 = I_2 = 0.672 \text{ Amp}$$

Q.11 A star connection contains three equal resistances of 30 ohm. Find the resistances of the equivalent Delta connection. (IPU-2018)

Ans.



From star to delta transformation:

$$R_1 = \frac{R_1 R_2 + R_2 R_3 + R_3 R_1}{R_1} = \frac{(30 \cdot 30) + (30 \cdot 30) + (30 \cdot 30)}{30} = 90 \Omega$$

$$R_2 = \frac{R_1 R_2 + R_2 R_3 + R_3 R_1}{R_2} = \frac{(30 \cdot 30) + (30 \cdot 30) + (30 \cdot 30)}{30} = 90 \Omega$$

$$R_3 = \frac{R_1 R_2 + R_2 R_3 + R_3 R_1}{R_3} = \frac{(30 \cdot 30) + (30 \cdot 30) + (30 \cdot 30)}{30} = 90 \Omega$$

$$\Rightarrow R_1 = R_2 = R_3 = 90 \Omega \quad \text{Ans.}$$

Q.12. Give statements of Thevenin's and Norton's theorem. (IPU-2018)

Ans. Thevenin's Theorem: Thevenin's theorem states that any two-terminal, linear bilateral dc network can be replaced by an equivalent circuit consisting of a voltage source, E_{Th} (or V_{Th}) and a series resistor, R_{Th} as shown in Fig. 1.

Here, V_{Th} is voltage across two terminals (load terminals). It is also known as V_{oc} (open circuit voltage). R_{Th} is internal resistance of the network as viewed back into the open circuited network from terminals a and b with all voltage sources replaced by their internal resistance (if any) and current sources by infinite resistance.

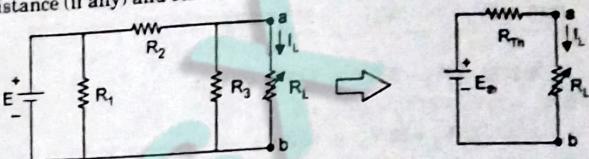


Fig. 1. Illustration of Thevenin's Theorem

Norton's Theorem: Norton Theorem states that any two-terminal linear bilateral dc network can be replaced by an equivalent circuit consisting of a current source, I_N (or I_{oc}) and a parallel resistor, R_N as shown in Fig.

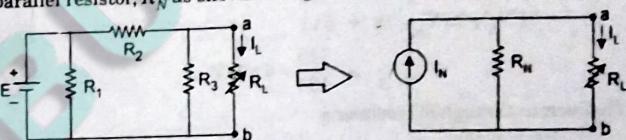
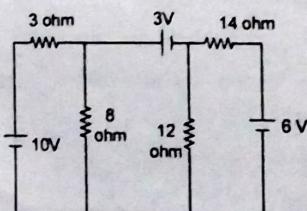


Fig. 2. Illustration of Norton's Theorem

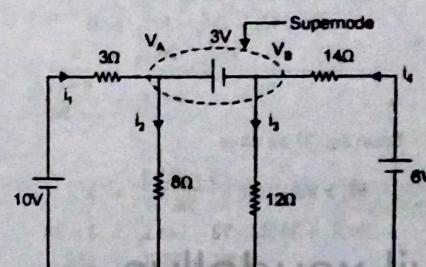
Here, I_N is the constant current equal to the current which would flow in a short-circuit placed across the terminals a and b . R_N is internal resistance of the network as viewed back into the open circuited network from terminals a and b with all voltage sources replaced by their internal resistance (if any) and current sources by infinite resistance.

Q.13 For the circuit shown in fig. Find current across 8 ohm resistor by nodal analysis OR by mesh analysis. (IPU-2015)



Ans. By Nodal Analysis:

From the given circuit, it is clear that it is the case of super node.



12-2021

Fourth Semester, Circuit and System (EEC-213/EEC-208)

Let the direction of current in different branches be i_1, i_2, i_3 and i_4 as shown in modified circuit diagram.

By nodal analysis, we have

$$\frac{10 - V_A}{3} + \frac{6 - V_B}{14} = \frac{V_A}{6} + \frac{V_B}{12}$$

$$(140 - 14V_A + 18 - 3V_B) = \frac{3V_A + 2V_B}{24}$$

$$4(158 - 14V_A - 3V_B) = 7(3V_A + 2V_B)$$

$$632 - 56V_A - 12V_B - 21V_A - 14V_B = 632$$

$$77V_A + 26V_B = 632$$

From the super node, we have

$$V_A - V_B = 3$$

$$V_B = V_A - 3$$

$$77V_A + 26(V_A - 3) = 632$$

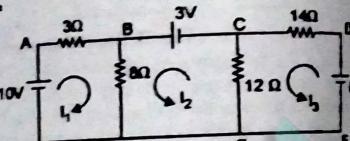
$$77V_A + 26V_A - 78 = 632$$

$$V_A = \frac{710}{103} = 6.893V$$

The current through 8Ω resistor =

$$I_1 = \frac{V_A - 6.893}{8} = \frac{6.893}{8} = 0.862A$$

By Mesh Analysis



From loop ABGH, we get

$$10 - 3I_1 - 8I_1 + I_2 = 0$$

$$10 - 3I_1 - 8I_1 - 8I_2 = 0$$

$$11I_1 + 8I_2 = 10$$

From loop BCFG, we get

$$3 - 8(I_1 + I_2) - 12(I_2 - I_3) = 0$$

$$3 - 8I_1 - 8I_2 - 12I_2 + 12I_3 = 0$$

$$8I_1 + 20I_2 - 12I_3 = 3$$

From loop CFDE, we get

$$6 - 14I_3 + 12(I_2 - I_3) = 0$$

$$6 - 14I_3 + 12I_2 - 12I_3 = 0$$

$$12I_2 - 26I_3 = -6$$

$$\Rightarrow I_3 = \frac{6 + 12I_2}{26}$$

From eq. (2) we have

$$8I_1 + 20I_2 - 12\left(\frac{6 + 12I_2}{26}\right) = 3$$

$$208I_1 + 520I_2 - 72 - 144I_2 = 3 \times 26$$

$$208I_1 + 376I_2 = 150$$

$$\text{From eq. (1) we have } I_2 = \frac{10 - 11I_1}{8}$$

From eq. (4) we have

$$208I_1 + 376\left(\frac{10 - 11I_1}{8}\right) = 150$$

$$208I_1 + 47(10 - 11I_1) = 150$$

$$208I_1 + 470 - 517I_1 = 150$$

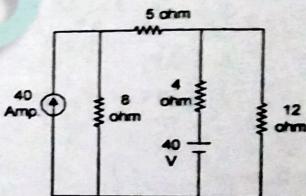
$$309I_1 = 320$$

$$I_1 = 1.035A$$

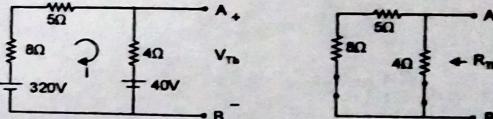
$$\Rightarrow I_2 = \frac{10 - 11 \times 1.035}{8} \Rightarrow I_2 = -0.173A$$

Current though 8Ω resistor = $I_1 + I_2$
 $= 1.035 - 0.173 = 0.862A$

Q. 14 Draw equivalent Thevenin's circuit for Network shown in fig. Take 12 Ohm as load resistance. (IPU-2018)



Ans. By Thevenin's Theorem



$$R_{Th} = (5 + 8) \parallel 4 = 13 \parallel 4 = \frac{13 \times 4}{17} = \frac{52}{17} \Omega$$

$$320 - 8I - 5I - 4I - 40 = 0$$

$$17I = 280$$

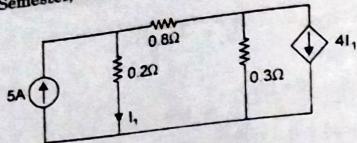
$$I = \frac{280}{17} = 16.47A$$

$$40 + 4I - V_{Th} = 0$$

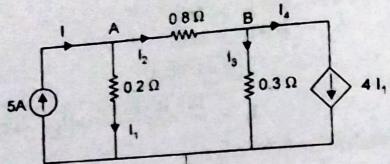
$$V_{Th} = 40 + 4 \times 16.47 = 105.88V$$

$$I_L = \frac{V_{Th}}{R_{Th} + R_L} = \frac{105.88}{12 + \frac{52}{17}} = 7.03A$$

Q. 15 Find the voltage across the 0.8Ω resistor using nodal analysis for circuit shown in Fig. (IPU-2018)



Ans.



Applying KCL at node A, we get $I_1 = I_2 + I_3$

$$5 = \frac{V_A - V_B}{0.2} + \frac{V_A - V_B}{0.8}$$

$$5 = 5V_A + \frac{5}{4}(V_A - V_B)$$

$$20 = 20V_A + 5V_A - 5V_B$$

$$25V_A - 5V_B = 20$$

$$5V_A - V_B = 4 \quad \dots(1)$$

Applying KCL at node B, we get

$$I_2 = I_3 + I_4$$

$$\frac{V_A - V_B}{0.8} = \frac{V_B + 4I_1}{0.3}$$

$$\frac{5}{4}(V_A - V_B) = \frac{10}{3}V_B + \frac{4V_A}{0.2}$$

$$\frac{5}{4}(V_A - V_B) = \frac{10V_B}{3} + 20V_A$$

$$15(V_A - V_B) = 4(10V_B + 60V_A)$$

$$15V_A - 15V_B = 40V_B + 240V_A$$

$$225V_A = -55V_B$$

$$V_A = -\frac{55}{225}V_B = -\frac{11}{45}V_B \quad \dots(2)$$

From eq (1) and (2), we get $V_B = 5V_A - 4$

$$\Rightarrow V_A = -\frac{4}{45}(5V_A - 4)$$

$$45V_A = -55V_A + 44$$

$$100V_A = 44$$

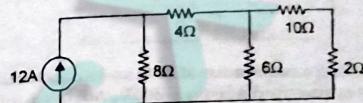
$$V_A = \frac{44}{100}V \Rightarrow V_A = 0.44V$$

$$\Rightarrow V_B = 5 \times 0.44 - 4$$

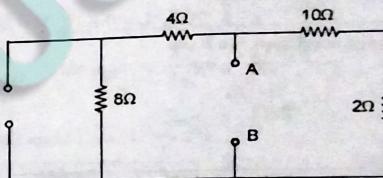
$$V_B = -1.80V$$

$$\therefore \text{Voltage across } 0.8\Omega = V_A - V_B \\ = 0.44 - (-1.80) = 2.24V$$

Q. 16 Find current in 6Ω resistor using Norton's theorem for Fig. shown below.
(IPU-2018)

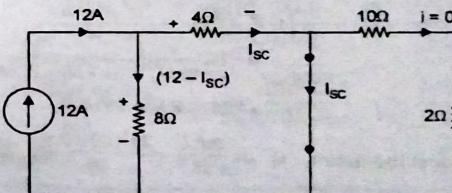


Ans. Here

Rearranging the network for Norton's Resistance, R_N 

$$R_N = (4 + 8) \parallel (10 + 2)$$

$$= 12 \parallel 12 = \frac{12 \times 12}{24} = 6\Omega$$

Rearranging the network for Norton's current, I_N (in I_{sc})

Applying KVL in a loop, we get

$$8(12 - I_{sc}) - 4I_{sc} = 0$$

$$96 - 8I_{sc} - 4I_{sc} = 0$$

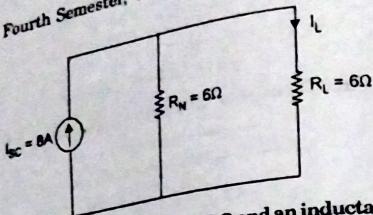
$$I_{sc} = \frac{96}{12} = 8A$$

The Norton's Equivalent Circuit is shown as

$$\therefore I_L = \frac{R_N}{R_N + R_L} \times I_{sc} = \frac{6}{6+6} \times 8 = 4A$$

16-2021

Fourth Semester, Circuit and System (EEC-213/EEC-208)



Q. 17 A circuit having a resistance of 20Ω and an inductance of $0.8H$ and a capacitor in series is connected across a $200V$, $50Hz$ supply. Calculate:
 (i) The capacitance to give resonance.
 (ii) The voltage across the inductor and the capacitor

(iii) The Q factor of the circuit
 Ans. Given, $R = 20\Omega$; $L = 0.8 H$; $V = 200 V$; $f = 50 Hz$

(i) Under Resonant condition, we have

$$X_L = X_C$$

$$2\pi f L = \frac{1}{2\pi f C}$$

$$C = \frac{1}{(2\pi f)^2 L} = \frac{1}{(2\pi \times 50)^2 \times 0.8} = 12.66 \mu F$$

(ii) At resonance, current through the circuit,

$$I = \frac{V}{R} = \frac{200}{20} = 10 A$$

$$V_L = IX_L = I \times 2\pi f L = 10 \times 2\pi \times 50 \times 0.8 \\ = 2513.27 V \approx 2514 V$$

\Rightarrow

$$V_C = IX_C \\ = I \times \frac{1}{2\pi f C} = \frac{10}{2\pi \times 50 \times 12.66 \times 10^{-6}} \\ = 2514.3 V \approx 2514 V$$

$$(iii) Q-factor of the circuit, Q = \frac{2\pi f L}{R} = \frac{2\pi \times 50 \times 0.8}{20} = 12.57$$

Q. 18 Derive $I_0 = 1/(2\pi\sqrt{LC}) \frac{\sqrt{R^2 - L/C}}{R^2 - L/C}$ for a parallel resonant circuit

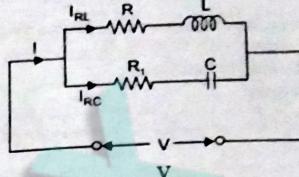
R_1 is the resistance in series with the inductor and R_2 is the resistance with the capacitor.

Ans. When an inductive reactance and a capacitive reactance are connected as shown in fig. condition may reach under which parallel or current resonance

- For parallel resonance-

Reactive component of RL branch = Reactive component of RC branch
 i.e. $I_{RL} \sin \phi_{RL} = I_{RC} \sin \phi_{RC}$

I.P. University-(B.Tech)-Akash Books



- From fig.

$$I_{RL} = \frac{V}{\sqrt{R^2 + (\omega_r L)^2}}$$

and

$$\sin \phi_{RL} = \frac{X_L}{Z_{RL}} = \frac{\omega_r L}{\sqrt{R^2 + (\omega_r L)^2}}$$

and

$$I_{RC} = \frac{V}{Z_{RC}} = \frac{V}{\sqrt{R_1^2 + \left(\frac{1}{\omega_r C}\right)^2}}$$

and

$$\sin \phi_{RC} = \frac{X_C}{Z_{RC}} = \frac{1/\omega_r C}{R_1^2 + \left(\frac{1}{\omega_r C}\right)^2}$$

From equations (2) and (3) in (1) we get-

$$\frac{V}{\sqrt{R^2 + (\omega_r L)^2}} \times \frac{\omega_r L}{\sqrt{R^2 + (\omega_r L)^2}} = \frac{V}{\sqrt{R_1^2 + \left(\frac{1}{\omega_r C}\right)^2}} \times \frac{1/\omega_r C}{\sqrt{R_1^2 + \left(\frac{1}{\omega_r C}\right)^2}}$$

$$\text{or } \frac{\omega_r L}{R^2 + (\omega_r L)^2} = \frac{1/\omega_r C}{R^2 + (1/\omega_r C)^2}$$

$$\text{or } \frac{\omega_r L}{R^2 + \omega_r^2 L^2} = \frac{\omega_r C}{\omega_r^2 R_1^2 C^2 + 1}$$

$$\text{or } L(\omega_r^2 R_1^2 C^2 + 1) = C(R^2 + \omega_r^2 L^2)$$

$$\text{or } \omega_r^2 LC(R_1^2 C - L) = CR^2 - L$$

$$\text{or } \omega_r = \frac{1}{\sqrt{LC}} \sqrt{CR^2 - L}$$

Resonant Frequency

$$f_r = \frac{1}{2\pi} \omega_r$$

$$\text{or } f_r = \frac{1}{2\pi\sqrt{LC}} \sqrt{CR^2 - L}$$

Q. 19 State thevenin theorem. Find thevenin equivalent voltage and thevenin equivalent resistance in fig. (A) & draw Norton equivalent circuit? (IPU-2016)

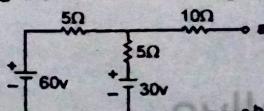
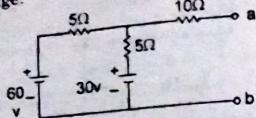


Fig. A.

Ans. A linear two-terminal circuit can be replaced by an equivalent circuit consisting of voltage source V_{TH} in series with resistor R_{TH} .
Where R_{TH} = Equivalent Resistance
 V_{TH} = Equivalent Voltage.

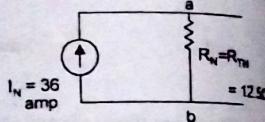


$$R_{ab} = R_{TH}$$

$$R_{ab} = R_{TH} = (5 + 5) + 10 = 12.5 \Omega$$

For V_{TH}
 $= 5i + 5i + 30 = 60$
 $10i = 30$

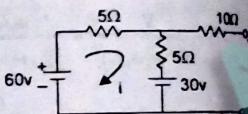
$$i = 3 \text{ amp}$$



$$V_{ab} = V_{TH} = 10 \times 0 + 5i + 30 = 60$$

$$= 0 + 5 \times 3 + 30$$

$$V_{ab} = V_{TH} = 45V$$



For Norton's Equivalent

$$\Rightarrow I_N = \frac{V_{TH}}{R_{TH}} = \frac{45}{12.5} = 36 \text{ amp Ans.}$$

Q.20 Find the equivalent resistance across AB in the Fig. 1, all the resistances are equal and 5 ohm. (IPU-2010)

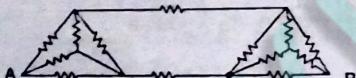
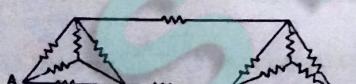
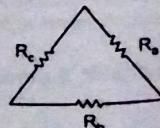
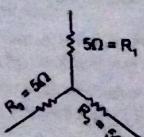


Fig. 1.

Ans. Each resistance value = 5Ω



Converting from star to delta



\Rightarrow

\Rightarrow

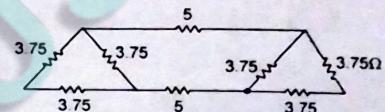
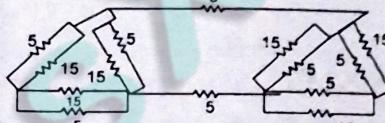
Now

$$R_a = \frac{R_1 R_2 + R_2 R_3 + R_3 R_1}{R_3}$$

$$= \frac{5 \times 5 + 5 \times 5 + 5 \times 5}{5} = \frac{75}{5} = 15 \Omega$$

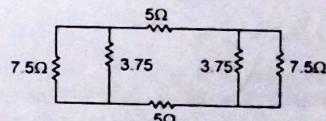
$$R_b = 15 \Omega, R_c = 15 \Omega$$

$$15 || 15 \Rightarrow \frac{15 \times 15}{2 \times 15} = \frac{15}{4} = 3.75 \Omega$$



$$\Rightarrow 3.75 + 3.75 = 7.50 \Omega$$

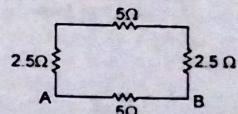
\Rightarrow



\Rightarrow

$$7.5 || 7.5 \Rightarrow \frac{7.5 \times 7.5}{7.5 + 7.5} = \frac{56.25}{15} = 3.75 \Omega$$

Now



$$\Rightarrow R_{AB} = 2.5 + 2.5 + 5 + 5 = 15 \Omega \text{ Ans.}$$

Q.21. Find the current through, 2 ohm resistor using nodal analysis and Thevenin's theorem for the circuit shown in fig A. (IPU-2016)

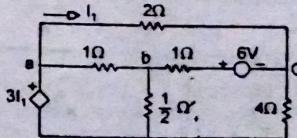
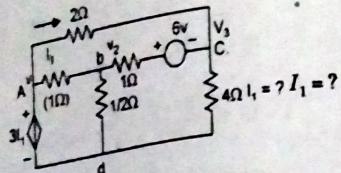


Fig.A



Nodal Analysis

$$V_1 = 3I_1$$

$$= \frac{V_2 - V_1}{1} + \frac{V_2 - 6 - V_3}{1} + \frac{2V_1}{1} = 0$$

$$4V_1 - V_1 - V_3 = 6$$

$$\frac{V_1 - V_2}{2} = I_1$$

Now,

$$2I_1 = V_1 - V_3$$

$$V_1 = \frac{3(V_1 - V_3)}{2}$$

$$[3V_3 = V_1]$$

∴

$$= \frac{V_1}{4} + \frac{V_2 + 6 - V_1}{1} + \frac{V_3 - V_1}{2} = 0$$

$$V_3 + 4V_3 + 24 - 4V_1 + 2V_3 - 2V_1 = 0$$

$$7V_3 - 6V_1 = 24$$

After solving

$$V_1 = 99 \text{ volt}, V_3 = 33 \text{ volt}$$

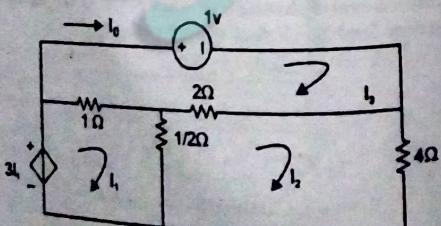
$$I_1 = \frac{V_1 - V_3}{2} = \frac{99 - 33}{2} = \frac{66}{2}$$

$$[I_1 = 33 \text{ Amp}] \text{ Ans.}$$

Thevenin's Equivalent-

For R_{TH}

$$R_{TH} = \frac{1}{I_0}$$



$$3I_1 + (I_1 - I_3) + \frac{1}{2}(I_1 - I_2) = 0$$

$$\Rightarrow 4I_1 - I_3 + \frac{1}{2}I_1 - \frac{1}{2}I_2 = 0$$

$$\Rightarrow 3.5I_1 - 0.5I_2 - I_3 = 0$$

$$2(I_2 - I_3) + 4I_2 + 1/2(I_2 - I_1) = 0$$

$$2I_2 - 2I_3 + 4I_2 + 0.5I_2 - 0.5I_1 = 0$$

$$\Rightarrow -0.5I_1 + 6.5I_2 - 2I_3 = 0$$

$$0.5I_1 - 6.5I_2 + 2I_3 = 0$$

$$(I_3 - I_1) + 1 + 2(I_3 - I_2) = 0$$

$$\Rightarrow I_3 - I_1 + 1 + 2I_3 - 2I_2 = 0$$

$$\Rightarrow -I_1 - 2I_2 + 3I_3 = -1$$

$$I_1 + 2I_2 - 3I_3 = 1$$

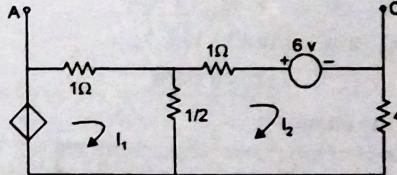
$$I_1 = 0.166 \text{ Amp}$$

$$I_2 = 0.166 \text{ Amp}$$

$$[I_3 = -0.5] \text{ Amp}$$

$$R_{TH} = \frac{1}{0.5} = 2\Omega$$

$$[R_{TH} = 2\Omega]$$

for $V_{TH} = V_{oc}$ 

$$\Rightarrow I_1 + 1/2(I_1 - I_2) = 0$$

$$0.5I_1 - 0.5I_2 = 0$$

$$I_2 + 6 + 4I_2 + 1/2(I_2 - I_1) = 0 \quad I_1 = 1 \text{ amp.}$$

$$I_2 + 6 + 4I_2 + 1/2I_2 - 0.5I_1 = 0 \quad I_2 = -1 \text{ amp}$$

$$-0.5I_1 + 5.5I_2 = -6$$

$$\frac{V_{oc}}{I_1} = V_{TH}$$

$$\Rightarrow 1 \times I_1 + 1I_2 + 6$$

$$= 1 - 1 + 6$$

$$= 6V$$

$$[V_{TH} = 6V] \text{ Ans.}$$

UNIT-II

Q.22 In the circuit shown in Fig. A, $I_s = \cos 1000 t$. Determine the frequency domain circuit and determine the phasors I_1 and I_2 . Draw the phasor diagram for V_1 , V_2 , V_3 and V_4 in the same figure. (IPU-2016)

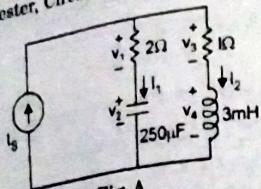


Fig. A.

Ans.

Comparing with reference equation-

$$\begin{aligned}I_s &= \cos 1000t \\I_s &= \cos \omega t \Rightarrow \omega = 1000 \\&= 2\pi f = 1000\end{aligned}$$

$$f = \frac{1000}{2\pi}$$

$$f = 159.15 \text{ Hz}$$

$$C = 250 \mu\text{F}, X_C = \frac{1}{2\pi f C}$$

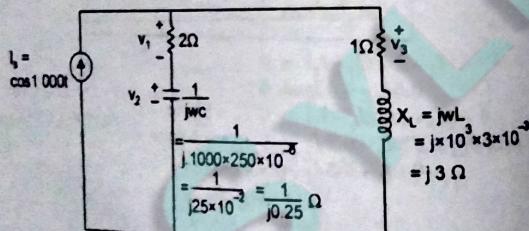
Now

$$\begin{aligned}X_L &= 2\pi f L = 2\pi \times 159.15 \times 3 \times 10^{-3} \\&= 4.00 \Omega\end{aligned}$$

$$L = 3 \text{ mH } X_L = 2\pi f l = 2\pi \times 159.15 \times 3 \times 10^{-3}$$

$$X_L = 0.333 \Omega$$

Frequency domain circuit



=

$$Z_{eq} = Z_1 || Z_2$$

$$= \left(2 + \frac{1}{j\omega c} \right) \parallel (1 + j\omega L)$$

$$= \frac{\left(2 + \frac{1}{j0.25} \right) \times (1 + j3)}{\left(2 + \frac{1}{j0.25} \right) + (1 + j3)} = \frac{(2 - j4)(1 + j3)}{(2 - j4) + (1 + j3)}$$

$$Z_{eq} = \frac{(14 + j2)}{(3 - j)} = (4 + j2) \Omega$$

$$\begin{aligned}V_{eq} &= I_m \times Z_{eq} = 1 \times (4 + j2), [I_m = 1] \\&= (4 + j2) \text{ volt}\end{aligned}$$

⇒ Now

$$I_1 = \frac{V_{eq}}{Z_1} = \frac{(4 + j2)}{(2 - j4)} = 1 \angle 90^\circ$$

$$I_2 = \frac{V_{eq}}{Z_2} = \frac{(4 + j2)}{(1 + j3)} = 1.414 \angle -45^\circ \text{ amp}$$

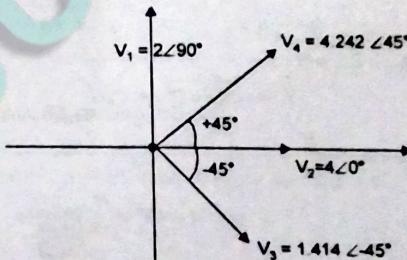
$$V_1 = I_1 \times 2 = 1 \angle 90^\circ \times 2 = 2 \angle 90^\circ$$

$$V_2 = I_1 \times (-j4) = 1 \angle 90^\circ \times (j4) = 4 \angle 0^\circ$$

$$V_3 = I_2 \times 1 = 1.414 \angle -45^\circ \times 1 = 1.414 \angle -45^\circ$$

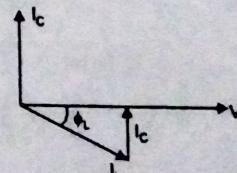
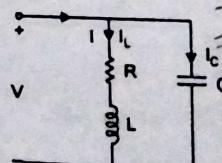
$$V_4 = I_2 \times j3 = 1.414 \angle -45^\circ \times j3 = 4.242 \angle 45^\circ$$

Phasor diagram



Q.23. For a parallel RLC circuit define resonant frequency, damped resonant frequency and Q. Obtain exact expressions for half power frequencies in terms of resonant frequency and Q. (IPU-2016)

Ans. Parallel Resonant



⇒ The admittance of the circuit is

$$Y = j\omega c + \frac{1}{R + j\omega L} = j\omega c + \frac{R - j\omega L}{R^2 + \omega^2 L^2}$$

$$\frac{R}{R^2 + \omega^2 L^2} + j\omega \left(C - \frac{L}{R^2 + \omega^2 L^2} \right)$$

At resonance the j term is zero, and $\omega = \omega_0$:

$$C \frac{L}{R^2 + \omega_0^2 L^2} = 0$$

$$R^2 + \omega_0^2 L^2 = \frac{L}{C}$$

$$\omega_0^2 L^2 = \frac{L}{C} - R^2 \Rightarrow \omega_0 = \sqrt{\frac{1}{LC} - \frac{R^2}{L^2}} \text{ rad/sec}$$

Resonant frequency in Hz

$$f_0 = \frac{\omega_0}{2\pi} = \frac{1}{2\pi} \sqrt{\frac{1}{LC} - \frac{R^2}{L^2}} \text{ rad/sec}$$

if R is small than

$$f_0 = \frac{1}{2\pi} \sqrt{\frac{1}{LC}} \text{ Hz}$$

bandwidth

$$\text{At } f_1, \text{ susceptance } B_{L1} - B_{CL} = G$$

$$\text{At } f_2, \text{ susceptance } B_{CL} - B_{L2} = G$$

$$Y = \sqrt{(G^2 + B^2)} = \sqrt{2}G$$

$$\text{and phase angle } \phi = \tan^{-1} \frac{B}{G}$$

$$= \tan^{-1} 1 = 45^\circ \text{ or } \frac{\pi}{4} \text{ radian.}$$

Quality factor

$$\text{Q-factor} = \frac{\text{Circulating current between Land C}}{\text{Line current}}$$

$$I_C = 2 \pi f_r C V$$

line current,

$$I = \frac{V}{L C R} = V_c R / L$$

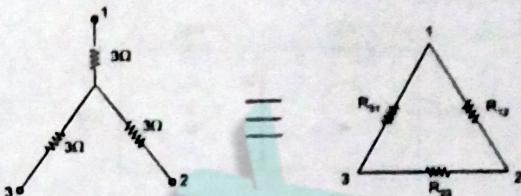
$$\text{Q-factor} = \frac{I_C}{I} = \frac{2 \pi f_r L}{R}$$

$$f_r = \frac{1}{2\pi} \sqrt{\frac{1}{LC}}$$

$$\text{Q-factor} = 2\pi \times \frac{1}{2\pi} \sqrt{\frac{1}{LC}} \times \frac{L}{R}$$

$$Q = \frac{1}{R} \sqrt{\frac{L}{C}} \text{ Ans.}$$

Q.24. Three equal resistance of 8 ohm are connected in star. What resistance in one of the arms in an equivalent delta circuit? (IPU-2017)



$$R_{31} = R_{23} = R_{12} = 3 + 3 + \frac{3 \times 3}{3} = 9 \Omega$$

Q.25 Find the Thevenin's and Norton's Equivalents for the circuit as shown in fig 1 with respect to terminals ab. (IPU-2017)

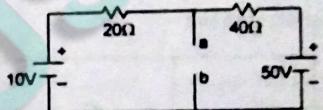


Fig 1

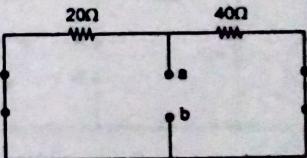
Ans. (a) Thevenin's Equivalent circuit

Step (i)

$$i = \frac{50 - 10}{20 + 40} = \frac{40}{60} = \frac{2}{3} A$$

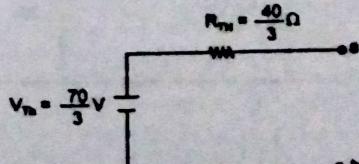
$$V_{ab} = V_{ab} = 50 - 40 \times \frac{2}{3} = \frac{70}{3} V$$

Step (ii) For R_{Th}

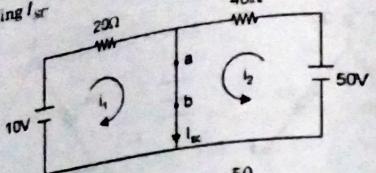


$$R_{Th} = 20 \Omega \parallel 40 \Omega = \left(\frac{1}{20} + \frac{1}{40} \right)^{-1} = \frac{40}{3} \Omega$$

Step (iii) Thevenin equivalent circuit



(b) Norton's Equivalent circuit:
Step (i) For finding I_{sc}



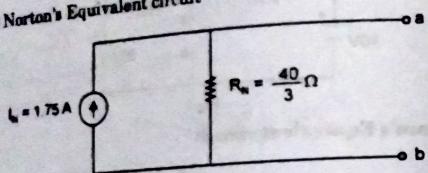
$$i_1 = \frac{10}{20} = 0.5 \text{ A}; i_2 = \frac{50}{40} = 1.25 \text{ A}$$

$$I_{sc} = i_1 + i_2 = 0.5 + 1.25 = 1.75 \text{ A}$$

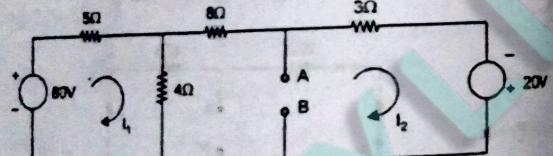
Step (ii) For finding R_N

$$R_N = R_{th} = \frac{40}{3} \Omega$$

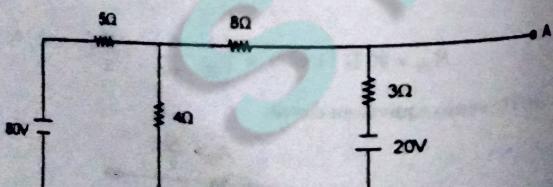
Step (iii) Norton's Equivalent circuit



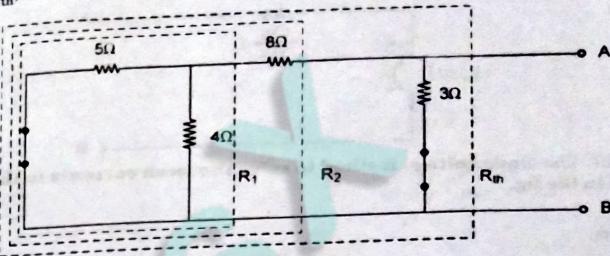
Q.26 Obtain Thevenin equivalent circuit at AB as in fig. (IPU-III)



Ans.



for R_{th}



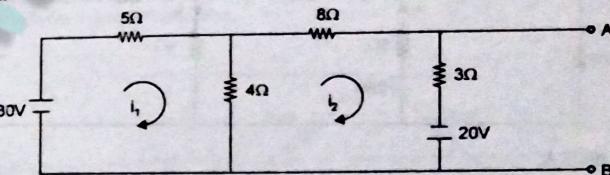
$$R_1 = 5\Omega \parallel 4\Omega$$

$$= \left(\frac{1}{5} + \frac{1}{4} \right)^{-1} = \frac{20}{9} \Omega$$

$$R_2 = \left(\frac{20}{9} \Omega \right) + 8\Omega = \frac{92}{9} \Omega$$

$$R_{th} = R_2 \parallel 3\Omega = \left(\frac{92}{9} + \frac{1}{3} \right)^{-1} = \frac{276}{119} \Omega$$

for V_{th}



Apply KVL,

$$80 - 5i_1 - 4(i_1 - i_2) = 0$$

$$9i_1 - 4i_2 = 80 \quad \dots(1)$$

$$4(i_2 - i_1) + 8i_2 + 3i_2 + 20 = 0$$

$$4i_1 - 15i_2 = 20 \quad \dots(2)$$

equation (2) $\times 9 - \text{eq. (1)} \times 4$

$$119i_2 = 140$$

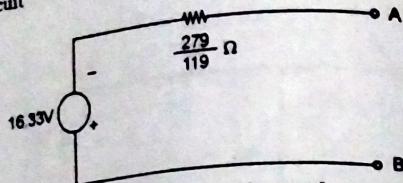
$$i_2 = \frac{140}{119}$$

$$V_{th} = 3i_2 - 20$$

$$= 3 \times \frac{140}{119} - 20 = \frac{420 - 2380}{119} = \frac{-1960}{119}$$

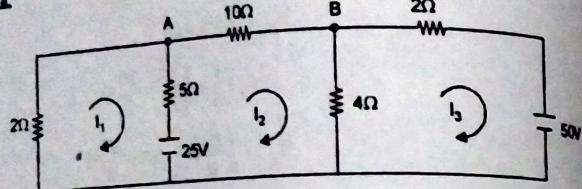
$$= -16.33V$$

Equivalent circuit

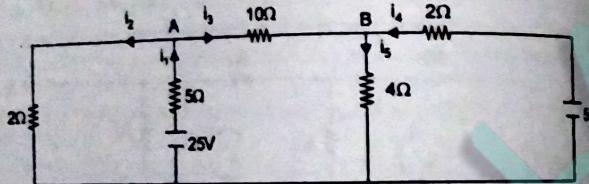


Q.27. Use node voltage method to solve the mesh currents in the network shown in the fig. (IPU-2018)

Ans.



Using Node Voltage Method,



At node A,

$$i_1 = i_2 + i_3$$

$$\frac{25 - V_A}{5} = \frac{V_A - 0}{2} + \frac{V_A - V_B}{10}$$

$$50 - 2V_A = 5V_A + V_A - V_B$$

$$8V_A - V_B = 50$$

At node B,

$$i_3 + i_4 = i_5$$

$$\frac{V_A - V_B}{10} + \frac{50 - V_B}{2} = \frac{V_B - 0}{4}$$

$$2V_A - 2V_B + 500 - 10V_B = 5V_B$$

$$2V_A - 17V_B = -500$$

equation (1) - (2) $\times 4$

$$67V_B = 2050$$

$$V_B = \frac{2050}{67} V$$

in equation (1)

$$8V_A = 50 + \frac{2050}{67}$$

$$V_A = \frac{5400}{8 \times 67} = \frac{675}{67} V$$

$$i_2 = \frac{V_A}{2} = \frac{675}{67 \times 2} = \frac{675}{134} A$$

Current

$$I_1 = -i_2 = \frac{-675}{134} A$$

Current

$$I_2 = i_3 = \frac{V_A - V_B}{10} = \frac{675}{67} - \frac{2050}{67} = \frac{-1375}{67} A$$

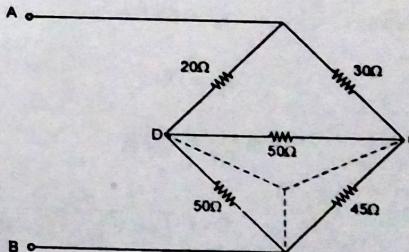
Current

$$I_3 = -i_4 = \frac{V_B - 50}{2}$$

$$= \frac{\frac{2050}{67} - 50}{2} = \frac{1300}{134} = \frac{-650}{67} A$$

Q.28. Find the resistance at A-B terminals in the electric circuit as shown using star-delta transformation. (IPU-2018)

Ans.

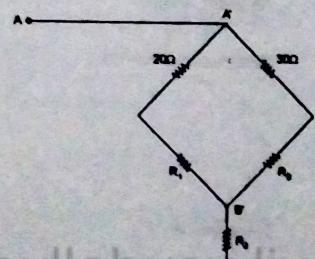


Using Star-Delta conversion

$$R_1 = \frac{50 \times 50}{50 + 50 + 45} = \frac{2500}{145} = \frac{500}{29} \Omega$$

$$R_2 = \frac{50 \times 45}{50 + 50 + 45} = \frac{2250}{145} = \frac{450}{29} \Omega$$

$$R_3 = \frac{50 \times 45}{50 + 50 + 45} = \frac{450}{29} \Omega$$



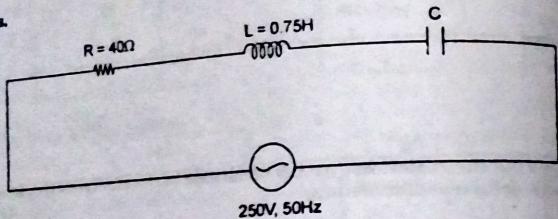
$$R_{AB} = \left(20 + \frac{500}{29} \right) || \left(30 + \frac{450}{29} \right)$$

$$= \left(\frac{29}{1080} + \frac{29}{1320} \right)^{-1} = \frac{120}{29} \left(\frac{1}{9} + \frac{1}{11} \right)^{-1} = \frac{594}{29} \Omega$$

$$R_{AB} = R_{A'B'} + \frac{450}{29} = \frac{594}{29} + \frac{450}{29} = \frac{1044}{29} = 36 \Omega$$

Q.29. A coil of resistance 40Ω and inductance 0.75 H forms part of a circuit for which resonant frequency is 55 Hz . If the supply is $250 \text{ V}, 50 \text{ Hz}$,
 (i) Line current (ii) Power factor (iii) Power consumed (iv) Voltage across
 coil. (IPU-2010)

Ans.



Resonant frequency

$$f_r = 55 \text{ Hz}$$

At resonance,

$$X_L = X_C$$

$$2\pi f_r L = \frac{1}{2\pi f_r C}$$

$$C = \frac{1}{(2\pi f_r)^2 L} = \frac{1}{(2\pi \times 55)^2 \times 0.75} = 11.16 \mu\text{F}$$

At $250V, 50\text{Hz}$

Reactance of circuit,

$$X = \omega L \frac{1}{\omega C}$$

$$X = 2\pi \times 50 \times 0.75 - \frac{1}{2\pi \times 50 \times 11.16 \times 10^{-6}}$$

$$= 235.62 - 285.1 = -49.48 \Omega$$

$$Z = \sqrt{R^2 + X^2} = \sqrt{40^2 + (49.48)^2}$$

$$= 63.63 \Omega$$

Impedance

$$I = \frac{V}{Z} = \frac{250}{63.63} = 3.93 \text{ A}$$

$$\cos \phi = \frac{R}{Z} = \frac{40}{63.63} = .629 \text{ (leading)}$$

$$P = I^2 R = (3.93)^2 \times 40 = 618 \text{ W}$$

$$V_{RL} = I Z_{R-L}$$

$$= 3.93 \sqrt{40^2 + (2\pi \times 50 \times 0.75)^2}$$

$$= 939.2 \text{ V}$$

ACCORDING TO NEW SYLLABUS (EEC 213/EEC-308)

UNIT - I

- Q.1 Refer to Q 1 (b) of First Term Examination 2014 (Pg. No. 1-2014).
 Q.2 Refer to Q 2 (a),(b),(c) of First Term Examination 2014 (Pg. No. 3-2014).
 Q.3 Refer to Q 3 (c) of First Term Examination 2014 (Pg. No. 5-2014).
 Q.4 Refer to Q 1 (b),(c),(d),(e) of End Term Examination 2014 (Pg. No. 1-2014).
 Q.5 Refer to Q 5 (a),(b),(c) of End Term Examination 2014 (Pg. No. 20-21).
 Q.6 Refer to Q 1 (i) to (v),(vii),(ix) of First Term Exam 2015 (Pg. No. 1-2015).
 Q.7 Refer to Q 4 (a) of First Term Examination 2015 (Pg. No. 4-2015).
 Q.8 Refer to Q 1 (a) of End Term Examination 2015 (Pg. No. 16-2015).
 Q.9 Refer to Q 2 (a) of End Term Examination 2015 (Pg. No. 16-2015).
 Q.10 Refer to Q 5 (a),(b) of End Term Examination 2015 (Pg. No. 19-2015).
 Q.11 Refer to Q 1 (a),(b) of First Term Examination 2016 (Pg. No. 1-2-2016).
 Q.12 Refer to Q 2 (a),(b) of First Term Examination 2016 (Pg. No. 3-5-2016).
 Q.13 Refer to Q 3 (a) of First Term Examination 2016 (Pg. No. 5-2016).
 Q.14 Refer to Q 1 (b) of End Term Examination 2016 (Pg. No. 9-2016).
 Q.15 Refer to Q 2 (a) of End Term Examination 2016 (Pg. No. 10-2016).
 Q.16 Refer to Q 4 (a),(b) of End Term Examination 2016 (Pg. No. 11-2016).
 Q.17 Refer to Q 5 (a) of End Term Examination 2016 (Pg. No. 11-2016).
 Q.18 Refer to Q 1 (a),(b),(c),(d),(e) of First Term Exam 2017 (Pg. No. 1-2-2017).
 Q.19 Refer to Q 2 (b) of First Term Examination 2017 (Pg. No. 3-2017).
 Q.20 Refer to Q 3 (a) of First Term Examination 2017 (Pg. No. 4-2017).
 Q.21 Refer to Q 1 (a),(b),(c) of End Term Examination 2017 (Pg. No. 9-2017).
 Q.22 Refer to Q 2 (a) of End Term Examination 2017 (Pg. No. 10-2017).
 Q.23 Refer to Q 3 (a),(b) of End Term Examination 2017 (Pg. No. 11-2017).
 Q.24 Refer to Q 4 (a),(b) of End Term Examination 2017 (Pg. No. 13-14-2017).
 Q.25 Refer to Q 5 (b) of End Term Examination 2017 (Pg. No. 16-2017).
 Q.26 Refer to Q 1 (a),(b),(e) of First Term Examination 2018 (Pg. No. 1-2018).
 Q.27 Refer to Q 2 (a),(b) of First Term Examination 2018 (Pg. No. 3-4-2018).
 Q.28 Refer to Q 4 (a) of First Term Examination 2018 (Pg. No. 7-2018).
 Q.29 Refer to Q 1 (d),(e) of End Term Examination 2018 (Pg. No. 9-2018).
 Q.30 Refer to Q 2 (a),(b) of End Term Examination 2018 (Pg. No. 10-2018).
 Q.31 Refer to Q 3 (a),(b) of End Term Examination 2018 (Pg. No. 11-2018).
 Q.32 Refer to Q 4 (b) of End Term Examination 2018 (Pg. No. 12-2018).

UNIT - II

- Q.1 Refer to Q 1 (c),(d),(e) of First Term Examination 2014 (Pg. No. 1-2014).
 Q.2 Refer to Q 3 (a),(b) of First Term Examination 2014 (Pg. No. 4-2014).
 Q.3 Refer to Q 4 (a),(b) of First Term Examination 2014 (Pg. No. 5,6-2014).
 Q.4 Refer to Q 1 (a) of Second Term Examination 2014 (Pg. No. 7-2014).
 Q.5 Refer to Q 2 (a) of Second Term Examination 2014 (Pg. No. 8-2014).

2021

Fourth Semester, Circuits and Systems

- Q.6 Refer to Q 1 (a) of End Term Examination 2014 (Pg. No. 14-2014).
 Q.7 Refer to Q 2 (b) of End Term Examination 2014 (Pg. No. 15-2014).
 Q.8 Refer to Q 3 (a),(b) of End Term Examination 2014 (Pg. No. 17-2014).
 Q.9 Refer to Q 4 (a),(b) of End Term Examination 2014 (Pg. No. 18-2014).
 Q.10 Refer to Q.6 (a),(b) of End Term Examination 2014 (Pg. No. 22,23-2014).
 Q.11 Refer to Q.1 (vi),(vii),(x) of First Term Examination 2015 (Pg. No. 1,2-2015).
 Q.12 Refer to Q 2 (a),(b) of First Term Examination 2015 (Pg. No. 2,3-2015).
 Q.13 Refer to Q.3 (a),(b) of First Term Examination 2015 (Pg. No. 3,4-2015).
 Q.14 Refer to Q.4 (b) of First Term Examination 2015 (Pg. No. 5-2015).
 Q.15 Refer to Q.1 (b),(c) of End Term Examination 2015 (Pg. No. 14,15-2015).
 Q.16 Refer to Q 2 (b) of End Term Examination 2015 (Pg. No. 16-2015).
 Q.17 Refer to Q.3 of End Term Examination 2015 (Pg. No. 17-2015).
 Q.18 Refer to Q.4 (a),(b) of End Term Examination 2015 (Pg. No. 18-2015).
 Q.19 Refer to Q.3 (b) of First Term Examination 2016 (Pg. No. 6-2016).
 Q.20 Refer to Q 4 (a),(b) of First Term Examination 2016 (Pg. No. 6,7-2016).
 Q.21 Refer to Q.1 (c) of End Term Examination 2016 (Pg. No. 9-2016).
 Q.22 Refer to Q.2 (b) of End Term Examination 2016 (Pg. No. 10-2016).
 Q.23 Refer to Q.5 (b) of End Term Examination 2016 (Pg. No. 12-2016).
 Q.24 Refer to Q.2 (a) of First Term Examination 2017 (Pg. No. 3-2017).
 Q.25 Refer to Q.3 (b) of First Term Examination 2017 (Pg. No. 4-2017).
 Q.26 Refer to Q.4 (a),(b) of First Term Examination 2017 (Pg. No. 6,7-2017).
 Q.27 Refer to Q.2 (b) of End Term Examination 2017 (Pg. No. 10-2017).
 Q.28 Refer to Q.5 (a) of End Term Examination 2017 (Pg. No. 15-2017).
 Q.29 Refer to Q.1 (c) of First Term Examination 2018 (Pg. No. 3-2018).
 Q.30 Refer to Q.3 (a),(b) of First Term Examination 2018 (Pg. No. 5,6-2018).
 Q.31 Refer to Q.4 (b) of First Term Examination 2018 (Pg. No. 7-2018).
 Q.32 Refer to Q 4 (a) of End Term Examination 2018 (Pg. No. 11-2018).
 Q.33 Refer to Q.5 (a),(b) of End Term Examination 2018 (Pg. No. 12,14-2018).

UNIT - III

- Q.1 Refer to Q.1 (a) of First Term Examination 2014 (Pg. No. 1-2014).
 Q.2 Refer to Q.1 (c) of Second Term Examination 2014 (Pg. No. 7-2014).
 Q.3 Refer to Q.1 (x) of Second Term Examination 2015 (Pg. No. 7-2015).
 Q.4 Refer to Q.4 (b) of Second Term Examination 2015 (Pg. No. 13-2015).
 Q.5 Refer to Q.6 (b) of End Term Examination 2016 (Pg. No. 13-2016).
 Q.6 Refer to Q.7 (a) of End Term Examination 2016 (Pg. No. 14-2016).
 Q.7 Refer to Q.1 (d) of End Term Examination 2017 (Pg. No. 9-2017).
 Q.8 Refer to Q.9 (a),(b) of End Term Examination 2017 (Pg. No. 21,22-2017).
 Q.9 Refer to Q.1 (c) of End Term Examination 2018 (Pg. No. 8-2018).
 Q.10 Refer to Q.9 (a) of End Term Examination 2018 (Pg. No. 21-2018).

UNIT - IV

- Q.1 Refer to Q.1 a,b of Second Term Examination 2014 (Pg. No. 7,8-2014)
 Q.2 Refer to Q.2 a,b of First Term Examination 2014 (Pg. No. 9-2014)
 Q.3 Refer to Q.3 a,b of Second Term Examination 2014 (Pg. No. 10,11-2014)
 Q.4 Refer to Q.4 a,b of End Term Examination 2014 (Pg. No. 12-2014)
 Q.5 Refer to Q.5 a,b of End Term Examination 2014 (Pg. No. 23,24-2014)
 Q.6 Refer to Q.6 a,b of Second Term Examination 2015 (Pg. No. 6,7-2015)
 Q.7 Refer to Q.7 a,b of Second Term Examination 2015 (Pg. No. 7,8-2015)
 Q.8 Refer to Q.8 a,b of Second Term Examination 2015 (Pg. No. 9,10-2015)
 Q.9 Refer to Q.9 a,b of End Term Examination 2015 (Pg. No. 15-2015)
 Q.10 Refer to Q.10 a,b of End Term Examination 2015 (Pg. No. 19-2015)
 Q.11 Refer to Q.6 a,b of End Term Examination 2015 (Pg. No. 21,22-2015)
 Q.12 Refer to Q.7 a,b of End Term Examination 2015 (Pg. No. 23-2015)
 Q.13 Refer to Q.8 a,b of End Term Examination 2016 (Pg. No. 10-2016)
 Q.14 Refer to Q.9 a,b of End Term Examination 2016 (Pg. No. 12-2016)
 Q.15 Refer to Q.6 a,b of End Term Examination 2016 (Pg. No. 14-2016)
 Q.16 Refer to Q.7 a,b of End Term Examination 2017 (Pg. No. 9-2017)
 Q.17 Refer to Q.11 a,f,g of End Term Examination 2017 (Pg. No. 16,17-2017)
 Q.18 Refer to Q.5 a,b of End Term Examination 2017 (Pg. No. 18,19-2017)
 Q.19 Refer to Q.7 a,b of End Term Examination 2018 (Pg. No. 8,9-2018)
 Q.20 Refer to Q.11 a of End Term Examination 2018 (Pg. No. 15,16-2018)
 Q.21 Refer to Q.6 a,b of End Term Examination 2018 (Pg. No. 16,17-2018)
 Q.22 Refer to Q.7 a,b of End Term Examination 2018 (Pg. No. 21-2018)
 Q.23 Refer to Q.9 b of End Term Examination 2018 (Pg. No. 21-2018).

THIRD SEMESTER (B.TECH) FIRST TERM EXAMINATION [2014] CIRCUITS AND SYSTEMS [ETEE-207]

Time : 1.30 hrs.

M.M. : 30

Note: Attempt Question no. 1, which is compulsory and any two more questions from remaining. There is step-marking and use of scientific calculator (non-programmable) is permitted. Assume missing data, if any.

Q.1. (a) Clearly distinguish between Transient Analysis and Steady State Analysis. Under what interval of time, as a multiple of Time Constant of the series R-L or series R-C circuit, can we approximate the values of $v(t)$ or $i(t)$ as its steady state value? Why? (14)

Ans. The value of voltage and current during the transient period are known as transient response.

The values of voltage and current after the transient has died out are known as the steady state response *

4 time constant.

Q.1. (b) An LTI system has an impulse response $h(t)$ for which the Laplace transform is

$H(s) = 1/(s + 1)$: $\text{Re}(s) > -1$. Determine the step response for the same LTI system assuming it to be initially relaxed. (2)

Ans.

$$H(s) = \frac{1}{s+1}$$

On taking Inverse LT we get

$$h(t) = e^{-t} u(t)$$

If input is $u(t)$ then $U(s) = \frac{1}{s}$

$$y(s) = \frac{1}{s+1} \times \frac{1}{s} = \frac{1}{s} - \frac{1}{s+1}$$

on taking LT

$$y(t) = u(t) - e^{-t} u(t)$$

Q.1. (c) What is the rate of change of current at $t = 0+$ in a coil of resistance Ω and inductance of 0.8 H when connected to a 200 V DC supply? Determine value using classical method. (2)

Ans.

$$V = R i(t) + L \frac{di(t)}{dt}$$

$$20 = 20 i(t) + 0.8 \frac{di(t)}{dt}$$

$$\frac{di(t)}{dt} + 25 i(t) = 250$$

$$C.F. = K e^{-25t}$$

2-2014

Third Semester, Circuits & Systems

$$PI = \frac{250 e^{-st}}{D + 25} = \frac{250}{25} = 10$$

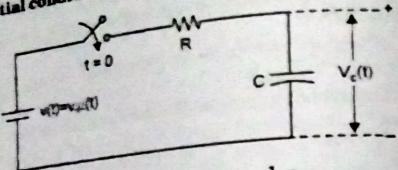
$$i(t) = Ke^{-25t} + 10$$

$$t = 0^+ i = 0 =$$

$$0 = K + 10 \Rightarrow K = -10$$

$$i(t) = 10(1 - e^{-25t})$$

Q.1 (d) Derive an expression for $V_c(t)$ for the circuit given below, assuming zero initial condition.



$$V = R i(t) + \frac{1}{C} \int i(t) dt$$

Ans.

On taking LT

$$\frac{V}{s} = R I(s) + \frac{1}{C} I(s)$$

$$I(s) = \frac{V}{s(R + \frac{1}{CS})} = \frac{CV}{RCS + 1} = \frac{V}{R} \left[\frac{1}{s + \frac{1}{RC}} \right]$$

On taking ILT we get $i(t) = \frac{V}{R} e^{-t/RC}$

$$V_c(t) = \frac{1}{C} \int \frac{V}{R} e^{-t/RC} dt$$

$$= \frac{1}{C} \times \frac{V}{R} \times e^{-t/RC} = Ve^{-t/RC}$$

Q.1 (e) Solve the differential equation, with $y(0) = 0.5$ & $y(0) = 0$

$$\frac{d^2y(t)}{dt^2} + 9 \frac{dy(t)}{dt} + 20y(t) = 1$$

$$\text{Ans. } \frac{d^2Y(s)}{ds^2} + 9 \frac{dY(s)}{ds} + 20Y(s) = 1$$

On taking LT

$$s^2 Y(s) - s y(0^+) - y(0) + 9[sY(s) - y(0^+)] + 20Y(s) = \frac{1}{5}$$

$$s^2 Y(s) - 5S + 9sY(s) - 4.5 + 20Y(s) = \frac{1}{5}$$

$$Y(s)[s^2 + 9s + 20] = \frac{1}{5} + .5s + 4.5$$

$$Y(s) = \frac{.5s^2 + 4.5s + 1}{s(s^2 + 9s + 20)} = \frac{(s^2 + 9s + 2)}{2s(s^2 + 9s + 20)}$$

on taking ILT, we get $y(t)$

Other method to solve

$$CF = D^2 + 9D + 20$$

$$CF = Ae^{-5t} + Be^{-4t}$$

$$= D^2 + 5D + 4D + 20$$

$$(D + 5)(D + 4)$$

$$D = 5, 4$$

$$\text{for } PI \frac{1 e^{0t}}{D^2 + 9D + 20} = \frac{1}{20}$$

$$Y(t) = Ae^{-5t} + Be^{-4t} + \frac{1}{20}$$

$$\text{at } t = 0, Y(0) = .5A + B = .45$$

$$\text{on differentiating } y(t) = -5Ae^{-5t} + e^{-4t} Br - 4$$

$$\text{at } t = 0, y'(0) = 0$$

$$-5A - 4B = 0$$

$$5A = -4B \Rightarrow A = \frac{-4B}{5}$$

$$-\frac{4B}{5} + B = .45$$

$$B = 2.25$$

$$A = -1.8$$

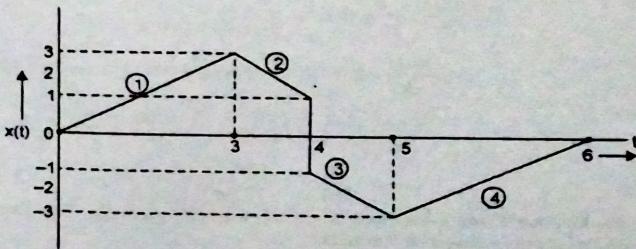
$$y(t) = -1.8e^{-5t} + 2.25e^{-4t} + \frac{1}{20}$$

Q.2. (a) Let $x(t)$ and $y(t)$ be periodic signals with fundamental periods T_1 and T_2 respectively. Under what conditions is the sum $[x(t) + y(t)]$ periodic, and what shall be the fundamental period of the signal, if it is periodic. (2)

Ans. if $\frac{T_1}{T_2}$ is a rational number

T_2 is the Fundamental period

Q.2. (b) Synthesize the given waveform using step, ramp signals only: (4)



$$\text{Ans. } y(t) = t[u(t) - u(t-3)] + (-2t+4)[u(t-3) - u(t-4)] \\ + (-2t+7)[u(t-4) - u(t-5)] + (t-8)[u(t-5) - u(t-8)]$$

Q.2.

(e) Determine $x(t)$ for the following conditions if $X(s)$ is given.

$$\frac{1}{(s+1)(s+2)} \text{ when}$$

- (i) $x(t)$ is right-sided.
- (ii) $x(t)$ is two-sided with ROC lying in between -1 and -2.

$$X(s) = \frac{1}{(S+1)(S+2)} = \frac{1}{S+1} - \frac{1}{S+2}$$

Ans.

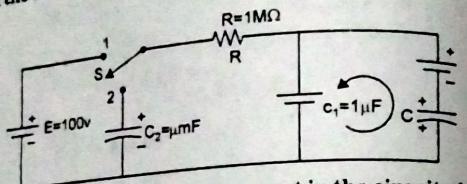
$$x(t) = e^{-t} u(t) - e^{-2t} u(t)$$

$$x(t) = -e^{-t} u(t) - e^{-2t} u(t)$$

(1)

(2)

Q.3. (a) In the circuit of the figure below, switch S has been in position 2 for a long time:



- (i) Find the complete solution for the current in the circuit when S is in position 2.
(ii) How long does it take in seconds for the transient to disappear to decay within 1%
(iii) Determine the voltage which appears across each capacitor at steady state.

Ans.

$$V_c(0^-) = 1000 V$$

$$1000 = R i(t) + \frac{1}{C_2} \int i(t) dt + \frac{1}{C_1} \int i(t) dt$$

on differentiating above equation we get

$$R \frac{di(t)}{dt} + \frac{1}{C_2} i(t) + \frac{1}{C_1} i(t) = 0$$

$$10^6 \frac{di(t)}{dt} + \frac{2}{10^{-6}} i(t) = 0$$

$$\frac{di(t)}{dt} + 2i(t) = 0 \Rightarrow i(t) = A e^{-2t}$$

at

$$t = 0^+ i(0^+) = \frac{-1000}{10^6} = -10^{-3}$$

$$A = -10^{-3}$$

$$i(t) = -10^{-3} e^{-2t}$$

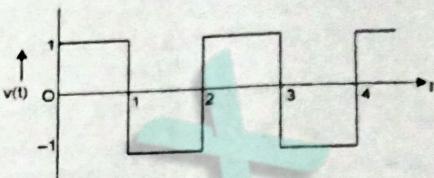
Q.3. (b) Define Time Constant of an RL and RC circuit. Why transients in purely resistive circuits?

Ans.

$$\text{In RL circuit time constant} = \frac{L}{R}$$

$$\text{In RC circuit} = RC$$

Q.3. (c) For the given square wave, determine the Laplace transform, using its properties: (3)



Ans.
on taking LT

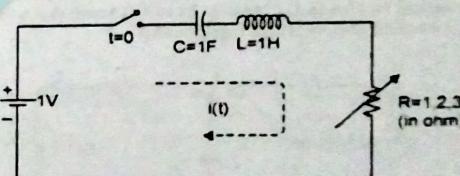
$$x(t) = u(t) - 2u(t-1) - 2u(t-2) - 2u(t-3)$$

$$x(s) = \frac{1}{s} - 2 \frac{e^{-s}}{s} - 2 \frac{e^{-2s}}{s} - 2 \frac{e^{-3s}}{s} + \dots$$

$$= \frac{1}{s} - \frac{2}{s} (e^{-s} + e^{-2s} + e^{-3s} \dots \infty)$$

$$= \frac{1}{s} - \frac{2}{s(1-e^{-s})} = \frac{1}{s} \left[\frac{1-e^{-s}-2}{1-e^{-s}} \right] = \frac{-1}{s} \left(\frac{1+e^{-s}}{1-e^{-s}} \right)$$

Q.4. (a) A series R-L-C circuit having a pure Inducto having Inductance 1 H and a pure Capacitor having Capacitance 1 F is connected with a variable resistor which can take three values: 1 Ω, 2Ω and 3Ω.



Determine $i(t)$ for $t > 0$ in each of the three cases, indicating the nature of response. (Assume all initial conditions to be zero) (6)

$$\text{Ans. } L \frac{di(t)}{dt} + Ri(t) + \frac{1}{C} \int i(t) dt = 1$$

On differentiating above equation we get

$$L \frac{d^2 i(t)}{dt^2} + R \frac{di(t)}{dt} + \frac{1}{C} i(t) = 0$$

$$\frac{d^2 i(t)}{dt^2} + \frac{R}{L} \frac{di(t)}{dt} + \frac{1}{LC} i(t) = 0$$

$$D^2 + \frac{R}{L} D + \frac{1}{LC} = 0$$

$$R = 1, L = 1, C = 1$$

$$D^2 + D + 1 = 0$$

if

$$D = \frac{-1-i\sqrt{3}}{2}, \frac{-1+j\sqrt{3}}{2}$$

$$i(t) = Ae^{\left(\frac{-1-i\sqrt{3}}{2}\right)t} + Be^{\left(\frac{-1+j\sqrt{3}}{2}\right)t}$$

$$t = 0 i = 0$$

$$A+B=0$$

$$R=2$$

$$P^2+2P+1=0$$

$$P = -1, -1$$

$$i(t) = Ae^{-t} + Bte^{-t}$$

$$t = 0 i = 0$$

$$A = 0$$

$$B = 3$$

$$P^2+2P+1=0$$

$$D = b^2 - 4ac$$

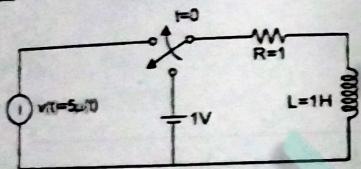
$$P = \frac{5-3-\sqrt{5}}{2} = \frac{3-\sqrt{5}}{2}$$

$$i(t) = Ae^{\left(\frac{3-\sqrt{5}}{2}\right)t} + Be^{\left(\frac{-3+\sqrt{5}}{2}\right)t}$$

$$t = 0 i = 0$$

$$A+B=0$$

Q4. (b) The switch S is moved from the position 1 to position 2 at time $t=0$. A 5V DC is impressed to the R-L circuit. At what time does the voltage across inductor become half of the voltage impressed?



Ans.

$$i(0^-) = iA$$

(because inductor behave as short circuit)

$$5u(t) = 1i(t) + L \frac{di(t)}{dt}$$

$$\frac{d i(t)}{dt} + i(t) = 5u(t)$$

$$Cf = Ae^{-t}$$

$$PI = \frac{5}{D+1} = 5$$

$$i(t) = 5 + Ae^{-t}$$

$$t = 0 \quad i = 1A$$

$$1 = 5 + A \quad A = -4$$

$$i(t) = 5 - 4e^{-t}$$

THIRD SEMESTER (B.TECH) SECOND TERM EXAMINATION [2014] CIRCUITS AND SYSTEMS [ETEE-207]

M.M. : 30

Time : 1.30 hrs.

Note: Attempt Question no. 1, which is compulsory and any two more questions from remaining. There is step-marking and use of scientific calculator (non-programmable) is permitted. Assume missing data, if any.

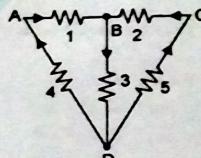
Q.1. (a) Give an expression for the transient response of an initially relaxed purely inductive circuit having an inductance of 1 H when subjected to an input $i = 2 \cos t$.

Ans.

$$i(t) = \frac{1}{L} \int V(t) dt$$

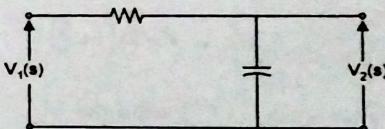
$$i(t) = \frac{1}{1} \int 2 \cos t dt = 2 \sin t$$

Q.1. (b) Define node and branch of an oriented graph. Draw any electrical circuit without using Inductor and Capacitor which represents the following graph with A, B, C, D as nodes and 1 to 5 as branches.

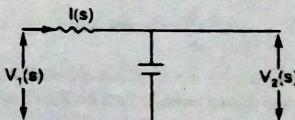


Ans. The components in a circuit is replaced by line segments called branch. Two or more branches meet at a point is called node.

Q.1. (c) Determine $V_2(s)/V_1(s)$ for the given R-C circuit, where R is in ohm and C is in Farad.



Ans.



$$V_1(s) = I(s)R + I(s) \times \frac{1}{Cs}$$

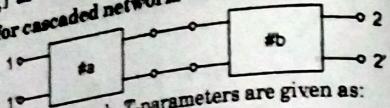
$$I(s) = \frac{V_1(s)}{R + \frac{1}{Cs}}$$

Q1.14

$$V_2(s) = I(s) \times \frac{1}{cs} = \frac{V_1(s)}{R + \frac{1}{cs}} \times \frac{1}{cs}$$

$$\frac{\dot{V}_1(s)}{V_1(s)} = \frac{1/cs}{R + 1/cs} = \frac{1}{1 + Rcs}$$

Q.1. (d) Two networks 'a' and 'b' are connected in cascade as shown. If $[T_a]$ and $[T_b]$ are their inverse transmission parameters, derive the overall value for cascaded network.



Ans. For the cascaded network, T -parameters are given as:
 $[T] = [T_a][T_b]$

$$\text{For the inverse parameters, } [T] = [[T_a][T_b]]'$$

By using matrix property

$$(AB)^{-1} = [B^{-1}A^{-1}]$$

$$T = [T_a][T_b]$$

Q.1. (e) Check whether the polynomial $F(s) = s^3 + 4s^2 + 2s + 8$ is Hurwitz or not.

Ans.

$$s^3 + 4s^2 + 2s + 8$$

odd part = $s^3 + 2s$
 even part = $4s^2 + 8$

$$4s^2 + 8 \overline{s^3 + 2s} (1/9s)$$

$$\frac{s^3 + 2s}{0}$$

$$F(s) = s^3 + 2s \left(1 + \frac{4}{s}\right)$$

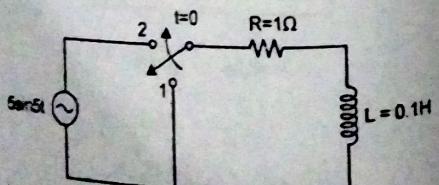
From above equation we can say $\left(1 + \frac{4}{s}\right)$ is Hurwitz

Now check for $s^3 + 2s$

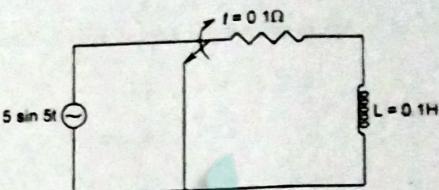
$$s(s^2 + 2) = s(s + i\sqrt{2})(s - i\sqrt{2}) \text{ is Hurwitz}$$

So $F(s)$ is Hurwitz

Q.2. (a) Obtain the current for $t > 0$, if an AC voltage $v = 5 \sin 5t$ is applied across the two terminals of the two port network when the switch 'k' is moved from position 1 to 2 at $t = 0$.



Ans.



$$5 \sin 5t = I(t) \times R + L \frac{dI(t)}{dt}$$

$$= I(t) + 1 \frac{dI(t)}{dt}$$

$$\frac{dI(t)}{dt} + 10 I(t) = 50 \sin 5t$$

$$CF = D + 10 = 0$$

$$D = -10$$

$$CF = Ae^{-10t}$$

$$PI = \frac{50 \sin 5t (D - 10)}{(D + 10)(D - 10)}$$

$$= \frac{(D - 10)(50 \sin 5t)}{D^2 - 10^2}$$

$$= \frac{D(50 \sin 5t) - 500 \sin 5t}{-25 - 100}$$

$$= \frac{5 \times 50 \cos 5t}{-75} + \frac{500}{75} \sin 5t$$

$$E(t) = CF + PI$$

$$= Ae^{-10t} - \frac{10}{3} \cos 5t + \frac{20}{3} \sin 5t$$

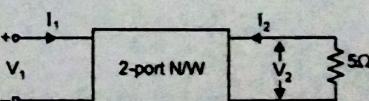
$t = 0$ i.e. 0 (inductor behave as open circuit)

$$0 = A - \frac{10}{3}$$

$$A = \frac{10}{3}$$

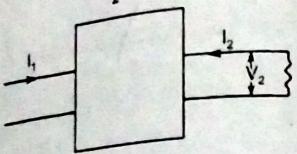
$$I(t) = \frac{10}{3} e^{-10t} - \frac{10}{3} \cos 5t + \frac{20}{3} \sin 5t$$

Q.2. (b) The following equation give the voltage V_1 and V_2 at the two ports of two port network:



$$\begin{aligned}V_1 &= 5I_1 + 6I_2 \\V_2 &= 2I_1 + I_2\end{aligned}$$

A load resistor of 5 ohm is connected across port 2. Calculate its impedance.
Ans.



on putting this value in equation (2)

$$\begin{aligned}-5I_2 &= 2I_1 + I_2 \\-6I_2 &= 2I_1 \Rightarrow I_1 = -3I_2\end{aligned}$$

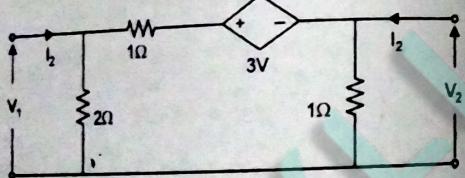
Putting the value of I_1 in equation (1)

$$V_1 = 5I_1 + 6 \times -\left(\frac{I_1}{3}\right)$$

$$V_1 = 5I_1 - 2I_1$$

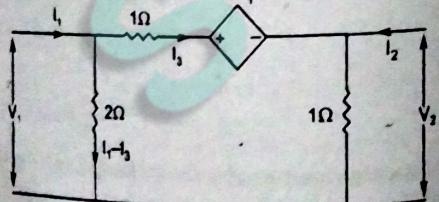
$$Z_{in} = \frac{V_1}{I_1} = 3$$

Q.3. (a) Determine the Z parameters for the following network figure below:



State whether it is reciprocal, symmetrical or not.

Ans.



$$\begin{aligned}I_3 + 3V_1 - 2(I_1 - I_3) - (I_2 + I_3) &= 0 \\4I_3 - 2I_1 + I_2 + 3V_1 &= 0 \\V_2 &= I_2 + I_3\end{aligned}$$

from equation (1), (2) and (3)

$$V_1 = 2I_1 - 2\left(\frac{I_1}{2} - \frac{I_2}{4} - \frac{3V_1}{4}\right) \quad (4)$$

$$V_1 = 2I_1 - I_2$$

$$V_2 = I_2 + \frac{1}{4}(2I_1 - I_2 - 3V_1)$$

$$V = 2I_1 + \frac{3}{2}I_2 \quad (5)$$

from equation 4 and 5

$$Z = \begin{bmatrix} -2 & -1 \\ 2 & 3/2 \end{bmatrix}$$

Q.3. (b) Determine the Incidence Matrix, Cut-set Matrix and Tie-Se matrix, assuming (1, 2, 3) as set of twigs and (4, 5, 6, 7) as set of links, for the given oriented graph. (5)

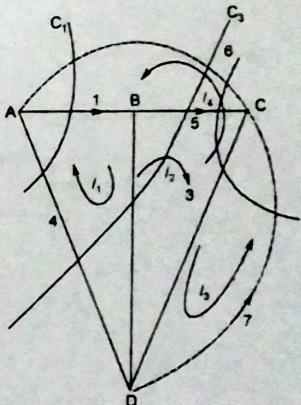
Ans.

Incident matrix

$$A = \begin{array}{|c|ccccccc|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 \\ \hline A & 1 & 0 & 0 & -1 & 0 & -1 & 0 \\ B & -1 & 1 & 0 & 0 & 1 & 0 & 0 \\ C & 0 & 0 & -1 & 0 & -1 & 1 & -1 \\ D & 0 & -1 & 1 & 1 & 0 & 0 & 1 \\ \hline \end{array}$$

Cut set matrix

$$\begin{array}{|c|cccccc|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 \\ \hline c_1 & 1 & 0 & 0 & -1 & 0 & -1 & 0 \\ c_2 & 0 & 0 & 1 & 0 & 1 & -1 & 0 \\ c_3 & 0 & 1 & 0 & -1 & 1 & -1 & 0 \\ \hline \end{array}$$



Tie set

$$\begin{array}{|c|cccccc|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 \\ \hline l_1 & 1 & 0 & 0 & -1 & 0 & -1 & 0 \\ l_2 & -1 & 1 & 0 & 0 & 1 & 0 & 0 \\ l_3 & 0 & 0 & -1 & 0 & -1 & 1 & -1 \\ l_4 & 0 & -1 & 1 & 1 & 0 & 0 & 1 \\ \hline \end{array}$$

Q.4. (a) The driving point impedances of a one port reactive network is given

$$Z(s) = \frac{4s(s^2 + 4)}{(s^2 + 1)(s^2 + 16)}$$

Obtain Foster's I OR Foster's II form of realization. Draw the circuit. (5)

$$Z(s) = \frac{4s(s^2 + 4)}{(s^2 + 1)(s^2 + 16)}$$

Ans.
On partial fraction

$$\frac{A_1 s}{s^2 + 1} + \frac{A_2 s}{s^2 + 16}$$

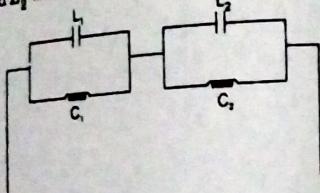
$$A_1 = \left. \frac{4s(s^2 + 4)}{(s - 1j)(s^2 + 16)} \right|_{s=-j} = .8$$

$$A_2 = \left. \frac{4s(s^2 + 4)}{(s^2 + 1)(s - 4j)} \right|_{s=-4j} = 3.2$$

$$Z = \frac{.8s}{s^2 + 1} + \frac{3.2s}{s^2 + 16}$$

$$Z(s) = \frac{\frac{1}{s}}{s^2 + \frac{1}{LC}}$$

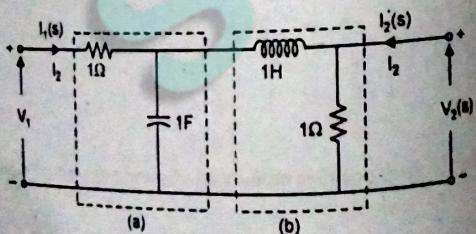
for faster I

on comparing Z_1 and Z_2 with Z we get

$$L_1 = .8 \quad C_1 = \frac{1}{0.8} \quad \frac{1}{LC} = 16$$

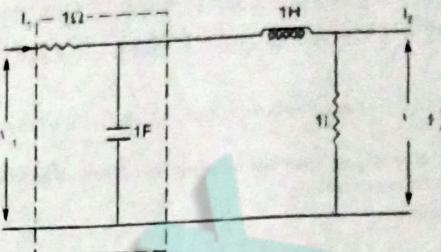
$$L_2 = .2 \quad C_2 = \frac{1}{3.2} \quad L = \frac{1}{16 \times C} = \frac{1}{16}$$

Q.4 (b) Obtain the Transmission parameters for the network shown using properties of inter-connection or otherwise. Check for reciprocity condition.

**Ans.**

$$V_1 = AV_2 + B(-I_2)$$

$$I_1 = CV_2 + D(-I_2)$$



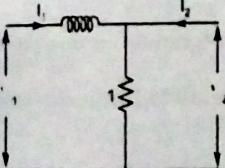
$$V_1 = I_1 + (I_1 + I_2) \frac{1}{s} \\ = I_1 \left(1 + \frac{1}{s} \right) + I_2 / s \quad \dots(1)$$

$$V_2 = \frac{(I_2 + I_1)}{s} \\ I_1 = SV_2 - I_2 \quad \dots(2)$$

Putting the value of I_1 and in equation (1)

$$V_1 = (SV_2 - I_2) \left(1 + \frac{1}{s} \right) + I_2 / s \\ = S \left(1 + \frac{1}{s} \right) V_2 + I_2 \left(s - 1 - \frac{1}{s} \right) \\ = (S + 1) V_2 + I_2 / s - 1 \quad \dots(3)$$

From equation (3) and (2)



$$I_a = \begin{bmatrix} (s+1) & +1 \\ s & 1 \end{bmatrix} \quad \dots(1)$$

$$V_1 = SI_1 + (I_1 + I_2) \quad \dots(1)$$

$$V_2 = (I_2 + I_1) \quad \dots(2)$$

$$I_1 = V_2 - I_2 \quad \dots(2)$$

$$V_1 = (S+1)(V_2 - I_2) + I_2 \quad \dots(2)$$

$$= (S+1)V_2 + I_2(1-S-1) \quad \dots(2)$$

$$= (S+1)V_2 - I_2 S \quad \dots(2)$$

$$T_b = \begin{bmatrix} s+1 & -s \\ 1 & -1 \end{bmatrix} \quad \dots(2)$$

$$T = T_a T_b = \begin{bmatrix} s^2 + 2s + 2 & s^2 + s + 1 \\ s^2 + s + 1 & s^2 + 1 \end{bmatrix}$$

THIRD SEMESTER (B.TECH)
END TERM EXAMINATION [2014]
CIRCUITS AND SYSTEMS [ETEE-207]

Time : 3 hrs.

Note: Attempt any five questions including Q.No. 1 which is compulsory. Answer missing data if any.

Q.1. (a) Show that voltage across a capacitor & current through an inductor cannot change instantaneously.

Ans. For Modulator

$$L_1(t) = \frac{1}{L} \int v_i dt$$

$$L_1(0-) = (0-) t = 0$$

$$L_1(0+) = 0$$

therefore

$$t = 0.$$

$$i_L(0+) = \frac{1}{L} \int_{-\infty}^{0+} V_L dt$$

$$= i_L(0) + \frac{T}{L} \int_{0^-}^{0+} V_L dt$$

Interval 0₋ to 0₊ is almost zero.

$$\text{So } \frac{1}{L} \int_{0^-}^{0+} V_L dt = 0$$

$$i_L(0+) = i_L(0-)$$

Similarly for Capacitor

$$V(0-) = V(0+)$$

This shows the voltage across a capacitor is constant & current across it is constant for instantaneous change

Q.1. (b) A resistor of 10 Ω has a current $i = 6 \sin 500 \pi t$. Find the instantaneous voltage, power & energy over one cycle.

Ans. Instantaneous voltage = $IR = 60 \sin 500 \pi t$

$$\text{Power} = I_{rms}^2 R$$

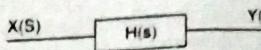
$$= \left(\frac{6}{\sqrt{2}}\right)^2 \times 10 = \frac{360}{2} \times 10 = 1800 \text{ W}$$

$$E = PT$$

$$= p \times \frac{1}{f} = 1800 \times \frac{1}{250} = 72$$

Q.1. (c) Show that the output of an LTI system is simply its impulse response convolved with the excitation.

Ans.



Let a LTI system with transfer function $H(s)$ and input $X(s)$

Then output of the system is

$$y(s) = H(s) \times x(s)$$

Applying convolution theorem

$$H(s) X(s) \xrightarrow{\text{ILT}} h(t) \times x(t)$$

Q.1. (d) State significance of impulse, unit step, ramp & exponential signals why are they used?

Ans. Impulse

$$\delta(t) = \begin{cases} 1 & t = 0 \\ 0 & \text{o.w} \end{cases}$$

Unit step

$$u(t) = \begin{cases} t & t \geq 0 \\ 0 & \text{o.w} \end{cases}$$

$$\text{ramp } r(t) = \begin{cases} t & t \geq 0 \\ 0 & \text{o.w} \end{cases}$$

$$\text{exponential function} = \begin{cases} e^{at} & t \geq 0 \\ 0 & \text{o.w} \end{cases}$$

These all basic signals are used to know the basic input response of the system.

Q.1. (e) Check the system $y(t) = x(t) \cos \omega_0 t$ for time invariance $y(t) = Ax(t) + B$ for linearity. (3 x 5 = 15)

Ans.

$$y(t) = x(t) \cos \omega_0 t$$

1st to Apply Shifted input $x(t - T)$ then output is

$$x(t - T) \cos \omega_0 t$$

and time shifted output is

$$c(t - T) \cos \omega_0 (t - T)$$

both are not equal so system is time variant

$$y(t) = A x(t) + B$$

for input $x_1(t) \rightarrow y_1(t)$

$$y_1(t) = Ax_1(t) + B$$

for input $ax_1(t) + b x_2(t)$

$$y(t) = A(ax_1(t) + b x_2(t)) + B$$

for input $x_2(t) \rightarrow y_2(t)$

$$y_2(t) = Ax_2(t) + B$$

linear combination of output

$$a(Ax_1(t) + B) + b(Ax_2(t) + B)$$

$$y(t) = Aa x_1(t) + aB + bA x_2(t) + bB$$

$$y(t) \neq y'(t)$$

So system is non linear.

16-2014

Q.2. (a) A 2 element series circuit has an average power 940 W & factor 0.707 lagging. Determine the circuits elements if the expressed voltage $v = 99 \sin(6000t + 30^\circ) V$.

Ans. (RL) An ac circuit in which the current lags behind the voltage is said to have a lagging power factor. (RC) An ac amount in which current leads the voltage is said to have a leading power factor.

Lagging power factor means current lags behind voltage means RL circuit

$$\cos \phi = 0.707$$

$$\phi = 45^\circ$$

$$\text{Power} = VI \cos \phi$$

$$940 = 99 \times I \times 0.707$$

$$I = \frac{940}{99 \times 0.707} = 13.42$$

$$I = 13.42 \sin(6000t + 30 - 45) \\ = 13.42 \sin(6000t - 15)$$

Q.2. (b) Derive the "Q" for a parallel RLC circuit.

Ans. θ = factor for parallel RLC

$$\text{Let } V = V_m \sin \omega t$$

$$\text{current through } i_L = \frac{V_m \sin(\omega_0 t - 90)}{XL_0}$$

inductor where

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

Instantaneous energy in circuit is

$$w(t) = \frac{1}{2} L i_L^2 + \frac{1}{2} C V_m^2$$

$$= \frac{1}{2} C V_m^2$$

Average power loss in circuit is

$$P = \frac{V^2}{R} = \frac{(V_m / \sqrt{2})^2}{R} = \frac{V_m^2}{2R}$$

Energy loss per cycle

$$\frac{P \cdot 2\pi}{\omega_0} = \frac{\pi V_m^2}{\omega_0 R}$$

Quality factor

$$Q_{OP} = \frac{2\pi \text{ (maximum energy stored in ckt)}}{\text{total energy loss frequency}}$$

$$= \frac{2\pi \frac{1}{2} C V_m^2}{\pi V^2 / \omega_0 R}$$

$$Q_{OP} = \omega_0 C R$$

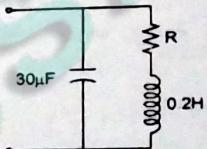
Q.3. (a) Find the rms value of $v = (10 + 14.4 \cos \omega t + 3.55 \sin 3\omega t) V$. (5)

$$\text{Ans. } V^2 = \frac{1}{2\pi} \int_0^{2\pi} v^2 dt = \frac{1}{2\pi} \int (10 + 14.4 \cos \omega t + 3.55 \sin 3\omega t)^2 dt$$

$$V_{rms}^2 = \left(10^2 + \frac{(14.4)^2}{2} + \frac{(3.55)^2}{2} \right)$$

$$V_{rms} = \sqrt{10^2 + \frac{(14.4)^2}{2} + \frac{(3.55)^2}{2}}$$

Q.3. (b) Compare the resonant frequency of the circuit shown for $R = 0$ & $R = 50 \Omega$.



LC parallel tank circuit.

Ans.

if

$$R = 0$$

$$Y = j\omega C + \frac{1}{j\omega L}$$

$$Y = j\omega C - j\frac{1}{\omega L}$$

for resonance

$$\text{Im}(Y) = 0$$

$$\omega C - \frac{1}{\omega L} = 0$$

$$\omega C = \frac{1}{\omega L} \Rightarrow \omega^2 = \frac{1}{LC} \Rightarrow \omega = \frac{1}{\sqrt{LC}}$$

$$R = 50$$

$$Y = j\omega C + \frac{1}{R + j\omega L} : j\omega C + \frac{R - j\omega L}{R^2 + \omega^2 L^2}$$

$$Y = \frac{R}{R^2 + \omega^2 L^2} - j\omega \left(C - \frac{L}{R^2 + \omega^2 L^2} \right)$$

$$\text{Im}(Y) = 0$$

$$j\omega \left(C - \frac{L}{R^2 + \omega^2 L^2} \right) = 0$$

$$C = \frac{L}{R^2 + \omega^2 L^2}$$

$$\omega^2 L^2 C = L - CR^2$$

$$\omega^2 = \frac{L - CR^2}{L^2 C} \Rightarrow \omega = \sqrt{\frac{L - CR^2}{L^2 C}}$$

Putting the value of R , L & C

$$\omega = \sqrt{\frac{2 - 30 \times 10^{-6} \times 2500}{(2)^2 \times 3 \times 10^{-6}}}$$

Q.4. (a) A CT function has $H(s) = \frac{1}{s+5}$. If it is excited by a sinusoidal $x(t) = 10 \cos 200 \pi t$. Find the steady state output function amplitude frequency of the output waveform.

Ans.

$$H(s) = \frac{1}{s+5}$$

$$x(t) = 10 \cos 200 \pi t$$

$$X(s) = \frac{10s}{s^2 + (200\pi)^2}$$

$$y(s) = \frac{1}{s+5} \times \frac{10s}{s^2 + (200\pi)^2} \Rightarrow \frac{A}{s+5} + \frac{B}{s+200\pi j} + \frac{C}{s-200\pi j}$$

$$A = \left. \frac{10s}{s^2 + (200\pi)^2} \right|_{s=-5} = \frac{-50}{25 + 200^2 \pi^2}$$

$$B = \left. \frac{10s}{(s+5)(s-200\pi j)} \right|_{s=200\pi j}$$

$$C = \left. \frac{10s}{(s+5)(s+200\pi j)} \right|_{s=-200\pi j}$$

Steady state output $s \rightarrow 0$ or $t \rightarrow \infty$

Apply final value theorem

$$\lim_{s \rightarrow 0} sy(s) = \lim_{s \rightarrow 0} \frac{10s^2}{(s+5)(s^2 + (200\pi)^2)} = 0$$

Q.4. (b) A CTS is described by $\ddot{y} + 3\dot{y} + 2y = 3r$. Find.

(i) Transfer function $H(s)$.

(ii) Impulse response $h(t)$.

(iii) Step response

(iv) Frequency response

(v) Block diagram representation of this system.

Ans. (i)

$$\ddot{y} + 3\dot{y} + 2y = 3r$$

taking LT

$$s^2 y(s) + 3s y(s) + 2y(s) = 3R(s)$$

$$H \frac{y(s)}{R(s)} = \frac{3}{s^2 + 3s + 2} = \frac{3}{(s+1)(s+2)}$$

$$(ii) \quad \frac{A}{s+1} + \frac{B}{s+2} \Rightarrow A = 3, B = -3$$

$$H(s) = 3 \left[\frac{1}{s+1} - \frac{1}{s+2} \right]$$

on taking iLT

$$h(t) = 3e^{-t} - 3e^{-2t}$$

(iii)

$$y(s) = H(s) \times (s)$$

For unit step input $x(t) = u(t)$

$$x(s) = \frac{1}{s}$$

$$= \frac{3}{(s+1)(s+2)} \times \frac{1}{s} = \frac{3}{s(s+1)(s+2)}$$

$$\frac{A}{s} + \frac{B}{s+1} + \frac{C}{s+2}$$

$$A = \left. \frac{3}{(s+1)(s+2)} \right|_{s=0} = \frac{3}{2}$$

$$B = \left. \frac{3}{s(s+2)} \right|_{s=-1} = \frac{3}{-1(-1+2)} = -3$$

$$C = \left. \frac{3}{s(s+1)} \right|_{s=-2} = 3/2$$

$$y(s) = \frac{3}{2} \times \frac{1}{s} - \frac{3}{s+1} + \frac{3}{2} \frac{1}{s+2}$$

$$y(t) = \frac{3}{2} u(t) - 3e^{-t} + \frac{3}{2} e^{-2t}$$

$$(iv) \quad \frac{3}{(s+1)(s+2)} \text{ putting } s = jw$$

$$H(jw) = \frac{3}{(jw+1)(jw+2)} \Rightarrow \frac{3}{-w^2 + 3jw + 2} = \frac{3}{(2 - \omega^2) + 3j\omega}$$

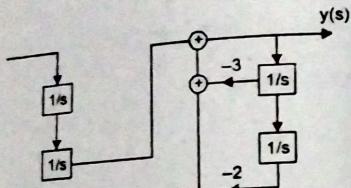
$$\text{on rationalizing } \frac{3[(2 - \omega^2) - 3j\omega]}{(2 - \omega^2)^2 + (3\omega)^2} = \frac{3(2 - \omega^2) - 9j\omega}{4 + \omega^4 + 9\omega^2}$$

$$(i) \frac{3}{s^2 + 3s + 2}$$

$$\frac{\frac{3}{s^2}}{1 + \frac{3}{s} + \frac{2}{s^2}} = \frac{y(s)}{x(s)}$$

$$\frac{3}{s^2}x(s) = y(s) + \frac{3}{s}x(s) + \frac{2}{s^2}y(s)$$

$$y(s) = \frac{3}{s^2}x(s) - \frac{3}{s}y(s) - \frac{2}{s^2}y(s)$$



Q.5. (a) Given $F(s) = \frac{2s+5}{(s+2)(s+5)}$. Find $f(t)$ if the ROC is

- (i) $s > -2$
- (ii) $-5 < s < -2$
- (iii) $s < -5$

$$\text{Ans. (a)} F(s) \frac{2s+5}{(s+2)(s+5)}$$

$$= \frac{A}{s+2} + \frac{B}{s+5}$$

$$A = \left. \frac{2s+5}{s+5} \right|_{s=-2} = \frac{-4+5}{-2+5} = \frac{1}{3}$$

$$B = \left. \frac{2s+5}{5+2} \right|_{s=-5} = \frac{-10+5}{-5+2} = -\frac{5}{3}$$

$$F(s) = \frac{1}{3} \frac{1}{s+2} + \frac{5}{3} \frac{1}{s+5}$$

1. If ROC $s > -2$

$$\frac{1}{2} e^{-st} u(t) + \frac{5}{3} e^{-st}$$

(ii)

$$-5 < s < -2$$

$$\frac{1}{2} e^{-2s} u(-t) + \frac{5}{3} e^{-5s} u(t)$$

$$(iii) s < -5$$

$$\frac{1}{2} e^{-2s} u(t) + \frac{5}{3} e^{-5s} u(-t)$$

Q.5. (b) Show that $LT(f(t)) = s.F(s) - f(0^-)$.

Ans. if

$$L(f(t)) = F(s)$$

then

$$L\left[\frac{df(t)}{dt}\right] = sF(s) - f(0^-)$$

Proof

$$L\left[\frac{d}{dt}f(t)\right] = \int_0^\infty \frac{d}{dt}f(t) e^{-st} dt$$

on integrating by parts

$$u = e^{-st} \text{ and } dv = df(t)$$

$$du = -se^{-st} \text{ and } v = f(t)$$

$$\int u dv = vu - \int v du$$

$$= e^{-st}f(t) \Big|_0^\infty - \int_0^\infty f(t)(-se^{-st}) dt$$

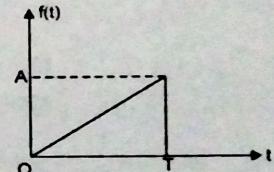
$$= e^{-st}f(t) \Big|_0^\infty + s \int_0^\infty f(t)e^{-st} dt$$

$$= -f(0^-) + sF(s)$$

$$L\left[\frac{d f(t)}{dt}\right] = sF(s) - f(0^-)$$

Q.5. (c) Find Laplace transform (LT) of the saw tooth wave form shown in figure:

Ans.



$$f(t) = \frac{A}{T} t[u(t) - u(t-T)]$$

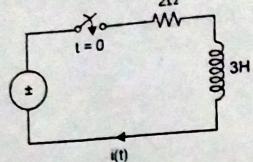
$$= \frac{A}{T} t + u(t) - \frac{A}{T} u(t-T)$$

$$= \frac{A}{T} tu(t) - \frac{A}{T} [(t-T) - u(t-T) + Tu(t-T)]$$

on taking LT

$$FS = \frac{A}{T} \frac{1}{s^2} - \frac{A}{T} \left[\frac{e^{-TS}}{s^2} + T e^{-TS} \right]$$

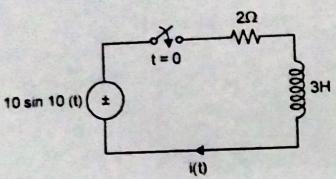
Q.6. (a) Switch is closed at $t = 0$. Find $i(t)$ for $t \geq 0$ using Laplace transform



Ans.

$$\Delta t \quad t = 0$$

$$i = \frac{10 \sin 10(0)}{2}$$



Apply KVL

$$10 \sin 10t = 2i(t) + 3 \frac{di(t)}{dt}$$

$$\text{taking (LT)} = \frac{10 \times 10}{s^2 + 10^2} = 2I(s) + 3s I(s)$$

$$I(s) = \frac{100}{s^2 + 100} \times \frac{1}{(2+3s)} = \frac{A}{3s+2} + \frac{B}{(S+10i)} + \frac{C}{(S-10j)}$$

$$A = \left. \frac{100}{s^2 + 100} \right|_{s=-\frac{2}{3}} = \frac{100}{\frac{4}{9} + 100} = \frac{900}{904}$$

$$B = \left. \frac{100}{(2+3s)(s-10j)} \right|_{s=10j} = \frac{100}{(2-30j)(-20j)}$$

$$= \frac{5}{(-2j-30)}$$

$$C = \left. \frac{100}{(2+3s)(s+10j)} \right|_{s=10j} = \frac{100}{(2+30j)(20j)} = \frac{5}{(2j-30)}$$

$$I(s) = \frac{900}{904 \times 3 \left(s + \frac{2}{3} \right)} + \frac{5}{(-2j-30)} \frac{1}{s+10j} + \frac{s}{(2j-30)} \frac{1}{(s-10j)}$$

$$= \frac{300}{904} e^{-\frac{2}{3}t} + \frac{5}{(-2j-30)} e^{j8t} + \frac{5}{(2j-30)} e^{j10t}$$

Q.6. (b) Find the transient steady state response of a causal system having $h(t) = e^{-t}$ & $x(t) = 10 \sin 4t u(t)$.

Ans.

$$h(t) = e^{-t}$$

$$x(t) = 10 \sin 4t u(t)$$

taking LT

$$H(s) = \frac{1}{s+1} x(s) = \frac{10 \times 4}{s+j^2}$$

$$y(s) = \frac{1}{s+1} \times \frac{40}{s^2 + 4^2}$$

$$= \frac{A}{s+1} + \frac{B}{s+j4} + \frac{C}{s-j4}$$

$$A = \left. \frac{40}{s^2 + 4^2} \right|_{s=-1} = \frac{40}{17}$$

$$B = \left. \frac{40}{(s+1)(s-4j)} \right|_{s=4j} = \frac{40}{(-4j+1)(-8j)} = \frac{5}{(-4+j)}$$

$$C = \left. \frac{40}{(s+1)(s+4j)} \right|_{s=4j} = \frac{40}{(4j+1)(8j)} = \frac{5}{(-4+j)}$$

$$y(s) = \frac{40}{17} \frac{1}{s+1} + \frac{5}{(-4-j)} \frac{1}{(s+j4)} + \frac{5}{(-4+j)} \frac{1}{(s-j4)}$$

$$= \frac{40}{17} e^{-t} + \frac{5}{(-4-j)} e^{-j4t} + \frac{5}{(-4+j)} e^{j4t}$$

Q.7. (a) What are ABCD parameters? Show that $AD-BC = 1$ for a bilateral network.

Ans. In terms of T-parameters

$$V_1 = AV_2 + B(-I_2)$$

$$I_1 = CV_2 + D(-I_2)$$

$$V_1 = V_s I_1, V_2 = 0, I_2 = -I_1$$

$$I'_2 = \frac{V_1}{B}$$

As in figure (b);

$$V_2 = V_s I_2 = I_1 V_1 = 0, I_1 = -I_2$$

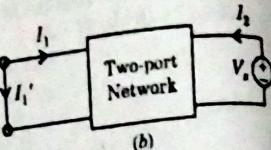
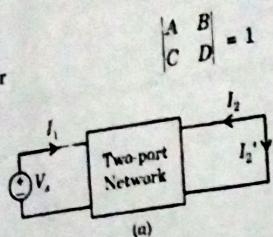
$$I'_1 = V_s \left(\frac{AD-BC}{B} \right)$$

Above discussion leads to the condition of reciprocity,

$$AD - BC = 1 \text{ or } \Delta T = 1$$

$$\begin{vmatrix} A & B \\ C & D \end{vmatrix} = 1$$

or



Q.7. (b) Show that $Z_{11} = Z_{22}$ for a symmetric network & $Z_{12} = Z_{21}$ for a reciprocal network.

Ans. In terms of Z-parameters.

As in (a); $V_1 = V_2, I_1 = I_1, I_2 = 0, V_2 = V_r$

$$V_1 = Z_{11} I_1$$

$$\left. \frac{V_1}{I_1} \right|_{I_2=0} = Z_{11}$$

As in figure 8.14 (b); $V_1 = V_2, I_2 = I_r, I_1 = 0, V_1 = V_r$

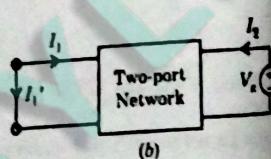
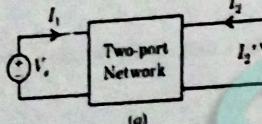
$$V_1 = Z_{21} I_2$$

$$\left. \frac{V_1}{I_2} \right|_{I_1=0} = Z_{21}$$

from the definition of symmetry,

$$\left. \frac{V_1}{I_1} \right|_{I_2=0} = \left. \frac{V_1}{I_2} \right|_{I_1=0} \text{ leads to}$$

$$Z_{11} = Z_{22}$$



In terms of Z-parameters

$$V_1 = Z_{11} I_1 + Z_{12} I_2$$

$$V_2 = Z_{21} I_1 + Z_{22} I_2$$

As in figure (a); $V_1 = V_r, I_1 = I_1, V_2 = 0, I_2 = -I_2$

$$V_1 = Z_{11} I_1 - Z_{12} I_2$$

Therefore,

$$V_1 = Z_{11} I_1 - Z_{12} I_2$$

and

$$0 = Z_{21} I_1 - Z_{22} I_2$$

Hence

$$I_2 = \frac{V_r Z_{21}}{Z_{11} Z_{22} - Z_{12} Z_{21}}$$

As in figure 8.13 (b); $V_1 = V_s I_1 = I_r V_1 = 0, I_1 = -I_2$

Therefore,

$$0 = -Z_{11} I_1 + Z_{12} I_2$$

and

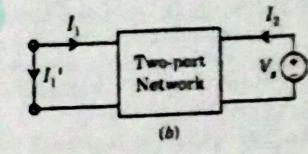
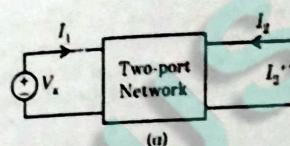
$$V_1 = -Z_{21} I_1 + Z_{22} I_2$$

Hence

$$I_1 = \frac{V_r Z_{21}}{Z_{11} Z_{22} - Z_{12} Z_{21}}$$

Comparing I_2 and I_1' , we get

$$Z_{12} = Z_{21}$$



Q.8. (a) List the difference between tree & cotree. What is meant by the terms Tie set & Cut set?

Ans. The concept of a tree is now introduced. Consider a connected graph G with n nodes and b branches. A tree is defined as a connected graph which has no closed path. Alternatively, a tree graph is a connected graph in which there is a unique path between every pair of nodes. A tree is an important concept in linear graph theory.

A tree is defined as any set of branches in the original graph that is just sufficient to connect all the nodes. This number (of branches) is $n - 1$.

For a given graph it is possible to draw numerous trees. The tree branches are $(n - 1)$, which are called twigs. The remaining branches are called links. The branches of the graph which are not in the tree form the co-tree or complement of the tree. Link is any branch belonging to the co-tree. It is obvious that for each tree there exists a particular co-tree corresponding to that particular tree.

A graph, is then, the union of tree and its co-tree. This decomposition of a graph into tree and co-tree or its branches into twigs and links is not unique.

Number of twigs; $nt = n - 1$

Number of links; $nl = b - nt = b - n + 1$

A tree and its co-tree of graph.

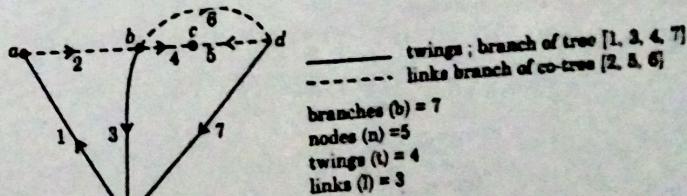


Fig. Tree and co-tree of the oriented linear graph

The tree of a graph has the following properties.

1. In a tree, there exists one and only one path between any pair of nodes.
2. Every connected graph has at least one tree.

3. A connected subgraph of a connected graph is a tree if there exist all the nodes in the graph.

4. Each tree has $(n - 1)$ branches
5. The rank of a tree is $(n - 1)$; this is also the rank of the graph to which it belongs.

Q.8. (b) List the necessary & sufficient condition for +ve real function.
Ans. The necessary and sufficient conditions for a rational function $T(s)$ with coefficients to be p.r. are:

Condition (1): $T(s)$ must have no poles in the right half of s -plane, i.e., Denominator $D(s)$ of $T(s)$ has a factor of the type $s^2 + a$, where a is positive real constant, imaginary axis ($j\omega$ -axis) with real and positive residues. This condition is tested by making partial fraction expansion of $T(s)$ and checking whether the residues of the poles on $j\omega$ -axis are positive and real.

Condition (3): $\operatorname{Re}[T(j\omega)] \geq 0$, for all ω

$$\text{or } A(\omega^2) = M_1(j\omega) \cdot M_2(j\omega) - N_1(j\omega) \cdot N_2(j\omega) \geq 0, \text{ for all } \omega$$

Q.8. (c) Realize $F(s) = \frac{(s+2)(s+5)}{s(s+4)(s+6)}$ using Foster-I & Foster-II representations.

Ans. Foster - I form: Since we know that the residues of poles of $Z_{R-L}(s)$ are and negative. So determine the residues of

$\frac{Z(s)}{s}$ as:

$$\frac{Z(s)}{s} = \frac{(s+2)(s+5)}{(s+1)(s+4)}$$

$$\begin{array}{r} s^2 + 5s + 4 \\ \hline s^2 + 7s + 10 \\ \hline s^2 + 5s + 4 \\ \hline 2s + 6 \end{array} \left(\begin{array}{l} 1 \\ 1 \end{array} \right)$$

$$= 1 + \frac{2s + 6}{(s+1)(s+4)}$$

Using partial fraction expansion.

$$\frac{Z(s)}{s} = 1 + \frac{\frac{4}{3}}{s+1} + \frac{\frac{2}{3}}{s+4}$$

or,

$$Z(s) = s + \frac{\frac{4}{3}s}{s+1} + \frac{\frac{2}{3}s}{s+4}$$

Therefore, synthesized networks is shown in figure (a)

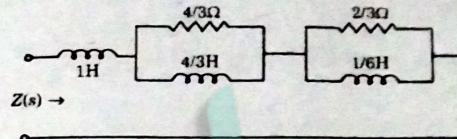


Fig. (a)

Foster-II form:
$$Y(s) = \frac{(s+1)(s+4)}{s(s+2)(s+5)}$$

Using partial fraction expansion, we have

$$Y(s) = \frac{2}{s} + \frac{1}{s+2} + \frac{4}{s+5}$$

Therefore, synthesized network is shown in figure (b).

(b) Cauer-I form:

$$Z(s) = \frac{s^3 + 7s^2 + 10s}{s^2 + 5s + 4}$$

As found in previous example.

$$Z_1 = s, Y_2 = \frac{1}{2}$$

$$Z_3 = s, Y_4 = 1, Z_5 = \frac{1}{2}s$$

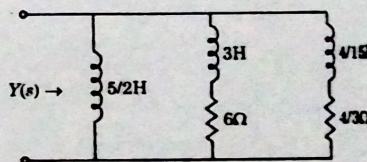


Fig. (b)

Therefore, the synthesized network shown in figure (c).

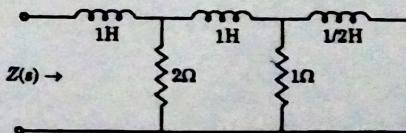


Fig. (c).

28-2014

Third Semester, Circuit & System

Cause-II form:

$$Z(s) = \frac{s^3 + 7s^2 + 10s}{s^3 + 5s + 4} = \frac{10s + 7s^2 + s^3}{4 + 5s + s^2}$$

$$\text{or } Y(s) = \frac{4 + 5s + s^2}{10s + 7s^2 + s^3}$$

As found in previous example.

$$Y_1 = \frac{2}{5s}, Z_2 = \frac{50}{11}, Y_3 = \frac{121}{235s}, Z_4 = \frac{2209}{44}, Y_5 = \frac{4}{47s}$$

Therefore, the synthesized network is shown in figure (d).

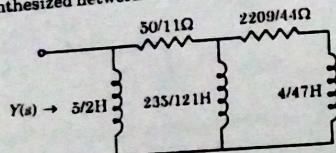


Fig. (d)

FIRST TERM EXAMINATION [SEPT. 2015]

THIRD SEMESTER [B.TECH]

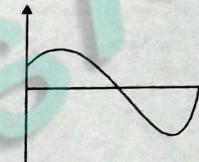
CIRCUIT AND SYSTEMS

M.M. : 30

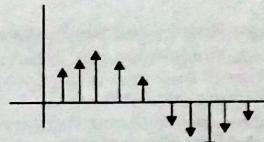
Time. 1.30 Hours

Note: Question No. 1 is compulsory and attempt any two from the rest.

Q.1. (i) What are Continuous-time and Discrete-time Signals? (10 × 1 = 0)

Ans. Signal which has value for all instant of time is called continuous time signal and represented by $x(t)$ Eg:

$$x(t) = \sin t$$

Signal which has value for some particular instant of time is known as discrete time signal $x[n]$ 

Q.1. (ii) What is a Gate Signal?

Ans. Gate Signal

$$g_{t_0, t_1}(t) = \begin{cases} 1 & t_0 < t < t_1 \\ 0 & \text{else} \end{cases} = u(t - t_0) - u(t - t_1)$$

Q.1. (iii) What is a Linear System?

Ans. If $x_1(t)$ is an input of a signal and $y_1(t)$ is the output corresponding to input $x_1(t)$ and $y_2(t)$ is the output corresponding to input $x_2(t)$ and output corresponding to linear combination of $x_1(t)$ and $x_2(t)$ is equal to the linear combination of $y_1(t)$ and $y_2(t)$ then system is known as linear system

Q.1. (iv) What are Singularity Functions?

Ans.

$$\text{sign}(t) = \begin{cases} 1 & t > 0 \\ -1 & t < 0 \end{cases}$$

Q.1. (v) What do you understand by Waveform Synthesis?

Ans. To express any deterministic signal into mathematical expression is known as waveform synthesis.

Q.1. (vi) Define the Time Constant of a series R-L Circuit.

Ans.

$$T = \frac{L}{R}$$

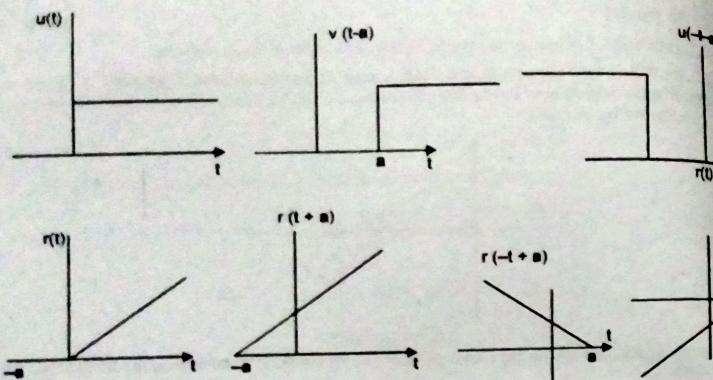
Q.1. (vii) What are the advantages of Laplace Transform technique?

Ans. (i) The homogeneous equation and the particular integral of the solution are obtained in one operation.

(ii) It converts the integro-differential equation onto an algebraic equation in S

**Q.1. (viii) Represent the following functions by suitable Waveforms
 $u(-t-a)$ and $-r(-t+a)$**

Ans.



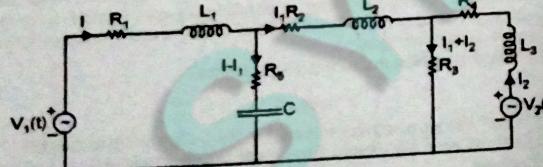
Q.1. (ix) What are Single Energy and Double Energy Transients?

Ans. If the systems contain only resistance Induction or capacitance for C system is known as single energy transient. If the system contain L and C both system is known as double energy transient.

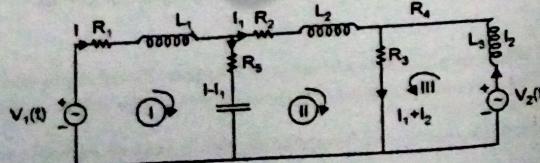
Q.1. (x) Write down the expression for the current in an initially relaxed series R-C Circuit energized by a Step voltage.

$$\text{Ans. } i(t) = \frac{1}{R} e^{-\frac{1}{RC} t}$$

Q.2. (a) Write down the Integro-Differential Equations for the electrical circuit shown in Fig (1) using KVL.



Ans.



On Applying KVL is loop I

$$V_1(t) = IR_1 + L_1 \frac{dI}{dt} + (I - I_1)R_5 + \frac{1}{c} \int (I - I_1) dt$$

on Applying KVL is loop II

$$I_1 R_2 + L_2 \frac{dI_1}{dt} + (I_1 + I_2)R_3 = (I - I_1)R_5 + \frac{1}{c} \int (I - I_1) dt$$

On Applying KVL is loop III

$$V_2(t) = L_3 \frac{dI_2}{dt} + I_2 R_4 + (I_1 + I_2)R_3$$

Q.2. (b) A series circuit consisting of a resistance of 10Ω and an inductance of $2H$ is energized with a ramp function of 5 occurring at $t = 5$ seconds. Find the current $i(t)$ for any time $t \leq 0$ seconds, assuming the initial current through the inductance to be zero.

Ans.

$$t[u(t) - u(t-5)]$$

Applying KVL

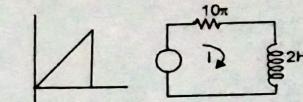
$$t[u(t) - u(t-5)] = 10I + 2 \frac{dI}{dt}$$

taking L.T

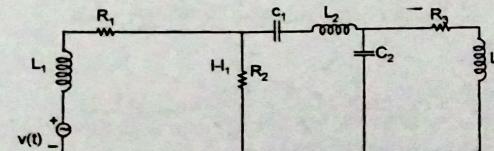
$$= 10I(s) + 2sI(s) = \frac{1}{s^2} - LT((t-5)u(t-5) + 5u(t-5))$$

$$\frac{1}{s^2} - \frac{e^{-5s}}{s^2} - \frac{5e^{-5s}}{s} = I(s)(10 + 2s)$$

$$I(s) = \frac{1 - e^{-5s} - 5se^{-5s}}{s^2(10 + 2s)}$$



Q.3. (a) Frame the performance equations in time domain for the electrical circuit shown in Fig (2) using KCL.



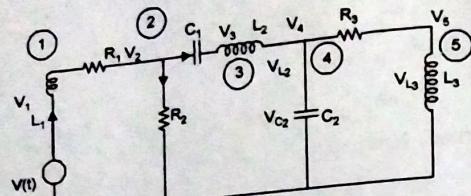
Ans.

Applying KCL at node 1.

$$\frac{1}{L_1} \int [V(t) - V_1(t)] = \frac{V_1 - V_2}{R_1}$$

Applying KCL at node 2

$$\frac{V_1 - V_2}{R_1} = \frac{V_2}{R_2} + C_1 \frac{d(V_2 - V_3)}{dt}$$



Applying KCL at node 3

$$C_1 \frac{d(V_3 - V_2)}{dt} = \frac{1}{L_2} \int (V_3 - V_4) dt$$

At node 4

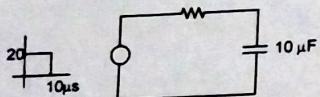
$$\frac{1}{L_2} \int (V_3 - V_4) dt = C_2 \frac{dV_4}{dt} + \frac{V_4 - V_5}{R_3}$$

At node 5

$$\frac{V_4 - V_5}{R_3} = \frac{1}{L_3} \int V_5 dt$$

Q.3. (b) A voltage pulse of 20 volts magnitude and 10 μ s duration is applied to a series R-C Circuit. Determine the current in the circuit. Assume the circuit is initially relaxed. The value of R=10 Ω and C=10 μ F.

Ans.



$$20(u(t) - u(t-10\mu s))$$

Applying KVL

$$20(u(t) - u(t-10\mu s)) = I \times 10 + \frac{1}{10\mu F} \int I dt$$

taking LT

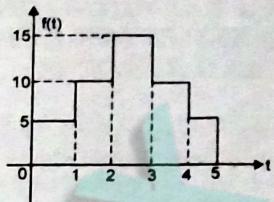
$$20 \left\{ \frac{1}{s} - \frac{e^{-10s}}{s} \right\} = 10I(s) + 10^5 \frac{I(s)}{s}$$

$$I(s) = \frac{20(1 - e^{-10s})}{10s + 10^5}$$

$$= \frac{2(1 - e^{-10s})}{s + 10^4}$$

$$= 2e^{-10s} - 2e^{-10s(t-10)}$$

Q.4. (a) Synthesize the following function into its component signs hence find the mathematical equation for it.

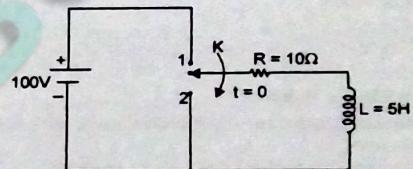


$$\text{Ans. } f(t) = 5(u(t) - u(t-1)) + 10[u(t-1) - u(t-2)] + 15[u(t-2) - u(t-3)] + 10[u(t-3) - u(t-4)] + 5[u(t-4) - u(t-5)]$$

Q.4. (b) The Switch in the circuit shown in Fig (3) is kept in position-1 for a sufficiently long time so that the Steady State Conditions are attained in the circuit. The switch 'K' is moved to position-2 at $t = 0$ sec. Obtain expression for the circuit for any time, $t \geq 0$. Use Laplace transform method.

Ans. When K at position 1 and steady state reach inductor behave as short circuit

$$L = \frac{V}{R} = \frac{100}{10} = 10A$$



when K at 2

$$5 \frac{dI}{dt} + I \times 10 = 0$$

$$\frac{dI}{dt} + 2I = 0$$

$$I = Ae^{-2t}$$

$$t = 0$$

$$i = 10A$$

Putting this values en above equation $10 = Ae^0$

$$I = 10e^{-2t} \rightarrow A = 10$$

$$I = 10e^{-2t}$$

SECOND TERM EXAMINATION [NOV. 2015]

THIRD SEMESTER [B.TECH]

CIRCUITS AND SYSTEMS

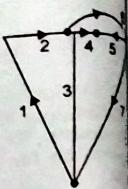
Time: 1.30 Hours

Note: Question No. 1 is compulsory and attempt any two from the rest.

Q.1. (i) What is an Oriented Graph? Explain with an example. (10x1)

Ans. In a graph each branch carries an arrow to indicate its orientation of graph is known as oriented graph.

M.M.



Q.1. (ii) With reference to an Oriented Network Graph define (i) Tree, (ii) Co-tree

Ans. If three is this the 1, 2, 4, 7 is twing and 3, 5, 6 is the co turg and 3, 5, 6 is the co tree or link



Q.1. (iii) What is a Tie-set Schedule?

Ans. Loop which contain only one link are independent are called basic fundamental loops or tie sets.

Q.1. (iv) Define h-Parameters for a two-port network.

Ans.

$$V_1 = h_{11} I_1 + h_{12} V_2$$

$$I_2 = h_{21} I_1 + h_{22} V_2$$

$$h_{11} = \left. \frac{V_1}{V_2} \right|_{V_2=0}$$

$$h_{21} = \left. \frac{V_2}{V_1} \right|_{V_1=0}$$

$$h_{12} = \left. \frac{I_1}{V_2} \right|_{I_1=0}$$

$$h_{22} = \left. \frac{I_2}{V_2} \right|_{I_1=0}$$

Q.1. (v) Define the Network Functions of a Single Port Network.

Ans. In single port network Network function is Impedance and transadmittance

$$Z(s) = \frac{V(s)}{I(s)}$$

$$Y(s) = \frac{I(s)}{V(s)}$$

Q.1. (vi) Write down the relationships between the Z-parameters and Y-parameters.

Ans.

$$Z_{11} = \frac{\Delta h}{h_{22}}$$

$$Z_{12} = \frac{h_{12}}{h_{22}}$$

$$Z_{21} = \frac{-h_{21}}{h_{22}}$$

$$Z_{22} = \frac{1}{h_{22}}$$

where $\Delta h = h_{11} h_{22} - h_{12} h_{21}$

Q.1. (vii) What is the difference between the network analysis and network synthesis?

Ans. To Analysis any circuit is network analysis or to know all parameter of circuit is called network analysis.

Q.1. (viii) What are Hurwitz polynomials?

Ans. Hurwitz polynomial: Polynomial whose all roots lies in left side of imaginary axis.

Q.1. (ix) What do you mean by a Positive Real Function?

Ans. A Transfer function $T(s) = \frac{N(s)}{D(s)}$ is prf if

(1) $T(s)$ is real for all real value of s

(2) $D(s)$ is Hurwitz polynomial

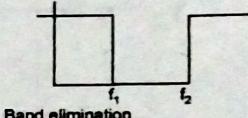
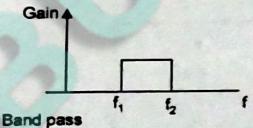
(3) $T(s)$ may have pole on $J\omega$ axis

(4) Real part of $T(s)$ is greater than or equal to zero for the real part of s is greater than or equal to zero

Q.1. (x) What are Band pass and Band Elimination Filters?

Ans. A filter which pass a certain range frequency and reject other all frequency is called Band pass filter.

→ A filter which pass a certain range of frequency is known as Band elimination filter.



Q.2. (a) For the network Graph shown in Fig.1, identify the tie-sets and write the tie-set schedule on the basis of current variables. (5)

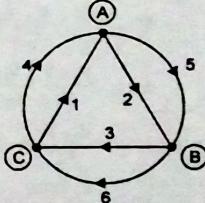
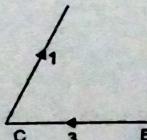
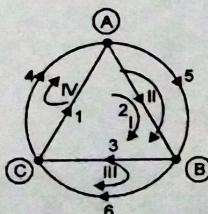


Fig. 1

Ans.



	1	2	3	4	5	6
loop1	1	1	1	0	0	0
loop2	1	0	1	0	1	0
loop3	0	0	-1	0	0	1
loop4	-1	0	0	1	0	0

Q.2. (b) Determine the Y-Parameters of the two-Port network shown in Fig.2.

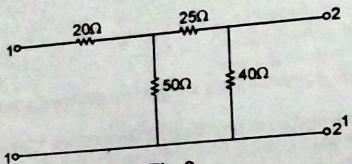
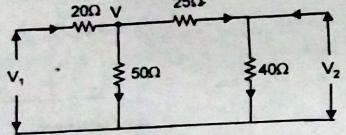


Fig. 2

Ans.



$$\frac{V_1 - V}{20} = \frac{V}{50} + \frac{V - V_2}{25}$$

$$I_1 = \frac{V}{50} + \frac{V - V_2}{25}$$

$$I_2 = \frac{V_2 - V}{25} + \frac{V_2}{40}$$

$$I_1 = \frac{V_1 - V}{20} \Rightarrow -20I_1 + V_1 = V$$

$$I_1 = \frac{V_1 - 20I_1 + V_1 - 20I_1 - V_2}{50} = \frac{V_1 - 40I_1 - V_2}{50}$$

$$I_1 + \frac{20I_1}{50} + \frac{20I_1}{25} = \frac{V_1}{50} + \frac{V_1 - V_2}{25}$$

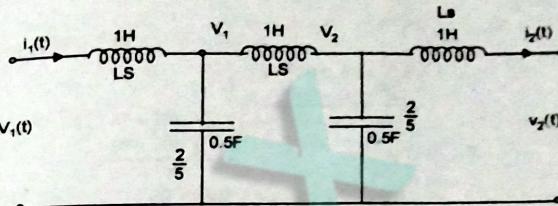
$$\frac{110I_1}{50} = \frac{3V_1}{50} - \frac{V_2}{25}$$

$$I_1 = \frac{3V_1 - V_2}{110 - 55} = \frac{3V_1 - V_2}{55}$$

Putting the value of I_1 in equation (3)

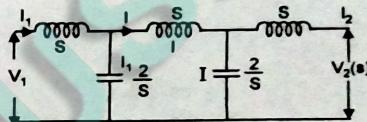
$$I_2 = V_2 \left(\frac{1}{25} + \frac{1}{40} \right) - \frac{1}{25} \left(\frac{20V_2}{55} - \frac{60V_1}{110} \right)$$

Q.3. (a) Find $G_{21}(S)$ for the circuit shown in Fig.3.



(Fig.3)

Ans.



$$G_{21}(s) = \frac{V_2(s)}{V_1(s)} \text{ at } I_2 = 0$$

$$\begin{aligned} Z_{eq}(s) &= \frac{\left(s + \frac{2}{s} \right) \frac{2}{s}}{\left(s + \frac{2}{s} + \frac{2}{s} \right)} + s \\ &= \frac{2(s^2 + 2)}{s^2 + 4} + s \\ &= \frac{s^2}{s^2 + 4} + s \end{aligned}$$

$$= \frac{2(s^2 + 2) + s}{s(s^2 + 4)} = \frac{2s^2 + 4 + s^4 + 4s^2}{s(s^2 + 4)}$$

$$I_1 = \frac{V_1}{\frac{s^4 + 6s^2 + 4}{s(s^2 + 4)}} = \frac{s(s^2 + 4)}{s^4 + 6s^2 + 4} V_1$$

$$I = \frac{\frac{2 \times I_1}{s}}{\left(s + \frac{4}{s} \right)} = \frac{\frac{2}{s} \left(\frac{s(s^2 + 4)}{(s^4 + 6s^2 + 4)} \right) V_1}{\left(s + \frac{4}{s} \right)}$$

$$V_2 = \frac{2}{s} \times I = \frac{2}{s} \times \frac{2}{s} \left(\frac{s(s^2 + 4)}{(s^4 + 6s^2 + 4)} \right) V_1$$

$$\frac{V_2}{V_1} = \frac{4(s^2 + 4)}{(s^4 + 6s^2 + 4)(s^2 + 4)}$$

Q.3. (b) Test the polynomial $Q(s) = s^6 + 2s^5 + 6s^4 + 10s^3 + 9s^2 + 8s + 4$ Hurwitz property.

$$\text{Ans. } s^6 + 2s^5 + 6s^4 + 10s^3 + 9s^2 + 8s + 4$$

$$\begin{array}{r} 2s^6 + 10s^3 + 8s \\ -s^6 + 5s^4 + 4s^2 \\ \hline s^4 + 5s^2 + 4 \\ \left(\frac{1}{2}s \right) 2s^5 + 10s^3 + 8s \\ \hline 2s^6 + 10s^3 + 8s \\ \times \end{array}$$

$$\begin{array}{l} 2s^5 + s^4 + 5s^2 + 4 + 10s^3 + 8s \\ (2s + 1)(s^4 + 5s^2 + 4) \\ (2s + 1) \text{ is hurtwitz} \end{array}$$

$$\begin{array}{r} 4s^3 + 10s \\ -s^4 + 10s^2 \\ \hline \frac{4}{5}s^2 + 4 \\ \left(\frac{4}{5}s^2 + 4 \right) 4s^3 + 10s \\ -4s^3 + 32s \\ \hline \frac{18}{5}s \\ \left(\frac{18}{5}s \right) \frac{5}{2}s^2 + 4 \\ \frac{5}{2}s^2 \\ \hline 4 \\ \left(\frac{18}{5}s \right) \frac{20}{18} \\ \frac{15s}{X} \end{array}$$

all coefficient is the Positive So function is hurwitz.

Q.4. (a) Realize the following driving point impedance function (i) as Foster Form and (ii) as a Second Foster of LC Networks.

$$Z(s) = \frac{s^3 + 4s}{2s^4 + 20s^3 + 18}$$

Ans. From the pole zero diagram

$$Z(s) = \frac{K(s^2 + 1)(s^2 + 9)}{s(s^2 + 4)}$$

$$Z(-2) = \frac{130}{16} = \frac{K \cdot 5 \cdot 13}{-2 \cdot 8} \text{ gives } K = 2$$

$$Z(s) = \frac{2(s^2 + 1)(s^2 + 9)}{s(s^2 + 4)}$$

By putting

Therefore,

(a) Foster - I Form:

$$\begin{array}{r} s^3 + 4s \\ \left(\frac{2s^3 + 8s^2}{12s^2 + 18} \right) 2s \\ \hline 2s^4 + 20s^3 + 18 \end{array}$$

$$Z(s) = 2s + \frac{12s^2 + 18}{s(s^2 + 4)}$$

Using partial fraction expansion,

$$\begin{array}{l} \frac{12s^2 + 18}{s(s^2 + 4)} = \frac{A}{s} + \frac{Bs + C}{s^2 + 4} \\ A = 9/2, C = 0 \text{ and } B = \frac{15}{2} \end{array}$$

Therefore,

$$Z(s) = 2s + \frac{\frac{9}{2}}{s} + \frac{\frac{15}{2}s}{s^2 + 4}$$

We then obtain the synthesized network in figure 1(a).

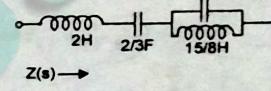


Fig. 1.(a)

Foster-II form:

$$Y(s) = \frac{s(s^2 + 4)}{2(s^2 + 1)(s^2 + 9)}$$

Using partial fraction expansion,

$$\begin{array}{l} \frac{s(s^2 + 4)}{2(s^2 + 1)(s^2 + 9)} = \frac{1}{2} \left[\frac{As + B}{s^2 + 1} + \frac{Cs + D}{s^2 + 9} \right] \\ A = \frac{3}{8}, B = D = 0, C = \frac{5}{8} \end{array}$$

Therefore,

$$Y(s) = \frac{1}{2} \left[\frac{\frac{3}{8}s}{s^2 + 1} + \frac{\frac{5}{8}s}{s^2 + 9} \right]$$

$$= \frac{\frac{3}{16}s}{s^2 + 1} + \frac{\frac{5}{16}s}{s^2 + 9}$$

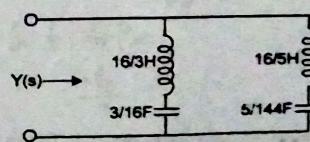


Fig. 1.(b)

Hence, synthesized network is shown in figure 1 (b).

(b) Cauer-I form:

$$Z(\bar{s}) = \frac{2(s^2 + 1)s^2 + 18}{s(s^2 + 4)} = \frac{2s^4 + 20s^2 + 18}{s^3 + 4s}$$

The continued fraction expansion is

$$\frac{s^3 + 4s}{2s^4 + 8s^2} \left(\frac{2s^4 + 18}{2s^4 + 8s^2} \leftrightarrow Z_1 \right)$$

$$\frac{12s^2 + 18}{s^3 + 3s} \left(\frac{1}{12}s \leftrightarrow Y_2 \right)$$

$$\frac{\frac{5}{2})12s^2 + 18}{12s^2} \left(\frac{2}{5} \times 12s = \frac{24}{5}s \leftrightarrow Z_2 \right)$$

$$\frac{18}{\frac{5}{2}s} \left(\frac{1}{18} \cdot \frac{1}{18}s = \frac{1}{18}s \leftrightarrow Y_4 \right)$$

$$\frac{\frac{5}{2}s}{x}$$

Therefore, the final synthesized network is shown in figure 1. (c).

Cauer-II form:

$$Z(s) = \frac{2s^4 + 20s^2 + 18}{s^3 + 4s}$$

$$= \frac{18 + 20s^2 + 2s^4}{4s + s^3}$$

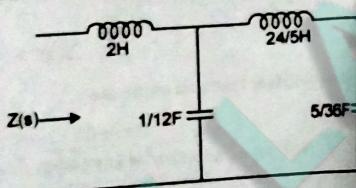


Fig. 1(c)

The Continued fraction expansion is

$$\frac{4s + 63}{18 + 9s^2} \left(18 + 20s^2 + 2s^4 \left(\frac{18}{4s} = \frac{9}{2s} \leftrightarrow Z_1 \right) \right)$$

$$18 + \frac{9}{2}s^2$$

$$\frac{31s^2 + 2s^4}{\frac{3}{2}s^2 + 2s^4} \left(4s + s^3 \left(\frac{2}{31} \cdot \frac{4}{5} = \frac{8}{315} \leftrightarrow Y_2 \right) \right)$$

$$\frac{48 \cdot 16s^3}{13} \left(\frac{31s^2 + 2s^4}{\frac{15}{2}s^2} \left(\frac{31}{15} \cdot \frac{31}{2s} = \frac{981}{308} \leftrightarrow Z_3 \right) \right)$$

$$\frac{31s^2}{2s^4} \left(\frac{15}{31}s^2 \left(\frac{1}{2} \cdot \frac{15}{31s} = \frac{15}{62s} \leftrightarrow Y_4 \right) \right)$$

$$\frac{15}{31}s^3$$

The synthesized network is shown in figure 1 (d).

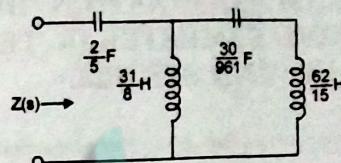
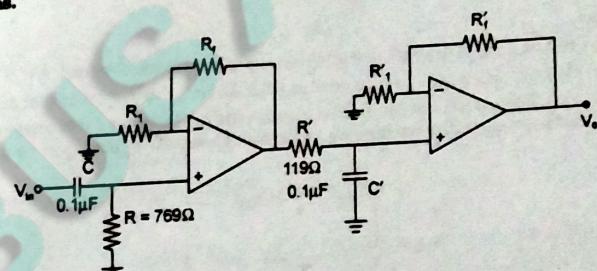


Fig. 1 (d)

Q.4. (b) Design a Band Pass Filter having a Design impedance of 400Ω and cut off frequencies of 2 KHz and 8 KHz.

Ans.



Given that
and
we know that

$$f = 2 \text{ KHz for HPF}$$

$$f = 8 \text{ KHz for LPF}$$

$$f = \frac{1}{2\pi RC}$$

$$C = 0.1\mu\text{F} \text{ then}$$

$$2 \times 10^3 = \frac{1}{2\pi \times R \times 0.1\mu\text{F}}$$

$$R = \frac{1}{2 \times 3.14 \times 2 \times 10^3 \times 0.1 \times 10^{-6}} = 796\Omega$$

$$8\text{KHz} = \frac{1}{2\pi RC}$$

$$R = \frac{1}{2 \times 3.14 \times 8 \times 10^3 \times 0.1 \times 10^{-6}}$$

$$R = 199\Omega$$

END TERM EXAMINATION [DEC. 2015]

THIRD SEMESTER [B. TECH]

CIRCUIT AND SYSTEM

Time: 3 Hrs.

Note: Attempt any five question including Q no. 1. which is compulsory. Select one question from each unit.

Q.1. (a) Determine the following systems are LT1, causal or not.

$$(i) y(t) = t^2 x(t-1)$$

$$(ii) y(n) = \sum_{k=n_0}^{n+n_0} x(k)$$

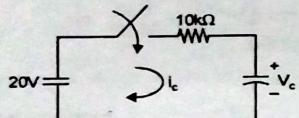
Ans.

$$y(t) = t^2 x(t-1)$$

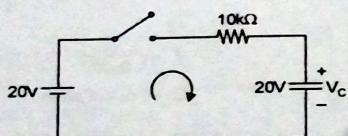
(i) Present output depends on only past input so system is causal.

(ii) Present output depends on past and future input so system is non causal.

Q.1. (b) The switch in the following circuit is closed at $t = 0$, determine equations for capacitor voltage and current. Compute v_c and i_c at $t = 50$ ms.



Ans.



$$20 = 10^4 I + \frac{1}{C} \int I dt$$

On differentiating we get

$$\frac{1}{C} I + 10^4 \frac{dI}{dt} = 0$$

$$\frac{dI}{dt} + \frac{1}{10^4 C} I = 0$$

$$I = A e^{-\frac{t}{10^4 C}}$$

at

$$t = 0 \quad I = \frac{20}{10^4} = 2 \times 10^{-3} A$$

$$V = \frac{1}{C} \int I dt = \frac{1}{C} \int A e^{-t/10^4 C} dt$$

Putting the value of initial condition we get

$$A = 2 \times 10^{-3} A$$

$$I = 2 \times 10^{-3} e^{-\frac{t}{10^4 C}}$$

Q.1. (c) Find Laplace transform of $\frac{1}{4} t \sin(2t) u(t)$.

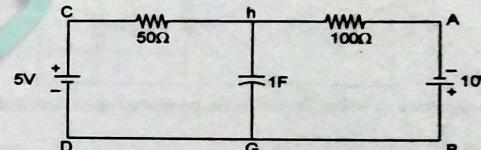
$$\text{Ans. LT } \sin 2t \rightarrow \frac{2}{s^2 + 2^2}$$

Applying differentiation property we get

$$\text{LT of } t \sin 2t \rightarrow -\frac{d\left(\frac{2}{s^2 + 2^2}\right)}{ds} = \frac{2s \times 2}{(s^2 + 4)^2} = \frac{4s}{(s^2 + 4)^2}$$

$$\text{So LT of } \frac{1}{4} t \sin 2t = \frac{s}{(s^2 + 4)^2}$$

Q.1. (d) For the following circuit draw directed graph and write incidence matrix.

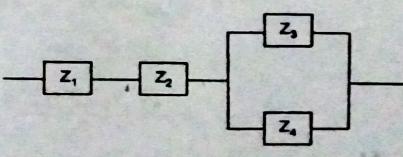


Ans.

1	2	3	4	5
a	1	0	-1	-1
b	0	-1	1	0
c	-1	1	0	0
d	0	0	-1	1

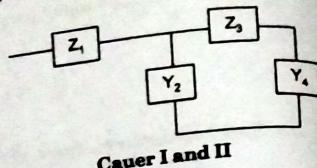
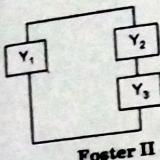
Q.1. (e) Write down Foster I, II and Cauer I, II forms of circuit synthesis.

Ans. Foster I.



16-2015

Third Semester, Circuit and Systems

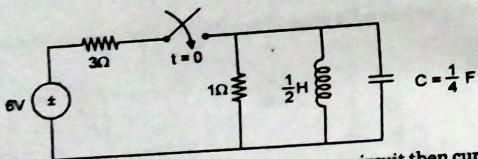


UNIT-I

Q.2. (a) Find E_a for the signal $x(t) = \delta(t+2) - \delta(t-2)$.
 Ans. $x(t) = \delta(t+2) - \delta(t-2)$

$$E_a = \int |x(t)|^2 dt = \int (\delta^2(2t+2) + \delta^2(t-2) - 2\delta(t+2)\delta(t-2)) dt = 1 + 1 = 2$$

Q.2. (b) Switch of the following circuit is opened at $t = 0$ after a long time. Write expression for $v(t)$ at $t > 0$.
 Ans.



$t < 0$ inductor work as short circuit and capacitor as open circuit then current through conductor is $I = \frac{6}{3} = 2A$ and

$$c \frac{dV_c}{dt} = \frac{1}{L} \int V_c dt + \frac{v_c}{1}$$

$$\frac{1}{4} \frac{dv_c}{dt} = 2 \int v_c dt + v_c$$

On differentiating the above eqn.

$$\frac{1}{4} \frac{d^2v_c}{dt^2} = 2 v_c + \frac{dv_c}{dt}$$

$$\frac{d^2v_c}{dt^2} - 4 \frac{dv_c}{dt} - 8 v_c = 0$$

$$v_c = Ae^{-(2+2\sqrt{3})t} + Be^{-(2-2\sqrt{3})t}$$

$$\alpha, \beta = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

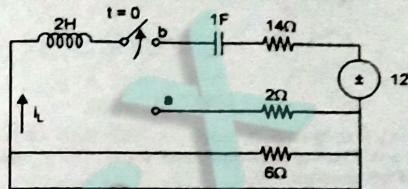
$$= \frac{4 \pm \sqrt{16 - 4 \times 1 \times -8}}{2}$$

$$= \frac{4 \pm \sqrt{48}}{2} = 2(1 \pm \sqrt{3}).$$

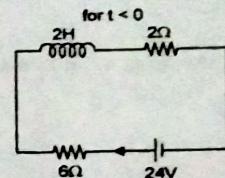
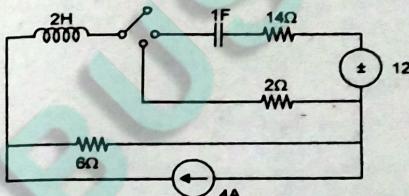
I.P. University-[B. Tech]-Akash Books

2015-17

Q.3. For the following circuit switch is moved from position (a) to (b) at $t = 0$. Then find $i_1(t)$ for $t > 0$. (12.5)



Ans.



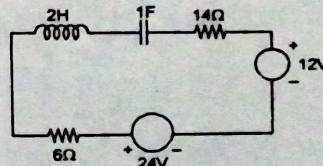
Inductor work as short circuit

$$I = \frac{24}{8} = 3A$$

Applying KVL

$$24 - 12 = 20I + 2 \frac{dI}{dt} + \frac{1}{1} \int I dt$$

$$12 = 20I + 2 \frac{dI}{dt} + \int I dt$$



On differentiating both side we get

$$2 \frac{d^2I}{dt^2} + 20 \frac{dI}{dt} + I = 0$$

$$\frac{d^2I}{dt^2} + 10 \frac{dI}{dt} + .5I = 0$$

$$I = Ae^{-0.5t} + Be^{-9.5t}$$

syabusx.live

18-2015

Third Semester, Circuit and Systems

$$\alpha, \beta = \frac{-10 + \sqrt{100 - 4 \times 5}}{2}$$

$$= \frac{-10 \pm \sqrt{96}}{2} = -5 \pm \frac{7}{2}\sqrt{2} = 0.036 - 9.97$$

UNIT-II

Q.4. Consider the following circuits, the two switches are closed simultaneously at $t = 0$. The voltage on capacitor C_1 and C_2 before the switches are closed are 1 and 2V respectively.

(a) Find the currents $i_1(t)$ and $i_2(t)$.

Ans. Applying KVL in Loop 1

$$4 = (I_1 + I_2)2 + \int I_1 dt$$

$$2 = (I_1 + I_2)2 + \int I_2 dt$$

Applying LT on both equation we get

$$\frac{4}{s} = 2I_1(s) + \frac{I_1(s)}{s} + 2I_2(s)$$

$$\frac{2}{s} = 2I_1(s) + 2I_2(s) + \frac{I_2(s)}{s}$$

$$\left[I_1(s) \left(2 + \frac{1}{s} \right) + 2I_2(s) = \frac{4}{s} \right] \times 2$$

$$\left[I_1(s) 2 \pm \left(2 + \frac{1}{s} \right) I_2(s) = \frac{2}{s} \right] \left(2 + \frac{1}{s} \right)$$

$$\left[4 - \left(2 + \frac{1}{s} \right)^2 \right] I_2(s) = \frac{8}{s} - \frac{4}{s} - \frac{2}{s^2}$$

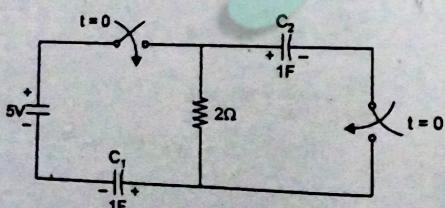
$$I_2(s) = \frac{\frac{4s-2}{s^2}}{4 - 4 - \frac{2}{s} - \frac{1}{s^2}} = \frac{\frac{12s+2}{s^2}}{\frac{8s^2+2s+1}{s^2}} = \frac{12s+2}{8s^2+2s+1}$$

$$= \frac{2(s-1)}{-(2s+1)}$$

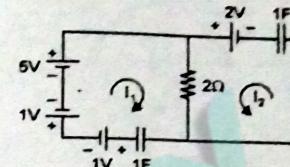
$$I_1(s) = \frac{8}{s} +$$

$$\frac{5}{5}$$

Q.4. (b) Find capacitor voltages at $t = 0$.



Ans.



$$V_{C1} = 5 \text{ volt}$$

$$V_{C2} = 0$$

Q.5. (a) For the LTI system described by the following differential equation determine system function $H(s)$.

$$y''(t) + y'(t) - 2y(t) = x(t)$$

Ans.

$$y''(t) + y'(t) - 2y(t) = x(t)$$

Taking LT

$$s^2 Y(s) + s Y(s) - 2 Y(s) = X(s)$$

$$\frac{Y(s)}{X(s)} = \frac{1}{s^2 + s - 2}$$

$$H(s) = \frac{1}{s^2 + s - 2}$$

Q.5. (b) Find Inverse Laplace transform of

$$X(s) = \frac{2 + 2s e^{-2s} + 4 e^{-4s}}{s^2 + 4s + 3}$$

Re S > -1

$$\text{Ans. } X(s) = \frac{2 + 2s e^{-2s} + 4 e^{-4s}}{s^2 + 4s + 3} = \frac{2}{s^2 + 4s + 3} + \frac{2s e^{-2s}}{s^2 + 4s + 3} + \frac{4 e^{-4s}}{s^2 + 4s + 3}$$

LT of

$$\frac{2}{(s+3)(s+1)} = \frac{A}{s+3} + \frac{B}{s+1}$$

$$A = \frac{2}{(s+3)(s+1)} \Big|_{s=-3} = \frac{2}{-2} = -1$$

$$B = \frac{2}{(s+3)(s+1)} \Big|_{s=-1} = 1$$

$$X(s) = \frac{-1}{s+3} + \frac{1}{s+1} + \frac{-se^{-2s}}{s+3} + \frac{se^{-2s}}{s+1} - \frac{2e^{-4s}}{s+3} + \frac{2e^{-4s}}{s+1}$$

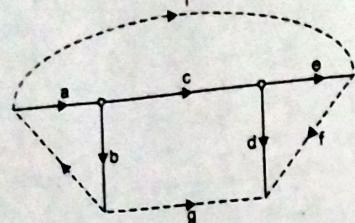
taking ILT

$$r(t) = -e^{-3t} + e^{-t} - e^{-2t}$$

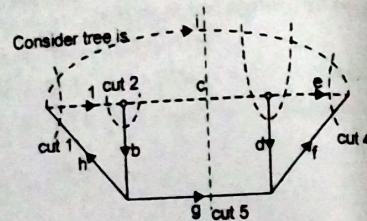
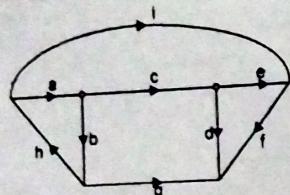
UNIT-III

Q.6. Determine the fundamental cut set and fundamental loop matrix for the following graph. Where solid lines are twigs and dotted lines are links.

(12.5)

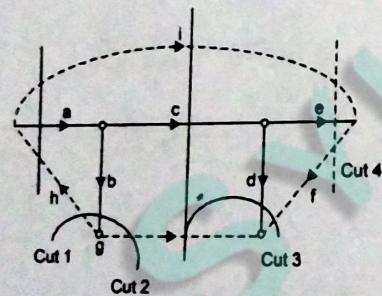


Ans.



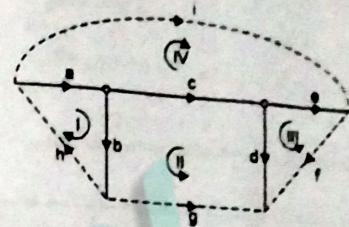
Twig are h, b, g, d, f
Link are a, c, e, i

	a	b	c	d	e	f	g	h	i
cut 1	-1	0	0	0	0	0	0	1	-1
cut 2	-1	1	1	0	0	0	0	0	0
cut 3	0	0	-1	1	1	0	0	0	0
cut 4	0	0	0	0	1	1	0	0	1
cut 5	0	0	1	0	0	0	1	0	1



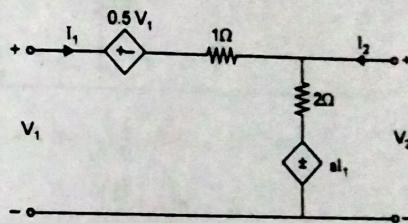
Fundamental cutset Matrix

	a	b	c	d	e	f	g	h	i
cut 1	1	0	0	0	0	0	0	-1	1
cut 2	0	1	0	0	0	0	-1	-1	0
cut 3	0	0	0	1	0	-1	1	0	0
cut 4	0	0	0	0	1	1	0	0	1
cut 5	0	0	1	0	0	0	1	0	1



Fundamental loop matrix

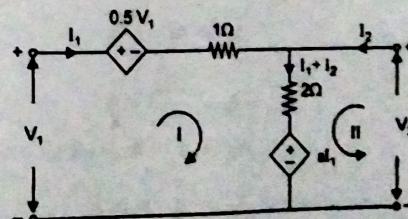
	a	b	c	d	e	f	g	h	i
loop 1	1	1	0	0	0	0	0	0	1
loop 2	0	1	-1	-1	0	0	1	0	0
loop 3	0	0	0	1	-1	1	0	0	0
loop 4	-1	0	-1	0	-1	0	0	0	1

Q.7. (a) For what value of a is the following circuit reciprocal. (6)

Ans.

On applying KVL in loop 1

$$\begin{aligned} V_1 - 0.5V_1 - al_1 &= I_1 + 2(I_1 + I_2) \\ .5V_1 &= (3+a)I_1 + 2I_2 \\ V_1 &= (6+2a)I_1 + 4I_2 \end{aligned} \quad \text{---(1)}$$

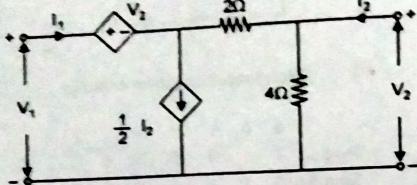


Applying KVL in loop 2

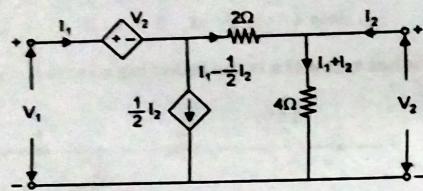
$$\begin{aligned}V_2 &= 2I_1 + I_2 + \alpha I_1 \\V_1 &= (2+\alpha)I_1 + 2I_2 \\x_{11} &= (6+2\alpha) \quad x_{12} = 4 \\x_{21} &= 2+\alpha \quad x_{22} = 2 \\x_{12} &= x_{21} \\2+\alpha &= 4 \Rightarrow \alpha = 2\end{aligned}$$

for Reciprocity

Q.7. (b) Find h parameters of the following circuit.



Ans.



$$V_1 - V_2 = 2\left(I_1 - \frac{1}{2}I_2\right) + 4\left(I_1 + \frac{I_2}{2}\right)$$

$$V_2 = 4\left(I_1 + \frac{I_2}{2}\right)$$

$$V_1 - V_2 = 6I_1 + I_2$$

$$V_2 = 4I_1 + 2I_2$$

$$V_1 = h_{11}I_1 + h_{12}V_2$$

$$I_2 = h_{21}I_1 + h_{22}V_2$$

Putting the value of I_2 from equation 2 to equation 1.

$$V_1 - V_2 = 6I_1 + \frac{V_1}{2} - 2I_1$$

$$V_1 = 4I_1 + \frac{3}{2}V_2$$

$$I_2 = \frac{-4I_1}{2} + \frac{V_2}{2}$$

$$h_{11} = 4 \quad h_{21} = -2$$

$$h_{12} = \frac{3}{2} \quad h_{22} = \frac{1}{2}$$

UNIT-IV

Q.8. (a) What are the properties of Hurwitz Polynomial.

Ans. Properties of Hurwitz Polynomial.

Hurwitz polynomial $P(s)$ have the following properties:(i) If the polynomial $P(s)$ can be written as

$$P(s) = a_n s^n + a_{n-1} s^{n-1} + \dots + a_1 s + a_0$$

Then, All the coefficients a_i must be positive. A corollary is that between the highest order term in s and the lowest order term, none of the coefficients may be zero unless the polynomial is even or odd. In other words, $a_{n-1}, a_{n-3}, \dots, a_2, a_1$ must not be zero if the polynomial is neither even nor odd.

(ii) Both the odd and even parts of a Hurwitz polynomial $P(s)$ have roots on the $j\omega$ -axis only. If we denote the even part of $P(s)$ as $M(s)$ and the odd part as $N(s)$, so that

$$P(s) = M(s) + N(s) \dots$$

then $M(s)$ and $N(s)$ both have roots on the $j\omega$ -axis only.

(iii) As a result of property (ii), if $P(s)$ is either even or odd, all its roots are on the $j\omega$ -axis (including origin).

(iv) The continued fraction expansion of the ratio ($\psi(s)$) of the odd to even parts ($N(s)/M(s)$) or the even to odd parts ($M(s)/N(s)$) of a Hurwitz polynomial yields all positive quotient terms. As,

$$\begin{aligned}\psi(s) &= \frac{N(s)}{M(s)} \text{ or } \frac{M(s)}{N(s)} = q_1 s + \frac{1}{q_2 s + \frac{1}{\dots}} \\&\quad + \frac{1}{q_n s}\end{aligned}$$

Where the quotients q_1, q_2, \dots, q_n must be positive if the polynomial $P(s) = M(s) + N(s)$ is Hurwitz.

(v) If $P(s)$ is Hurwitz polynomial and $W(s)$ is a multiplicative factor. Then $P_1(s) = P(s) \cdot W(s)$ is also Hurwitz polynomial, if $W(s)$ is Hurwitz polynomial.

(vi) In case the polynomial is either only even or only odd, it is not possible to obtain the continued fraction expansion in such cases, the polynomial $P(s)$ is Hurwitz if the ratio of $P(s)$ and its derivative $P'(s)$ gives a continued fraction expansion.

Q.8. (b) $F(s) = \frac{s^2 + 4s + 3}{s^2 + 6s + 8}$ check whether the function is positive real or not.

(6.5)

Ans.

$$F(s) = \frac{s^2 + 4s + 3}{s^2 + 6s + 8} = \frac{(s+3)(s+1)}{(s+2)(s+4)} = \frac{N(s)}{D(s)}$$

1. All pole of the $D(s)$ lies on the -ve side of real axis.

2. No any pole on imaginary axis.

3.

$$M_1 M_2 - N_1 N_2 \geq 0 \text{ for all value of } s$$

$$M_1 = s^2 + 3 \quad M_2 = s^2 + 8$$

$$N_1 = 4s \quad N_2 = 6s$$

$$(s^2 + 3)(s^2 + 8) - 4s \cdot 6s = s^4 - 13s^2 + 24$$

24-2015

Putting

Third Semester, Circuit and Systems

$$\begin{aligned}s &\rightarrow j\omega \\&= \omega^4 + 13\omega^2 + 24\end{aligned}$$

this is always +ve for any value of ω

So function is P.R.F

Q.9. Realize $Z(s) = \frac{s^2 + 2s + 2}{s^2 + s + 1}$ by cauer-I form.

Ans.

$$Z(s) = \frac{s^2 + 2s + 2}{s^2 + s + 1}$$

$$\begin{aligned}s^2 + s + 1 &\overline{\Big|} s^2 + 2s + 2 \quad (1 \leftrightarrow z_1) \\s^2 + s + 1 &\overline{\Big|} s^2 + s + 1 \quad (s \leftrightarrow y_2) \\s^2 + s &\overline{\Big|} s+1 \quad (s \leftrightarrow z_2) \\s &\overline{\Big|} 1 \quad (s \leftrightarrow y_4)\end{aligned}$$

MID TERM EXAMINATION [SEPT. 2016]
THIRD SEMESTER [B.TECH]
CIRCUITS AND SYSTEMS [ETEE-207]

M.M. : 30

Time : 1½ Hrs.

Note: Answer any three questions. All questions carry equal marks.

Q.1. (a) Define a signal and also describe the different types of the signals.

Ans. A signal may be considered to be a function of time that represents a physical variable of interest associated with a system. (4)

Types of Signal

1. Continuous time signal
2. Discrete time signal

On the basis of symmetry

1. Even signal
2. Odd-signal

On the basis of periodicity

1. Periodic signal
2. Non periodic signal

On the basis of power and energy

1. Power signal
2. Energy signal

Basic Signal

1. Step Signal: $f_s(t)$ is defined by

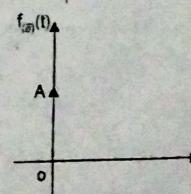
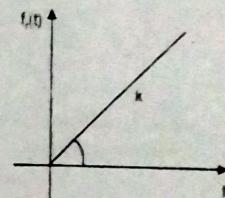
$$f_s(t) = \begin{cases} 0; t < 0 \\ K, t \geq 0 \end{cases}$$

where K is the amplitude of step signal2. Ramp Signal: $f_r(t)$ is defined by

$$f_r(t) = \begin{cases} 0; t < 0 \\ Kt; t \geq 0 \end{cases}$$

 K is the slope of ramp signal.3. Impulse Signal: $f_\delta(t)$ is defined by

$$f_\delta(t) = \begin{cases} 0; t \neq 0 \\ A; t \geq 0 \end{cases}$$

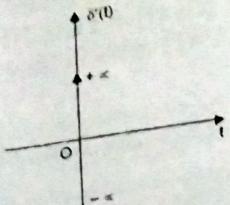
where A is the area of impulse signal.

Other Basic Signals

1. Unit Doublet Signal: If a unit impulse signal $\delta(t)$ is differentiated with respect to t , we get

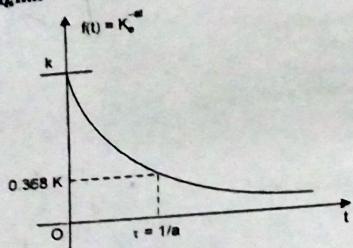
Third Semester, Circuits and Systems

2-2016



$$\begin{aligned}\delta(t) &= \frac{d}{dt}[(\delta t)] = +\infty \text{ and } -\infty; t=0 \\ &= 0; t \neq 0\end{aligned}$$

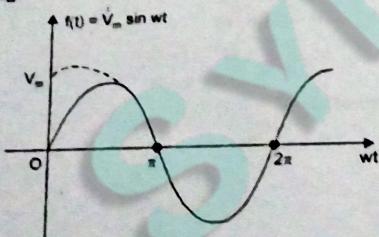
2. Exponential Signal



$$f(t) = \begin{cases} 0 & ; t \leq 0 \\ K_0 e^{-at} & ; t \geq 0 \end{cases}$$

where a and K are real constants.

3. Sinusoidal Signal



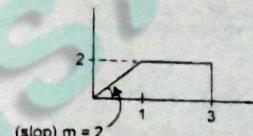
$$f(t) = \begin{cases} 0 & ; t < 0 \\ V_m \sin wt & ; t \geq 0 \end{cases}$$

Q.1. (b) Draw the waveform of the signal represented by the mathematical equation $V(t) = 2tu(t) - 2(t-1)u(t-1) - u(t-1) - 2u(t-3)$ and find its Laplace Transformation.

$$\text{Ans. } V(t) = 2tu(t) - 2(t-1)u(t-1) - u(t-1) - 2u(t-3)$$

$$\begin{aligned}&\text{If } 0 < t < 1 \\ &\text{Only} \\ &\text{Then} \\ &\text{If} \\ &\quad 1 < t < 3 \\ &\quad u(t) = u(t-1) = 1 \text{ and } u(t-3) = 0 \\ &\quad V(t) = 2t - 2t + 2 = 2 \\ &\quad t > 3 \\ &\quad u(t) = u(t-1) = u(t-3) = 1 \\ &\quad V(t) = 2t - 2t + 2 - 2 = 0\end{aligned}$$

The final wave.



Q.2. (a) What is LTI System and describe its properties in detail?

Ans. LTI Systems

A system is instantaneous (or memoryless or zero memory or without memory) if its output at any time depends only on the value of the input at the same time, otherwise dynamic i.e., a dynamic system or system with memory is one whose output depends on past or future values of the input or past values of output in addition to the present input.

A without memory continuous-time LTI system has the form

$$y(t) = Kx(t) \quad (\text{where } K \text{ is any constant})$$

Its impulse response

$$h(t) = K\delta(t)$$

Similarly, the form of a without memory discrete-time LTI system and its corresponding impulse response we $y[n] = Kx(n)$ and $h[n] = K\delta(n)$, respectively

Note that if $K = 1$, then these systems become identity systems, with outputs equal to the inputs and with unit impulse responses equal to the unit impulse signals, i.e., $h(t) = 0$ for $t \neq 0$ and $h[n] = 0$ for $n \neq 0$

In this case, the convolution integral and sum formulas imply that

$$x(t) = x(t) * \delta(t) \text{ and } x[n] = x[n] * \delta[n]$$

If an LTI system has an impulse response $h(t)$ or $h[n]$ that is not identically zero for $t \neq 0$ or $n \neq 0$, respectively, then the system is with memory or dynamic

2. Causality of LTI Systems: A system is causal or non-anticipative if the output of the system at any time depends only on values of the input at the present time and in the past otherwise non-causal i.e., a non-causal system is the system whose output depends (or anticipate) future values of the input.

A continuous-time LTI system to be causal, output $y(t)$ must not depend on input $x(\tau)$ for $\tau > t$. This results

$$h(t) = 0 \text{ for } t < 0$$

Similarly, for a causal discrete-time LTI system the output $y[n]$ depends on input $x(k)$ for $k < n$. This results $h[n] = 0$ for $n < 0$.

That is the impulse response of a causal LTI system must be zero before the impulse occurs.

More generally, causality for an LTI system is equivalent to the condition of initial rest. And the system output is

$$y(t) = \int_{-\infty}^t x(\tau) h(t-\tau) d\tau \quad \text{or} \quad y[n] = \sum_{k=-\infty}^n x(k) h[n-k]$$

In other words, the causality of an LTI system is equivalent to its impulse response being a causal signal.

3. Invertibility of LTI Systems: A system is invertible only if an inverse system exists that, when cascaded with the original system, yields an output equal to the input to the first system. Here, if an LTI system is invertible, then it has an LTI inverse. If we have an LTI system with impulse response $h(t)$ or $h[n]$, must satisfy

$$h(t) * g(t) = \delta(t)$$

$$h[n] * g[n] = \delta[n]$$

4. Stability of LTI Systems: An LTI system is said to stable if the impulse response is absolutely integrable in case of continuous-time or absolutely summable in discrete-time systems, i.e.,

$$\int |h(\tau)| d\tau < \infty \quad \text{or} \quad \sum_{k=-\infty}^{\infty} |h[k]|$$

More general, an LTI system is said to be stable if the impulse response approaches zero as $t \rightarrow \infty$ or $n \rightarrow \infty$ for continuous-time or discrete-time system, respectively.

5. Commutative Property: The output of an LTI system with impulse response $h(t)$ or $h[n]$ to input $x(t)$ or $x[n]$ is equal to the output of the system with impulse response $x(t)$ or $x[n]$ to input $h(t)$ or $h[n]$, i.e.,

$$y(t) = x(t) * h(t) = h(t) * x(t)$$

$$y[n] = x[n] * h[n] = h[n] * x[n]$$

or

This leads to

$$y(t) = \int_{-\infty}^t x(\tau) h(t-\tau) d\tau = \int_{-\infty}^t x(t-\tau) h(\tau) d\tau$$

or

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k] = \sum_{k=-\infty}^{\infty} x[n-k] h[k]$$

which may at times be easier to evaluate than equation.

6. Distributive Property: The output of an LTI system with impulse response $h_1(t) + h_2(t)$ or $h_1[n] + h_2[n]$ to input $x(t)$ or $x[n]$ is equal to the sum of the output of two systems with impulse response $h_1(t)$ or $h_1[n]$ to input $x(t)$ or $x[n]$ and system with impulse response $h_2(t)$ or $h_2[n]$ to input $x(t)$ or $x[n]$, i.e.,

$$y(t) = x(t) * [h_1(t) + h_2(t)] = x(t) * h_1(t) + x(t) * h_2(t)$$

or

$$y[n] = x[n] * [h_1[n] + h_2[n]] = x[n] * h_1[n] + x[n] * h_2[n]$$

The distributive property is useful when two or more systems are connected in parallel.

Also, as a consequence of both commutative and distributive properties, we have

$$y(t) = [x_1(t) + x_2(t)] * h(t) = x_1(t) * h(t) + x_2(t) * h(t)$$

or

$$y[n] = [x_1[n] + x_2[n]] * h[n] = x_1[n] * h[n] + x_2[n] * h[n]$$

Which simply state that the response of an LTI system to the sum of two inputs must equal the sum of the responses to these inputs individually.

7. Associative Property: The output of an LTI system with impulse response $[h_1(t) + h_2(t)]$ or $[h_1[n] + h_2[n]]$ to input $x(t)$ or $x[n]$ is equal to the output of the system with impulse response $h_1(t) * h_2(t)$ or $h_1[n] * h_2[n]$ to input $x(t) * h_1(t)$ or $x[n] * h_1[n]$, i.e.,

$$y(t) = x(t) * [h_1(t) * h_2(t)] = [x(t) * h_1(t)] * h_2(t)$$

or

$$y[n] = x[n] * [h_1[n] * h_2[n]] = [x[n] * h_1[n]] * h_2[n]$$

The associative property is useful when two or more systems are connected in series or in cascade.

Also, as a consequence of this property, we can say that the overall system response does not depend upon the order of the systems in the series or in cascade.

Q.2. (b) Find the Laplace Transform of the following functions

$$(i) 10e^{at} \sin(ut) \quad (ii) 10u(t-1) - 5(t-2) - 5\delta(t-3).$$

Ans. Laplace Transform

$$(i) e^{at} (\sin ut)$$

As we know the LT of $\sin ut$ is $\frac{u}{s^2 + u^2}$

$$\begin{aligned} e^{at} \sin ut &\xrightarrow{\text{LT}} \frac{u}{(s-a)^2 + u^2} \\ (i) f(t) &\xrightarrow{\text{LT}} \frac{1}{(s-a)^2 + u^2} \end{aligned}$$

$$(ii) f(t) = 10u(t-1) - 5(t-2) - 5\delta(t-3)$$

$$u(t-1) \xrightarrow{\text{LT}} \frac{e^{-s}}{s}$$

$$\begin{aligned} \text{Property} \\ f(t) &\longrightarrow F(s) \\ f(t-a) &\longrightarrow e^{-as} F(s) \end{aligned}$$

$$\delta(t-2) \xrightarrow{\text{LT}} e^{-2s}$$

$$\delta(t-3) \xrightarrow{\text{LT}} e^{-3s},$$

$$f(t) \xrightarrow{\text{LT}} 10 \frac{e^{-s}}{s} - e^{-2s} - 5e^{-3s}$$

Q.3. (a) Write the mathematical equation for the waveform shown in Fig. using Signal Synthesis Concept and find its Laplace Transformation.

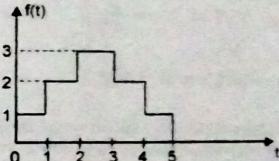
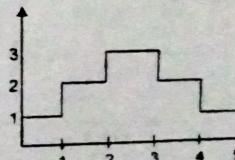


Fig. 1.

Ans.

$$f(t) = u(t) + u(t-1) + u(t-2) - u(t-3) - u(t-4) - u(t-5)$$

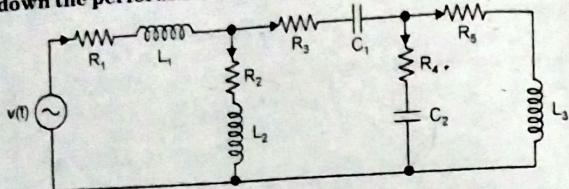
$$f(t) \xrightarrow{\text{LT}} \frac{1}{s} + \frac{e^{-s}}{s} + \frac{e^{-2s}}{s} - \frac{e^{-3s}}{s} - \frac{e^{-4s}}{s} - \frac{e^{-5s}}{s}$$

As we know $u(t) \xrightarrow{\text{LT}} \frac{1}{s}$

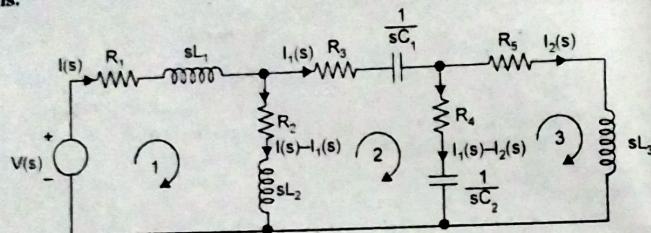
$$f(t-a) \longrightarrow e^{-as} F(s)$$

$$\text{So } u(t-a) \rightarrow \frac{e^{-as}}{s}$$

Q.3. (b) Draw the s-domain equivalent circuit for the circuit shown in Fig. 4 and write down the performance equations using KVL.



Ans.



Applying KVL in loop 1, 2 and 3

$$\text{In loop 1: } V(s) = R_1 I + sL_1 I + (R_2 + sL_2)(I - I_1)$$

$$\text{In loop 2: } (R_2 + sL_2)(I - I_1) = \left(R_3 + \frac{1}{sC_1} \right) I_1 + \left(R_4 + \frac{1}{sC_2} \right) (I_1 - I_2)$$

$$\text{In loop 3: } \left(R_4 + \frac{1}{sC_2} \right) (I_1 - I_2) = (R_5 + sL_3) I_2.$$

Q.4. (a) Obtain an expression for the current in the inductor for any time $t > 0$, in the circuit shown in Fig. 3 using Laplace Transformation. Assume the circuit to be initially relaxed.

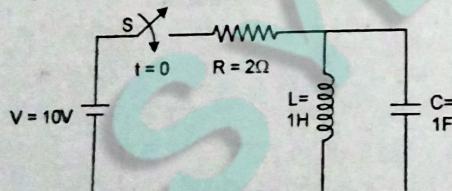
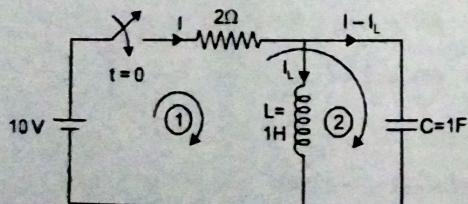


Fig. 3

Ans.

IP University-(R.Tech)-Akash books
Applying KVL in loop 1 and 2

$$10 = 2I + \frac{dI_L}{dt}$$

$$\frac{10}{s} = 2I(s) + sI_L(s) I_L(O^+)$$

$$\frac{10}{s} = 2I + sI_L$$

$$10 = 2I + \frac{1}{C} \int (I - I_L) dt$$

$$\frac{10}{s} = 2I + \frac{I - I_L}{s}$$

$$\frac{10}{s} = \left(2 + \frac{1}{s} \right) I - \frac{I_L}{s}$$

$$= \left(sI_L + 2I = \frac{10}{s} \right) \times \left(2 + \frac{1}{s} \right)$$

$$\left(-\frac{I_L}{s} + \left(2 + \frac{1}{s} \right) I + \frac{10}{s} \right) \times 2$$

$$\left[\left(2 + \frac{1}{s} \right) s + \frac{2}{s} \right] I_L = \frac{20}{s} + \frac{10}{s^2} - \frac{20}{s}$$

$$\left(2s + 1 - \frac{2}{s} \right) I_L = \frac{10}{s^2}$$

$$I_L = \frac{10}{s(2s^2 + s + 2)}$$

Q.4. (b) Determine the current $i(t)$ in the circuit shown in Fig. 4 using Laplace Transformation. (5)

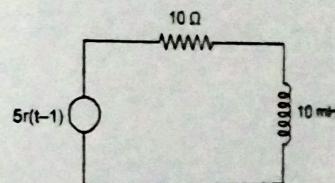
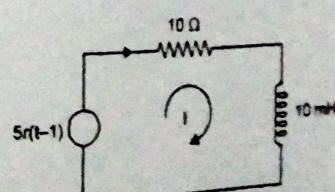


Fig. 4

Ans.



$$5r(t-1) = 10I + 10 \times 10^{-3} \frac{dI}{dt}$$

S-2016

Third Semester, Circuits and Systems

Taking LT

$$\frac{5e^{-s}}{s^2} = 10I(s) + 10^{-2}sJ(s)$$

$$\Rightarrow I(s) = \frac{5e^{-s}}{s^2(10^{-2}s + 1)} = \frac{500e^{-s}}{s^2(s + 1000)}$$

$$\text{Now ILT: } \frac{1}{s^2(s + 1000)} = \frac{A}{s} + \frac{B}{s^2} + \frac{C}{s + 1000}$$

$$B = \frac{1}{1000} \quad C = \frac{1}{10^6}$$

$$\frac{1}{s^2(s + 1000)} \xrightarrow{\text{LT}} Au(t) + Btu(t) + Ce^{-1000t}$$

$$\text{Finally: } \frac{500e^{-s}}{s^2(s + 1000)} \xrightarrow{\text{LT}} 500Au(t-1) + 500B(t-1)u(t-1) + 500Ce^{-1000(t-1)}$$

Put the value of A, B, C, we get I.

END TERM EXAMINATION [DEC. 2016]
THIRD SEMESTER [B.TECH]
CIRCUIT AND SYSTEM [ETEC-207]

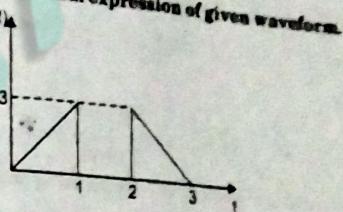
Time : 3 Hrs.

Note: Attempt any five questions including Q. no. 1 which is compulsory. Select one question from each unit. Assume suitable missing data if any.

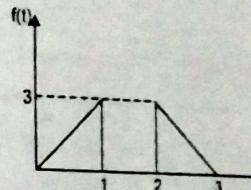
Q.1. (a) What is LTI system and describe their properties in brief.

Ans. Refer Q. 2. (a) Mid Term Examination 2016.

Q.1. (b) Write the mathematical expression of given waveform.

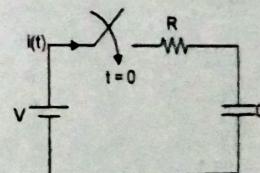


Ans.



$$f(t) = 3t[u(t) - u(t-1)] + (9 - 3t)[u(t-2) - u(t-3)]$$

Q.1. (c) Find the current i(t) in the given network using Laplace technique.



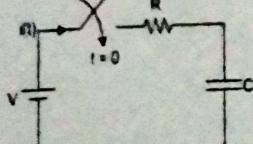
Ans.

$$V = IR + \frac{1}{C} \int i dt$$

$$\frac{V}{s} = IR + \frac{1}{C} \left[\frac{I(s)}{s} - \frac{I(0)}{s} \right]$$

$$\frac{V}{s} = IR + \frac{I}{Cs}$$

$$\Rightarrow I = \frac{V}{s\left(\frac{1}{Cs} + R\right)} = \frac{CV}{CRs + 1} = \frac{V}{R} \left(\frac{1}{s + \frac{1}{RC}} \right)$$



10-2016

Third Semester, Circuits and Systems

$$I(t) = \frac{V}{R} e^{-\frac{1}{RC}t}$$

Q.1. (d) Find T parameter in terms of g parameter.

$$V_1 = AV_2 + BI - I_2$$

$$I_1 = CV_2 + D(-I_2)$$

$$V_2 = \frac{1}{A} V_1 + \frac{B}{A} I_2$$

$$g_{11} = \frac{1}{A} \text{ and } g_{22} = \frac{B}{A}$$

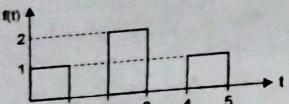
Putting the value of V_2 in equation (2)

$$I_1 = C\left[\frac{1}{A}V_1 + \frac{B}{A}I_2\right] + D(-I_2) = \frac{C}{A}V_1 + \left(\frac{BC}{A} - D\right)I_2$$

$$g_{11} = \frac{C}{A} \text{ and } g_{12} = \frac{B}{A}$$

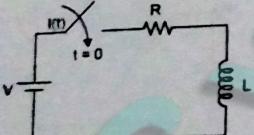
UNIT-I

Q.2. (a) Synthesis the given waveform using gate signal.



$$\text{Ans. } f(t) = [u(t) - u(t-1)] + 2[u(t-2) - u(t-3)] + [u(t-4) - u(t-5)] \\ = g_{(0,1)}^{(t)} + 2g_{(2,3)}^{(t)} + g_{(4,5)}^{(t)}$$

Q.2. (b) Find the step transient response of series RL network using differential equation method.



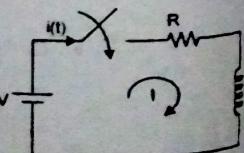
Ans.

$$\text{Applying KVL: } V = IR + L \frac{dI}{dt} \quad \frac{dI}{dt} + \frac{R}{L} I = \frac{V}{L}$$

$$\text{C.F. } D + \frac{R}{L} = 0$$

$$I_d(t) = Ae^{-\frac{R}{L}t}$$

$$\text{P.I. } = \left. \frac{V}{L} \right|_{D=0} = \frac{V}{R}$$



$$i(t) = Ae^{-\frac{R}{L}t} + \frac{V}{R}$$

$$t = 0 \quad i = 0$$

$$A = -\frac{V}{R}$$

$$i(t) = \frac{V}{R} \left(1 - e^{-\frac{R}{L}t} \right).$$

Q.3. (a) Define different type of test signals with their mathematical and graphical representation and Laplace.

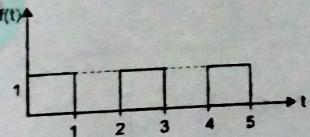
Ans. Refer Q. 1 (a) of Mid Term 2016.

Q.3. (b) Draw the waveform of given expression $f(t) = 2tu(t) - 2(t-1)u(t-1) - 2u(t-3)$.

Ans. Refer Q. 1 (b) of Mid Term 2016.

UNIT-II

Q.4. (a) Find the Laplace of given periodic waveform.



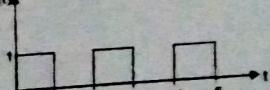
Ans.

$$f(t) = [u(t) - u(t-1)] + [u(t-2) - u(t-3)] + [u(t-4) - u(t-5)] + \dots$$

$$\text{Taking LT: } F(s) = \frac{1}{s} - \frac{e^{-s}}{s} + \frac{e^{-2s}}{s} - \frac{e^{-3s}}{s} + \frac{e^{-4s}}{s} - \frac{e^{-5s}}{s} + \dots$$

$$= \frac{1}{s} [1 - e^{-s} + e^{-2s} - e^{-3s} + e^{-4s} - e^{-5s} + \dots]$$

$$F(s) = \frac{1}{s} \times \frac{1}{1 + e^{-s}}$$

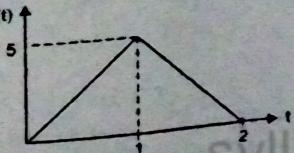


Q.4. (b) Find the Laplace of given function $f(t) = 5tu(t)$.

$$\text{Ans. } f(t) = 5tu(t)$$

$$= 5 \int_0^t te^{-st} dt = 5 \left[\frac{te^{-st}}{-s} - \frac{1}{-s} \int e^{-st} dt \right]_0^t = 5 \left[-\frac{e^{-st}}{s^2} \right]_0^t = \frac{5}{s^2}$$

Q.5. (a) Find the Laplace of given waveform.



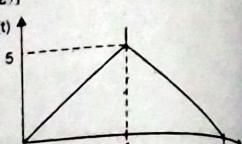
12-2016

Third Semester, Circuits and Systems

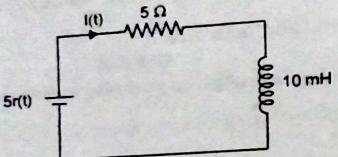
Ans.

$$\begin{aligned}f(t) &= 5[tu(t) - u(t-1)] + (2-t)[u(t-1) - u(t-2)] \\f(t) &= 5[tu(t) - tu(t-1) + 2u(t-1) - 2u(t-2) - tu(t-1) + tu(t-2)] \\&= 5[tu(t) - 2(t-1)u(t-1) + (t-2)u(t-2)] \\&= 5[r(t) - 2r(t-1) + r(t-2)]\end{aligned}$$

$$\begin{aligned}F(s) &= 5 \left[\frac{1}{s^2} - \frac{2e^{-s}}{s^2} + \frac{e^{-2s}}{s^2} \right] \\&= \frac{5}{s^2} [1 - 2e^{-s} + e^{-2s}].\end{aligned}$$



Q.5. (b) Find the current in given network using laplace transform technique (d)



Ans.

$$5r(t) = 5I + 10^{-2} \frac{dI}{dt}$$

$$\text{Taking LT: } \frac{5}{s^2} = 5I + 10^{-2}sI$$

$$\Rightarrow I = \frac{5}{s^2(5 + 10^{-2}s)} = \frac{500}{(5 + 500)s^2}$$

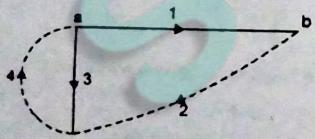
$$I(s) = \frac{A}{s} + \frac{B}{s^2} + \frac{C}{s + 500}$$

$$B = 1 \quad C = \frac{1}{500} \quad A = \text{Find}$$

$$I(t) = Au(t) + bu(t) + \frac{1}{500} e^{-500t}$$

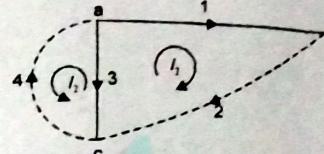
UNIT-II

Q.6. (a) Determine f-tie set matrix for given graph.

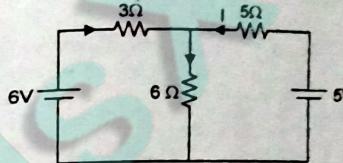


Ans.

$$B_f = 2 \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 1 & -1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \rightarrow \text{for loop 1}$$



Q.6. (b) Find the current in given network using super position theorem. (6.5)



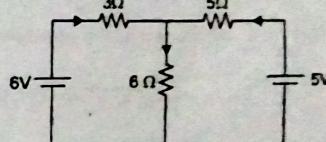
Ans. 1st consider 6 V and replace 5 V with short circuit.

$$\begin{aligned}R_{eq} &= (6 || 5) + 3 \\&= 3 + \frac{6 \times 5}{6 + 5} = 3 + \frac{30}{11} = \frac{63}{11}\end{aligned}$$

$$I = \frac{6}{63} = \frac{66}{63}$$

$$I_1 = \frac{5}{11} \times I$$

$$= \frac{5}{11} \times \frac{66}{63} = \frac{30}{63}$$



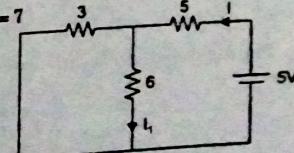
Consider 5 V and replace 6 V by short circuit

$$I = \frac{5}{7}$$

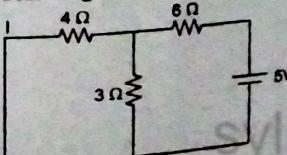
$$R_{th} = (6 || 3) + 5 = 5 + \frac{6 \times 3}{9} = 7$$

$$I'_1 = \frac{3}{9} \times \frac{5}{7} = \frac{15}{63}$$

$$\text{Total } I = I_1 + I'_1 = \frac{30}{63} + \frac{15}{63} = \frac{45}{63}$$



Q.7. (a) Find the current in given network using Norton's theorem. (6)



Third Semester, Circuits and Systems

14-2016

Ans.

$$\text{Total current} = \frac{5}{(4+13)+6}$$

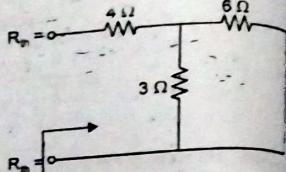
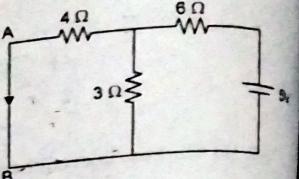
$$= \frac{5}{\frac{12}{7} + 6}$$

$$= \frac{35}{54}$$

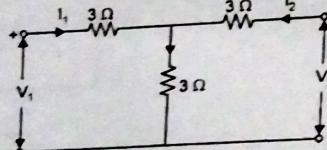
$$\text{Current through } AB = \frac{3}{7} \times I$$

$$I_N = \frac{3}{7} \times \frac{35}{54} = \frac{15}{54}$$

$$R_{th} = 4 + (6+3) \\ = 4 + \frac{18}{9} = 6$$



Q.7. (b) Find transmission parameter of given two port network. (6)



Ans.

$$V_1 = AV_2 + B(-I_2)$$

$$I_1 = CV_2 + D(-I_2)$$

$$V_1 = 6I_1 + 3I_2$$

$$V_2 = 3I_1 + 6I_2$$

From equation (2),

$$I_1 = \frac{V_2}{3} - 2I_2$$

Putting the value of I_1 in equation (1)

$$V_1 = 6\left(\frac{V_2}{3} - 2I_2\right) + 3I_2$$

$$V_1 = 2V_2 - 9I_2$$

On comparing, we get

$$A = 2, B = 9$$

$$V_2 = 3I_1 + 6I_2$$

$$I_1 = \frac{V_1 - 6I_2}{3}$$

$$I_1 = \frac{V_1}{3} - 2I_2$$

On comparing, we get

$$C = \frac{1}{3}, D = 2$$

Q.8. (a) Realize the function in Foster-1 and Foster-2 form.

(12.5)

$$Z(s) = \frac{s(s+2)(s+5)}{s(s+1)(s+4)}$$

$$Z(s) = \frac{s(s+2)(s+5)}{s(s+1)(s+4)} = \frac{s(s+2)(s+5)}{(s+1)(s+4)}$$

$$\text{Foster 1: } \frac{Z(s)}{s} = \frac{(s+2)(s+5)}{(s+1)(s+4)} = \frac{s^2 + 7s + 10}{s^2 + 5s + 4}$$

$$\frac{s^2 + 5s + 4}{s^2 + 5s + 4} \frac{s^2 + 7s + 10}{s^2 + 5s + 4} (1)$$

$$\frac{Z(s)}{s} = 1 + \frac{2s + 6}{(s+1)(s+4)}$$

Using partial fraction

$$\frac{Z(s)}{s} = 1 + \frac{A}{s+1} + \frac{B}{s+4}$$

$$A = \frac{4}{3}, B = \frac{2}{3}$$

 $Z(s) \rightarrow$

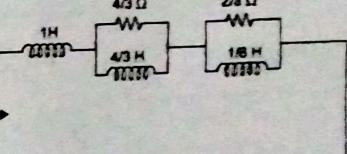
$$Z(s) = s + \frac{\frac{4}{3}s}{s+1} + \frac{\frac{2}{3}s}{s+4}$$

$$\text{Foster II: } Y(s) = \frac{(s+1)(s+4)}{s(s+2)(s+5)}$$

$$Y(s) = \frac{A}{s} + \frac{B}{s+2} + \frac{C}{s+5}$$

$$A = \frac{2}{5}, B = \frac{1}{3}, C = \frac{4}{15}$$

$$Y(s) = \frac{\frac{2}{5}}{s} + \frac{\frac{1}{3}}{s+2} + \frac{\frac{4}{15}}{s+5}$$



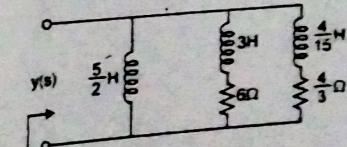
Q.9. Realize the function in Caur-1 and Caur-2 form.

(12.5)

$$Z(s) = \frac{(s+1)(s+4)}{s(s+2)(s+5)}$$

$$\text{Ans. } Z(s) = \frac{(s+1)(s+4)}{s(s+2)(s+5)}$$

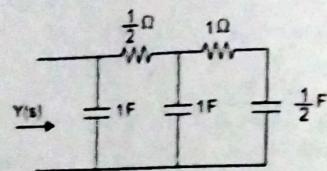
$$\text{Caur-1: } Y(s) = \frac{s^3 + 7s^2 + 10s}{s^2 + 5s + 4}$$



16-2016

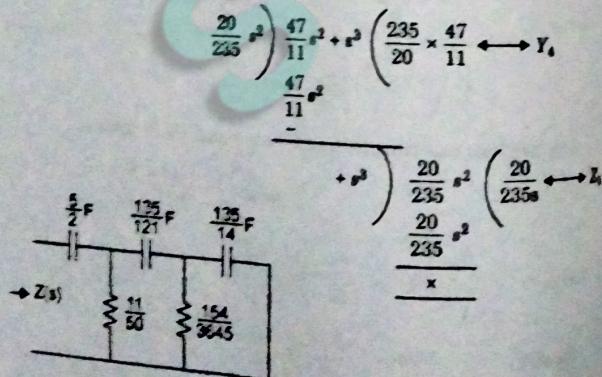
Third Semester, Circuits and Systems

$$\begin{aligned}
 & \frac{s^2 + 5s + 4}{s^3 + 7s^2 + 10s} \left(s \longleftrightarrow Y_1 \right) \\
 & \frac{s^2 + 5s^2 + 4s}{2s^2 + 6s} \left(\frac{1}{2} \longleftrightarrow Z_2 \right) \\
 & \frac{s^2 + 3s}{2s^2 + 4s} \left(s \longleftrightarrow Y_3 \right) \\
 & \frac{2s^2 + 6s}{2s^2 + 4s} \left(\frac{1}{2} \longleftrightarrow Z_4 \right) \\
 & \frac{2s^2 + 4s}{2s} \left(\frac{1}{2}s \longleftrightarrow Y_5 \right) \\
 & \times
 \end{aligned}$$



Case-II: $Z(s) = \frac{s^2 + 5s + 4}{s^3 + 7s^2 + 10s} = \frac{4 + 5s + s^2}{10s + 7s^2 + s^3}$

$$\begin{aligned}
 & \frac{4 + 5s + s^2}{10s + 7s^2 + s^3} \left(\frac{4}{10s} \longleftrightarrow Z_1 \right) \\
 & \frac{4 + \frac{14}{5}s + \frac{2}{5}s^2}{10s + 7s^2 + s^3} \left(\frac{5}{11} \cdot 10 \longleftrightarrow Y_2 \right) \\
 & \frac{\frac{11}{5}s + \frac{3}{5}s^2}{10s + 30s^2} \left(\frac{11}{47} \times \frac{11}{5s} \longleftrightarrow Z_3 \right) \\
 & \frac{\frac{47}{11}s^2 + s^3}{\frac{11}{5}s + \frac{121}{235}s^2} \left(\frac{235}{20} \times \frac{47}{11} \longleftrightarrow Y_4 \right)
 \end{aligned}$$



FIRST TERM EXAMINATION (SEPT. 2017)

THIRD SEMESTER (B.TECH)

CIRCUITS AND SYSTEMS

[ETEE-207]

1½ hrs.

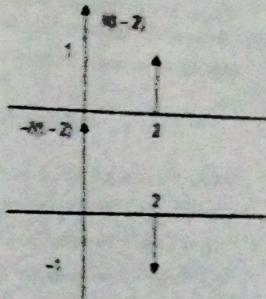
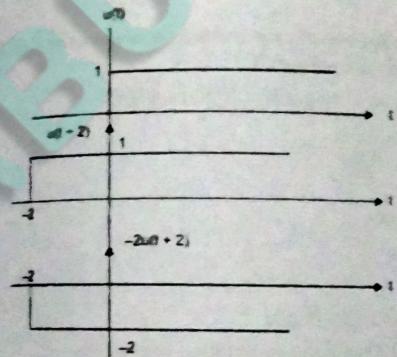
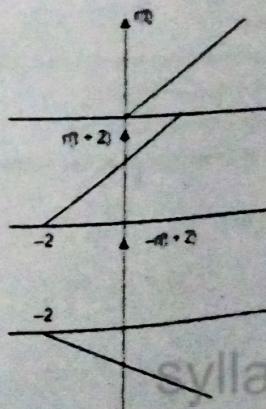
Attempt any three questions including Q.No 1 which is compulsory.

M.M. 30

Q.1 Attempt all of the following:

Q.1 (a) Draw the waveform of

(i) $-2u(t+2)$ (ii) $\delta(t-2)$ (iii) $-r(t+2)$

Ans. (i) $u(t)$ (ii) $\delta(t-2)$ (iii) $-r(t+2)$ (iii) $-r(t+2)$ 

Q.1. (b) Write the equation for the waveform shown in the figure 1 using shifted step function.

Ans.

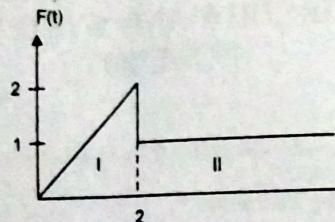


Fig. 1

Section I $t[u(t) - u(t-2)]$ Section II $u(t-2)$

$$F(t) = t[u(t) - u(t-2)] + u(t-2)$$

Q.1. (c) Prove that the impulse response of any network is inverse Laplace transform of the transfer function of that network.

Ans. As we know the transfer function is the ratio of $Y(S)$ and $X(S)$

$$T(S) = H(S) = \frac{Y(S)}{X(S)}$$

Where $Y(S)$ is the LT of $y(t)$ i.e. outputand $X(S)$ is the LT of $x(t)$ i.e., inputif input is $x(t) = \delta(t)$ then $X(s) = 1$ On putting this value in eqn 1 we get $H(S) = Y(S)$ On taking ILT $h(t) = y(t)$ that means if the input is $\delta(t)$ then $h(t) = y(t)$.and Impulse response of a system is the response if input is $\delta(t)$.

Q.1. (d) What are the advantages of Laplace Transform techniques.

Ans. Advantage of LT

1. It gives complete solution
2. Initial conditions are automatically considered in the transformed equation
3. Easy to solve differential equation using LT
4. It gives systematic solution of differential eqn.

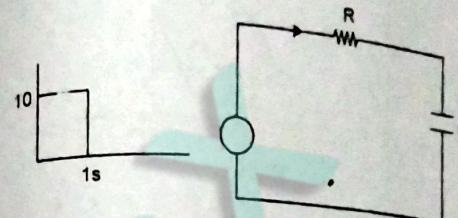
Q.1. (e) Find even and odd component of the signal $x(t) = e^{-2t} \cos 2t$.Ans. $x(t) = e^{-2t} \cos 2t$

$$x(-t) = e^{+2t} \cos(-2t) = e^{+2t} \cos 2t$$

$$x_{\text{even}}(t) = \frac{e^{-2t} \cos 2t + e^{+2t} \cos 2t}{2}$$

$$x_{\text{odd}}(t) = \frac{e^{-2t} \cos 2t - e^{+2t} \cos 2t}{2}$$

Find out the response $i(t)$ for $t > 0$ for the series R-C circuit excited by a voltage source of 10V for one second duration. Explain the graph. Assuming initial conditions zero. $R = 1\Omega$, $C = 1F$. (5)



$$V = iR + \frac{1}{C} \int i dt$$

$$10[u(t) - u(t-1)] = iR + \frac{1}{C} \int i dt$$

$$\frac{10}{s} - \frac{10}{s} e^{-s} = I(s)R + \frac{1}{C} \frac{I(s)}{s}$$

$$R = 1\Omega \quad C = 1F$$

$$\frac{10}{s} - \frac{10}{s} e^{-s} = I(s) \left(1 + \frac{1}{s}\right) = I(s) \left(\frac{s+1}{s}\right)$$

$$I(s) = \frac{10(1 - e^{-s})}{(1+s)} = \frac{10}{s+1} - \frac{10e^{-s}}{s+1}$$

$$i(t) = 10e^{-t} - 10e^{-(t-1)} \\ = 10e^{-t}(1 - e)$$

Q.1(b) Given $F(s) = \frac{s+1}{(s+2)(s+3)}$. Find Initial value and Final Value of the

Initial Value Theorem $\lim_{s \rightarrow \infty} sF(s)$

$$= \frac{s(s+1)}{(s+2)(s+3)}$$

$$= \lim_{s \rightarrow \infty} \frac{\cancel{s} \left(1 + \frac{1}{s}\right)}{\cancel{s} \left(1 + \frac{2}{s}\right) \left(1 + \frac{3}{s}\right)} = \frac{1}{1 \times 1} = 1$$

Final Value Theorem $= \lim_{s \rightarrow 0} sF(s)$

$$= \lim_{s \rightarrow 0} \frac{s(s+1)}{(s+2)(s+3)} = 0$$

Q.3. (a) Calculate Laplace Transform of periodic function as shown in Fig. 2.

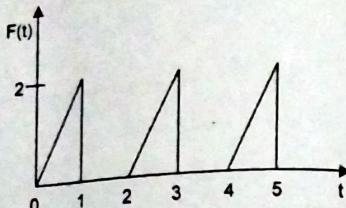
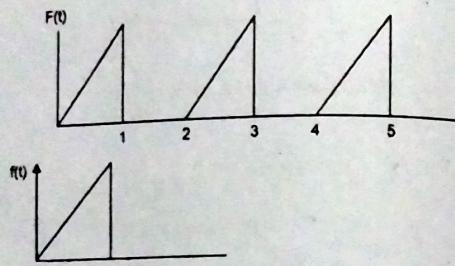


Fig. 2

Ans.



$$f(t) = t[u(t) - u(t-1)] = t u(t) - t u(t-1)$$

taking LT

$$\begin{aligned} F(s) &= \frac{1}{s^2} - LT[(t-1)u(t-1)] - LT[u(t-1)] \\ &= \frac{1}{s^2} - \frac{e^{-s}}{s^2} - \frac{e^{-s}}{s} \end{aligned}$$

$$LT\text{ of }F(t) = \frac{1}{1-e^{-2s}} \left(\frac{1}{s^2} - \frac{e^{-s}}{s^2} - \frac{e^{-s}}{s} \right)$$

Q.3. (b) In the circuit of figure 3 switch S_1 is closed at $t = 0$ and switch S_2 is open at $t = 0.2$ second. Find the expression for the transient current for different intervals.

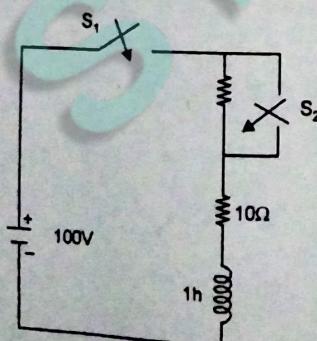
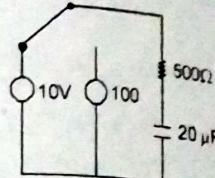


Fig. 3



$$100 = 20i + L \frac{di}{dt}$$

$$100 = 20i + \frac{di}{dt}$$

$$Cf = Ae^{-20t}$$

$$PI = \frac{100}{D+20} = \frac{100}{20} = 5$$

$$i(t) = Ae^{-20t} + 5$$

$$A = -5$$

$$i(t) = 5(1 - e^{-20t})$$

$$t = .2s \text{ at } i = 5(1 - e^{-2 \cdot 20}) = 5(1 - e^{-4})$$

$$100 = 10i + L \frac{di}{dt}$$

$$CF = Be^{-10t}$$

$$PI = \frac{100}{D+10} = 10$$

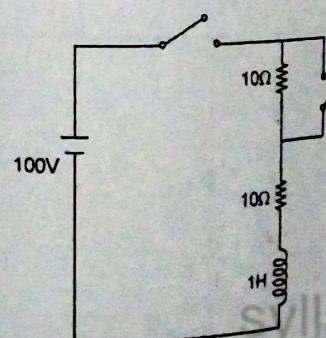
$$i(t) = Be^{-10t} + 10$$

$$t = 0, i = 5(1 - e^{-4})$$

$$5(1 - e^{-4}) = B + 10 \Rightarrow B = -10 + 5 - 5e^{-4}$$

$$= -4.9$$

$$i(t) = -4.9e^{-10t} + 10$$



6-2017

Third Semester, Circuits and Systems

When both switch is on 1st 10Ω is bypassed
So KVL eqn is

$$100 = 10i + 1 \frac{di}{dt}$$

$$CF = Ae^{-10t}$$

$$PI = \frac{100}{10} = 10$$

$$i(t) = Ae^{-10t} + 10$$

at $t = 0; i = 0$

$$0 = Ae^{-10 \times 0} + 10 \Rightarrow A = -10$$

$$i(t) = 10(1 - e^{-10t})$$

at $t = .2S$

$$i = 10(1 - e^{-10 \times .2})$$

$$= 10(1 - e^{-2})$$

$$= 8.64$$

When S_1 is off

then Applying on KVL on loop we get

$$100 = 20i + \frac{di}{dt}$$

$$CF = Be^{-20t}$$

$$PI = \frac{100}{20} = 5$$

$$i(t) = 5 + Be^{-20t}$$

at

$$t = 0.05 \quad i(t) = 8.64$$

$$8.64 = 5 + Be^0 \Rightarrow B = 8.64 - 5 = 3.64$$

$$i(t) = 5 + 3.64e^{-20t}$$

at

$$t = 0.05 \quad i(t) = 8.64 - 5 = 3.64$$

$$i(t) = 5 + 3.64e^{-20t}$$

Q.4. (a) Find the time at which D.C. Source deliver a current of $500mA$ below circuit as shown in figure 4 after closing the switch K at $t = 0$ sec.

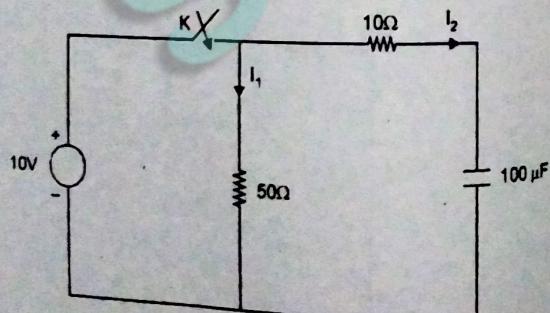


Fig. 4

$$I_1 = \frac{10}{50} = 2A = 200mA$$

$$I = 500mA$$

$$\Rightarrow 500 = 200 + I_2$$

$$I_2 = 300mA$$

$$I_2 = \frac{V}{R} e^{-t/T}$$

$$0.3 = \frac{10}{70} e^{-\frac{t}{RC}} = \frac{10}{70} e^{-\frac{t}{0.007}}$$

$$-\frac{t}{0.007} = \log_e(2.1) = t = 5.2ms$$

Q.4. (b) In the circuit of figure 5 the switch S is closed on position 1 at $t = 0$ and after one time constant is moved to position 2. Find the current before and after moving to position 2. Assuming all initial conditions are zero. (5)

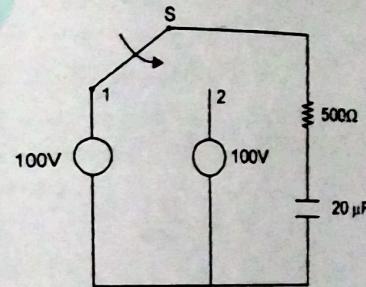


Fig. 5

Ans.

$$\text{Applying KVL } 100 = 500i + \frac{1}{20\mu F} \int i dt$$

On differentiating above eqn

$$0 = 500 \frac{di}{dt} + \frac{1}{20 \times 10^{-6}} i$$

$$\frac{di}{dt} + 100i = 0$$

$$i(t) = Ke^{-100t}$$

$$\text{at } t = 0 \quad i = \frac{100}{500} = 2A$$

$$K = 2$$

$$i(t) = 0.2e^{-100t}$$

$$\text{time constant } T = RC = 500 \times 20 \times 10^{-6} = 10^{-3}$$

$$= 10^{-3}$$

$$i(t) = 2e^{-100} \times 10^{-2} = \frac{2}{e} = .074 A$$

$$V_C = 100(1 - e^{-1}) = 63.7 V$$

When switch move to position 2

$$100 = 500i + \frac{1}{20 \times 10^{-6}} \int i dt$$

On differentiating we get

$$\frac{di}{dt} + 100i = 0$$

$$i(t) = Ke^{-100t}$$

$$V = \frac{1}{C} \int i dt = \frac{1}{20 \times 10^{-6}} \int Ke^{-100t} dt$$

$$= -\frac{K}{20 \times 10^{-6} \times 100} e^{-100t}$$

$$V_C = -500Ke^{-100t}$$

$$t = 0 V_C = 63.7 V$$

$$63.7 = 500Ke^0 \Rightarrow K = -\frac{63.7}{500}$$

$$i(t) = -\frac{63.7}{500} e^{-100t}$$

at

END TERM EXAMINATION [DEC. 2017]

THIRD SEMESTER [B.TECH]

CIRCUITS AND SYSTEMS

[ETEE-207]

M.M. : 75

Time : 3 hrs.

Note: Attempt any five questions including Q.No. 1 which is compulsory.

Q.1. (a) What are even and odd signals? Give examples.

Ans. If

$$x(-t) = x(t) \text{ then signal is even}$$

$$x(-t) = -x(t) \text{ then signal is odd}$$

Q.1. (b) What are energy and power signal? Discuss.

Ans. A signal is power signal if Average power of a system is finite and energy is infinite.

A signal is energy signal if total energy of the signal is finite and power is zero.

Q.1. (c) What is the relation between unit step function and ramp function?

Ans.

$$r(t) = t[u(t)]$$

$$u(t) = \frac{1}{t} \rightarrow r(t)$$

Q.1. (d) Give the classification of filters.

Ans. Classification of filter:

1. Low pass filter
2. High pass filter
3. Band pass filter
4. Band stop filter

Q.1. (e) What are the characteristics of Hurwitz polynomial? Discuss. (4)

Ans. 1. The coefficients of the s terms must be +ve.

2. Both odd and even part of the polynomial have roots on the imaginary axis.

3. The continued fraction expansion of the ratio of even to odd parts of hurwitz polynomial gives all +ve quotient terms.

4. If $P(s)$ is a Hurwitz polynomial and $W(S)$ is a even multiplicative factor the $P_1(s) = W(S)P(S)$ is also a Hurwitz polynomial.

Q.1. (f) Define tree, twigs, links and loop.

Ans. Tree: It is an inter connected open set of branches which include all the nodes of the given graph. In a Tree of the graph there cannot be any closed loop.

Twig: The branch involved in tree is known as Twig.

Link: It is that branch of graph that does not belongs to the particular tree.

Loop: This is closed contour selected in a graph.

Q.1. (g) Write a short note on h-parameters.

Ans.

$$V_1 = h_{11}I_1 + h_{12}V_2$$

$$I_2 = h_{21}I_1 + h_{22}V_2$$

(5)

$$h_{11} = \left. \frac{V_1}{V_2} \right|_{V_2=0}, \quad h_{21} = \left. \frac{V_2}{V_1} \right|_{V_1=0}, \quad h_{12} = \left. \frac{I_1}{V_2} \right|_{I_1=0}, \quad h_{22} = \left. \frac{I_2}{V_1} \right|_{I_1=0}$$

Q.2. (a) Determine whether the system described by the differential equation $\frac{dy(t)}{dt} + y(t) + 4 = x(t)$ is linear. (8)

Ans. $\frac{dy(t)}{dt} + y(t) + 4 = x(t)$

Let a input $x_1(t)$ and corresponding output is $y_1(t)$.

$$\frac{dy_1(t)}{dt} + y_1(t) + 4 = x_1(t)$$

Similarly Input $x_2(t)$ and output $y_2(t)$.

$$\frac{dy_2(t)}{dt} + y_2(t) + 4 = x_2(t)$$

Linear combination of them

$$\begin{aligned} a \frac{dy_1(t)}{dt} + ay_1(t) + 4a + b \frac{dy_2(t)}{dt} + by_2(t) + 4b \\ = ax_1(t) + bx_2(t) \end{aligned}$$

$\frac{d}{dt}[ay_1(t) + by_2(t)] + [ay_1(t) + by_2(t)] + 4[a + b] = ax_1(t) + bx_2(t)$ is not in the linear combination

So system is non linear.

Q.2. (b) A Cosine wave $\cos \omega t$ is applied as input to the series RL circuit as shown in fig-1. Find the resultant current $I(t)$ if the switch "S" is closed at $t=0$. (6.5)

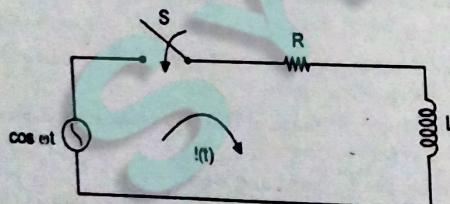


Fig. 1

Ans.

$$\cos \omega t = IR + L \frac{dI}{dt}$$

$$\frac{1}{L} \cos \omega t = \frac{R}{L} I + \frac{dI}{dt}$$

$$D + \frac{R}{L} = 0 \Rightarrow D = -\frac{R}{L}$$

$$CF = e^{-pt} I$$

$$PI = \frac{1}{L} \left(\frac{\cos \omega t}{D + \frac{R}{L}} \right) \left(\frac{(D - R/L)}{D^2 - \left(\frac{R}{L} \right)^2} \right)$$

$$= \frac{1}{L} \frac{D \cos \omega t - \frac{R}{L} \cos \omega t}{D^2 - \left(\frac{R}{L} \right)^2}$$

$$= \frac{1}{L} \times \frac{1}{-\omega^2 - \left(\frac{R}{L} \right)^2} \left[-\omega \sin \omega t + \frac{R}{L} \cos \omega t \right]$$

$$i(t) = Ae^{-\frac{R}{L}t} - \frac{1}{L \left(\omega^2 + \frac{R^2}{L^2} \right)} \left[-\omega \sin \omega t + \frac{R}{L} \cos \omega t \right]$$

Initially inductor work as open circuit. So at $t=0$ $i=0$

$$0 = A - \frac{R}{L} \frac{1}{L \left(\omega^2 + \frac{R^2}{L^2} \right)} \Rightarrow A - \frac{R}{L^2 \omega^2 + R^2} = 0$$

$$A = \frac{R}{L^2 \omega^2 + R^2}$$

Q.3. (a) A system has a transfer function given by $H(s) = \frac{1}{(s+1)(s^2+s+1)}$ (6.5)

Find the response of the system when the excitation is $x(t) = (1 + e^{-3t} - e^{-t}) u(t)$

Ans.

$$x(t) = (1 + e^{-3t} - e^{-t}) u(t)$$

taking LT

$$X(s) = \frac{1}{s} + \frac{1}{s+3} - \frac{1}{s+1} = \frac{s^2 + 4s + 3 + s - s^2 - 3s}{s(s+3)(s+1)}$$

$$= \frac{s^2 + 2s + 3}{s(s+3)(s+1)}$$

$$Y(s) = \frac{1}{(s+1)(s^2+s+1)} \times \frac{s^2 + 2s + 3}{s(s+3)(s+1)}$$

$$Y(s) = \frac{s^3 + 2s + 3}{s(s+1)^2(s+3)(s^2+s+1)}$$

Using partial fraction we can write it

$$\frac{A}{s} + \frac{B}{s+3} + \frac{C}{s+1} + \frac{D}{(s+1)^2} + \frac{Ps}{s^2+s+1}$$

$$A = \frac{s^2+2s+3}{s(s+1)^2(s+3)(s^2+s+1)} \times s \Big|_{s=0} = \frac{3}{3} = 1$$

$$B = \frac{s^2+2s+3}{s(s+1)^2(s+3)(s^2+s+1)} \times s+3 \Big|_{s=-3} = \frac{9-6+3}{-3 \times 4 \times (9-3+1)} = \frac{6}{-12 \times 7} = -\frac{1}{14}$$

$$D = \frac{s^2+2s+3}{s(s+1)^2(s+3)(s^2+s+1)} \times (s+1)^2 \Big|_{s=-1} = \frac{2}{-1 \times 2 \times 1} = -1$$

C and also find P

$$\begin{aligned} & \frac{Ps}{s^2+s+1} \\ &= P \frac{s}{s^2+2\frac{1}{2}s+\left(\frac{1}{2}\right)^2+\frac{5}{4}} \\ &= P \frac{\left(s+\frac{1}{2}\right)}{\left(s+\frac{1}{2}\right)^2+\frac{5}{4}} - P \frac{e^{\frac{1}{2}}}{\left(s+\frac{1}{2}\right)^2+\frac{5}{4}} \\ &= P \left[e^{-\frac{1}{2}t} \cos \frac{\sqrt{5}}{2}t - \frac{1}{2} e^{-\frac{1}{2}t} \sin \frac{\sqrt{5}}{2}t \right] \end{aligned}$$

$$\frac{1}{s} + -\frac{1}{14(s+3)} + \frac{-1}{(s+1)^2} + \frac{C}{s+1} + \frac{Ps}{s^2+s+1}$$

$$u(t) = \frac{1}{14} e^{-3} - t e^{-t} + c e^{-t} + P \left[e^{-\frac{1}{2}t} \cos \frac{\sqrt{5}}{2}t - \frac{1}{2} e^{-\frac{1}{2}t} \sin \frac{\sqrt{5}}{2}t \right]$$

Q.3 (b) Determine the frequency response, magnitude response, and phase response and time delay of the system given by $y(n) + \frac{1}{2}y(n-1) = x(n) - x(n-1)$. (6)

$$\text{Ans. } Y(n) + \frac{1}{2}y(n-1) = x(n) - x(n-1)$$

Taking FT

$$Y(jw) + \frac{1}{2}(jw)Y(jw) = X(jw) - jwX(jw)$$

$$H(jw) = \frac{Y(jw)}{X(jw)} = \frac{1-jw}{1+\frac{1}{2}jw}$$

$$= \frac{2(1-jw) \times (2-jw)}{(2+jw) \times (2-jw)}$$

$$= \frac{2\{2-3jw-w^2\}}{4+w^2} = \frac{2(2-w^2)}{4+w^2} - \frac{6jw}{4+w^2}$$

$$|H(jw)| = \sqrt{\left(\frac{2(2-w^2)}{4+w^2}\right)^2 + \left(\frac{6jw}{4+w^2}\right)^2} = \frac{1}{(4+w^2)^2} \sqrt{4(4+w^4-4w^2) + 36j^2w^2}$$

$$= \frac{1}{4+w^2} \sqrt{16+4w^4-16w^2-36w^2} = \frac{4}{4+w^2} \sqrt{4+w^4-13w^2}$$

$$\angle H(jw) = \tan^{-1} \frac{-6w}{2(2-w^2)} = \tan^{-1} \left(\frac{-3w}{2-w^2} \right)$$

Q.4. (a) A sine wave $\sin \omega t$ is applied as the input to the series RC circuit shown in fig.2. Find the resultant current $i(t)$ if switch S is closed at $t=0$.

(6.5)

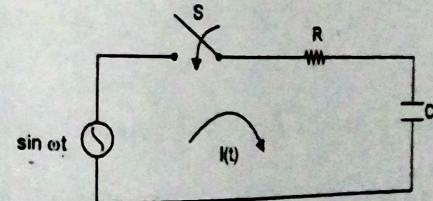


Fig. 2

Ans.

$$IR + \frac{1}{C} \int i dt = \sin \omega t$$

$$R \frac{di}{dt} + \frac{i}{c} = \omega \cos \omega t$$

$$\frac{di}{dt} + \frac{i}{RC} = \frac{\omega}{R} \cos \omega t$$

$$D + \frac{1}{RC} = 0 \Rightarrow D = -\frac{1}{RC}$$

$$CF = A e^{\frac{-t}{RC}}$$

$$PI = \frac{\frac{\omega \cos \omega t}{R} \left(D - \frac{1}{RC} \right)}{\left(D + \frac{1}{RC} \right) \left(D - \frac{1}{RC} \right)} = \frac{\omega \left[D \cos \omega t - \frac{1}{C} \cos \omega t \right]}{R \left[D^2 - \left(\frac{1}{RC} \right)^2 \right]}$$

$$\frac{\omega \left[-\omega \sin \omega t - \frac{1}{RC} \cos \omega t \right]}{R \left[-\omega^2 - \left(\frac{1}{RC} \right)^2 \right]}$$

$$= \frac{\left(\frac{\omega^2}{R} \sin \omega t + \frac{\omega^2}{R^2 C} \cos \omega t \right)}{\omega^2 + \left(\frac{1}{RC} \right)^2}$$

$$f(t) = A e^{\frac{-t}{RC}} + \frac{\omega}{R \left[\omega^2 + \left(\frac{1}{RC} \right)^2 \right]} \times \left[\omega \sin \omega t + \frac{1}{RC} \cos \omega t \right]$$

Q. 4. (b) Find the laplace transform of the triangular pulse shown.

(6)

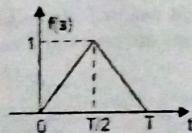


Fig. 3

$$Ans. \quad f(t) = \frac{2}{T} \left[u(t) - u\left(t - \frac{T}{2}\right) \right] + 2 \left(1 - \frac{t}{T} \right) \left[u\left(t - \frac{T}{2}\right) - u(t - T) \right]$$

$$= \frac{2}{T} \left[t u(t) - t u\left(t - \frac{T}{2}\right) \right] + \frac{2}{T} (T-t) \left[4 \left(t - \frac{T}{2} \right) - u(t-T) \right]$$

$$t u(t) \rightarrow \frac{1}{s^2}$$

$$t u\left(t - \frac{T}{2}\right) = \left(t - \frac{T}{2} \right) u\left(t - \frac{T}{2}\right) + \frac{T}{2} u(t-T/2)$$

$$\xrightarrow{-i\tau} \frac{e^{-\frac{T}{2}s}}{s^2} + \frac{T}{2} \frac{e^{-Ts}}{s}$$

$$(t-T) u(t-T) \rightarrow \frac{e^{-Ts}}{s^2}$$

$$(t-T) u(t-\frac{T}{2})$$

$$\left(t - \frac{T}{2} \right) u\left(t - \frac{T}{2}\right) - \frac{T}{2} u\left(t - \frac{T}{2}\right)$$

$$\frac{e^{-T/2 s}}{s^2} - \frac{T}{2} \frac{e^{-1/2 s}}{s}$$

$$f(t) \xrightarrow{LT} \frac{2}{T} \left[\frac{1}{s^2} - \frac{e^{-\frac{T}{2}s}}{s^2} - \frac{T e^{-\frac{T}{2}s}}{2s} \right]$$

$$= \frac{2}{T} \left[\frac{e^{-\frac{T}{2}s}}{s} - \frac{T e^{-\frac{T}{2}s}}{2s} - \frac{e^{-Ts}}{s^2} \right]$$

Q. 4(a) Consider R-L circuit with $R = 4\Omega$, $L = 1H$ excited by 20V dc source as shown in fig 4. Assume the initial value of current in inductor is 2A. Using Laplace Transform determine the current $I(t)$. Also draw the s-domain representation of the circuit.

(6.5)

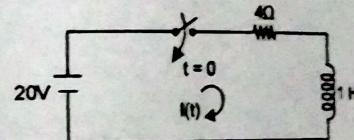


Fig. 4

Ans. Applying KVL in loop

$$I \times 4 + 1 \frac{dI}{dt} = 20$$

taking LT we get

$$4I(s) + sI(s) - i(0^+) = \frac{20}{s}$$

$$4I(s) + sI(s) = \frac{20}{s} + i(0^+)$$

$$I(s)(4+s) = \frac{20}{s} + 2 = \frac{20+2s}{s}$$

$$I(s) = \frac{s+10}{10(s+4)} = \frac{1}{10} \frac{s+4+6}{s+4} \text{ given } i(0) = 2A$$

$$= \frac{1}{10} \left[1 + \frac{6}{s+4} \right]$$

$$L(t) = \frac{1}{10} \delta(t) + \frac{6}{10} e^{-4t}$$

Q. 5. (b) State and explain the laplace transform and its inverse transform.

Ans. LT is a mathematical tool which transform a time domain signal into frequency (6.5) domain signal.

$$X(s) = \int_{-\infty}^{\infty} x(t)e^{-st} dt$$

Inverse LT is just inverse process of laplace transform

$$x(t) = \frac{1}{2\pi} \int X(s) e^{+st} ds$$

To represent the laplace and inverse transform we use following notation

$$x(t) \rightarrow X(s)$$

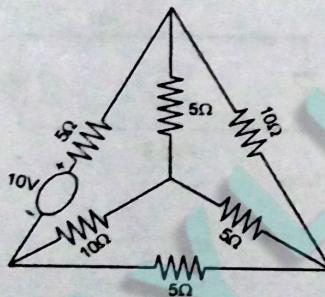
$$L(x(t)) = X(s)$$

and

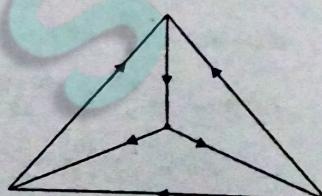
$$L^{-1}[X(s)] = x(t)$$

Where $X(s)$ is Laplace transform of $x(t)$ and $x(t)$ is inverse laplace transform of $X(s)$.

Q.6. (a) For the network shown write the tieset matrix and determine the (6.5) loop current and branch currents.

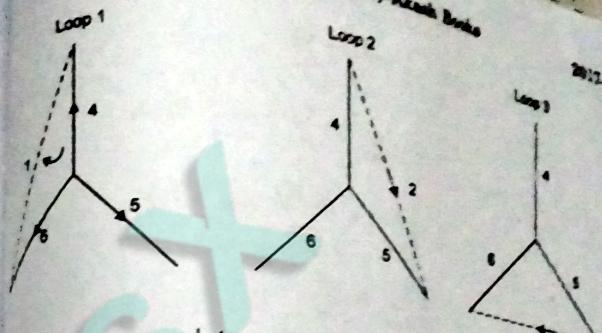


Ans.



Oriented graph of the given circuit.

We select tree (4, 5, 6) and link (1, 2, 3).



$$B_f = \begin{array}{|c c c c c c|} \hline & 4 & 5 & 6 & 1 & 2 & 3 \\ \hline 1 & -1 & 0 & 1 & 1 & 1 & 0 \\ 2 & 1 & -1 & 0 & 0 & 1 & 0 \\ 3 & 0 & 1 & -1 & 0 & 0 & 1 \\ \hline \end{array}$$

$$Z_b = \begin{array}{|c c c c c c|} \hline & 5 & 0 & 0 & 0 & 0 & 0 \\ 0 & 10 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 5 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 5 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 5 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 10 & 0 \\ \hline \end{array}$$

$$Z_i = B_f Z_b B_f^T \quad \& \quad V_i = Z_i T_i$$

$$I_b = [B_f]^T I_i - I_s$$

$$B_f Z_b = \begin{bmatrix} -5 & 0 & 5 & 5 & 0 & 0 \\ 5 & -10 & 0 & 0 & 5 & 0 \\ 0 & 10 & -5 & 0 & 0 & 10 \end{bmatrix}$$

$$B_f Z_b B_f^T = \begin{bmatrix} -5 & 0 & 5 & 5 & 0 & 0 \\ 5 & -10 & 0 & 0 & 5 & 0 \\ 0 & 10 & -5 & 0 & 0 & 10 \end{bmatrix} \begin{bmatrix} -1 & 1 & 0 \\ 0 & -1 & 1 \\ 1 & 0 & -1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Q. (b) Find the transmission parameter in terms of y and s parameters. (6.5)

$$V_1 = Z_{11} I_1 + Z_{12} I_2$$

$$V_2 = Z_{21} I_1 + Z_{22} I_2$$

$$I_1 = \frac{1}{Z_{11}} V_1 + \frac{Z_{21}}{Z_{11}} (-I_2)$$

$$C = \frac{1}{Z_{21}} \text{ and } D = \frac{Z_{22}}{Z_{21}}$$

$$V_1 = Z_{11} \left[\frac{1}{Z_{21}} V_2 + \frac{Z_{22}}{Z_{21}} (-I_2) \right] + Z_{12} I_2$$

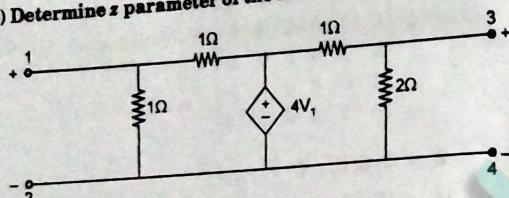
$$= \frac{(Z_{11})}{Z_{21}} V_2 + \left(\frac{Z_{11} Z_{22}}{Z_{21}} - Z_{12} \right) (-I_2)$$

$$A = \left(\frac{Z_{11}}{Z_{21}} \right) \quad B = \frac{\Delta Z}{Z_{21}}$$

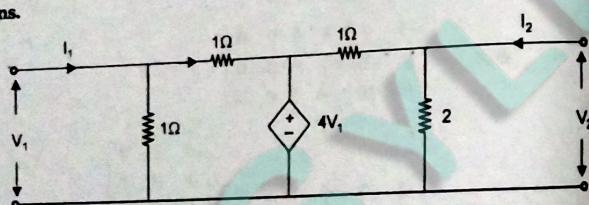
$$A = -\frac{Y_{22}}{Y_{21}} \quad B = -\frac{1}{Y_{21}}$$

$$C = -\frac{\Delta Y}{Y_{21}} \quad D = -\frac{Y_{11}}{Y_{21}}$$

Similarly Q.7. (a) Determine z parameter of the networks shown.



Ans.



$$I_1 = \frac{V_1}{1} + \frac{V_1 - 4V_1}{1}$$

$$I_2 = \frac{V_2}{2} + \frac{V_2 - 4V_1}{1}$$

$$I_1 = -2V_1 \Rightarrow V_1 = -\frac{I_1}{2}$$

$$I_2 = -4V_1 + \frac{3V_2}{2}$$

Putting the value of V_1 in above equation

$$\frac{3}{2}V_2 = I_2 - \frac{4I_1}{2}$$

$$V_2 = -\frac{2}{3} \times \frac{4}{2} I_1 + \frac{2}{3} I_2$$

$$V_2 = \frac{-4}{3} I_1 + \frac{2}{3} I_2$$

$$Z_{11} = \frac{1}{2} Z_{12} = 0$$

$$Z_{21} = \frac{-4}{3} \quad Z_{22} = \frac{2}{3}$$

Q.7. (b) Discuss the necessary conditions for transfer functions. (6)

Ans.

1. The coefficients in the polynomials $N(s)$ and $D(s)$ of $T = N/D$ must be real and those for $D(s)$ must be positive.
2. Poles and zeroes must be conjugate if imaginary or complex.
3. The real part of poles must be negative or zero, if the real part is zero, then that pole must be simple. This includes the origin.
4. The polynomial $D(s)$ may not have any missing term between that of highest and lowest degrees, unless all even or all odd terms are missing.
5. The polynomial $N(s)$ may have terms missing, and some of the coefficients may be negative.
6. The degree of $N(s)$ may be as small as zero independent of the degree of $D(s)$.

7. (a) for G and a : The maximum degree of $N(s)$ is equal to the degree of $D(s)$. (b) For Z and Y : The maximum degree of $N(s)$ is equal to the degree of $D(s)$ plus one.

Q.8. (a) Using the foster I Form synthesize the impedance function. (6.5)

$$z(s) = \frac{8(s^2 + 1)(s^2 + 3)}{s(s^2 + 2)(s^2 + 4)}$$

$$Z(s) = \frac{8(s^2 + 1)(s^2 + 3)}{s(s^2 + 2)(s^2 + 4)}$$

$$\frac{A_0}{s} + \frac{2A_1 s}{s^2 + 2} + \frac{2A_2 s}{s^2 + 4}$$

$$A_0 = \frac{8(s^2 + 1)(s^2 + 3)}{(s^2 + 2)(s^2 + 4)} \Big|_{s=0} = 3$$

$$A_1 = \frac{8(s^2 + 1)(s^2 + 3)}{(s^2 - j\sqrt{2})(s^2 + 4)} \Big|_{s=j\sqrt{2}} = 1$$

$$A_2 = \frac{8(s^2 + 1)(s^2 + 3)}{s(s^2 + 2)(s - j\sqrt{2})} \Big|_{s=j\sqrt{2}}$$

$$\frac{3}{5} + \frac{2s}{s^2 + 2} + \frac{3s}{s^2 + 4}$$

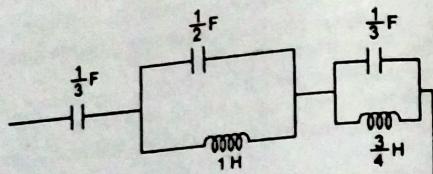
$$C_0 = \frac{1}{3} F$$

$$C_1 = \frac{1}{2 \times 1} = \frac{1}{2} F$$

$$L_1 = \frac{2}{(\sqrt{2})^2} = 1 H$$

$$C_2 = \frac{1}{2 \times 1.5} = \frac{1}{3}$$

$$L_2 = \frac{2 \times 1.5}{4} = \frac{3}{4} H$$



Q. 8. (b) Using the Foster II form synthesize the function

$$Y(s) = \frac{s(s^2 + 4)(s^2 + 6)}{(s^2 + 3)(s^2 + 5)}$$

Ans. Foster II

$$Y(s) = \frac{s(s^2 + 2)(s^2 + 4)}{8(s^2 + 1)(s^2 + 3)}$$

$$= \frac{2B_1 s + 2B_2 s}{s^2 + 1} + C_3$$

$$B_1 = \left. \frac{1}{8} \frac{s(s^2 + 2)(s^2 + 4)}{(s - 1)(s^2 + 3)} \right|_{s=-j1} = \frac{3}{32}$$

$$B_2 = \left. \frac{1}{8} \frac{(s^2 + 2)(s^2 + 4)}{(s^2 + 1)(s - 1\sqrt{3})} \right|_{s=-j\sqrt{3}} = \frac{1}{32}$$

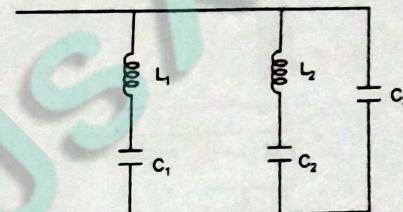
$$L_1 = \frac{1}{2} \times \frac{32}{3} = \frac{16}{3}$$

$$L_2 = \frac{1}{2} \times 32 = 16 H$$

$$C_1 = \frac{2 \times \frac{3}{32}}{1} = \frac{3}{16} F$$

$$C_2 = \frac{2 \times \frac{1}{32}}{3} = \frac{1}{48} F$$

$$C_3 = \frac{1}{8} F$$



Q. 9. (a) A series LCR type band pass filter has $L = 50 \text{ mH}$, $C = 130 \text{ nF}$ and $RF = 80 \Omega$. (6.5)

Determine

- (i) frequency of resonance
- (ii) bandwidth
- (iii) cutoff frequency

Ans. (a) For RLC Band pass filter

$$f_r = \frac{1}{2\pi\sqrt{LC}} = \frac{1}{2\pi\sqrt{50 \times 10^{-3} \times 130 \times 10^{-9}}} = 1.97 \times 10^3$$

$$Q = \frac{W_r L}{R} = \frac{\frac{1}{2\pi f_r} \times L}{R} = \frac{\sqrt{L/C}}{R} = \frac{\sqrt{50 \times 10^{-3}}}{80}$$

$$\frac{620}{80} = 7.75$$

$$BW = \frac{f_r}{Q} = \frac{1.97 \times 10^3}{7.75} = 254.2$$

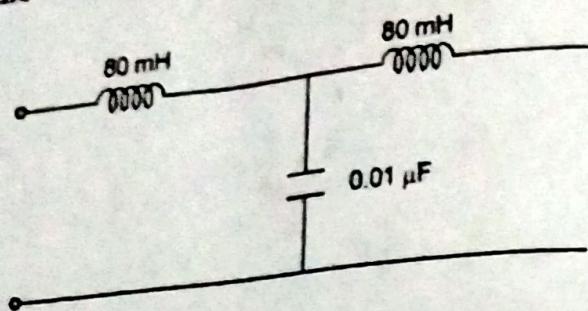
$$f_1 = f_r - \frac{BW}{2} = 1970 - 147 \\ = 1823$$

$$f_2 = f_r + \frac{BW}{2} = 1970 + 147 \\ = 2117$$

22-2017

Third Semester, Circuits and Systems

Q. 9. (b) For the T-section find cutoff frequency and nominal characteristics
impedance R_o . (6)



Ans.

$$w_c = \sqrt{\frac{4}{LC}}$$

$$= \sqrt{\frac{4}{80 \times 2 \times 10^{-3} \times 0.01 \times 10^{-6}}}$$

$$= \sqrt{\frac{4}{1.6 \times 10^{-9}}}$$

$$= 50000 = 50 \text{ KHz}$$

$$R_o = \sqrt{\frac{L}{C}} = \sqrt{\frac{160 \times 10^{-3+1}}{1 \times 10^{-6-2}}} = 4 \times 10^3$$

$$= 4000$$

$$Z_{OT} = R_o \sqrt{1 - \left(\frac{f_e}{f_c}\right)^2}$$

FIRST TERM EXAMINATION [SEP. 2018]

THIRD SEMESTER [B.TECH]

CIRCUITS AND SYSTEMS [ETEE-207]

Time : 1½ hrs.

M.M. : 30

Note: Q. No. 1 is compulsory. Attempt any two more Questions from the rest.

Q.1. (a) What are even and odd signals? Explain with example. (2)

Ans.

$$f(-x) = f(x) \quad \text{even signal}$$

$$f(-x) = -f(x) \quad \text{odd signal}$$

$$f(x) = \cos x \text{ is an even signal}$$

$$f(x) = \sin x \text{ is an odd signal}$$

Q. 1. (b) What is LTI system. Describe its properties. (2)

Ans. LTI – Linear time invariant

1. LTI Systems: A system is instantaneous (or memoryless or zero memory or without memory) if its output at any time depends only on the value of the input at the same time, otherwise dynamic i.e., a dynamic system or system with memory is one whose output depends on past or future values of the input or past values of output in addition to the present input.

A without memory continuous-time LTI system has the form

$$y(t) = Kx(t) \quad (\text{where } K \text{ is any constant})$$

Its impulse response

$$h(t) = K\delta(t)$$

Similarly, the form of a without memory discrete-time LTI system and its corresponding impulse response we $y[n] = Kx[n]$ and $h[n] = K\delta[n]$, respectively.

Note that if $K = 1$, then these systems become identity systems, with outputs equal to the inputs and with unit impulse responses equal to the unit impulse signals, i.e.,

$$h(t) = 0; \text{ for } t \neq 0 \quad \text{and} \quad h[n] = 0; \text{ for } n \neq 0$$

In this case, the convolution integral and sum formulas imply that

$$x(t) = x(t) * \delta(t) \quad \text{and} \quad x[n] = x[n] * \delta[n]$$

If an LTI system has an impulse response $h(t)$ or $h[n]$ that is not identically zero for $t < 0$ or $n < 0$, respectively, then the system is with memory or dynamic.

2. Causality of LTI Systems: A system is causal or non-anticipative if the output of the system at any time depends only on values of the input at the present time and in the past otherwise non-causal i.e., a non-causal system is the system whose output depends (or anticipate) future values of the input.

A continuous-time LTI system to be causal, output $y(t)$ must not depend on input $x(\tau)$ for $\tau > t$. This results

$$h(t) = 0 \quad \text{for } t < 0$$

Similarly, for a causal discrete-time LTI system the output $y[n]$ depends on input $x[k]$ for $k < n$. This results $h[n] = 0$ for $n < 0$.

That is the impulse response of a causal LTI system must be zero before the impulse occurs.

More generally, causality for an LTI system is equivalent to the condition of initial rest. And the system output is

$$y(t) = \int_{-\infty}^t x(\tau)h(t-\tau) d\tau \quad \text{or} \quad y[n] = \sum_{k=-\infty}^n x[k]h[n-k]$$

2-2018

Third Semester, Circuit and System

In other words, the causality of an LTI system is equivalent to its impulse response being a causal signal.

3. Invertibility of LTI Systems: A system is invertible only if an inverse system exists that, when cascaded with the original system, yields an output equal to the input to the first system. Here, if an LTI system is invertible, then it has an LTI inverse.

If we have an LTI system with impulse response $h(t)$ or $h[n]$, then inverse system with impulse response $g(t)$ or $g[n]$, must satisfy

$$h(t) \cdot g(t) = \delta(t)$$

$$h[n] \cdot g[n] = \delta[n]$$

or

4. Stability of LTI Systems: An LTI system is said to be stable if the impulse response is absolutely integrable in case of continuous-time or absolutely summable in case of discrete-time systems, i.e.,

$$\int_{-\infty}^{\infty} |h(\tau)| d\tau < \infty \quad \text{or} \quad \sum_{k=-\infty}^{\infty} |h[k]|$$

More general, an LTI system is said to be stable if the impulse response approaches zero as $t \rightarrow \infty$ or $n \rightarrow \infty$ for continuous-time or discrete-time system, respectively.

5. Commutative Property: The output of an LTI system with impulse response $h(t)$ or $h[n]$ to input $x(t)$ or $x[n]$ is equal to the output of the system with impulse response $x(t)$ or $x[n]$ to input $h(t)$ or $h[n]$, i.e.,

$$y(t) = x(t) * h(t) = h(t) * x(t)$$

$$y[n] = x[n] * h[n] = h[n] * x[n]$$

or

$$y(t) = \int_{-\infty}^t x(\tau) h(t-\tau) d\tau = \int_{-\infty}^t x(t-\tau) h(\tau) d\tau$$

This leads to

$$y[n] = \sum_{k=-\infty}^n x(k) h[n-k] = \sum_{k=-\infty}^n x(n-k) h[k]$$

or

which may at times be easier to evaluate than equation.

6. Distributive Property: The output of an LTI system with impulse response $h_1(t) + h_2(t)$ or $h_1[n] + h_2[n]$ to input $x(t)$ or $x[n]$ is equal to the sum of the output of system with impulse response $h_1(t)$ or $h_1[n]$ to input $x(t)$ or $x[n]$ and system with impulse response $h_2(t)$ or $h_2[n]$ to input $x(t)$ or $x[n]$, i.e.,

$$y(t) = x(t) * [h_1(t) + h_2(t)] = x(t) * h_1(t) + x(t) * h_2(t)$$

or

$$y[n] = x[n] * [h_1[n] + h_2[n]] = x[n] * h_1[n] + x[n] * h_2[n]$$

The distributive property is useful when two or more systems are connected in parallel.

Also, as a consequence of both commutative and distributive properties, we have

$$y(t) = [x_1(t) + x_2(t)] * h(t) = x_1(t) * h(t) + x_2(t) * h(t)$$

or

$$y[n] = [x_1[n] + x_2[n]] * h[n] = x_1[n] * h[n] + x_2[n] * h[n]$$

Which simply state that the response of an LTI system to the sum of two inputs must equal the sum of the responses to these inputs individually.

7. Associative Property: The output of an LTI system with impulse response $[h_1(t) + h_2(t)]$ or $[h_1[n] + h_2[n]]$ to input $x(t)$ or $x[n]$ is equal to the output of the system with impulse response $h_2(t)$ or $h_2[n]$ to input $[x(t) * h_1(t)]$ or $x[n] * h_1[n]$, i.e.,

$$y(t) = x(t) * [h_1(t) + h_2(t)] = [x(t) * h_1(t)] * h_2(t)$$

or

$$y[n] = x[n] * [h_1[n] + h_2[n]] = [x[n] * h_1[n]] * h_2[n]$$

The associative property is useful when two or more systems are connected in series or in cascade.

Also, as a consequence of this property, we can say that the overall system response does not depend upon the order of the systems in the series or in cascade.

Q. 1. (c) What is the rate of change of current at $t = 0^+$ in a coil of resistance 10 ohms and Inductance of 0.5 H, when connected to a 100 V d.c. supply. (2)

Ans.

$$L \frac{dI}{dt} + IR = 100$$

at

$$t = 0^+ \quad I = 0$$

$$L \frac{dI}{dt} = 100 \Rightarrow \frac{dI}{dt} = \frac{100}{0.5} = 200$$

Q. 1. (d) Find the Laplace Transform of the following functions: (2)

$$(i) e^{-at} \cos \omega t$$

$$(ii) 10U(t) - \delta(t) - 5\delta(t-4)$$

Ans. (i) $e^{-at} \cos \omega t$

$$\cos \omega t \rightarrow \frac{s}{s^2 + \omega^2}$$

$$e^{-at} \cos \omega t \rightarrow \frac{s+a}{(s+a)^2 + \omega^2}$$

$$(ii) 10U(t) - \delta(t) - 5\delta(t-4)$$

$$U(t) \rightarrow \frac{1}{s}$$

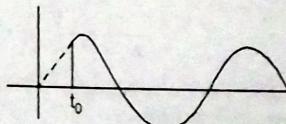
$$\delta(t) \rightarrow 1$$

$$\delta(t-4) \rightarrow e^{-4s}$$

LT of this function is

$$\frac{10}{s} - 1 - 5e^{-4s}$$

Q. 1. (e) What are Singularity functions? If $f(t) = \sin \omega t$, then draw the signal $f(t)u(t-t_0)$ (2)

Ans. $\sin \omega t u(t-t_0)$ 

Singularity function

1. Unit step

2. Sgn(t)

3. Ramp function

4. Impulse

Q. 2. (a) Synthesize the given waveform (fig. 1. and fig. 2) and find its Laplace Transform. (6)

4-2018

Third Semester, Circuit and System

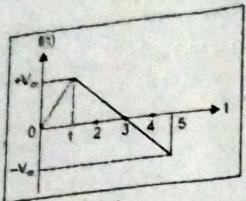


Fig. 1.

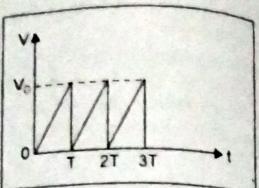


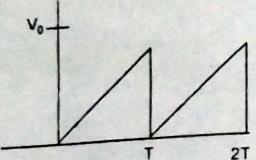
Fig. 2.

Ans.

$$\begin{aligned} f(t) &= V_m t [u(t) - u(t-1)] + \frac{-V_m}{2} (t-3)[u(t-1) - u(t-5)] \\ &= V_m t u(t) - \frac{3}{2} V_m (t-1) u(t-1) + \frac{V_m}{2} (t-5) u(t-5) + V_m u(t-5) \end{aligned}$$

taking LT

$$F(s) = \frac{V_m}{s^2} - \frac{3}{2} V_m \frac{e^{-s}}{s^2} + \frac{V_m}{2} \frac{e^{-5s}}{s^2} + \frac{V_m e^{-5s}}{s}$$



$$\begin{aligned} V_1(t) &= \frac{V_0}{T} t [u(t) - u(t-T)] \\ &= \frac{V_0}{T} t u(t) - \frac{V_0}{T} (t-T) u(t-T) - V_0 u(t-T) \\ &= \frac{V_0}{T} \left[\frac{1}{s^2} - \frac{e^{-Ts}}{s^2} \right] - \frac{V_0 e^{-Ts}}{s} \end{aligned}$$

taking LT

LT of a periodic signal with period T is

$$\frac{1}{1-e^{-Ts}} \left[\frac{V_0}{T} \frac{1}{s^2} - \frac{V_0 e^{-Ts}}{T s^2} - \frac{V_0 e^{-Ts}}{s} \right]$$

Q. 2. (b) Without finding the inverse Laplace Transform of $F(s)$, find initial and final values of following functions. (4)

$$(a) F(s) = \frac{s^2 + 5s + 7}{s^2 + 3s + 2}$$

$$(b) F(s) = \frac{5s^3 - 1600}{s(s^3 + 18s^2 + 90s + 800)}$$

$$\text{Ans. (a)} \quad f(0^+) = \lim_{s \rightarrow \infty} sF(s) = \frac{s(s^2 + 5s + 7)}{s^2 + 3s + 2} = \infty$$

$$f(\infty) = \lim_{s \rightarrow 0} sF(s) = \frac{s(s^2 + 5s + 7)}{s^2 + 3s + 2} = 0$$

$$f(0^+) = \lim_{s \rightarrow \infty} sF(s) = \lim_{s \rightarrow \infty} \frac{5s^3 - 1600}{s^3 + 18s^2 + 90s + 800}$$

$$= \lim_{s \rightarrow \infty} \frac{5 - \frac{1600}{s^3}}{1 + \frac{18}{s} + \frac{90}{s^2} + \frac{800}{s^3}} = 5$$

$$f(\infty) = \lim_{s \rightarrow 0} sF(s) = \lim_{s \rightarrow 0} \frac{5s^3 - 1600}{s^3 + 18s^2 + 90s + 800} = -2$$

Q. 3. (a) Write down the Integro-Differential equation for the electric circuit shown in fig. 3, using KVL. also draw the s-domain equivalent circuit. (5)

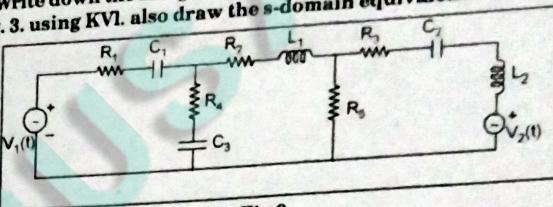
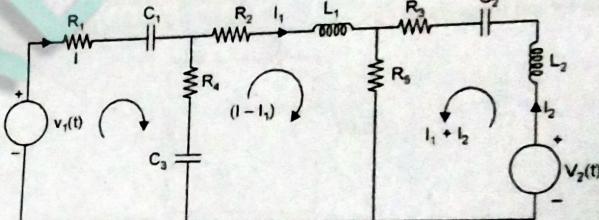


Fig.3.

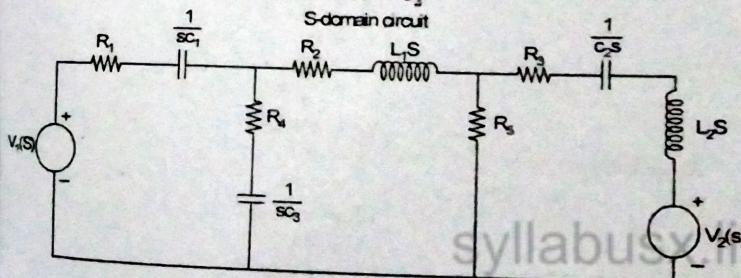
Ans.



$$V_1(t) = IR_1 + \frac{1}{C_1} \int Idt + (I - I_1) R_4 + \frac{1}{C_3} \int (I - I_1) dt$$

$$R_2 I_1 + L_1 \frac{dI_1}{dt} + (I_1 + I_2) R_5 - \frac{1}{C_3} \int (I - I_1) dt - R_4 (I - I_1)$$

$$V_2(t) = L_2 \frac{dI_2}{dt} + \frac{1}{C_2} \int I_2 dt + I_2 R_3 + (I_1 + I_2) R_5$$



Q.3. (b) Find $i(t)$ for $t > 0$ in the circuit of fig. 4. switch is opened at $t = 0$.

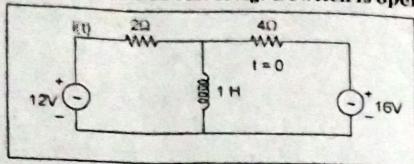
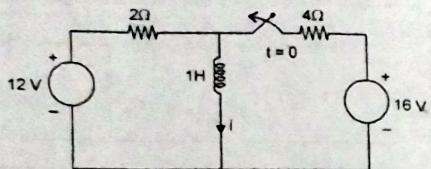


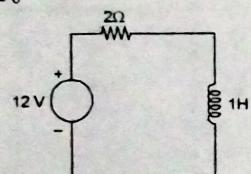
Fig. 4.

Ans.

$$t = 0^- \text{ inductor behave as short circuit}$$

$$\text{at } t = 0 \quad i = 4 + 6 = 10 \text{ A}$$

So,

When switch is open at $t = 0$ 

$$12 = I \times 2 + L \frac{dI}{dt}$$

$$12 = 2I + \frac{dI}{dt} \quad [L = 1 \text{ H}]$$

$$D + 2 = 0 \Rightarrow D = -2$$

$$CF = Ae^{-2t}$$

$$PI = \frac{12}{D + 2}$$

$$\text{at } D = 0$$

$$= \frac{12}{2} = 6$$

$$I(t) = 6 + Ae^{-2t}$$

$$t = 0$$

$$I = 10 \text{ A}$$

$$10 = 6 + Ae^0$$

$$A = 4 \text{ A}$$

$$I(t) = 6 + 4e^{-2t}$$

Auxiliary equation**As we know at**

Q.4. (a) Synthesize the given wave form (Fig. 5) using standard signals. (5)

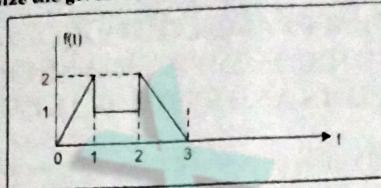
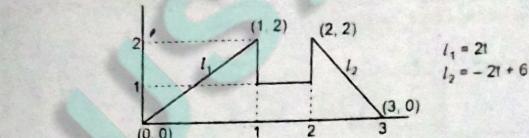
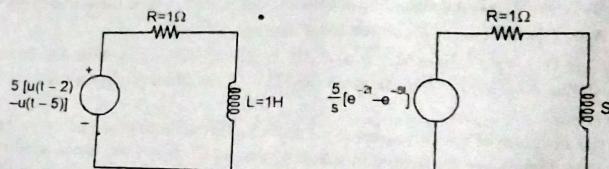


Fig. 5.

Ans.

$$f(t) = 2t[u(t) - u(t-1)] + [u(t-1) - u(t-2)] + (-2t + 6)[u(t-2) - u(t-3)]$$

Q.4. (b) A voltage pulse of magnitude 5V and duration of 3 seconds extending from $t = 2$ to $t = 5$ is applied to a series R-L circuit having $R=1 \Omega$ and $L=2 \text{ henry}$. Find $i(t)$, initially inductor is de-energized. (5)

Ans.

$$\frac{5}{s} (e^{-2s} - e^{-5s}) = I + si$$

$$I = \frac{5}{s(s+1)} (e^{-2s} - e^{-5s})$$

$$I(s) = 5 \left[\frac{1}{s} - \frac{1}{s+1} \right] (e^{-2s} - e^{-5s})$$

taking inverse LT

$$I(t) = 5[(u(t-2) - u(t-5)) - [e^{-(t-2)} - e^{-(t-5)}]]$$

END TERM EXAMINATION [NOV-DEC 2018]

THIRD SEMESTER [B.TECH]

CIRCUITS AND SYSTEMS [ETEE-207]

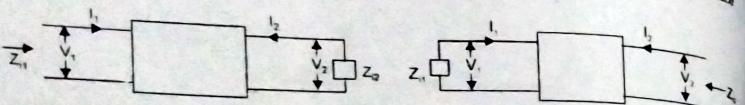
Time : 3 hrs.

M.M. : 75

Note: Attempt any five questions including Q no. 1 which is compulsory.

Q.1. (a) Write short on Image Impedance.

Ans. In two port network if the impedance at input port with impedance z_{11} connected across output port be z_{12} as shown in fig. and the impedance at output port with impedance z_{22} connected to input port be z_{21} as shown in fig. below. (5)



$$Z_{11} = \frac{V_1}{I_1}$$

$$Z_{22} = \frac{V_2}{I_2}$$

Q. 1. (b) What are the characteristics of positive real function (p.r.). (5)

Ans. Properties of Positive Real Function (p.r.f.)

(i) If $T(s)$ is p.r., then $1/T(s)$ is also p.r. This property implies that if a driving point impedance $Z(s)$ is p.r., then its reciprocal ($1/Z(s)$), the driving point admittance $Y(s)$, is also p.r.

(ii) The sum of p.r. functions is p.r. from an immittance stand point, we see that if two impedances are connected in series or two admittances are connected in parallel, the resultant impedance or admittance is p.r. (Note that the difference of two p.r. functions is not necessarily p.r.).

(iii) The poles and zeros of p.r.f cannot have positive real parts, i.e., they cannot be in the right half of the s-plane. In addition to this, only simple poles with real positive residues can exist on the jω-axis.

(iv) The poles and zeros of a p.r.f. are real or occur in conjugate pairs.

(v) The highest powers of the numerator $N(s)$ and denominator $D(s)$ polynomial may differ at most by unity. This condition prohibits multiple poles or zeros at $s = \infty$.

(vi) The lowest power of $D(s)$ and $N(s)$ polynomials may differ by at most unity. This condition prevents the possibility of multiple poles or zeros at $s = 0$.

Q. 1. (c) Write short note on types of filters with their characteristics graph. (5)

Ans. Low Pass Filters: These filters reject all frequencies above cut-off frequency f_c . The attenuation characteristic of an ideal LP filter is shown in figure 1(a). Thus the pass band or transmission band for the LP filter is the frequency range 0 to f_c and the stop band or attenuation band is the frequency range above f_c .

High Pass Filters: These filters reject all frequencies below cut-off frequency, f_c below f_c respectively. The pass band of the HP filter are the frequency range above f_c and the stop band or attenuation band is the frequency range below f_c .

Band Pass Filters: These filters allow transmission of frequencies between two designated cut off frequencies and reject all other frequencies. As shown in figure 1. (b) a band pass filter has two cut-off frequencies and will have the pass band $f_{C_2} - f_{C_1}$, f_{C_1} is called as the lower cut-off frequency while f_{C_2} is called the upper cut-off frequency.

Band Stop or Band Elimination Filters: These filters pass all frequencies lying outside a certain range, while it attenuates all frequencies between the two frequencies f_{C_1} and f_{C_2} . The characteristic of an ideal band stop filter is shown in figure 1. (d).

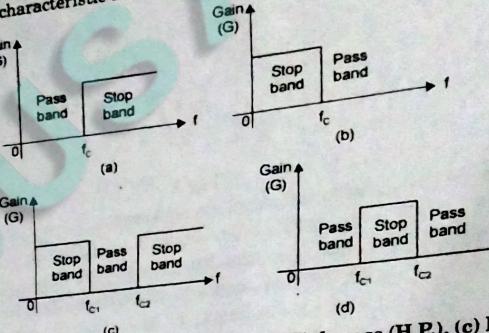


Fig. 1. Ideal response of (a) Low-pass (L.P) (b) High-pass (H.P.), (c) Band-Pass (B.P.) and (d) Band stop (B.S.) filters, Here $G = V_o/V_i$ represents the gain of the filter and attenuation is inverse of the gain of the filter

Q. 1. (d) Explain mathematically convolution in time domain for Laplace Transform. (5)

Ans. Convolution in time domain equivalent to multiplication in laplace transform.

$$x(t) \times h(t) = \int_0^t x(\tau)h(t-\tau)d\tau = X(s).H(s)$$

Q. 1. (e) Synthesize the following waveform as shown in fig. 1. Using gate function. (5)

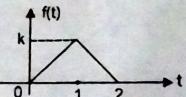


Fig.1

Ans. eqn of line 1

at (1, k)

at (2, 0)

$$y = kt$$

$$y = m + c$$

$$k = m + c$$

$$0 = 2m + c$$

$$-k = m + c$$

$$-k = m$$

$$c = -2m$$

Unit Response Circuit and System

$$u - 2u - 4 = 2$$

$$U(t) - 2U(t-1) - 4U(t-2) = 2$$

$$(U(t) - 2U(t-1) - 4U(t-2)) + 2U(t-1) - 4U(t-2)$$

$$U(t) - 2U(t-1) - 2U(t-2) = \cancel{2U(t-1)} - \cancel{4U(t-2)}$$

$$U(t) - 2U(t-1) - 2U(t-2) = 2U(t-1) - 4U(t-2)$$

Ans. 2

Q. 2 (a) Synthesize the following waveform as shown in fig. 2.

(a)

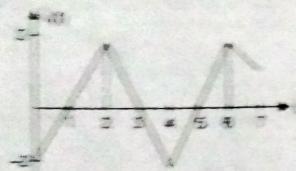


Fig. 2

Ans. 2 (a) Using gate functions, we can represent as

$$\begin{aligned} u(t) &= (2 - 2U(t))U(t) - (2 - 2)U(t-1) - (2 - 2U(t-1))U(t-1) \\ &\quad - (2U(t-1) - 2)(U(t-2) - 2)U(t-2) + \dots \\ &= (2 - 2)U(t) - (2 - 2 - 2)(U(t-2) - 2) \\ &\quad + (2 - 4 + 2 - 10)U(t-4) + \dots \\ &= (2 - 2)U(t) - 4U(t-2) + 2U(t-4) - 16U(t-6) + \dots \\ &= 2U(t) - 4U(t-2)U(t-2) - 8U(t-4)U(t-4) + \dots \end{aligned}$$

Q. 2 (b) Calculate the Laplace Transform of the periodic waveform as shown in fig. 2.

(b)

Ans. 2 (b) Using theorem for periodic functions

$$\begin{aligned} u(t) &= (2 - 2)U(t) - (2 - 2)U(t-1) - (2 - 2)U(t-2) - (2 - 2)U(t-3) \\ &= 2U(t) - 2U(t-1) - 2U(t-2) - 2U(t-3) + 2U(t-4) \\ &= 2U(t) - 2U(t-4) - 2U(t-2) - 2U(t-1) + 2U(t-4) - 2U(t-3) \end{aligned}$$

$$\begin{aligned} U(s) &= 2U(s) = \frac{2}{s^2 - 4} = \frac{2e^{-2s}}{s^2} - \frac{2e^{-4s}}{s^2} \\ &= \frac{2}{s^2}(1 - e^{-2s}) - \frac{2}{s^2}(1 - e^{-4s}) = \frac{2}{s^2}(1 - e^{-2s}) - \frac{2}{s^2}(1 - e^{-4s}) \end{aligned}$$

Since Time period, T = 4. Therefore,

$$I(s) = \frac{1}{1 - e^{-4s}} U(s) = \frac{2}{s^2} \left[\frac{1 - e^{-2s}}{1 - e^{-4s}} \right] = \frac{2}{s} \left[\frac{1}{2} \tanh \left(\frac{s}{2} \right) \right]$$

$$\begin{aligned} (a) \quad V(t) &= 1G_{0,1}(t) + (-2)G_{1,2}(t) \\ &= [U(t) - U(t-1)] - 2[U(t-1) - U(t-2)] \\ &= U(t) - 8U(t-1) + 2U(t-2) \end{aligned}$$

$$V(t) = \frac{1}{s} (1 - e^{-4s}) \cdot \frac{1}{s^2} \cdot \frac{1}{s} (1 - e^{-4s}) = \frac{1}{s^3} (1 - e^{-4s})^2$$

Since Time period, T = 4. Therefore,

$$V(s) = \frac{1}{1 - e^{-4s}} \frac{1}{s^3} = \frac{1}{1 - e^{-4s}} \frac{1}{s^3} \cdot \frac{1}{1 - e^{-4s}} = \frac{1}{1 - e^{-8s}} \frac{1}{s^3}$$

Alternative ways:

$$V(s) = U(s) - U(s - 4) + U(s - 8) - U(s - 12)$$

Q. 2 (c)

Ans.

$$\begin{aligned} f_1(t) &= e^{2t} \sin(2t) \\ &= e^{2t} \cdot 2 \sin(t) \\ &= 2e^{2t} \sin(t) \end{aligned}$$

$$f_2(t) = \frac{1}{t+2}$$

Applying time shifting theorem

$$e^{2(t-2)} f_1(t-2) = \frac{e^{2t}}{t-2}$$

Q. 2 (d) Determine whether or not each of the following signals is periodic. If signal is periodic, specify its fundamental period.

$$g_1(t) = e^{j\pi t}, \quad g_2(t) = e^{j\pi t/10}, \quad g_3(t) = e^{j\pi t/100}$$

$$T = 2\pi$$

$$N = \frac{2}{\pi}$$

So t is a periodic signal with period = 2

$$\frac{2}{\pi} < \frac{1}{\pi} < \frac{2}{10}$$

 $e^{j\pi t}$ is not periodicQ. 4 (a) The charge $q(t)$ in an electric circuit is given by $\frac{d^2q}{dt^2} + 6\frac{dq}{dt} + 8q = 100$

If all initial conditions are zero, determine the current through the circuit.

$$\text{Ans. } \frac{d^2q(t)}{dt^2} + 6 \frac{dq(t)}{dt} + 8q(t) = 100$$

Taking LT taking all initial condition zero

$$s^2 Q(s) + 6sQ(s) + 8Q(s) = \frac{100}{s}$$

$$Q(s) = \frac{100}{s^2 + 6s + 8}$$

$$\int \frac{100}{3} e^{-4t} \cos 3t dt$$

$$Q = 50 \int e^{-4t} \cos 3t dt$$

Taking LT

$$\text{LT of } \frac{1}{(s^2 + 8s + 25)}$$

$$\frac{1}{3} \times \frac{3}{(s+4)^2 + 3^2} \rightarrow \frac{1}{3} \cos 3t e^{-4t}$$

Q. 4. (b) In the given networks as shown in fig. 3, find the current.

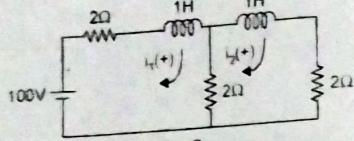


Fig. 3.

Ans. Applying KVL,

Loop 1:

$$100 = 2i_1(t) + 1 \cdot \frac{di_1(t)}{dt} + 2[i_1(t) - i_2(t)]$$

Taking Laplace transform, with $i_1(0^+) = 0$

$$\frac{100}{s} = 2I_1(s) + sI_1(s) + 2[I_1(s) - I_2(s)]$$

or

$$\frac{100}{s} = (4+s)I_1(s) - 2I_2(s) \quad \dots(1)$$

Loop 2: $2[i_2(t) - i_1(t)] + 1 \cdot \frac{di_2(t)}{dt} + 2i_2(t) = 0$ Taking Laplace transform, with $i_2(0^+) = 0$

$$2[I_2(s) - I_1(s)] + sI_2(s) + 2I_2(s) = 0$$

$$(4+s)I_2(s) = 2I_1(s) \quad \dots(2)$$

From equation (2), putting the value of $I_1(s)$ in equation (1), we have

$$\frac{100}{s} = \left[(4+s) \cdot \frac{(4+s)}{2} - 2 \right] I_2(s)$$

$$I_2(s) = \frac{200}{s(s^2 + 8s + 12)} = \frac{200}{s(s+2)(s+6)}$$

Using partial fraction expansion

$$I_2(s) = \frac{50/3}{s} - \frac{25}{s+2} + \frac{25/3}{s+6}$$

Therefore,

$$i_2(t) = \mathcal{L}^{-1}[I_2(s)] = \left[\frac{50}{3} - 25e^{-2t} + \frac{25}{3}e^{-6t} \right] U(t) A$$

Q. 5. (a) Find the value of current in series R-L-C circuit with unit step response for over damped, critically damped, and under damped conditions.

(6.5)

Ans. Application of KVL in the series RLC circuit at $t = 0^+$ after the switch is closed, leads to the following differential equation

$$iR + L \frac{di}{dt} + \frac{1}{C} \int i dt = V_0 \text{ (Fig. a)}$$

By differentiation,

$$L \frac{d^2 i}{dt^2} + R \frac{di}{dt} + \frac{i}{C} = 0$$

$$\left(p^2 + \frac{R}{L} p + \frac{1}{LC} \right) i = 0$$

Equation (1) is a second order, linear homogenous differential equation. The characteristic equation then becomes

$$p^2 + \frac{R}{L} p + \frac{1}{LC} = 0$$

where the coefficients are constant. The roots of the characteristic equation then become

$$p_1, p_2 = \frac{-R/L \pm \sqrt{(R/L)^2 - 4/LC}}{2}$$

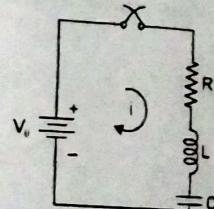


Fig. a. Series RLC circuit.

$$\alpha = (-R/2L)$$

$$\beta = \sqrt{(R/2L)^2 - \frac{1}{LC}}$$

$$p_1 = \alpha + \beta$$

$$p_2 = \alpha - \beta$$

Also, the solution of differential equation 1 becomes

$$i = C_1 e^{p_1 t} + C_2 e^{p_2 t} \quad \dots(2)$$

 C_1 and C_2 being the constants.Case 1. When $\left(\frac{R}{2L}\right)^2 > \frac{1}{LC}$ The time β is positive real quantity. Hence, the roots p_1 and p_2 are real but unequal.

$$p_1 = \alpha + \beta; p_2 = \alpha - \beta$$

$$i = C_1 e^{(\alpha+\beta)t} + C_2 e^{(\alpha-\beta)t}$$

$$= e^{\alpha t} (C_1 e^{\beta t} + C_2 e^{-\beta t})$$

The current response is over-damped fig. (b)

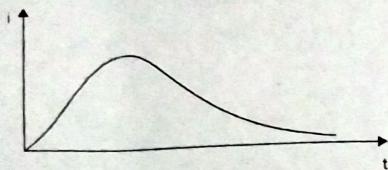


Fig. (b). Current over damping

$$\text{Case 2. When } \left(\frac{R}{2L}\right)^2 < \frac{1}{LC}$$

This time β is imaginary and then the roots p_1 and p_2 are complex conjugates

$$\begin{aligned} p_1 &= \alpha + j\beta; p_2 = \alpha - j\beta \\ i &= C_1 e^{(\alpha+j\beta)t} + C_2 e^{(\alpha-j\beta)t} \\ &= e^{\alpha t} (C_1 e^{j\beta t} + C_2 e^{-j\beta t}) \\ &= e^{\alpha t} [C_1 \cos(\beta t) + C_2 \sin(\beta t)] \end{aligned}$$

Thus the current solution is underdamped (or oscillatory) Fig. c.

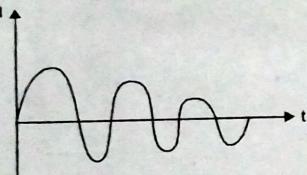


Fig. (c) Current oscillation

$$\text{Case 3. When } \left(\frac{R}{2L}\right)^2 = \frac{1}{LC}$$

This time β is zero.

Hence, roots p_1 and p_2 are real and equal.

$$\begin{aligned} p_1 &= p_2 = \alpha \quad \text{and} \quad i = C_1 e^{\alpha t} + C_2 t e^{\alpha t} \\ &= e^{\alpha t} (C_1 + C_2 t) \end{aligned}$$

The current response is then a critically damped one Fig. (d).

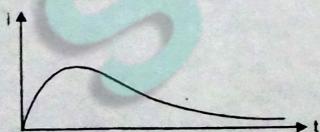
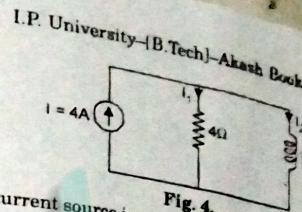


Fig. (d). Critical damping of current.

Q. 5. (b) In parallel circuit as shown in fig. 4. Calculate the branch current. (6)



Ans. Convert the current source in voltage source.

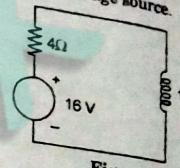


Fig.

$$16 = I \times 4 + L \frac{di}{dt}$$

$$16 = 4I + \frac{di}{dt}$$

$$CF = Ae^{-4t}$$

$$PI = \frac{16}{D+4} = \frac{16}{4} = 4$$

$$I = 4 + Ae^{-4t}$$

$$t = 0; I = 0$$

$$A = -4$$

$$I(t) = 4(1 - e^{-4t})$$

Q. 6. (a) Determine transmission (or ABCD) parameters of a T-network as shown in fig. 5, considering three sections assuming connected in cascade manner. (8)

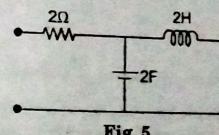
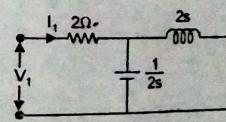


Fig. 5.

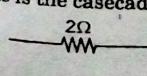
Ans.



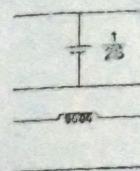
$$V_1 = AV_2 - BV_1$$

$$I_1 = CV_2 - DI_1$$

This is the cascad combination of three network



$$T_a = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$



$$T_b = \begin{bmatrix} 1 & 0 \\ 2s & 1 \end{bmatrix}$$

$$T_e = \begin{bmatrix} 1 & 2s \\ 0 & 1 \end{bmatrix}$$

For the combination

$$\begin{aligned} T &= T_a \times T_b \times T_e \\ &= \begin{bmatrix} 4s+1 & 2(4s^2+s+1) \\ 2s & 4s^2+1 \end{bmatrix} \end{aligned}$$

Q. 6. (b) Find the relationship between Z-parameters in terms of h-parameters.

Ans. Z-parameters in terms of h-parameters

The h-parameter are

$$V_1 = h_{11} I_1 + h_{12} V_2 \quad \dots(1)$$

$$I_2 = h_{21} I_1 + h_{22} V_2 \quad \dots(2)$$

Rewriting the equation (1), i.e.,

$$V_2 = -\frac{h_{21}}{h_{22}} I_1 + \frac{1}{h_{22}} I_2$$

Comparing with equation

$$Z_{21} = -\frac{h_{21}}{h_{22}} \text{ and } Z_{22} = \frac{1}{h_{22}}$$

Again from equation (1)

$$V_1 = h_{11} I_1 + h_{12} \left[-\frac{h_{21}}{h_{22}} I_1 + \frac{1}{h_{22}} I_2 \right] = \left[h_{11} - \frac{h_{21} h_{12}}{h_{22}} \right] I_1 + \frac{h_{12}}{h_{22}} I_2$$

Comparing with equation

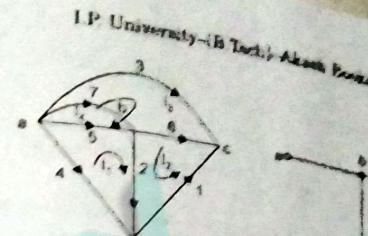
$$Z_{11} = \frac{\Delta h}{h_{22}} \text{ and } Z_{12} = \frac{h_{12}}{h_{22}}$$

Q. 7. (a) The reduced incidence matrix of a graph is given. Draw the graph and its tree and obtain fundamental loop matrix and cut-set matrix.

$$[A] = \begin{bmatrix} 0 & 0 & 1 & 1 & 1 & 0 & -1 \\ 0 & 1 & 0 & 0 & -1 & 1 & 1 \\ -1 & 0 & -1 & 0 & 0 & -1 & 0 \end{bmatrix}$$

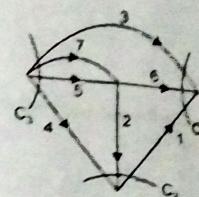
Ans. Complete matrix is

$$\begin{array}{c} a \\ b \\ c \\ d \end{array} \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 \\ 0 & 0 & 1 & 1 & 1 & 0 & -1 \\ 0 & 1 & 0 & 0 & -1 & 1 & 1 \\ -1 & 0 & -1 & 0 & 0 & -1 & 0 \\ 1 & -1 & 0 & -1 & 0 & 0 & 0 \end{bmatrix}$$



$$\begin{array}{c} l_1 \\ l_2 \\ l_3 \\ l_4 \end{array} \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

loop matrix



$$\begin{array}{c} C_1 \\ C_2 \\ C_3 \end{array} \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 \\ 1 & 0 & 1 & 0 & 0 & 1 & 0 \\ -1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 0 & 1 \end{bmatrix}$$

cut set matrix

Q. 7. (b) Check whether the given polynomial is Hurwitz or not.
 $P(s) = s^3 + 2s^2 + 3s + 6$

Ans. Condition (1): is satisfied (since all a are positive).

Condition (2): Even and odd parts of P(s) are

$$M(s) = 2s^2 + 6$$

$$N(s) = s^3 + 3s$$

So, continued fraction expansion of $\psi(s) = \frac{N(s)}{M(s)}$ is given as

$$\frac{s^3 + 6}{s^2 + 3s} = \frac{s^2 + 6}{s^2 + 3s} \cdot \frac{1}{s}$$

We see that the division has been terminated abruptly (suddenly) by a common factor $s^3 + 3s$. Thus

$$P(s) = (s^3 + 3s) \left(1 + \frac{2}{s}\right) = W(s)P_1(s)$$

We know that the term $P_1(s) = \left(1 + \frac{2}{s}\right)$ is Hurwitz. Now check for

$$W(s) = s^3 + 3s = s(s^2 + 3) = s(s + j\sqrt{3})(s - j\sqrt{3}) \text{ is Hurwitz}$$

Alternatively, since $W(s)$ is an odd function, therefore the continued fraction expansion of $\psi(s) = W(s)/Y_{W(s)}$ is given as

$$\begin{array}{c} 3s^2 + 3 \\ \overline{s^3 + s} \\ 2s \\ \overline{3s^3 + 3} \\ \overline{3s^2} \\ 3 \\ \overline{2s} \\ \overline{2s} \\ x \end{array}$$

Q. 8. An Impedance function for one port network is given by,

$$Z(S) = 2^*(S^2 + 1)(S^2 + 9)/S^*(S^2 + 4)$$

Synthesize the network in

(i) Foster's - I form

(ii) Foster's - II form

(iii) Cauer's - I form

Ans. (i) Foster - I Form

$$\begin{array}{c} s^3 + 4s \\ \overline{2s^4 + 20s^2 + 18} \\ \overline{2s^4 + 8s^2} \\ \overline{12s^2 + 18} \end{array}$$

$$Z(s) = 2s + \frac{12s^2 + 18}{s(s^2 + 4)}$$

Using partial fraction expansion,

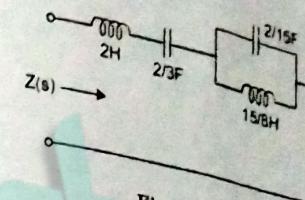
$$\frac{12s^2 + 18}{s(s^2 + 4)} = \frac{A}{s} + \frac{Bs + C}{s^2 + 4}$$

$$A = 9/2, C = 0 \text{ and } B = \frac{15}{2}$$

Therefore,

$$Z(s) = \frac{9}{2s} + \frac{\frac{15}{2}s}{s^2 + 4}$$

I.P. University-[B Tech]-Akash Books
We then obtain the synthesized network in figure 8.(a)



(ii) Foster - II form:

Fig. 8. (a)

$$Y(s) = \frac{s(s^2 + 4)}{2(s^2 + 1)(s^2 + 9)}$$

Using partial fraction expansion,

$$\frac{s(s^2 + 4)}{2(s^2 + 1)(s^2 + 9)} = \frac{1}{2} \left[\frac{As + B}{s^2 + 1} + \frac{Cs + D}{s^2 + 9} \right]$$

$$A = \frac{3}{8}, B = D = 0, C = \frac{5}{8}$$

Therefore,

$$Y(s) = \frac{1}{2} \left[\frac{\frac{3}{8}s}{s^2 + 1} + \frac{\frac{5}{8}s}{s^2 + 9} \right]$$

$$= \frac{\frac{3}{16}s}{s^2 + 1} + \frac{\frac{5}{16}s}{s^2 + 9}$$

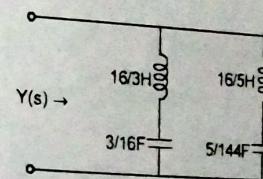


Fig. 8.(b)

Hence, synthesized network is shown in figure 8. (b).

(iii) Cauer - I from

$$Z(s) = \frac{2(s^2 + 1)(s^2 + 9)}{s(s^2 + 4)} = \frac{2s^4 + 20s^2 + 18}{s^3 + 4s}$$

The continued fraction expansion is

$$\begin{aligned}
 & \underbrace{s^3 + 4s}_{2s^4 + 20s^2 + 18} \xrightarrow{2s \leftrightarrow Z_1} \\
 & \underbrace{2s^4 + 8s^2}_{12s^2 + 18} \xrightarrow{s^3 + 4s} \left(\frac{1}{12} s \leftrightarrow Y_2 \right) \\
 & \underbrace{s^3 + \frac{3}{2}s}_{\frac{5}{2}s} \\
 & \underbrace{\frac{5}{2}s}_{12s^2} \xrightarrow{12s^2 + 18} \left(\frac{2}{5} \times 12s = \frac{24}{5} s \leftrightarrow Z_3 \right) \\
 & \underbrace{12s^2}_{x} \\
 & \underbrace{18}_{\frac{5}{2}s} \xrightarrow{\frac{5}{2}s} \left(\frac{1}{18} \frac{5}{2}s = \frac{5}{36} s \leftrightarrow Y_4 \right) \\
 & \underbrace{\frac{5}{2}s}_{x}
 \end{aligned}$$

Therefore, the final synthesized network is shown in figure 8. (c)

Cauer-II form:

$$Z(s) = \frac{2s^4 + 20s^2 + 18}{s^3 + 4s}$$

$$= \frac{18 + 20s^2 + 2s^4}{4s + s^3}$$

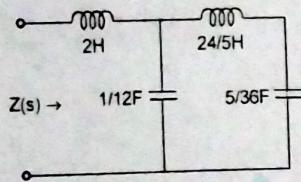


Fig. 8. (c)

The continued fraction expansion is

$$\begin{aligned}
 & \underbrace{4s + s^3}_{18 + 20s^2 + 2s^4} \xrightarrow{18 + 20s^2 + 2s^4} \left(\frac{18}{4s} = \frac{19}{4s} \leftrightarrow Z_1 \right) \\
 & \underbrace{18 + \frac{9}{2}s^2}_{\frac{31}{2}s^2 + 2s^4} \xrightarrow{\frac{31}{2}s^2 + 2s^4} \left(4s + s^3 \xrightarrow{\frac{2}{31}s - \frac{8}{31s}} Y_2 \right) \\
 & \underbrace{4s + \frac{16}{31}s^3}_{\frac{31}{2}s^2} \\
 & \underbrace{\frac{15}{31}s}_{\frac{31}{2}s^2} \xrightarrow{\frac{31}{2}s^2 + 2s^4} \left(\frac{31}{15} \frac{31}{2s} = \frac{961}{30s} \leftrightarrow Z_3 \right) \\
 & \underbrace{\frac{31}{2}s^2}_{x} \\
 & \underbrace{2s^4}_{\frac{15}{31}s^3} \xrightarrow{\frac{15}{31}s^3} \left(\frac{1}{2} \frac{15}{31s} = \frac{15}{62s} \leftrightarrow Y_4 \right) \\
 & \underbrace{\frac{15}{31}s^3}_{x}
 \end{aligned}$$

I.P. University-(B Tech)-Akash Books
Therefore, the final synthesized network is shown in figure 8. (d)

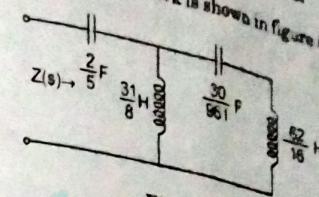


Fig. 8. (d)

fig. 7.

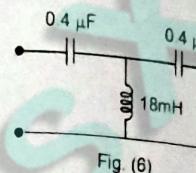


Fig. (6)

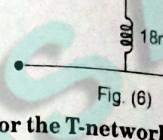


Fig. (7)

Ans. (a) For the T-network

$$\text{Given } 2C = 0.4 \mu F \text{ and } L = 18 \text{ mH}$$

$$K = \sqrt{\frac{L}{C}} = \sqrt{\frac{18 \times 10^{-3}}{0.2 \times 10^{-6}}} = 300 \Omega$$

$$\text{Cut-off frequency: } f_C = \frac{1}{4\pi\sqrt{LC}} = \frac{K}{4\pi L} = \frac{300}{4 \times 3.141 \times 18 \times 10^{-3}} = 1326 \text{ Hz}$$

$$\text{or } f_C = \frac{1}{4\pi KC} = \frac{1}{4 \times 3.141 \times 300 \times 0.2 \times 10^{-6}} = 1326 \text{ Hz}$$

(b) For the π-network

$$\text{Given } 2L = 80 \text{ mH and } C = 4 \mu F$$

$$\text{Cut-off frequency: } f_C = \frac{1}{4\pi\sqrt{LC}} = \frac{1}{4 \times 3.141 \times \sqrt{40 \times 10^{-3} \times 4 \times 10^{-6}}} = 198.94 \text{ Hz}$$

Q. 9. (b) Check whether the given polynomial is Hurwitz or not.

$Z(s) = (2s^2 + 5)s^*(s^2 + 1)$ is positive real function (prf) or not.

Ans. Condition (1)

$$D(s) = s^3 + s, \text{ then } D'(s) = 3s^2 + 1$$

$$\begin{aligned}
 & \underbrace{3s^2 + 1}_{s^3 + s} \xrightarrow{s^3 + s} \left(\frac{1}{3} s \right) \\
 & \underbrace{s^3 + \frac{1}{3}s}_{\frac{2}{3}s} \\
 & \underbrace{\frac{2}{3}s}_{3s^2 + 1} \xrightarrow{3s^2 + 1} \left(\frac{3}{2} \frac{3s + \frac{9}{2}}{s^2} \right) \\
 & \underbrace{\frac{3}{2} \frac{3s + \frac{9}{2}}{s^2}}_{1} \xrightarrow{1} \frac{2}{3} s \xrightarrow{\frac{2}{3}s}
 \end{aligned}$$

Therefore, $D(s)$ is Hurwitz polynomial.

Condition (2): We find that $Z(s)$ has a pair of poles $s = \pm j1$

The partial fraction expansion of $Z(s)$ is

$$Z(s) = \frac{-3s}{s^2 + 1} + \frac{5}{s}$$

which shows that the residue of the poles at $s = \pm j1$ is negative.

Therefore, $Z(s)$ is not p.r.f.

SYLLABUSX