

# Hysteric Boost Controller

#### Introduction



- So far, we have covered:
  - IPT
  - Full bridge rectifiers
  - Connecting boost converters onto a parallel tuned secondary
- This section discusses how to turn the energy that the IPT system receives into a controlled dc voltage

# **Learning Objectives**

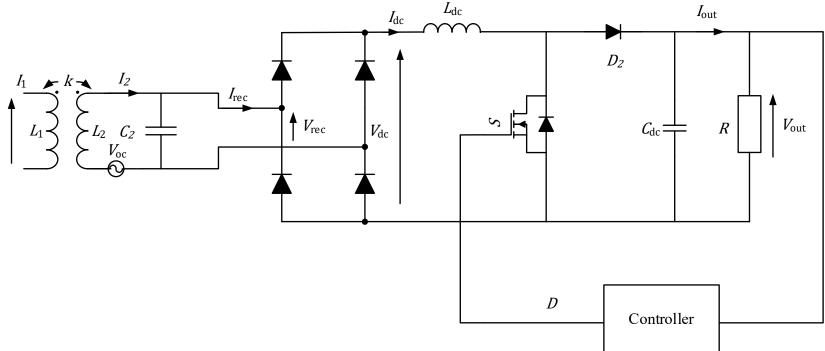


- Understand the operating principles of hysteretic (slow switched) controllers
- How you will be assessed:
  - Lab 1 task 3
  - Test
  - Practical build

#### A short circuit controller



- A short circuit (boost) controller is typically used to regulate the output of a parallel tuned pick-up
  - Rectifier converts AC to DC
  - DC inductor  $(L_{dc})$  decouples AC from DC side and maintains a continuous current through rectifier
  - Switch duty cycle controlled to regulate output current ( $I_{out}$ ) to maintain  $V_{out}$
  - Diode  $(D_2)$  avoids discharge of  $(C_{dc})$  through switch when 'on'
  - Output capacitor ( $C_{dc}$ ) minimizes output voltage ripple ( $\Delta V_{out}$ )



#### A short circuit controller



- From the rectifier slides:
  - $I_{dc} = \frac{\pi}{2\sqrt{2}}I_{sc} = I_{out}$  if the secondary network is well tuned
- RMS pick-up coil voltage can be calculated assuming 100% efficiency

$$V_{rec} = \frac{\pi}{2\sqrt{2}}V_{out} \text{ or } V_{out} = \frac{2\sqrt{2}}{\pi}V_{rec}$$

• The loaded quality factor (voltage boost), *Q*, of the pick-up coil is given by:

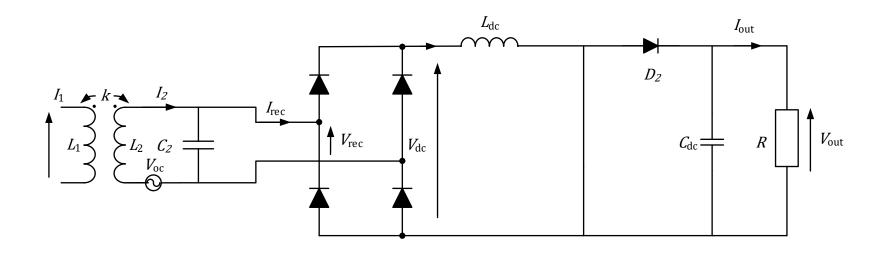
$$Q = \frac{V_{rec}}{V_{oc}} = \frac{\pi}{2\sqrt{2}} \frac{V_{out}}{V_{oc}}$$

- The maximum Q of the pick-up is 1.1 times the ratio between  $V_{out}$  and  $V_{oc}$
- In practice, due to non ideal operating conditions, relationship between  $I_{sc}$  and  $I_{out}$  as well as  $V_{rec}$  and  $V_{out}$  will be different
  - As a result of losses, imperfect tuning, current ripple in I dc, diode switching,

# Slow switching analysis



- When S is on  $I_{dc}$  is shunted through the switch collapsing the resonance and decoupling the pick-up
- $V_{out} = 0 V \rightarrow V_{rec} = 0 V \rightarrow I_2 = I_{sc}$
- $D_2$  blocks current from flowing backwards
- $C_{dc}$  discharges through R
- $V_{out}$  will ramp downwards



## Slow switching analysis



- When S is off  $I_{dc}$  (1.1 times  $I_{sc}$ ) is fed to the load through  $D_2$ 
  - There is now a duty cycle (*D*) which controls the boost converter
- Output current is the average current through *D*<sub>2</sub>

$$I_{out} = (1 - D)I_{dc} = \frac{\pi}{2\sqrt{2}}(1 - D)I_{sc}$$

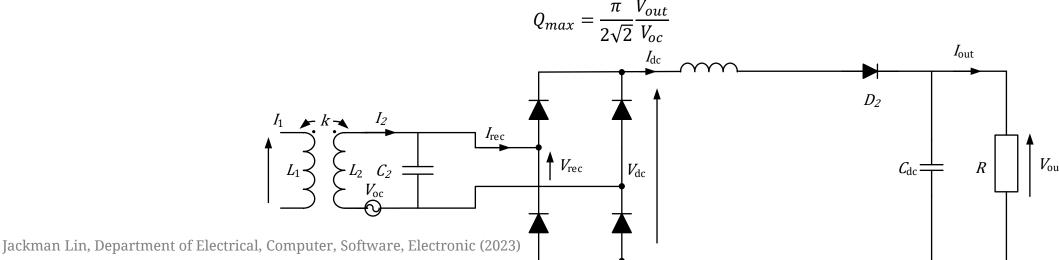
• If  $V_{out}$  is regulated (S is operating at 0 < D < 1), the output power is:

$$P_{out} = I_{out}V_{out} = \frac{\pi}{2\sqrt{2}}(1-D)I_{sc}V_{out} = (1-D)P_{max}$$

• If  $V_{out}$  is unregulated (S is off), output voltage is:

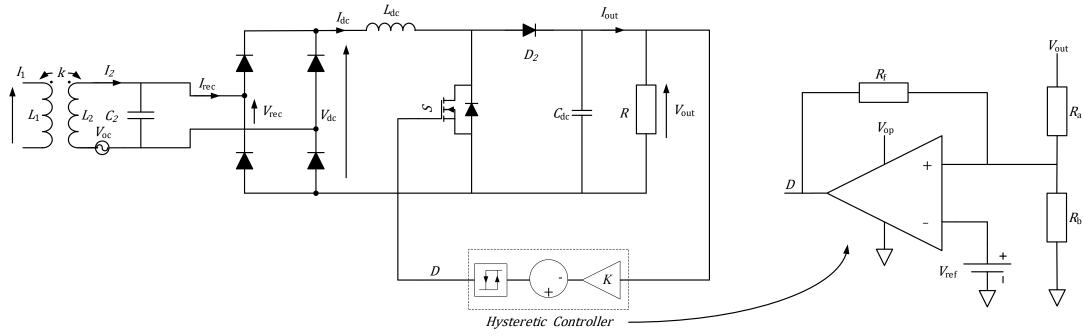
$$V_{out} = I_{out}R_2 = \frac{\pi}{2\sqrt{2}}I_{sc}R_2$$

• Pick up operates at maximum Q (when S is off) independent of load



## Slow switching implementation





- Controller turn off/turn on S when  $V_{out}$  is below/above a threshold
  - Can be implemented using a Schmitt trigger circuit

$$V_{op}$$
 is the output high voltage of the Op-amp whereas output low voltage is assumed to be 0 
$$\Delta V_{out} = V_{op} \frac{R_a}{R_f}$$
 
$$V_{out,avg} = V_{ref} \, \frac{R_a R_b + R_f (R_a + R_b)}{R_f R_b} - V_{op} \frac{R_a}{2_{R_f}}$$

## Slow switching analysis



• Switching frequency is a function of  $\Delta V_{out}$ ,  $C_{dc}$ , and  $R_2$ 

$$f_s \approx \frac{\pi I_{sc}}{2\sqrt{2}C_{dc}\Delta V_{out}}(1-D)D$$

• Maximum switching frequency occurs at D = 0.5

$$f_s \approx \frac{\pi I_{sc}}{8\sqrt{2}C_{dc}\Delta V_{out}}$$

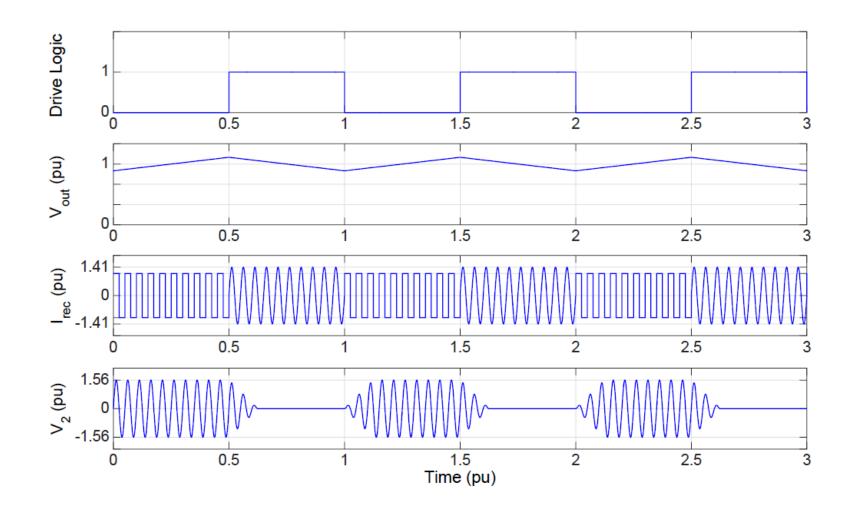
•  $C_{dc}$  should be chosen to keep the switching frequency within an acceptable range

$$C_{dc} > \frac{\pi I_{sc}}{8\sqrt{2}f_{s,max} \,\Delta V_{out}}$$

- Need to consider voltage ratings, RMS current ratings, ESRs, and capacitor lifetimes
- Secondary resonance between  $C_{dc}$  and  $L_{dc}$  should be avoided
- ESRs can lead to false triggering of the Schmitt trigger

# Slow switching waveforms





## **Summary**



- Discussed a simple way to control a short circuit controller
  - No microcontroller used
  - Slow switched
- The pick-up controller given to everyone in class will be based on these notes
- You will need to tune the resistor values as needed for this year's project