Engineering Analysis I, Fall 2017 Midterm 2

SOLUTIONS

Section number

Section number	Discussion time	Instructor
30	9:00 a.m.	Ilya Mikhelson
31	10:00 a.m.	Ilya Mikhelson
32	10:00 a.m.	Iman Hassani Nia
33	11:00 a.m.	Iman Hassani Nia
34	12:00 noon	Randy Berry

This exam is closed-book and closed-notes. Calculators, computers, phones, or other computing/communication devices are not allowed.

Students should skip this page—it is only for graders.

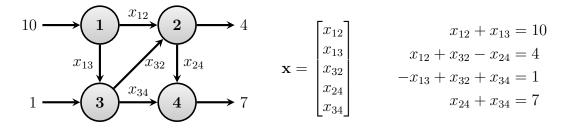
Question	Points	Score
1	12	
2	10	
3	13	
4	14	
5	10	
6	32	
7	9	
Total:	100	

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Answer each question in the space provided. There are 7 questions for a total of 100 points.

Problem 1

Consider the following network flow diagram and flow balance equations:



(a) [2 points] Write the flow balance equations in the form $A\mathbf{x} = \mathbf{b}$, with \mathbf{x} as defined above.

$$\begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & -1 & 0 \\ 0 & -1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_{12} \\ x_{13} \\ x_{32} \\ x_{24} \\ x_{34} \end{bmatrix} = \begin{bmatrix} 10 \\ 4 \\ 1 \\ 7 \end{bmatrix}$$
 (OK if rows are swapped or negative)

(b) [3 points] Find the reduced row echelon form of the augmented matrix $[A \ \mathbf{b}]$.

$$\begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 11 \\ 0 & 1 & -1 & 0 & -1 & -1 \\ 0 & 0 & 0 & 1 & 1 & 7 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

(c) [3 points] Write the solution set for your system of equations in parametric vector form.

$$\mathbf{x} = \begin{bmatrix} x_{12} \\ x_{13} \\ x_{32} \\ x_{24} \\ x_{34} \end{bmatrix} = \begin{bmatrix} 11 \\ -1 \\ 0 \\ 7 \\ 0 \end{bmatrix} + c_1 \begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 1 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$
 (\mathbf{x}_h \text{ (last 2 vectors) can be multiples)} \text{ (accept } x_{32} \text{ and } x_{34} \text{ as parameters.)}

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(d) [2 points] Find a parametric vector form solution in which the flows in the particular solution are all non-negative. There may be more than one right answer.

$$\mathbf{x} = \begin{bmatrix} x_{12} \\ x_{13} \\ x_{32} \\ x_{24} \\ x_{34} \end{bmatrix} = \begin{bmatrix} 10 \\ 0 \\ 1 \\ 7 \\ 0 \end{bmatrix} + c_1 \begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 1 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$

$$OR$$

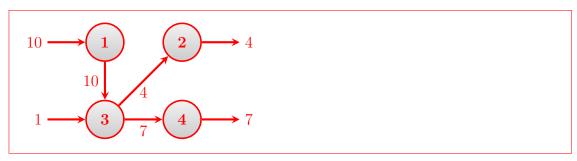
$$\mathbf{x} = \begin{bmatrix} x_{12} \\ x_{13} \\ x_{32} \\ x_{24} \\ x_{34} \end{bmatrix} = \begin{bmatrix} 9 \\ 1 \\ 2 \\ 7 \\ 0 \end{bmatrix} + c_1 \begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 1 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$

$$OR$$

$$\mathbf{x} = \begin{bmatrix} x_{12} \\ x_{13} \\ x_{32} \\ x_{24} \\ x_{34} \end{bmatrix} = \begin{bmatrix} 8 \\ 2 \\ 3 \\ 7 \\ 0 \end{bmatrix} + c_1 \begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 1 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$

$$OR$$

(e) [2 points] Draw a solution to the network flow problem with $x_{12} = 0$ and $x_{24} = 0$. Make sure no flows are negative!



Problem 2

Let

$$A = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix} \qquad B = \begin{bmatrix} 1 & -3 & 1 & 4 \\ 2 & 1 & -2 & 1 \end{bmatrix} \qquad C = \begin{bmatrix} 1 & -1 & 3 & -4 \\ 0 & 1 & 4 & 2 \\ 2 & -2 & 6 & -8 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Find each of the following quantities or write "not defined" if the operation is not defined.

(a) [2 points] A^{100}

 $\left[\begin{array}{cc} 0 & 0 \\ 0 & 0 \end{array}\right]$

(b) [2 points] C^{-1}

not defined

(c) [2 points] $(C^T)^{-1}$

not defined

(d) [2 points] $(BB^T)C$

not defined

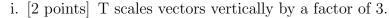
(e) [2 points] AB

 $\begin{bmatrix} 3 & -2 & -1 & 5 \\ -3 & 2 & 1 & -5 \end{bmatrix}$

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Problem 3

(a) Suppose T is a linear transformation from \mathbb{R}^2 to \mathbb{R}^2 . Write the standard matrix for each of the following transformations.



 $\left[\begin{array}{cc} 1 & 0 \\ 0 & 3 \end{array}\right]$

ii. [2 points] T first reflects across the line at -45 degrees through the origin and then rotates clockwise by 90 degrees about the origin.

 $\left[\begin{array}{cc} -1 & 0 \\ 0 & 1 \end{array}\right]$

iii. [2 points] T first projects onto the line at 45 degrees through the origin and then rotates clockwise by 90 degrees about the origin.

 $\left[\begin{array}{cc} 0.5 & 0.5 \\ -0.5 & -0.5 \end{array}\right]$

(b) [2 points] Select all transformations from part (a) that are **onto**. Put a check mark (\checkmark) in the box next to **EACH** correct answer.

(c) [2 points] Select all transformations from part (a) that are **one-to-one**. Put a check mark (\checkmark) in the box next to **EACH** correct answer.

(d) [3 points] Given a linear transformation $T: \mathbb{R}^7 \to \mathbb{R}^2$, suppose that $T(2\mathbf{x}) = \begin{bmatrix} 10 \\ 2 \end{bmatrix}$ and $T(\mathbf{x} + \mathbf{y}) = \begin{bmatrix} 5 \\ 7 \end{bmatrix}$ for two vectors \mathbf{x} and \mathbf{y} in \mathbb{R}^7 . What is $T(\mathbf{y})$?

 $\begin{bmatrix} 0 \\ 6 \end{bmatrix}$

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Problem 4

(a) Consider the following matrix:

$$\begin{bmatrix} a & 0 & c & 0 \\ 0 & 1 & 1 & 0 \\ 0 & b & 0 & d \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Here a, b, c, and d represent constant parameters. If this matrix is in **reduced** row echelon form, and there are *three pivots*, then what must be the values of these four parameters? For each parameter, either write a specific number or write "any number" if the parameter can have any value.

i. [2 points] What must be the value of a?

i. ____1

ii. [2 points] What must be the value of b?

ii. _____0

iii. [2 points] What must be the value of c?

iii. any number

iv. [2 points] What must be the value of d?

iv. ____1

(b) [2 points] What is the reduced row echelon form of the following matrix?

$$\begin{bmatrix} 5 & 0 & 1 & 3 & 4 & 8 \\ 0 & 0 & 3 & 4 & 4 & 7 \\ 0 & 0 & 0 & 5 & 2 & 3 \\ 0 & 0 & 0 & 0 & 4 & -8 \\ 0 & 0 & 0 & 0 & 0 & -4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

(c) Consider a system of linear equations of the form Ax = b, where the matrix A is 4-by-5 and the column vector x consists of the five unknown variables x_1, x_2, \ldots, x_5 . Suppose the reduced row echelon form of the augmented matrix is given by

$$\begin{bmatrix} A & b \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 8 \\ 0 & 0 & 1 & 0 & 0 & 7 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

i. [2 points] Which of the unknown variables are free?

 x_2 and x_5

ii. [1 point] How many solutions are there?

infinitely many

iii. [1 point] Does the solution set pass through the origin in \mathbb{R}^5 (yes or no)?

no

Problem 5

Answer each question in the space provided. Consider the following matrices:

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \qquad B = \begin{bmatrix} 1 & -5 & 3 \\ 0 & 4 & -2 \\ 0 & -2 & 1 \end{bmatrix} \qquad C = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & -5 & 3 \\ 0 & 4 & -2 \\ 0 & -2 & 1 \end{bmatrix}$$

$$C = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

(a) [2 points] Is A invertible? If so, find its inverse.

yes,
$$A^{-1} = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

(b) [2 points] Is B invertible? If so, find its inverse.

no

(c) [2 points] Is C invertible? If so, find its inverse.

yes,
$$C = A^T$$
 so $C^{-1} = (A^{-1})^T = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$

(d) [2 points] Is the product AB invertible? If so, find its inverse.

no (because B is not invertible)

(e) [2 points] Is the product AC invertible? If so, find its inverse.

yes,
$$(AC)^{-1} = C^{-1}A^{-1} = \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$

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Problem 6 32 points

Answer TRUE or FALSE for each of the following statements. You do not have to explain your answer. (2 points each)

(a) If $\{x, y, z\}$ is a linearly dependent set, then $\{x, y\}$ must be linear	ly independent.
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(a) False

(b) If a matrix is in reduced row echelon form, then the entry in its bottom left-hand corner must be 0.

(b) <u>False</u>

(c) The solution set for a system of linear equations of the form $A\mathbf{x} = \mathbf{b}$ can contain exactly two distinct vectors.

(c) False

(d) If a matrix A has a row of all zeros, then the system of linear equations $A\mathbf{x} = \mathbf{b}$ must be inconsistent.

(d) False

(e) No two matrices can have the same reduced row echelon form.

(e) False

(f) If a linear transformation from \mathbb{R}^5 to \mathbb{R}^5 is one-to-one, then the span of the columns of its standard matrix must be the same as its codomain.

(f) <u>True</u>

(g) If a matrix product AB exists and is invertible, then both A and B must be invertible with $(AB)^{-1} = B^{-1}A^{-1}$.

(g) False

(h) If a matrix product AB exists and has all zero entries, then either A or B (or both) must have all zero entries.

(h) False

(i) If $A = B^T$, and the columns of B are linearly independent, then it must be the case that the equation $A\mathbf{x} = \mathbf{b}$ is consistent for every \mathbf{b} in \mathbb{R}^m .

(i) <u>True</u>

(j) If the span of the set $\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n\}$ in \mathbb{R}^m does not include all vectors in \mathbb{R}^m , then the linear transformation defined by the standard matrix $A = [\mathbf{a}_1 \ \mathbf{a}_2 \cdots \mathbf{a}_n]$ is not onto.

(j) <u>True</u>

(K)	he onto.			
		(k)	False	
(l)	A linear transformation defined by a matrix with more columns onto.			
		(1)	False	
(m)	A linear transformation defined by a matrix with more columns be one-to-one.	than ro	ws cannot	
		(m)	True	
(n)	A linear transformation defined by a matrix with more columns one-to-one.	than row	vs must be	
		(n)	False	
	If the system of linear equations $A\mathbf{x} = \mathbf{b}$ has a unique solution the linear transformation defined by A must be both onto and o			
		(o)	True	
(p)	If matrix A has more rows than columns, then $A\mathbf{x} = \mathbf{b}$ cannot has solutions.	ave infini	itely many	
		(p)	False	

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Problem 7 9 points

Write a function called <code>check_cons</code> that has 2 inputs and 1 output. The inputs are a matrix A and a vector b, and the output is a logical scalar y. The function should check if the system defined by Ax = b is consistent. If it is, then y should be true. Otherwise, it should be false. No error checking, help lines, etc. is necessary. Just provide the code. *Hint: use rref*.

```
function y = check_cons(A,b) (3 points)

[~,pivs] = rref([A b]); (2 points)

if pivs(end) == size(A,2) + 1 (4 points for the whole block)
    y = false;
else
    y = true;
end

    or

y = pivs(end) ~= size(A,2) + 1;
```