ESO 208A: Computational Methods in Engineering

Richa Ojha

Department of Civil Engineering IIT Kanpur



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Non-linear equation

In computer, we have five approaches

- Graphical method
- Bracketing methods: Bisection, Regula-Falsi
- Open methods: Fixed point, Newton-Raphson, Secant
- Special methods for polynomials: Muller, Bairstow's
- **Hybrid methods:** Brent's



- 1. Bairstow's method is an iterative approach loosely related to both Müller and Newton Raphson methods
- 2. It is based on dividing the given polynomial by a quadratic polynomial x^2 -rx-s:

$$f_n(x) = a_o + a_1 x + a_2 x^2 + K + a_n x^n$$
$$= (x^2 - rx - s) f_{n-2}(x) + R$$

where

$$f_{n-2}(x) = b_2 + b_3 x + K + b_{n-1} x^{n-3} + b_n x^{n-2}$$

$$R = b_1(x-r) + b_o$$



3. The coefficients *b*'s are obtained very easily by using recursive relation

$$b_n = a_n$$

 $b_{n-1} = a_{n-1} + rb_n$
 $b_i = a_i + rb_{i+1} + sb_{i+2}$ $i = n-2 \text{ to } 0$

4. Using Newton Raphson approach, r and s are adjusted so as to make both b_o and b_1 approach zero

$$b_1 = a_1 + rb_2 + sb_3 \Rightarrow u(r,s)$$
$$b_0 = a_0 + rb_1 + sb_2 \Rightarrow v(r,s)$$



5. Obtain corrections in *r* and *s* by Newton-Raphson method

Changes Δs and Δr needed to improve guesses will be estimated by

$$\frac{\partial b_1}{\partial r} \Delta r + \frac{\partial b_1}{\partial s} \Delta s = -b_1$$

$$\frac{\partial b_o}{\partial r} \Delta r + \frac{\partial b_o}{\partial s} \Delta s = -b_o$$



6. Bairstow (1920) showed that the partial derivatives of b_0 and b_1 are obtained by the recursive relation

$$c_n = b_n$$

$$c_{n-1} = b_{n-1} + rc_n$$

$$c_i = b_i + rc_{i+1} + sc_{i+2} \quad i = n-2 \text{ to } 2$$
 where

$$\frac{\partial b_o}{\partial r} = c_1 \qquad \frac{\partial b_o}{\partial s} = \frac{\partial b_1}{\partial r} = c_2 \qquad \frac{\partial b_1}{\partial s} = c_3$$

7. Iterate the steps untill $(\Delta r/r)$ and $(\Delta s/s)$ drops below a specified threshold



Polynomial Methods: Single Root

$$p_n(x) = \sum_{k=0}^{n} a_k x^k = a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n$$

If we divide by a factor (x - r) such that, $r = \alpha$ is a root of the polynomial, we will get an exact polynomial of order (n - 1), say $q_{n-1}(x)$.

$$q_{n-1}(x) = \sum_{k=0}^{n-1} b_{k+1} x^k = b_1 + b_2 x + b_3 x^2 + \dots + b_n x^{n-1}$$

If $r \neq \alpha$, dividing by a factor (x - r) will have a remainder b_0 .

Polynomial Methods: Single Root

$$p_{n}(x) = \sum_{k=0}^{n} a_{k} x^{k} = a_{0} + a_{1} x + a_{2} x^{2} + \dots + a_{n} x^{n}$$

$$= (x - r)q_{n-1}(x) + b_{0} = (x - r) \sum_{k=0}^{n-1} b_{k+1} x^{k} + b_{0}$$

$$= b_{0} + b_{1}(x - r) + b_{2} x(x - r) + b_{3} x^{2}(x - r) + \dots + b_{n-2} x^{n-3}(x - r)$$

$$+ b_{n-1} x^{n-2}(x - r) + b_{n} x^{n-1}(x - r)$$

$$= (b_{0} - rb_{1}) + x(b_{1} - rb_{2}) + x^{2}(b_{2} - rb_{3}) + \dots + x^{n-2}(b_{n-2} - rb_{n-1})$$

$$+ x^{n-1}(b_{n-1} - rb_{n}) + b_{n} x^{n}$$

$$b_{n} = a_{n}; \ b_{i} - rb_{i+1} = a_{i}; \ i = (n-1), (n-2), \dots 2, 1, 0$$

$$b_{n} = a_{n}; \ b_{i} = a_{i} + rb_{i+1}; \ i = (n-1), (n-2), \dots 2, 1, 0$$

For a given $p_n(x)$, a_i are known. For a choice of r, one can determine b_i from n+1 equations above having n+1 unknowns



Polynomial Methods: Single Root

Remainder b_0 is a function of $r \to b_0(r)$, at $r = \alpha$, $b_0(r) = 0$

Problem: f(x) = 0, find a root $x = \alpha$ such that $f(\alpha) = 0$

Problem: $b_0(r) = 0$, find a root $r = \alpha$ such that $b_0(\alpha) = 0$

Apply Newton-Raphson:

Iteration Formula for Step *k*:

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$
 or $r_{k+1} = r_k - \frac{b_0(r_k)}{b'_0(r_k)}$

$$b_0 = a_0 + rb_1 \rightarrow b_0'(r) = b_1 \rightarrow r_{k+1} = r_k - \frac{b_0(r_k)}{b_1(r_k)}$$

Assume a value of r, estimate b_0 and b_1 , compute new r.

Continue until b_0 becomes zero. (with acceptable relative error)



$$p_n(x) = \sum_{k=0}^n a_k x^k = a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n$$

Let us divide by a factor $(x^2 - rx - s)$. If the factor is exact, the resulting polynomial will be of order (n - 2). Two roots of the polynomial can be estimated simultaneously as the roots of the quadratic factor. For the complex roots, they will be the complex conjugates.

$$q_{n-2}(x) = \sum_{k=0}^{n-2} b_{k+2} x^k = b_2 + b_3 x + b_4 x^2 + \dots + b_n x^{n-2}$$

If the factor $(x^2 - rx - s)$ is not exact, there will be two remainder terms, one function of x and another constant.

Let us express the remainder term as $b_1(x - r) + b_0$. This form instead of the standard $b_1x + b_0$ is chosen to device a convenient iteration formula!

$$p_{n}(x) = \sum_{k=0}^{n} a_{k}x^{k} = a_{0} + a_{1}x + a_{2}x^{2} + \dots + a_{n}x^{n}$$

$$= (x^{2} - rx - s)q_{n-2}(x) + b_{1}(x - r) + b_{0}$$

$$= (x^{2} - rx - s)\sum_{k=0}^{n-2} b_{k+2}x^{k} + b_{1}(x - r) + b_{0}$$

$$= b_{0} + b_{1}(x - r) + b_{2}(x^{2} - rx - s) + b_{3}x(x^{2} - rx - s) + \dots$$

$$+ b_{n-2}x^{n-4}(x^{2} - rx - s) + b_{n-1}x^{n-3}(x^{2} - rx - s) + b_{n}x^{n-2}(x^{2} - rx - s)$$

$$= (b_{0} - rb_{1} - sb_{2}) + x(b_{1} - rb_{2} - sb_{3}) + x^{2}(b_{2} - rb_{3} - sb_{4}) + \dots$$

$$+ x^{n-2}(b_{n-2} - rb_{n-1} - sb_{n}) + x^{n-1}(b_{n-1} - rb_{n}) + b_{n}x^{n}$$

$$b_n = a_n$$
; $b_{n-1} = a_{n-1} + rb_n$; $b_i = a_i + rb_{i+1} + sb_{i+2}$; $i = (n-2), \dots 2, 1, 0$

For a given $p_n(x)$, a_i are known. For a choice of r and s, one can determine b_i from n+1 equations above having n+1 unknowns



 b_0 and b_1 are functions of r and s \rightarrow $b_0(r, s)$ and $b_1(r, s)$

Expand in Taylor's series: Apply 2-d Newton-Raphson

$$0 = b_0(r + \Delta r, s + \Delta s) = b_0 + \frac{\partial b_0}{\partial r} \Delta r + \frac{\partial b_0}{\partial s} \Delta s + HOT$$
$$0 = b_1(r + \Delta r, s + \Delta s) = b_1 + \frac{\partial b_1}{\partial r} \Delta r + \frac{\partial b_1}{\partial s} \Delta s + HOT$$

$$\begin{bmatrix} \frac{\partial b_0}{\partial r} & \frac{\partial b_0}{\partial s} \\ \frac{\partial b_1}{\partial r} & \frac{\partial b_1}{\partial s} \end{bmatrix} \begin{bmatrix} \Delta r \\ \Delta s \end{bmatrix} = \begin{bmatrix} -b_0 \\ -b_1 \end{bmatrix}$$

Need to evaluate: $\frac{\partial b_0}{\partial r}$, $\frac{\partial b_0}{\partial s}$, $\frac{\partial b_1}{\partial r}$ and $\frac{\partial b_1}{\partial s}$

$$b_n = a_n$$
; $b_{n-1} = a_{n-1} + rb_n$; $b_i = a_i + rb_{i+1} + sb_{i+2}$; $i = (n-2), \dots 2, 1, 0$

Partial differentials with respect to *r*:

$$b_n = a_n \to \frac{\partial b_n}{\partial r} = 0;$$

$$b_{n-1} = a_{n-1} + rb_n \rightarrow \frac{\partial b_{n-1}}{\partial r} = b_n = c_n$$

$$b_{n-2} = a_{n-2} + rb_{n-1} + sb_n \rightarrow \frac{\partial b_{n-2}}{\partial r} = b_{n-1} + r\frac{\partial b_{n-1}}{\partial r} + s\frac{\partial b_n}{\partial r} = b_{n-1} + rc_n$$

$$= c_{n-1}$$

$$b_{n-3} = a_{n-3} + rb_{n-2} + sb_{n-1} \rightarrow \frac{\partial b_{n-3}}{\partial r} = b_{n-2} + r\frac{\partial b_{n-2}}{\partial r} + s\frac{\partial b_{n-1}}{\partial r}$$
$$= b_{n-2} + rc_{n-1} + sc_n = c_{n-2}$$

$$c_n = b_n$$
; $c_{n-1} = b_{n-1} + rc_n$; $c_i = b_i + rc_{i+1} + sc_{i+2}$; $i = (n-2), \dots 2, 1, 0$

$$\frac{\partial b_i}{\partial r} = c_{i+1}; \quad i = (n-1), \dots 2, 1, 0$$

$$b_n = a_n$$
; $b_{n-1} = a_{n-1} + rb_n$; $b_i = a_i + rb_{i+1} + sb_{i+2}$; $i = (n-2), \dots 2, 1, 0$

Partial differentials with respect to *s*:

$$b_{n} = a_{n} \rightarrow \frac{\partial b_{n}}{\partial s} = 0;$$

$$b_{n-1} = a_{n-1} + rb_{n} \rightarrow \frac{\partial b_{n-1}}{\partial s} = 0 \qquad = 0$$

$$b_{n-2} = a_{n-2} + rb_{n-1} + sb_{n} \rightarrow \frac{\partial b_{n-2}}{\partial s} = b_{n} + r\frac{\partial b_{n-1}}{\partial s} + s\frac{\partial b_{n}}{\partial s} = b_{n} = c_{n} \text{ (say)}$$

$$b_{n-3} = a_{n-3} + rb_{n-2} + sb_{n-1} \rightarrow \frac{\partial b_{n-3}}{\partial s} = b_{n-1} + r\frac{\partial b_{n-2}}{\partial s} + s\frac{\partial b_{n-1}}{\partial s} = b_{n-1} + rc_{n}$$

$$= c_{n-1}$$

$$b_{n-4} = a_{n-4} + rb_{n-3} + sb_{n-2} \rightarrow \frac{\partial b_{n-4}}{\partial s} = b_{n-2} + r\frac{\partial b_{n-3}}{\partial s} + s\frac{\partial b_{n-2}}{\partial s}$$

$$= b_{n-2} + rc_{n-1} + sb_{n} = c_{n-2}$$

$$c_{n} = b_{n}; \ c_{n-1} = b_{n-1} + rc_{n}; \ c_{i} = b_{i} + rc_{i+1} + sc_{i+2}; \ i = (n-2), \dots 2, 1, 0$$

$$\frac{\partial b_{i}}{\partial s} = c_{i+2}; \quad i = (n-2), \dots 2, 1, 0$$

$$\frac{\partial b_i}{\partial r} = c_{i+1}; \ i = (n-1), \dots 2, 1, 0 \text{ and } \frac{\partial b_i}{\partial s} = c_{i+2}; \ i = (n-2), \dots 2, 1, 0$$

$$\frac{\partial b_0}{\partial r} = c_1; \ \frac{\partial b_1}{\partial r} = c_2; \ \frac{\partial b_0}{\partial s} = c_2 \text{ and } \frac{\partial b_1}{\partial s} = c_3$$

$$\begin{bmatrix} \frac{\partial b_0}{\partial r} & \frac{\partial b_0}{\partial s} \\ \frac{\partial b_1}{\partial r} & \frac{\partial b_1}{\partial s} \end{bmatrix} \begin{bmatrix} \Delta r \\ \Delta s \end{bmatrix} = \begin{bmatrix} c_1 & c_2 \\ c_2 & c_3 \end{bmatrix} \begin{bmatrix} \Delta r \\ \Delta s \end{bmatrix} = \begin{bmatrix} -b_0 \\ -b_1 \end{bmatrix}$$

For any given polynomial, we know $\{a_0, a_1, \dots a_n\}$. Assume r and s. Compute $\{b_0, b_1, \dots b_n\}$ and $\{c_0, c_1, \dots c_n\}$. Compute Δr and Δs .

- ✓ Step 1: input $a_0, a_1, \dots a_n$ and initialize r and s.
- ✓ Step 2: compute $b_0, b_1, \dots b_n$
- $b_n = a_n$; $b_{n-1} = a_{n-1} + rb_n$; $b_i = a_i + rb_{i+1} + sb_{i+2}$; $i = (n-2), \dots 2, 1, 0$
- \checkmark Step 3: compute $c_0, c_1, \dots c_n$
- $c_n = b_n$; $c_{n-1} = b_{n-1} + rc_n$; $c_i = b_i + rc_{i+1} + sc_{i+2}$; $i = (n-2), \dots 2, 1, 0$
- ✓ Step 4: compute Δr and Δs from $\begin{bmatrix} c_1 & c_2 \\ c_2 & c_3 \end{bmatrix} \begin{bmatrix} \Delta r \\ \Delta s \end{bmatrix} = \begin{bmatrix} -b_0 \\ -b_1 \end{bmatrix}$
- ✓ Step 5: compute $r_{new} = r + \Delta r$, $s_{new} = s + \Delta s$
- ✓ Step 6: check for convergence, $\left|\frac{r_{new}-r}{r_{new}}\right|$, $\left|\frac{s_{new}-s}{s_{new}}\right| \le \varepsilon$ and $b_0, b_1 \le \varepsilon'$
- ✓ Step 7: Stop if all convergence checks are satisfied. Else, set $r = r_{new}$, $s = s_{new}$ and go to step 2.

Step 8. The roots quadratic polynomial x^2 -rx-s are obtained as

$$x = \frac{r \pm \sqrt{r^2 + 4s}}{2}$$

Step 9. At this point three possibilities exist:

- 1. The quotient is a third-order polynomial or greater. The previous values of *r* and *s* serve as initial guesses and Bairstow's method is applied to the quotient to evaluate new r and s values.
- 2. The quotient is quadratic. The remaining two roots are evaluated directly, using the above eqn.
- 3. The quotient is a 1st order polynomial. The remaining single root can be evaluated simply as x=-s/r.

Summary

• Bairstow method

• Derivation of Bairstow method

