

Ishaan Salian

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Computer Engineering graduate with hands-on experience in embedded platforms, motor control, and low-power system design. Proven track record of leading technical projects from PCB design to full robotic and IoT implementations.

Education

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| University of Massachusetts Amherst <i>Bachelor of Science in Computer Engineering</i> | Amherst, MA Graduated May 2025 |
| <ul style="list-style-type: none">Awards: Chancellor’s Award (\$56,000), Dean’s ListCoursework: Digital Design, Systems Programming, Networked Embedded Systems, Low Power Embedded Systems, Computer Architecture, Synthesis and Verification of Digital Systems, Electronic Circuits, Artificial Intelligence | |

Technical Skills

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| Programming: C, C++, Python, Verilog, MATLAB, Bash |
| Embedded Platforms: ESP32, Raspberry Pi, Arduino, nRF52832, ATtiny85, DE1-SoC |
| Hardware/Tools: KiCad, Altium, Fusion 360, Oscilloscope, GDB, PLCs, BLE, I2C, SPI, UART, Soldering |
| Software/DevOps: Git, RTOS, OpenCV, Linux, Quartus Prime, Yosys |

Experience

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| Coherent Corp. <i>Controls and Electrical Engineering Intern</i> | East Granby, CT June 2024 - August 2024 |
| <ul style="list-style-type: none">Supported control system upgrade for fiber draw tower; implemented PID tuning and Allen-Bradley PLC ladder logicIdentified and fixed a logic bug causing fiber length errors, improving product consistency and yieldIndependently proposed and prototyped a custom alcohol drip delivery system to reduce friction on capstan belts | |
| Department of Electrical and Computer Engineering <i>Undergraduate Teaching Assistant</i> | Amherst, MA Various Courses |
| <ul style="list-style-type: none">Assisted in courses such as Physical Computing, ECE Junior Design Project, Security EngineeringGuided students in bare-metal programming, secure computing, encryption/decryption, and hardware integration | |

Projects

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| Autonomous Workspace Organizer Robot <i>KiCad, Fusion 360, BLE, Object Detection</i> | Senior Design Project |
| <ul style="list-style-type: none">Identified a common desk clutter problem and proposed a robotics-based solution for organization as a capstone projectLed hardware design by creating a custom ESP32-based PCB and 3D-printed robot body with servo-actuated tracksArchitected BLE communication between the robot and an overhead camera running object detection with OpenCV | |
| Weather Monitor Station <i>C, Nordic nRF52832, ePaper display</i> | April 2025 |
| <ul style="list-style-type: none">Designed an outdoor weather monitor to track environmental data and predict storms using barometric pressure trendsCustomized Nordic SDK firmware to periodically sample sensor data, enter deep sleep mode, and wake via interruptsChose an ePaper display for low-power, always-on data visualization, balancing readability with energy constraints | |
| Campus Compass <i>Python, OpenAI API, Git version control</i> | November 2024 |
| <ul style="list-style-type: none">Developed an LLM-powered personalized meal recommendation system based on dietary preferences and availabilityLed backend development using real-time data from UMass Dining APIs achieving 82% alignment with preferences | |
| keyRING, a Smart Key Holder - HackUMASS XI <i>Arduino Uno, Embedded C</i> | November 2023 |
| <ul style="list-style-type: none">Prototyped a system for key sensing using a spring-like mechanical switch and sonar sensor for detecting door movementProgrammed the ATmega328P using C to communicate with the switch to detect keys using digital interruptsAwarded “Cheapest Hardware Hack” for a cost-effective design with 97% positive feedback from 50+ students | |

Organizations

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| Liaison - Institute of Electrical and Electronics Engineers (IEEE) | March 2024 - March 2025 |
| <ul style="list-style-type: none">Organized 5+ joint events with engineering orgs, helping create collaborative spaces for technical talks and workshops | |
| Electronics Co-Lead - UMass Mechatronics Team (ASME) | September 2023 - May 2024 |
| <ul style="list-style-type: none">Co-led electronics integration for a competitive mini-golf robot, including motor control and Bluetooth-based inputRepresented the team during design reviews and competition presentations; contributed to the team’s top-5 placementWorked closely with mechanical and software teams to synchronize movement, aiming, and power efficiency | |