

# A First Course in Optimization

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## Abstract

Lecture Notes for the course EE 659: A First Course in Optimization taught in Spring 2022 by Prof. Vivek Borkar. Additional references include *A first course in optimization* by Rangarajan K. Sundaram, *Optimization by vector space methods* by David Luenberger, and *Nonlinear programming* by Dimitri P. Bertsekas

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## §1. Lecture 1

### Definition 1.1: Open Ball

The *open ball* of radius  $\epsilon$  centered around  $\mathbf{x}_0 \in \mathbb{R}^d$  is defined as

$$B_\epsilon(\mathbf{x}_0) := \{ \mathbf{x} \in \mathbb{R}^d : \|\mathbf{x} - \mathbf{x}_0\| < \epsilon \}.$$

### Definition 1.2: Closed Ball

The *closed ball* of radius  $\epsilon$  centered around  $\mathbf{x}_0 \in \mathbb{R}^d$  is defined as

$$\overline{B}_\epsilon(\mathbf{x}_0) := \{ \mathbf{x} \in \mathbb{R}^d : \|\mathbf{x} - \mathbf{x}_0\| \leq \epsilon \}.$$

### Definition 1.3: Open and Closed Sets

A set  $A \subset \mathbb{R}^d$  is said to be *open* if for all  $\mathbf{x} \in A$ , there exists an  $\epsilon > 0$  such that  $B_\epsilon(\mathbf{x}) \subset A$ . A set  $A$  is said to be *closed* if  $A^c$  is open.

We have the following properties for open and closed sets.

1. Let  $\mathcal{I}$  be an arbitrary index set. If  $A_\alpha$  is open for each  $\alpha \in \mathcal{I}$ , then

$$\bigcup_{\alpha \in \mathcal{I}} A_\alpha$$

is open. In other words, open sets are closed under arbitrary unions.

2. Let  $\mathcal{I}$  be a finite index set. If  $A_\alpha$  is open for each  $\alpha \in \mathcal{I}$ , then

$$\bigcap_{\alpha \in \mathcal{I}} A_\alpha$$

is open. In other words, open sets are closed under finite intersections.

3. Let  $\mathcal{I}$  be an arbitrary index set. If  $A_\alpha$  is closed for each  $\alpha \in \mathcal{I}$ , then

$$\bigcap_{\alpha \in \mathcal{I}} A_\alpha$$

is closed. In other words, closed sets are closed under arbitrary intersections.

4. Let  $\mathcal{I}$  be a finite index set. If  $A_\alpha$  is closed for each  $\alpha \in \mathcal{I}$ , then

$$\bigcup_{\alpha \in \mathcal{I}} A_\alpha$$

is closed. In other words, closed sets are closed under finite unions.

**Definition 1.4: Convergence of a sequence**

Let  $\langle \mathbf{x}_n \rangle$  be a sequence in  $\mathbb{R}^d$ . Then,  $\langle \mathbf{x}_n \rangle$  converges to  $\mathbf{x}^*$  (written  $\mathbf{x}_n \rightarrow \mathbf{x}^*$ ) if for all  $\epsilon > 0$ , there exists an  $n_0 \in \mathbb{N}$  such that

$$\mathbf{x}_n \in B_\epsilon(\mathbf{x}^*) \quad \forall n > n_0.$$

Equivalently,  $\|\mathbf{x}_n - \mathbf{x}^*\| \rightarrow 0$ .

**Definition 1.5: Closure**

Let  $A \subset \mathbb{R}^d$ . The *closure* of  $A$  (denoted  $\overline{A}$ ) is the smallest closed set containing  $A$ . Equivalently,  $\overline{A}$  is the intersection of all closed sets containing  $A$ .

**Definition 1.6: Interior**

Let  $A \subset \mathbb{R}^d$ . The *interior* of  $A$  (denoted  $A^\circ$ ) is the largest open set contained in  $A$ . Equivalently,  $A^\circ$  is the union of all open sets contained in  $A$ .

Note that by definition, we have  $A^\circ \subset A \subset \overline{A}$ .

**Definition 1.7: Boundary**

Let  $A \subset \mathbb{R}^d$ . The *boundary* of  $A$  is defined as

$$\partial A := \overline{A} \setminus A^\circ.$$

Note that for a closed set,  $\overline{A} = A$ , and for an open set,  $A^\circ = A$ .

**Proposition 1.8**

A set  $A \subset \mathbb{R}^d$  is closed if and only if

$$\mathbf{x}_n \rightarrow \mathbf{x}^*, \mathbf{x}_n \in A \forall n \implies \mathbf{x}^* \in A.$$

*Proof.* Let  $A \subset \mathbb{R}^d$  be closed,  $\mathbf{x}_n \in A$  for all  $n$ , and  $\mathbf{x}_n \rightarrow \mathbf{x}^*$ . Assume to the contrary that  $\mathbf{x}^* \notin A$ . Then,  $\mathbf{x}^* \in A^c$ , which is open by assumption. Thus,  $\exists \epsilon > 0$  such that  $B_\epsilon(\mathbf{x}^*) \subset A^c$ . This implies that  $\mathbf{x}_n \notin B_\epsilon(\mathbf{x}^*)$  for all  $n$ , and thus  $\mathbf{x}_n \not\rightarrow \mathbf{x}^*$ , a contradiction. To prove the converse, assume that  $A$  is not closed. Thus, there exists a  $\tilde{\mathbf{x}} \in \partial A$  such that  $\tilde{\mathbf{x}} \notin A$ . Then, for all  $\epsilon > 0$ ,  $B_\epsilon(\tilde{\mathbf{x}}) \cap A \neq \emptyset$ . Let  $\epsilon_n \downarrow 0$  and let  $\mathbf{x}_n \in B_{\epsilon_n}(\tilde{\mathbf{x}}) \cap A$ . Then,  $\mathbf{x}_n \rightarrow \tilde{\mathbf{x}} \notin A$ , a contradiction.  $\square$

**Definition 1.9: Limit Point**

Let  $\langle \mathbf{x}_n \rangle$  be a sequence in  $\mathbb{R}^d$ .  $\tilde{\mathbf{x}}$  is a *limit point* of  $\langle \mathbf{x}_n \rangle$  if there exists a subsequence  $\langle \mathbf{x}_{n_k} \rangle$  such that  $\mathbf{x}_{n_k} \rightarrow \tilde{\mathbf{x}}$ .

**Proposition 1.10**

$\langle \mathbf{x}_n \rangle$  converges if and only if  $\langle \mathbf{x}_n \rangle$  has a unique limit point.

**Definition 1.11: Supremum and Infimum**

Let  $A \subset \mathbb{R}$  be bounded. Then,

$$\begin{aligned} \sup A &:= \text{smallest } x \in \mathbb{R} \cup \{+\infty\} \text{ such that } y \in A \implies y \leq x, \\ \inf A &:= \text{largest } x \in \mathbb{R} \cup \{-\infty\} \text{ such that } y \in A \implies y \geq x. \end{aligned}$$

**Definition 1.12: Cauchy Sequence**

A sequence  $\langle \mathbf{x}_n \rangle$  is said to be *Cauchy* if  $\lim_{m,n \uparrow \infty} \|\mathbf{x}_m - \mathbf{x}_n\| = 0$ .

**Proposition 1.13**

Cauchy sequences are bounded.

*Proof.* Let  $\langle \mathbf{x}_n \rangle$  be a Cauchy sequence and let  $\epsilon > 0$ . Pick  $N$  large enough such that

$$n, m > N \implies \|\mathbf{x}_m - \mathbf{x}_n\| < \epsilon.$$

We then have

$$\begin{aligned} \mathbf{x}_n &\in B_\epsilon(\mathbf{x}_m) \quad \forall n > N \\ \implies \langle \mathbf{x}_n : n > N \rangle &\text{ is bounded} \\ \implies \langle \mathbf{x}_n \rangle &\text{ is bounded.} \end{aligned}$$

□

**Proposition 1.14**

Cauchy sequences have at most one limit point.

*Proof.* Suppose  $\langle \mathbf{x}_n \rangle$  is a Cauchy sequence having two limit points,  $\tilde{\mathbf{x}}$  and  $\bar{\mathbf{x}}$ . Then,

there exist subsequences  $\mathbf{x}_{\tilde{n}_k} \rightarrow \tilde{\mathbf{x}}$  and  $\mathbf{x}_{\bar{n}_l} \rightarrow \bar{\mathbf{x}}$ . We then have

$$\lim_{\tilde{n}_k, \bar{n}_l \uparrow \infty} \|\mathbf{x}_{\tilde{n}_k} - \mathbf{x}_{\bar{n}_l}\| = 0 \implies \tilde{\mathbf{x}} = \bar{\mathbf{x}}. \quad \square$$

**Definition 1.15: Complete Space**

A metric space is *complete* if every Cauchy sequence converges.

**Theorem 1.16: Bolzano-Weierstrass Theorem**

Every bounded sequence has a convergent subsequence.