

COMP\_SCI 214: Data Structures and Algorithms

# Priority Queues

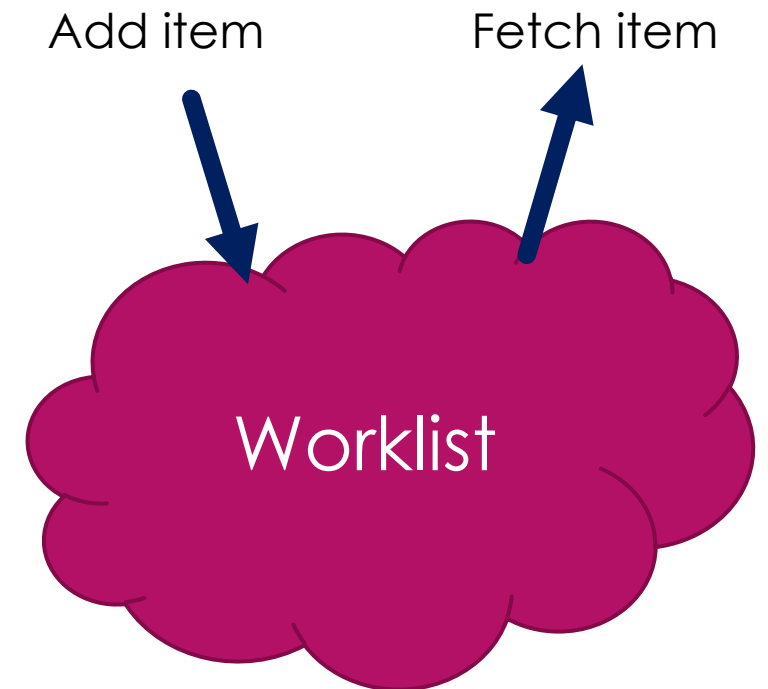
PROF. SRUTI BHAGAVATULA

# Announcements

- ▶ Reminder: Homework 3 was due Tuesday
  - ▶ We will release grade reports tomorrow
  - ▶ Resubmission is due Tuesday
  - ▶ HW3 self-eval to be released tomorrow
  - ▶ Self-eval is due Tuesday

# Recall: Worklists

- ▶ Say you need a program that:
  - ▶ Keeps track of “items” you need to handle
  - ▶ Allows you to fetch a single piece of “item” to handle next
- ▶ You may want to fetch:
  - ▶ The last item in **Last-in-first-out (LIFO)**
  - ▶ The earliest item in **First-in-first-out (FIFO)**



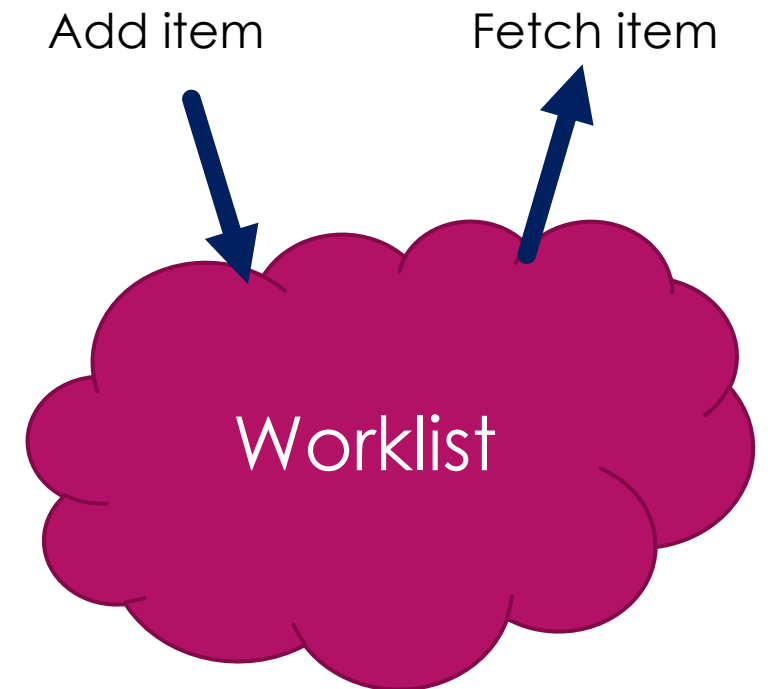
# What if you need to...

- ▶ Identify which patient to help in a hospital emergency room?
  - ▶ Identify which tasks are the most pressing in your TODO list?
  - ▶ Decide which homework assignment you should be working on next?
  - ▶ Decide which maintenance tasks to handle based on severity?
  - ▶ Identify and fix the most harmful bugs in your software production system?
- 
- ▶ Are stacks and queues good enough worklists for these?



# Recall: Worklists

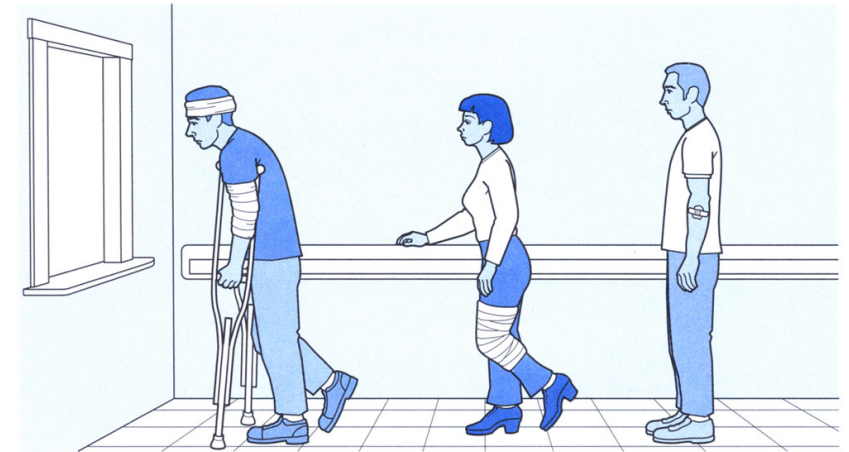
- ▶ Say you need a program that:
  - ▶ Keeps track of “items” you need to handle
  - ▶ Allows you to fetch a single piece of “item” to handle next
- ▶ You may want to fetch:
  - ▶ ~~The last item in **Last-in-first-out (LIFO)**~~
  - ▶ ~~The earliest item in **First-in-first-out (FIFO)**~~
  - ▶ The highest priority item



# A new ADT: Priority queue

# Priority queue (PQ)

- ▶ **Data:** set of task or item objects
- ▶ **Operations:**
  - ▶ Insert an item into the priority queue
  - ▶ Fetch the highest priority element
  - ▶ Check if there are any items left in the priority queue



# Priority queue ADT interface

- Abstract values look like (note the sorting) → Highest priority

2	Brain damage
5	Heart attack
17	Fever
89	Cold
...	...

```
interface PRIORITY_QUEUE[T]:  
  def empty?(self) -> bool?  
  def insert(self, priority: num?, value: T) -> NoneC  
  def remove_min(self) -> T
```



# Properties of a PQ

- ▶ Behavior of the PQ:
  - ▶ PQ keeps priority-value pairs sorted by priority
  - ▶ `remove_min` finds and removes pair with highest priority and returns the value
    - ▶ Lowest priority value (or rank) = highest urgency (it's confusing, I know!)
- ▶ There can be variants:
  - ▶ Separate `find_min` and `remove_min` functions
  - ▶ No separate priority value; priority determined from task data itself or combined structure that has both

# Other use of priority queues

- ▶ PQs are also useful for finding the shortest path between vertices in a graph
- ▶ We'll see this one soon – going back to graphs after next week!

# Operating on a priority queue

## ► Managing a hospital ER:

- New patient came in:

```
pq.insert(3, "cardiac arrest")
```

- Which patient to call in next?

```
pq.remove_min()
```

BD

Highest priority

2	Brain damage
5	Heart attack
17	Fever
89	Cold
...	...

3 CA

# Operating on a priority queue

## ► Managing homework deadline:

- Just got assigned a new HW with a deadline of tomorrow

```
pq.insert(1, "Music HW")
```

- Which HW should I start?

```
pq.remove_min()
```

Highest priority

2	Physics HW
3	214 HW
4	Chemistry HW
5	Math HW
...	...

~~1 Music HW~~



# Deciding priorities

- ▶ Priorities don't have to always be numbers!
- ▶ Can be any data type → just need to specify a comparator function (like with sorting)
  - ▶ You'll see this in HW5
  - ▶ Allows specifying what's a "priority" given the specific types of data
- ▶ These functions can have simple or complex logic to compare two tasks → up to the client!

# Priority queue laws

- ▶  $\{pq = \langle \rangle \mid pq.empty?() \Rightarrow \text{True}\}$
- ▶  $\{pq = \langle p_0 : e_0, \dots, p_n : e_n \rangle \wedge \forall i p_i \leq p_{i+1}\} \mid pq.empty?() \Rightarrow \text{False}\}$
- ▶  $\{pq = \langle \underline{p_0 : e_0}, \dots, p_{k-1} : e_{k-1}, p_{k+1} : e_{k+1}, p_n : e_n \rangle \wedge \forall i p_i \leq p_{i+1}\} \mid pq.insert(p_k, e_k) \Rightarrow \text{None}\}$   
 $\{pq = \langle p_0 : e_0, \dots, p_{k-1} : e_{k-1}, \underline{p_k : e_k}, p_{k+1} : e_{k+1}, p_n : e_n \rangle\}$
- ▶  $\{pq = \langle \underline{p_0 : e_0}, p_1 : e_1, \dots, p_n : e_n \rangle \wedge \forall i p_i \leq p_{i+1}\} \mid pq.remove\_min() \Rightarrow \underline{e_0}\}$   
 $\{pq = \langle \underline{p_1 : e_1}, \dots, p_n : e_n \rangle \wedge \forall i p_i \leq p_{i+1}\}$

# Implementing priority queues

# How can we implement a priority queue?

- ▶ Any suggestions using data structures we've seen so far?
  - ▶ Sorted linked list
  - ▶ Unsorted linked list

```
interface PRIORITY_QUEUE[T]:  
  def empty?(self) -> bool?  
  def insert(self, priority: num?, value: T) -> NoneC  
  def remove_min(self) -> T
```

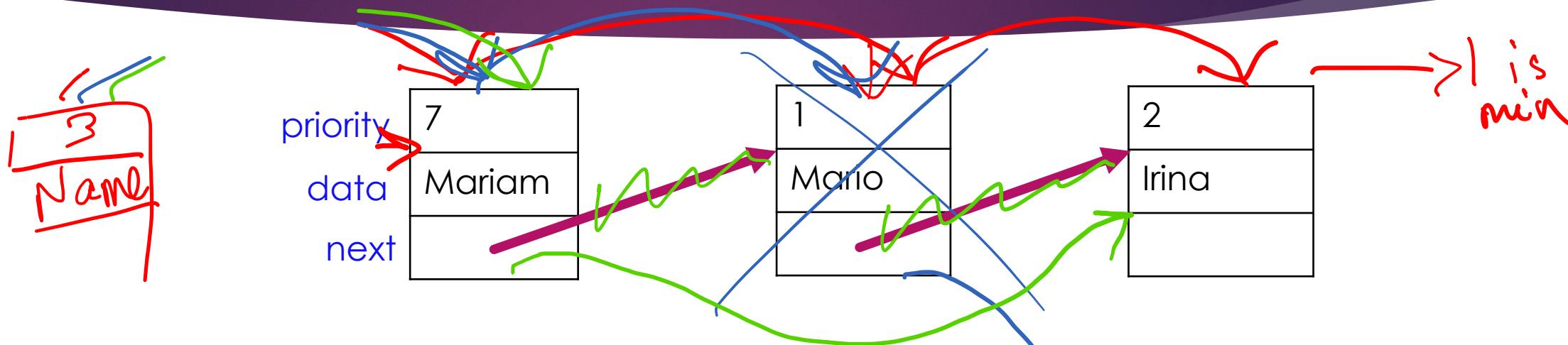


# Candidates to implement PQ ADT

	Sorted linked list	Unsorted linked list
<b>insert</b>	$O(n)$	$O(1)$
<b>remove_min</b>	$O(1)$	$O(n)$

$n$  is the number of elements in the priority queue

# Unsorted list PQ



- ▶ insert: add a node at the start in  $O(1)$ 
  - ▶ Inserting Sven with priority 3
- ▶ remove\_min: search for minimum priority in  $O(n)$ 
  - ▶ Look through list and then remove Mario

# Sorted list PQ

priority  
data  
next

1
Mario

2
Irina

7
Mariam

3
Sruti
next

- ▶ insert: find the right position and add a node:  $O(n)$ 
  - ▶ Inserting Sven with priority 3
- ▶ remove\_min: remove first element in  $O(1)$ 
  - ▶ Remove Mario from start of list

# So what do we choose?

- ▶ Pick your poison:
  - ▶ Which operation do we need more?
  - ▶ Make sure that is  $O(1)$

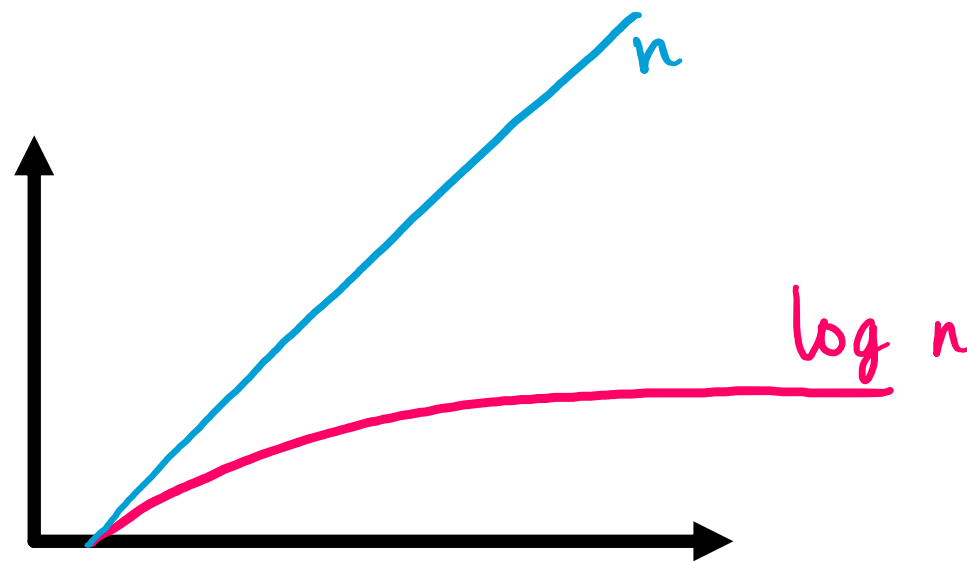
	Sorted list	Unsorted list	??
<b>insert</b>	$O(n)$	$O(1)$	$O(\log n)$
<b>remove_min</b>	$O(1)$	$O(n)$	$O(\log n)$

- ▶ What if I want both operations?!
  - ▶ Neither is great
  - ▶ Can we get the best of both worlds?
- ▶ Almost! We can't get  $O(1)$  for both **but** we can do  $O(\log n)$ !



Recall:  $O(\log n)$  is a big deal

n	10	100	1000	10K	100K	1M	10M	100M
$\log^2 n$	3.3	6.6	10	13.3	16.6	20	23.3	26.6

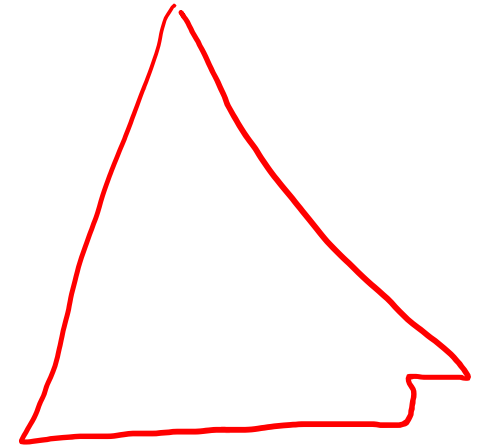
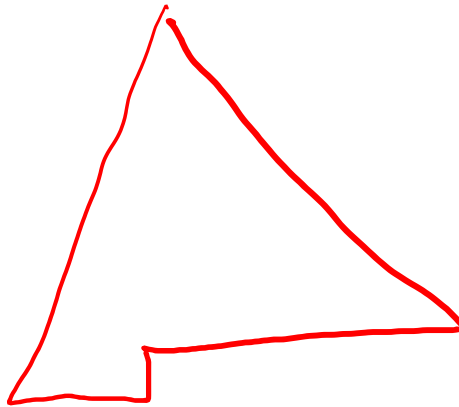
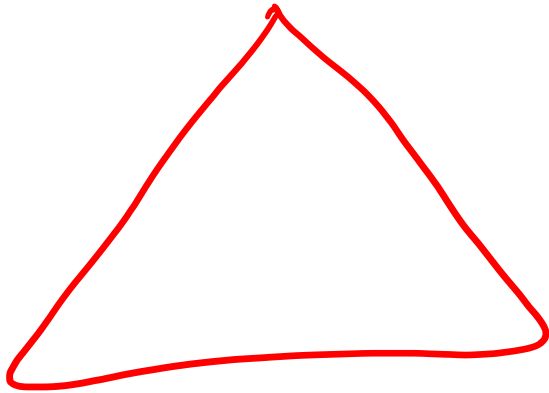


# Introducing the **binary heap**

- ▶ A new data structure!
- ▶ A binary heap is a **complete** binary tree that is **heap-ordered**
  - ▶ **Complete**: A  $k$ -ary tree is complete if every level is full of nodes. Last level can have nodes missing, but must be filled left to right
  - ▶ **Heap-ordered**: A tree is heap-ordered if each element is less than or equal to its children
- ▶ The above two are invariants for a binary heap

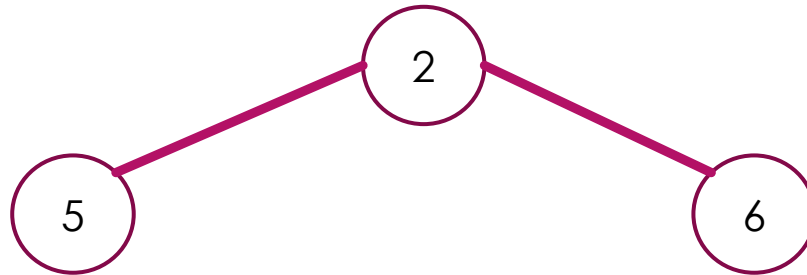
# Shape invariant (completeness)

- Possible shapes a binary heap represents



# Ordering invariant (heap-ordered)

- ▶ Our invariant specifies a min-heap

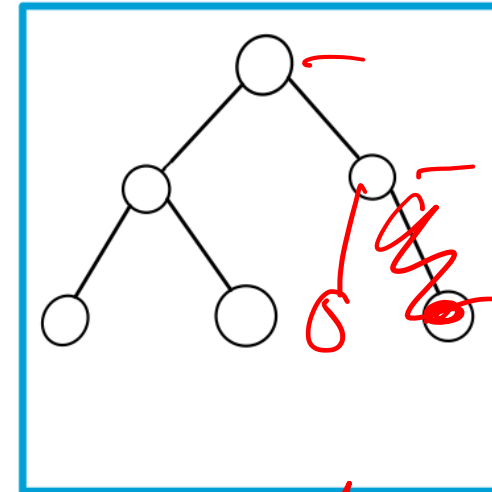
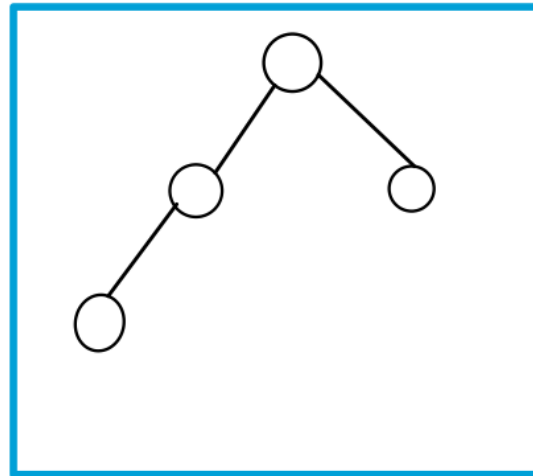
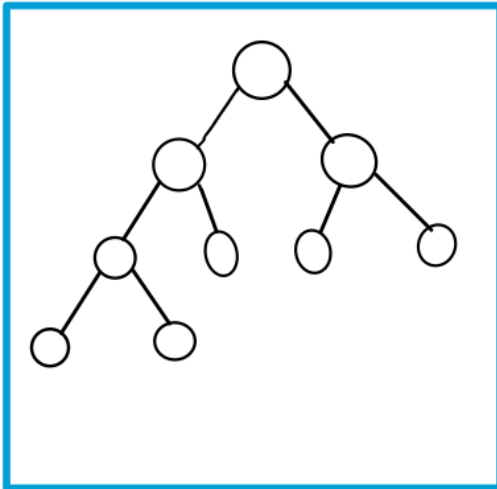


- ▶ Another variant: a max-heap where highest value is on top
  - ▶ But min-heap is most common
  - ▶ With custom comparators, min or max is irrelevant and priority order is up to the client



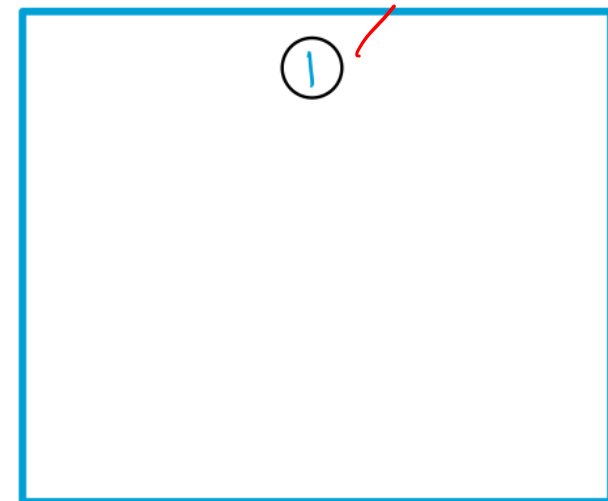
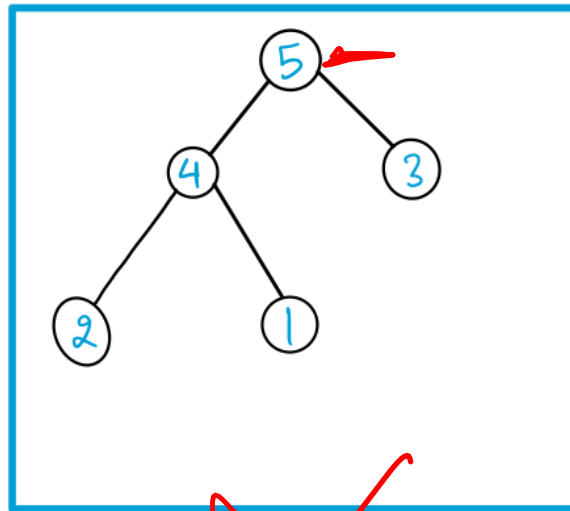
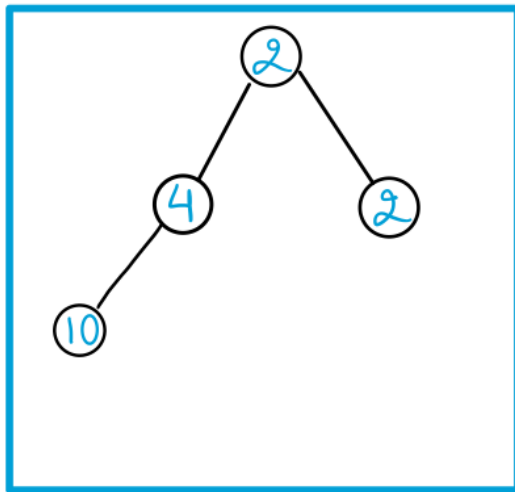
# Game: 2 valid heaps and an invalid one?

- Based on shape invariant



# Game: 2 valid heaps and an invalid one?

- Based on ordering invariant



# Binary heap for priority queue

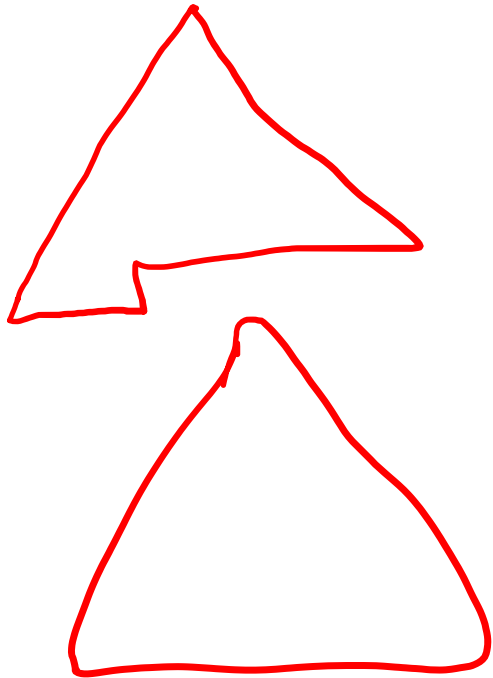
- ▶ ADT operations:
  - ▶ Let's look at the 2<sup>nd</sup> two
  - ▶ `empty? ()` is trivial by maintaining a count

```
interface PRIORITY_QUEUE[T]:  
  def empty?(self) -> bool?  
  def insert(self, priority: num?, value: T) -> NoneC  
  def remove_min(self) -> T
```

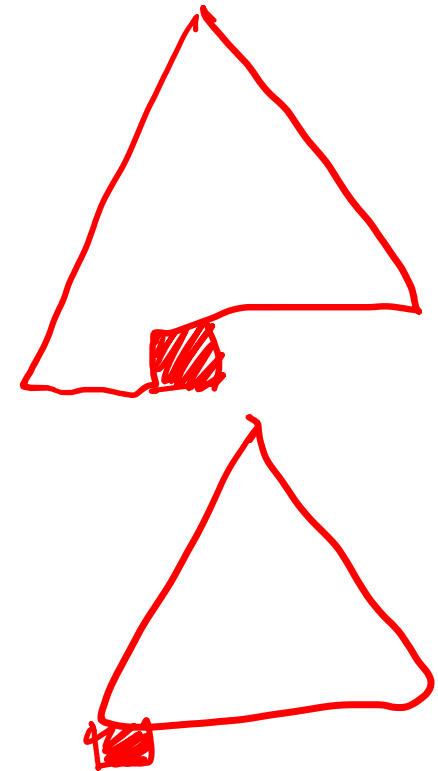
- ▶ Both shape and ordering invariant need to hold by the end of each operation

# insert operation on binary heap

- To preserve shape invariant, after insertion into

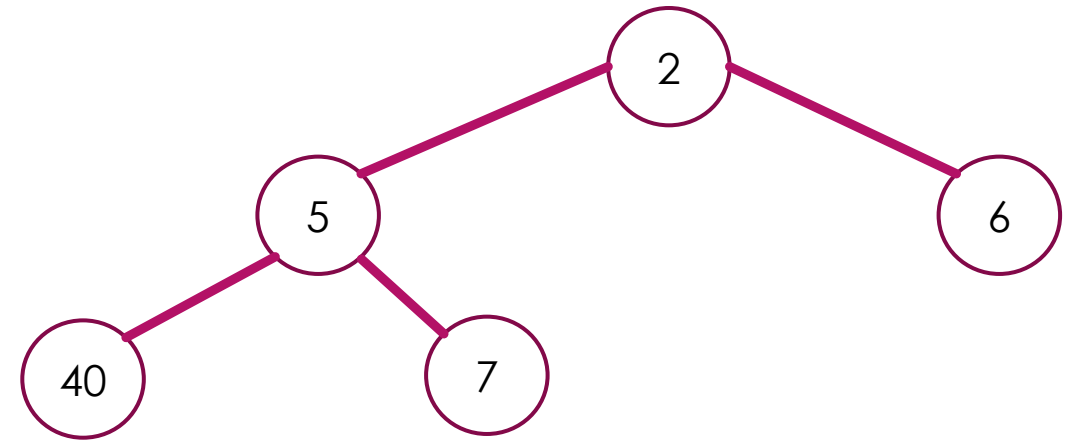


the new shape should look like



# insert operation on binary heap

1. First preserve shape invariant
2. Then restore ordering invariant

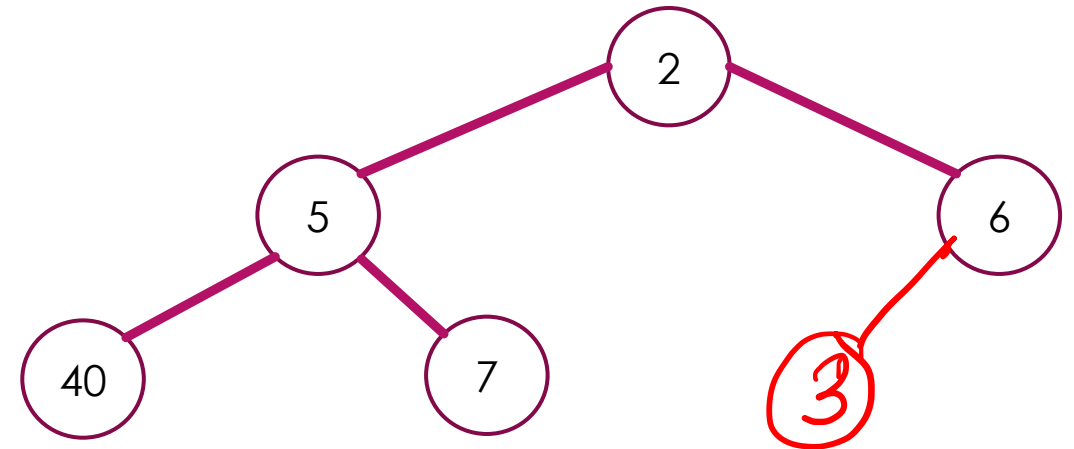




# insert operation on binary heap

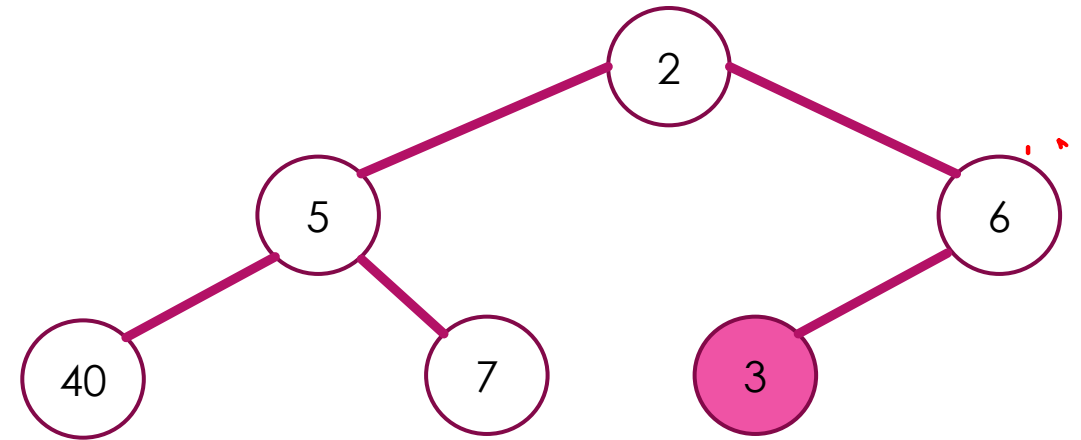
► Insert element with priority 3

1. First preserve shape invariant
  - Where can we insert 3 to preserve this?
2. Then restore ordering invariant



# insert operation on binary heap

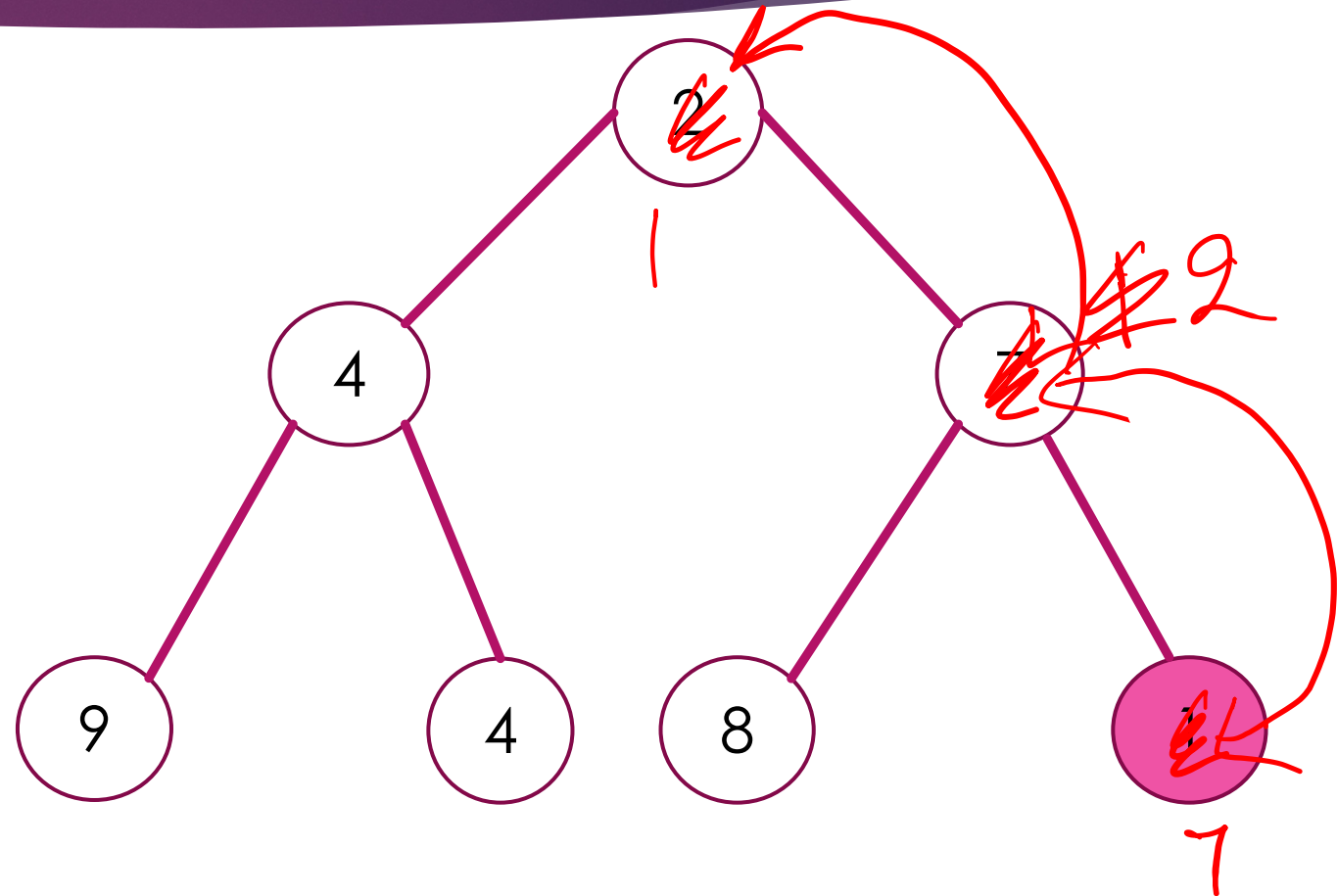
- ▶ Insert element with priority 3
  1. First preserve shape invariant
    - ▶ Insert element in spot expected by shape invariant
  2. Then restore ordering invariant
    - ▶ Swap newly inserted node with parent until no longer a violation of ordering invariant (bubbling up)



# insert in action

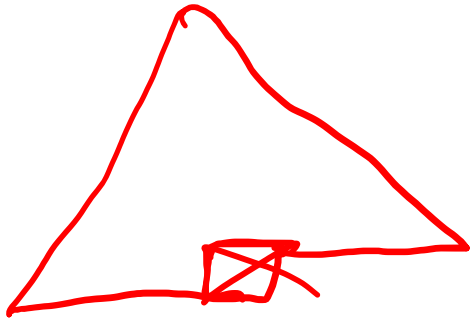
1. Insert element in spot expected by shape invariant
2. **Bubble up** until there is no longer an ordering invariant violation

$7 \leq 1$  ? No  $\rightarrow$  Swap  
 $2 \leq 1$  ? No  $\rightarrow$  Swap

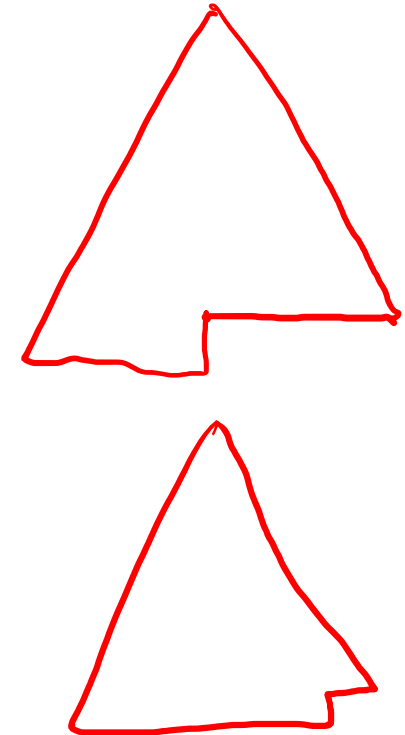
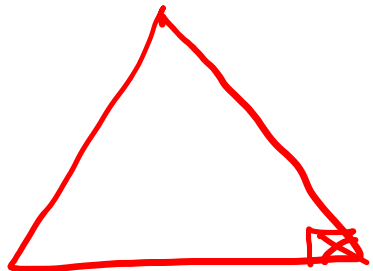


# remove\_min operation on binary heap

- To preserve shape invariant, after removing the min from

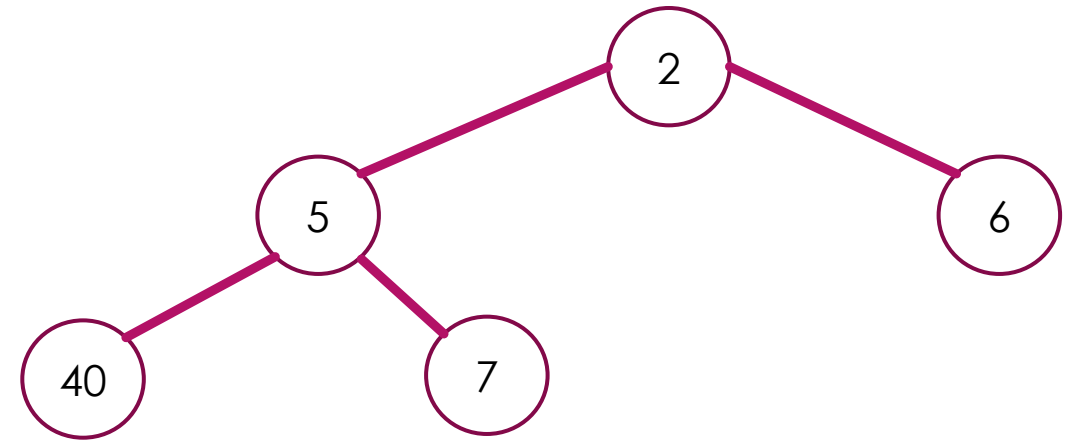


the new shape should look like



# remove\_min operation on binary heap

1. First preserve shape invariant
2. Then restore ordering invariant



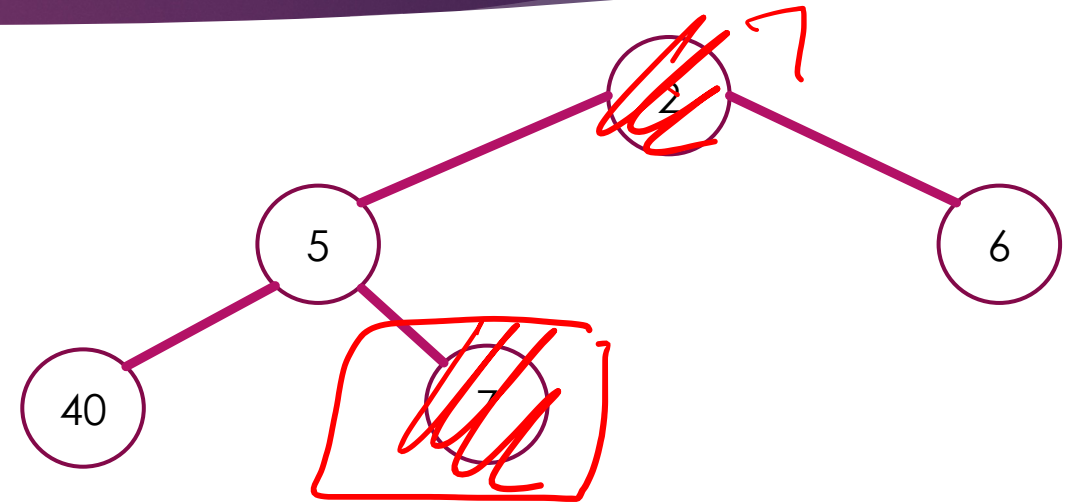


# remove\_min operation on binary heap

## ► Remove root

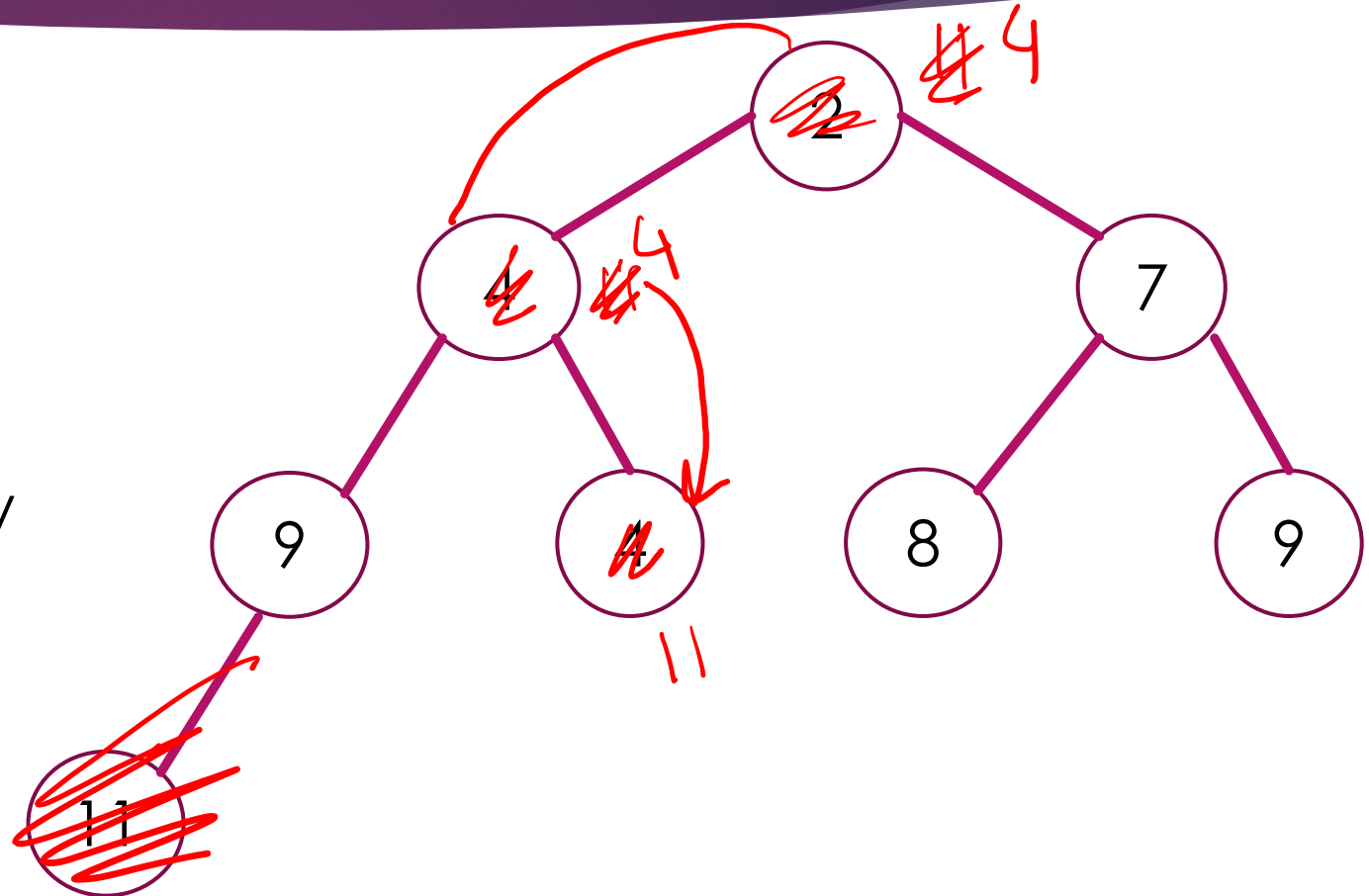
1. First preserve shape invariant
  - Remove "last" element in lowest level and put in root's place
2. Then restore ordering invariant
  - Swap new root with children until there is no longer an ordering invariant violation  
(percolating down)

Return 2



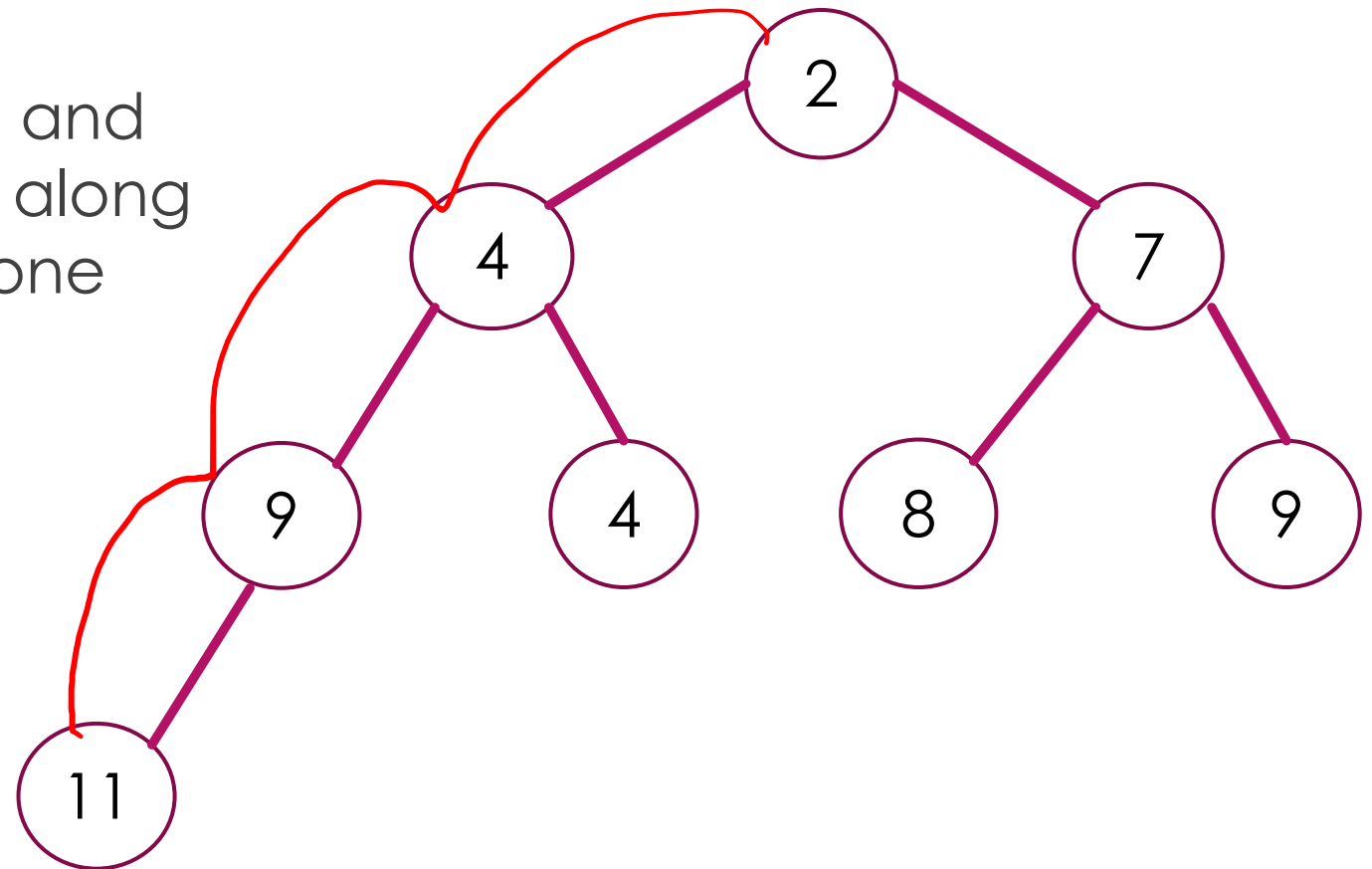
# remove\_min in action

1. Remove "last" element in lowest level and put in root's place
2. **Percolate down** from new root by swapping with smallest child until no longer an ordering invariant violation

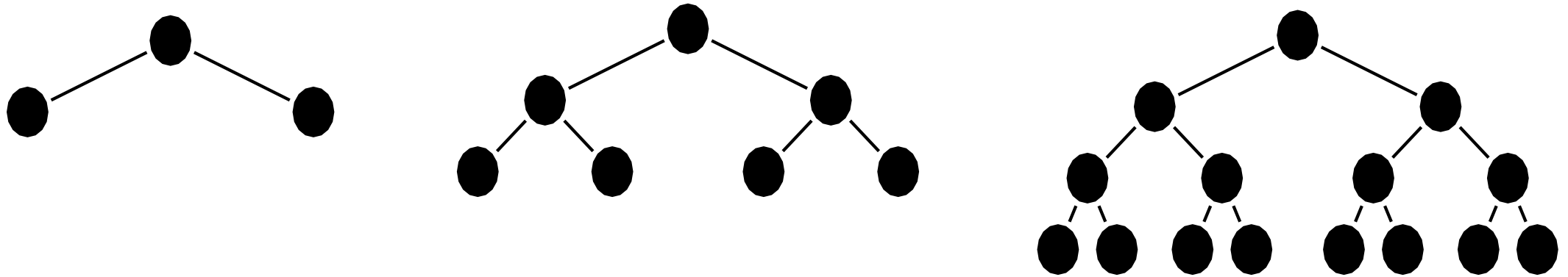


# Binary heap time complexity

- ▶ In the worst case, inserting and removing makes changes along the whole path between one leaf and the root
- ▶ How long is this path?
  - ▶ The **height** of the tree



# Height of a complete tree



Complete tree with _ nodes	Has height
3 ( $= 2^2 - 1$ )	2
7 ( $= 2^3 - 1$ )	3
15 ( $= 2^4 - 1$ )	4
...	...

# Height of a complete tree

Height of a complete tree with  $n$  nodes is  $O(\log n)$ !  
More on trees and height later in the quarter.

$2^4 - 1$	4
15 ( $= 2^4 - 1$ )	4
...	...



# Complexities for priority queue

	Sorted list	Unsorted list	Binary heap
<b>insert</b>	$O(n)$	$O(1)$	$O(\log n)$
<b>remove_min</b>	$O(1)$	$O(n)$	$O(\log n)$

# Pause

- ▶ Any questions or anything unclear?

# Other uses of binary heaps

- ▶ Heap sort!
- ▶ Put all your elements in a heap and keep finding and removing the next minimum or maximum
  - ▶ You'll do this in Homework 5
- ▶ On your own: what would be the complexity of this sort?

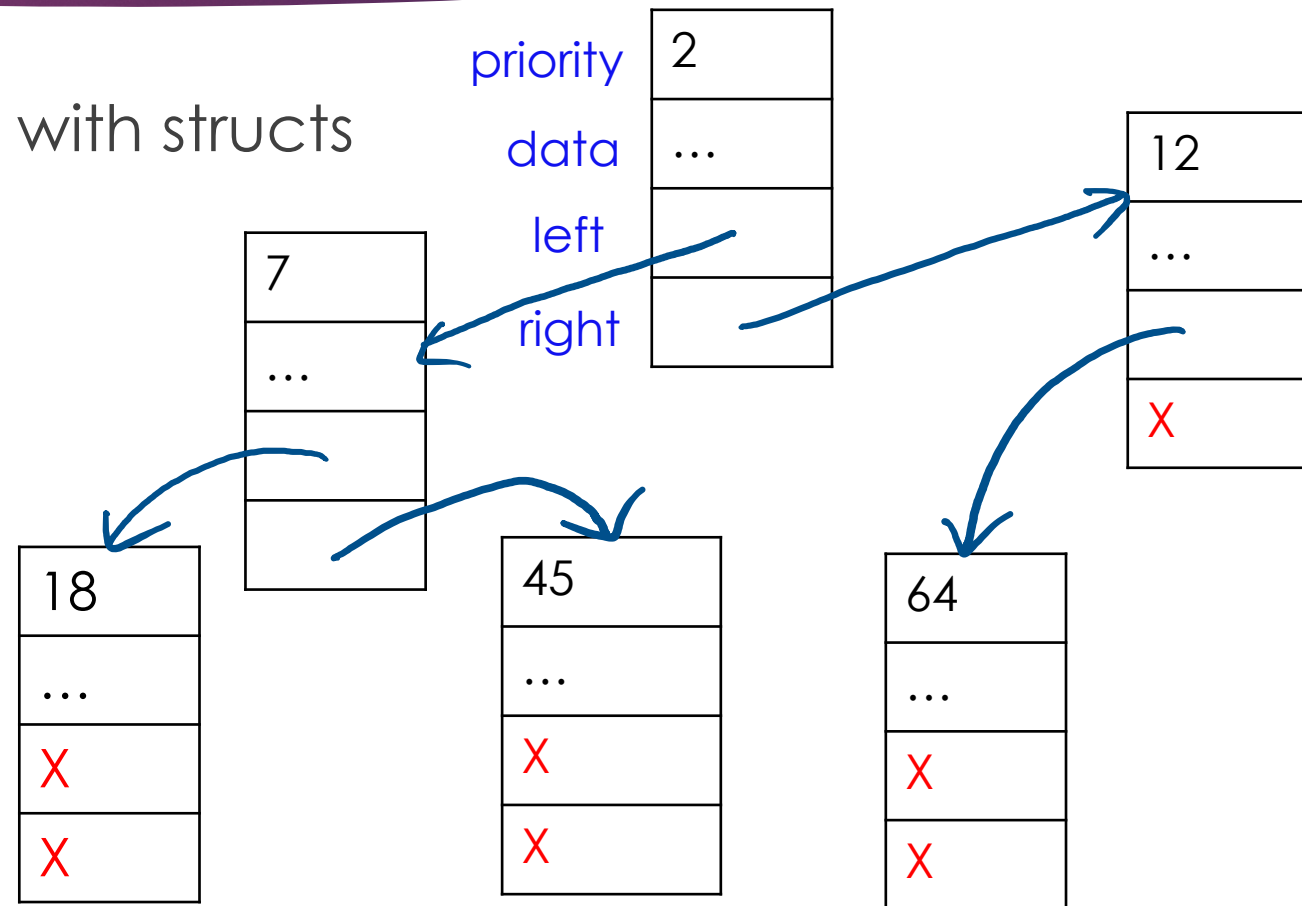
# Representing a binary heap

- ▶ Binary heap is a concrete data structure, but we need to represent it with building blocks
  - ▶ Similar to how a ring buffer is a data structure but is represented with a simple array
  - ▶ Two layers of abstraction
- ▶ Ideas using structs and/or vectors?

# Binary heap with structs

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- ▶ K-ary trees **could** be represented with structs
  - ▶ Intuitive representation

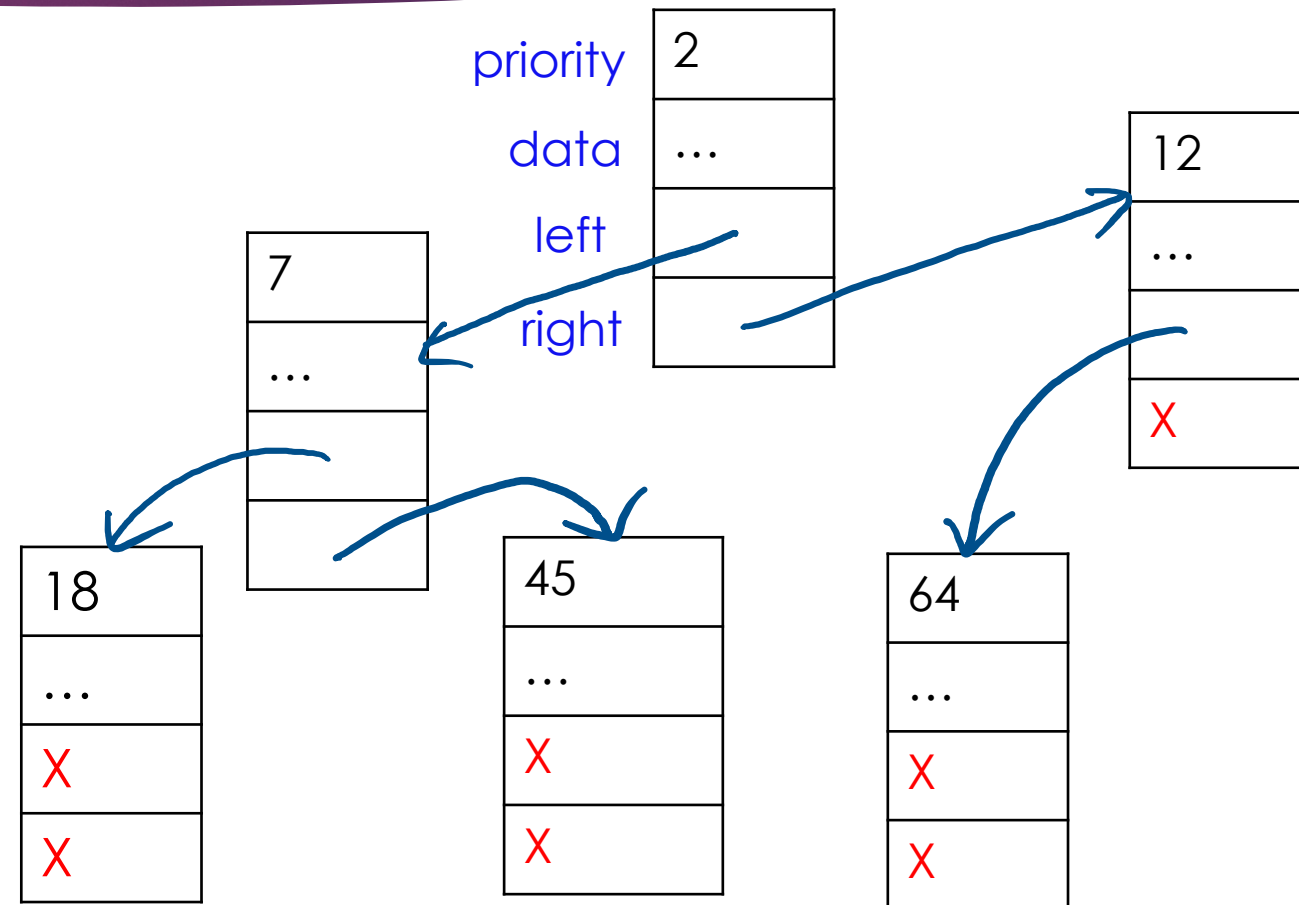




# In-class exercise (5 minutes)

This representation is not sufficient to enable bubbling up.

1. What is the issue?
2. What specifically would you need to add to enable that operation?



# Binary heap with structs

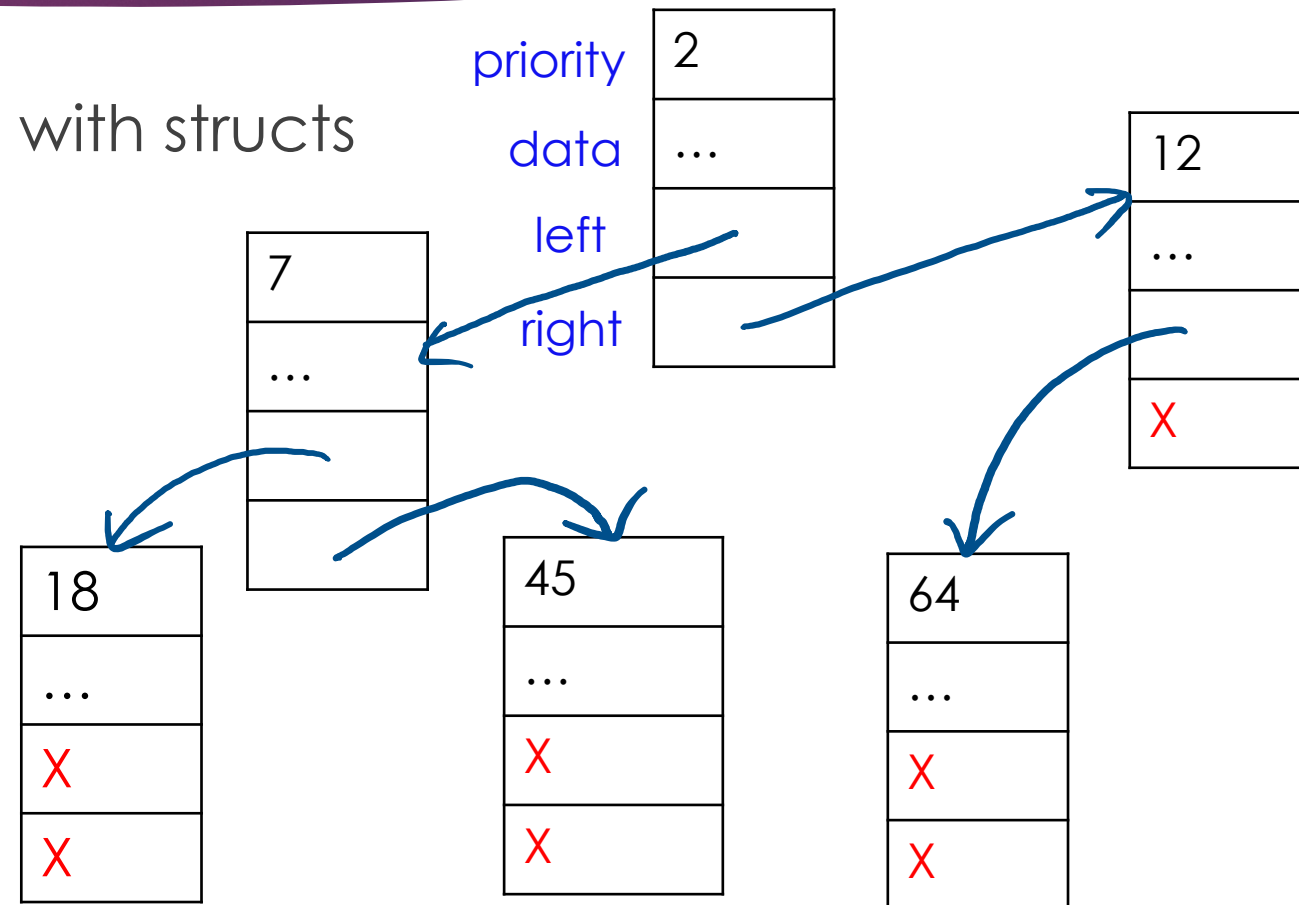
- ▶ K-ary trees **could** be represented with structs

- ▶ Intuitive representation

- ▶ Issues with this approach?

- ▶ What about bubbling up?
  - ▶ Need to have access to parent too
  - ▶ Becomes messy

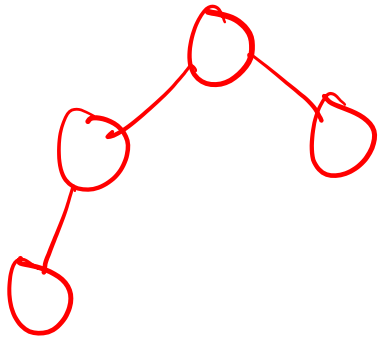
- ▶ Let's not do that



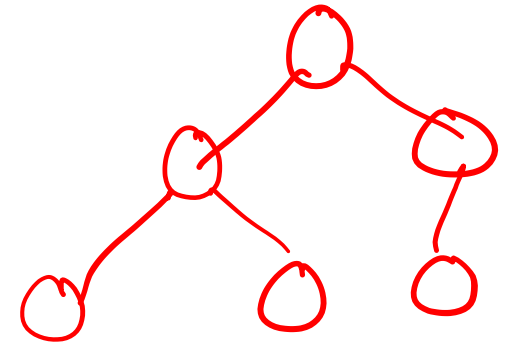
# However... recall the shape invariant

- ▶ Heaps are always complete trees!
- ▶ For a given number of elements, there is only one possible shape!

**Heap with 4 elements**

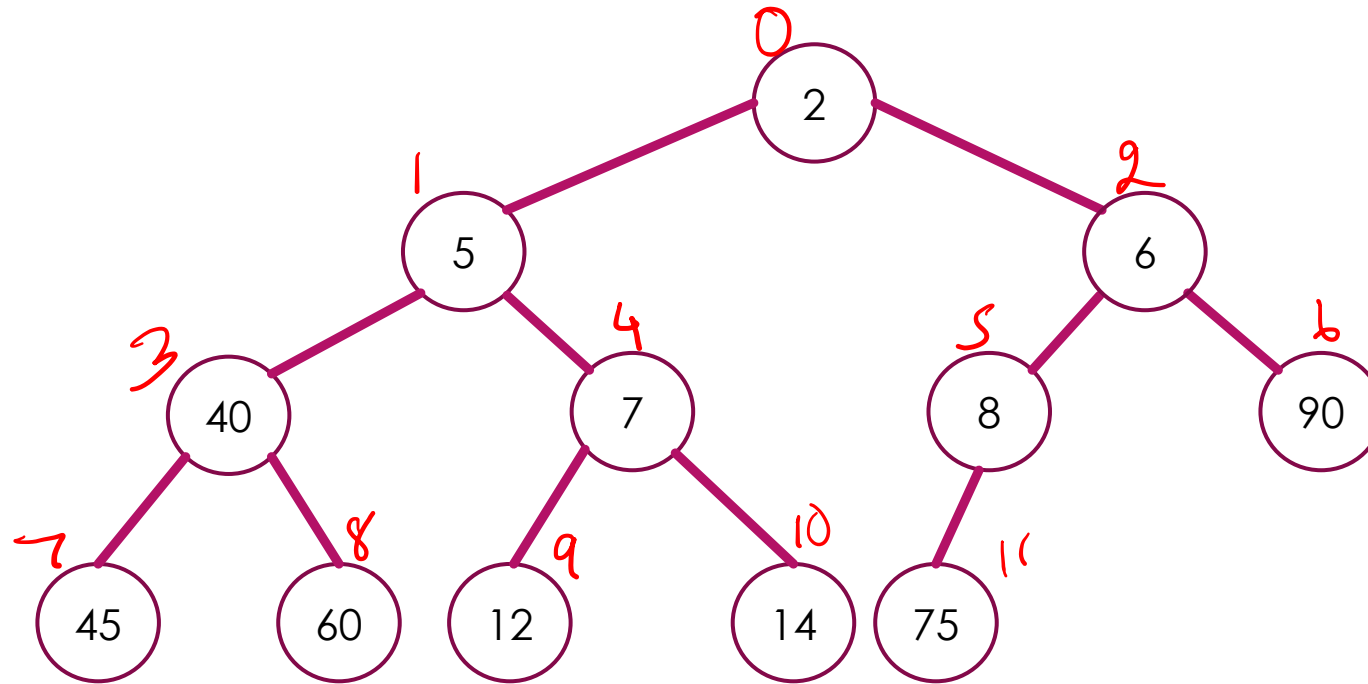


**Heap with 6 elements**



# Representing binary heaps

- Let's label each element from top-bottom and left-right



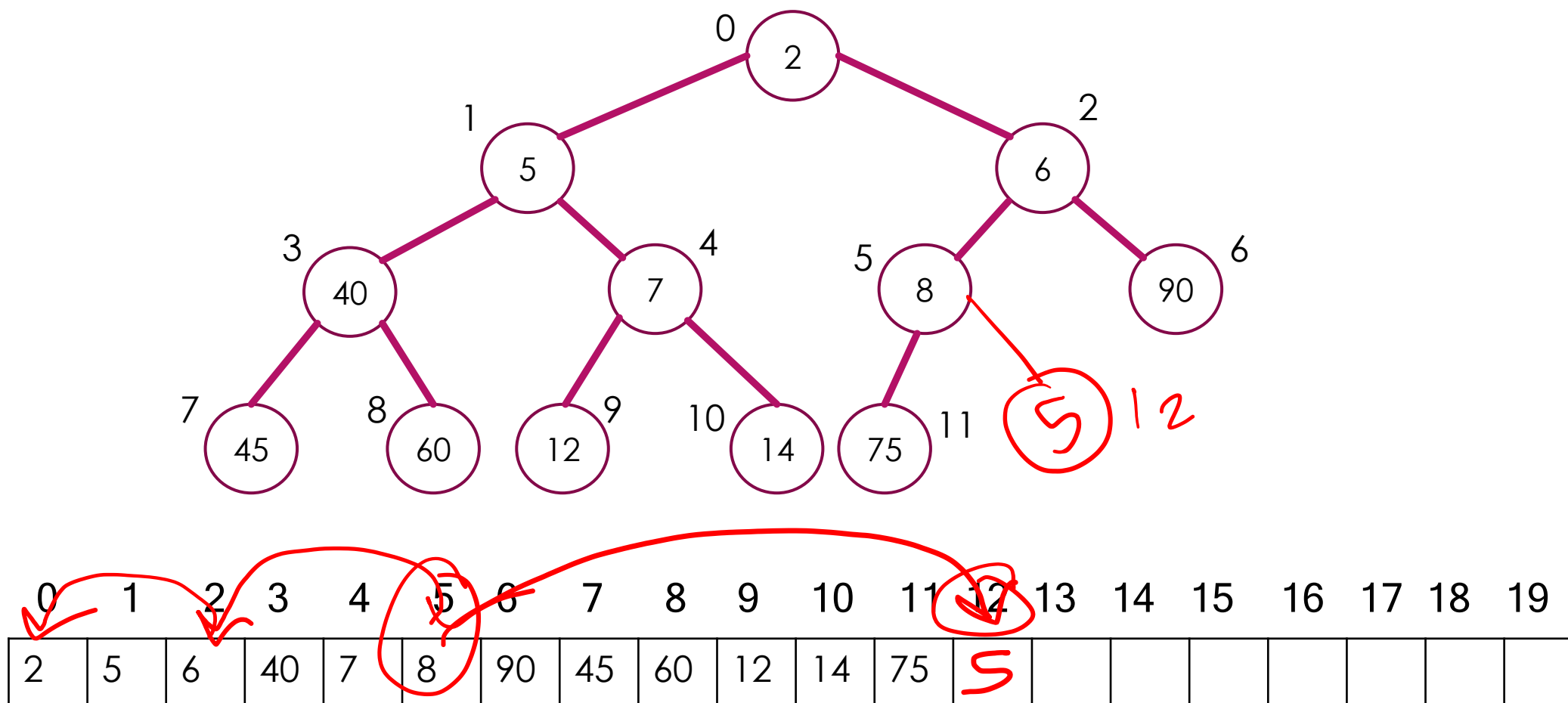
- This can fit perfectly in an array!

# Representing binary heaps as arrays

- ▶ Store values on the heap in an array:
  - ▶ In order from top level to bottom level
  - ▶ In order from left to right



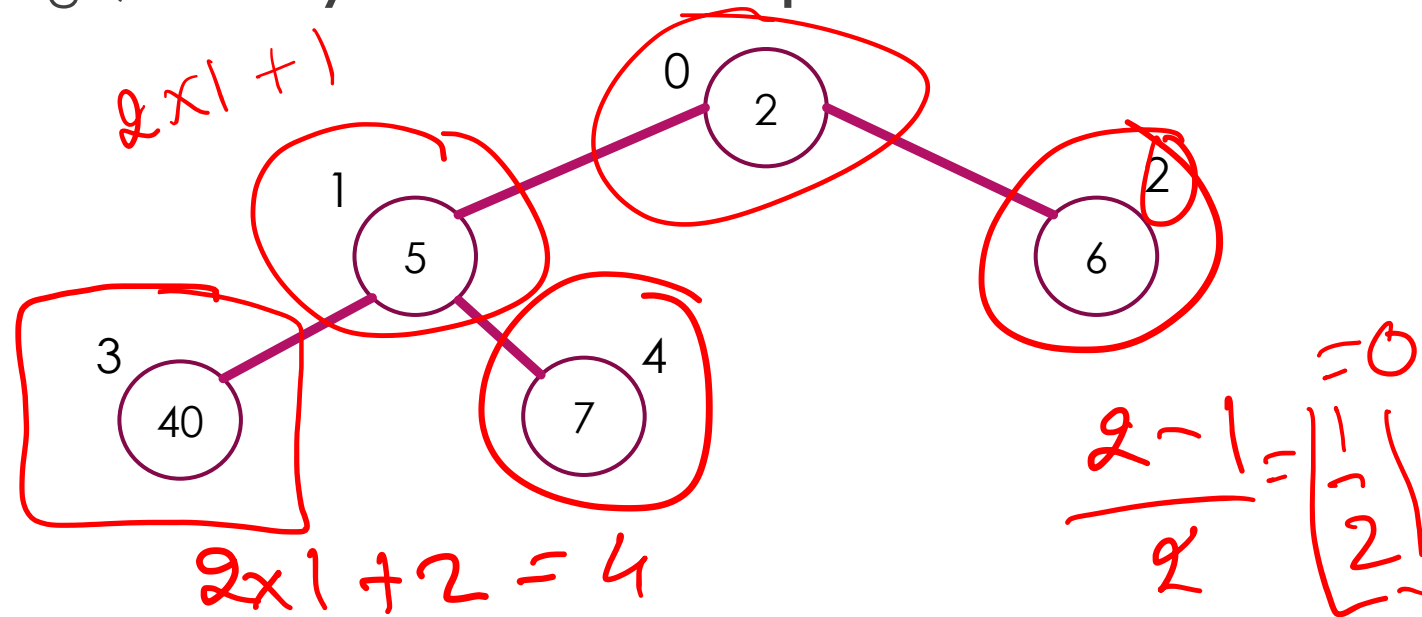
# Representing binary heaps as arrays



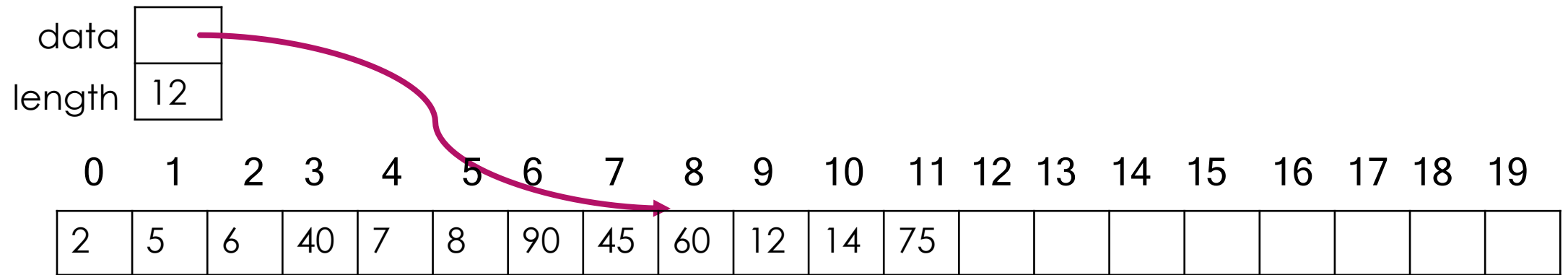
# Findings parents and children

- ▶ Structure is *implicit*, so can't just follow arrows as there are no real arrows
  - ▶ Structure is well-defined though, so **array indices follow a pattern**

- ▶ Given a node at index  $i$ 
  - ▶ Parent index =  $\lfloor (i-1)/2 \rfloor$ 
    - ▶ "floor" of quotient
  - ▶ Left child index =  $2*i + 1$
  - ▶ Right child index =  $2*i + 2$



# Mapping operations to the array



- ▶ Where would you insert?
  - ▶ At index `length`
- ▶ Where would you remove?
  - ▶ Remove what's at index `length-1` and put it at index 0
- ▶ Update `length` in both cases

# Next week

- ▶ Data Design
  - ▶ We'll ADTs and data structures to work on a problem from start to end
  - ▶ Come prepared to participate!
  - ▶ Preview for your final project
- ▶ Priority queues will make a comeback after next week