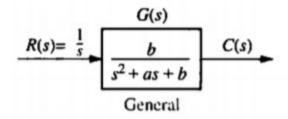
AIM

Study of time response of a second order system subjected to step input under varying damping conditions.

OBJECTIVE

To plot the Step Response of the general transfer function with following parameter specifications:



- a). a=9, b=9 (overdamped)
- b). a=2, b=9 (underdamped)

Also plot the pole-zero relationship plot. Label the axis and provide title for the plots.

MATLAB Code and Output

a) a=9 & b=9 (Overdamped System)

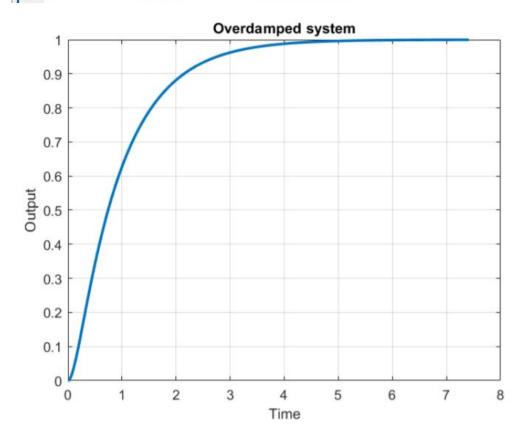
```
Command Window

fx >> clc % clear command window
  clear all % clear workspace

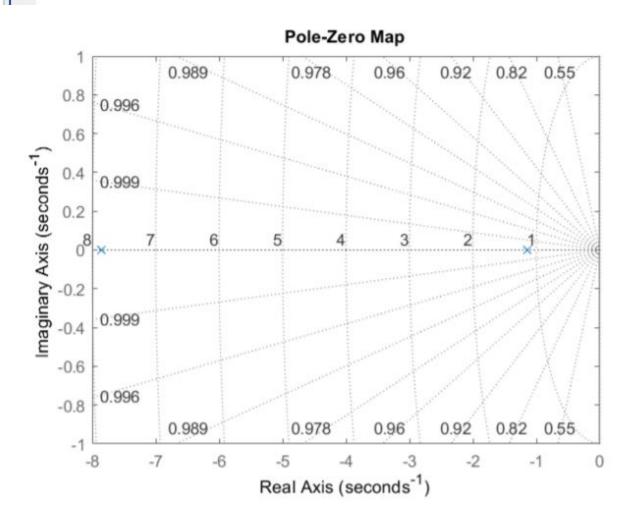
% Define Transfer Function G
  s = tf('s');
% G = b/(s^2 + a*s + b);
G1 = 9/(s^2 + 9*s + 9) % transfer function for Overdamped system
```

```
G1 = 9 ....s^2 + 9 s + 9
```

```
fx >> % Continuous-time transfer function
% Step Response Plot
[x1, t1] = step(G1);
plot(t1, x1, 'LineWidth', 2);
grid
title('Overdamped system') % title
xlabel('Time') % x-axis label
ylabel('Output') % y-axis label
```



```
fx >> % Pole-Zero Plot
pzmap(G1)
grid
```



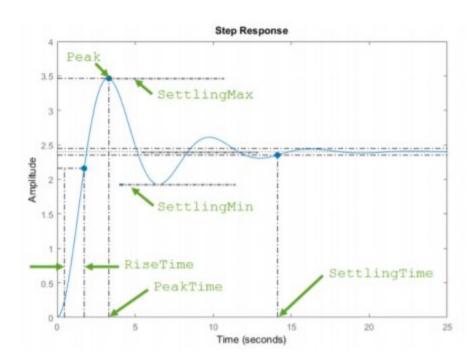
 $f_{x} >>$ stepinfo(G1) % step response specification

ans = struct with fields:

RiseTime: 1.9528 SettlingTime: 3.5516 SettlingMin: 0.9012 SettlingMax: 0.9999

Overshoot: 0 Undershoot: 0

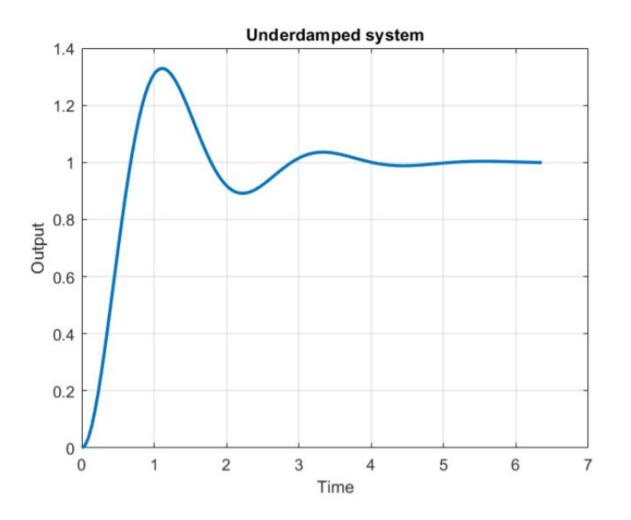
> Peak: 0.9999 PeakTime: 8.6661



b) a=2 & b=9 (Underdamped System)

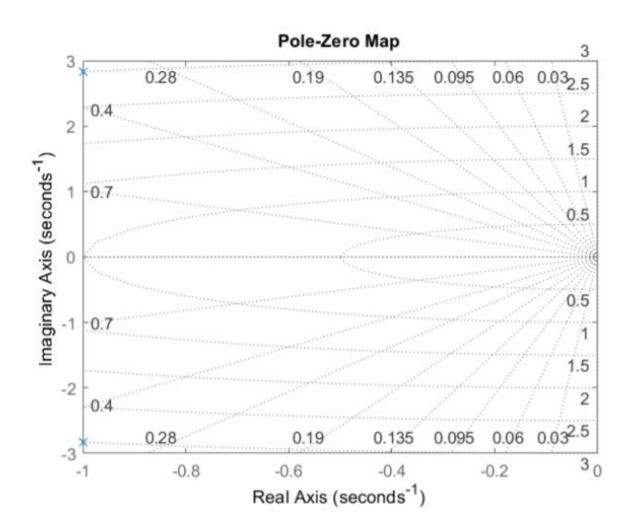
```
fx >> G2 = 9/(s^2 + 2*s + 9) % Transfer function for underdamped system

fx >> % Step Response Plot
  [x2, t2] = step(G2);
  plot(t2, x2, 'LineWidth', 2); % Plot command
  grid % grid lines
  title('Underdamped system')
  xlabel('Time')
  ylabel('Output')
```



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fx >> % Pole-Zero Plot pzmap(G2) grid



$f_{x} >>$ stepinfo(G2)

ans = struct with fields:

RiseTime: 0.4568

SettlingTime: 3.7005

SettlingMin: 0.8916

SettlingMax: 1.3293

Overshoot: 32.9277

Undershoot: 0

Peak: 1.3293

PeakTime: 1.1052