

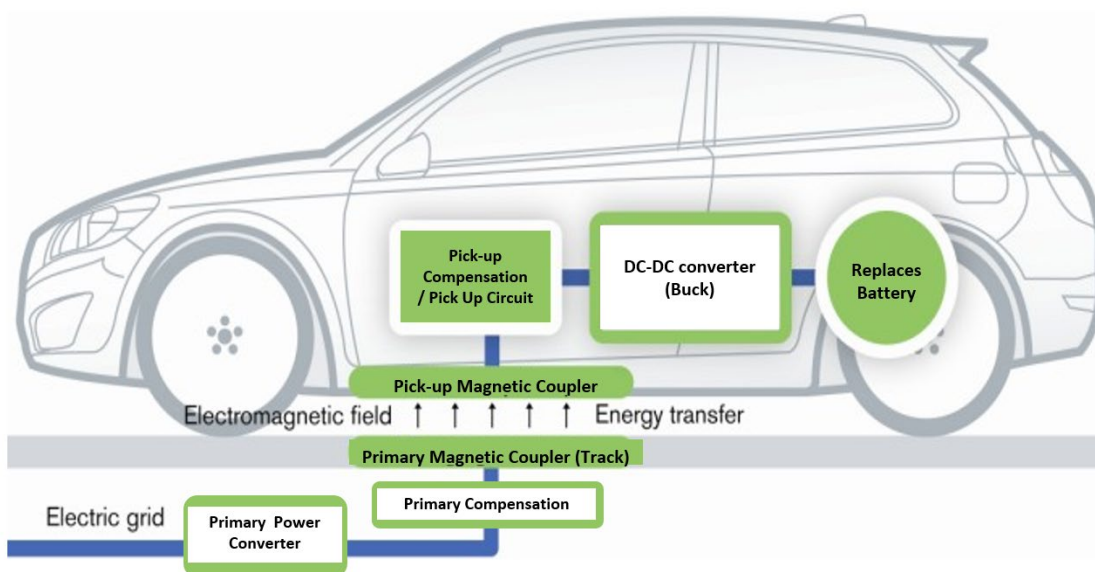
ELECTENG 734 - Power Electronics

Laboratory Assignment – Pick-up Regulator

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Introduction

In this laboratory you will be performing theoretical calculations as well as simulations using PLECS of an IPT pick-up circuit similar to what you will design and construct later in this course.



Simulation with PLECS

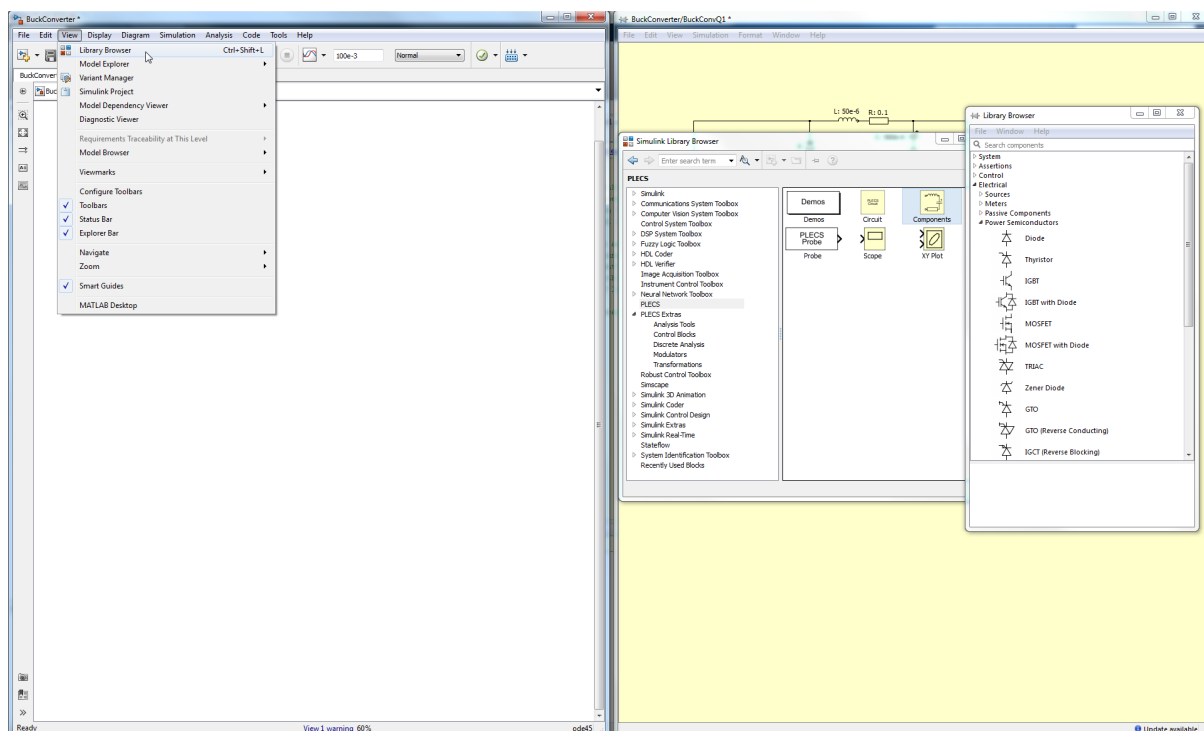
These simulations are run using PLECS Blockset package for Matlab Simulink. To open the simulation software and load a file:

- Open MATLAB
- Open Simulink file Lab_IPT_Student.slx (*this will take a little while to load*)
- Double click on the IPTQ1 PLECS circuit to view it (*right click menu will allow you to comment out PLECS circuits*)
- Ctrl-T to run simulation

Note that in PLECS, plots are produced by using a probe block connected to a scope block. Components may be added to the probe block by dragging and dropping them to the open probe block. You may redefine the number of scope channels in the scope if you want to.

You may add components by going (from the Simulink window) View -> Library Browser, then selecting PLECS and double clicking the Components block.

For further information on how to use PLECS refer to the PLECS user manual (www.plexim.com/files/plecsmanual.pdf).



Pick-up Specifications

In this lab we will look at the operating principles of the IPT pick-up used in your toy car by simulating an IPT pick-up with following parameters in PLECS.

Parameter	Symbol	Value	Unit
Track Current	I_1	80	A
Track Frequency	f_1	38.4	kHz
Primary (Track) Inductance	L_1	10	μH
Secondary (Pick-up) Inductance	L_2	40	μH
Coupling factor	k	5	%
Load Voltage	V_L	16 ± 0.5	V

Task I - V_{oc} and I_{sc}

A partially completed simulation model is provided to you in *Lab_IPT_Student.slx*. Ensure IPTQ1 is the only circuit uncommented and double click to open it.

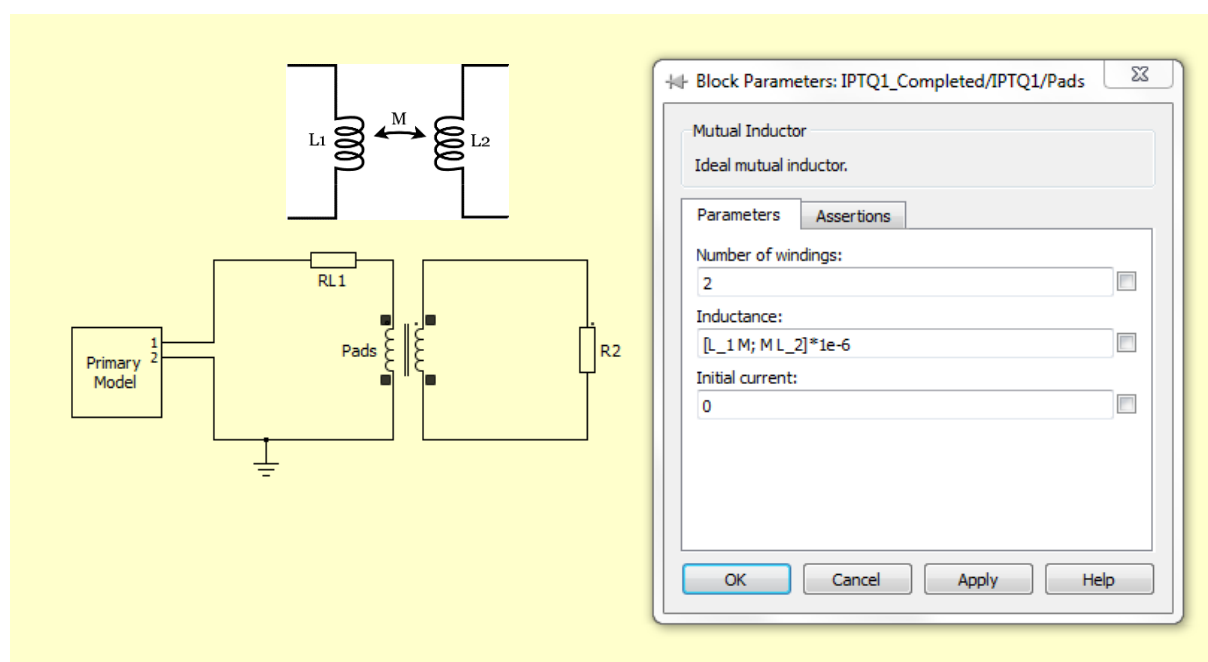
Setup the coupling between the coils in the mutual inductor model

$$\begin{bmatrix} L_1 & M \\ M & L_2 \end{bmatrix}$$

Where:

- L_1 is the self-inductance of the primary.
- L_2 is the self-inductance of the pick-up winding
- M (mutual inductance) is $k\sqrt{L_1 L_2}$ where k is the coupling factor between L_1 and L_2

Enter the values into the Block parameters for the magnetic couplers (by double clicking on pads)

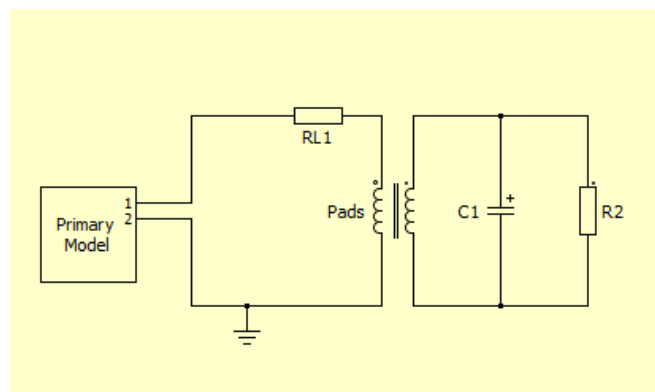


Questions

- Assuming ideal conditions, calculate V_{oc} and I_{sc} of the pick-up and verify using the simulation.
Hint: Use 0Ω or remove the resistor to simulate short circuit and open circuit conditions.
- Determine maximum uncompensated power of the pick-up and verify using the simulation.
Hint: Use maximum power transfer theory.

Task II - Compensating the Pick-up Coupler

A partially completed simulation model is provided to you, simply comment out IPTQ1 and ensure IPTQ2 is the only circuit uncommented and double click to open it. You will have to fill in the Mutual Inductor model parameters you calculated earlier before continuing.



Determine the compensation capacitance required to parallel tune the pick-up inductor and insert the value into C1.

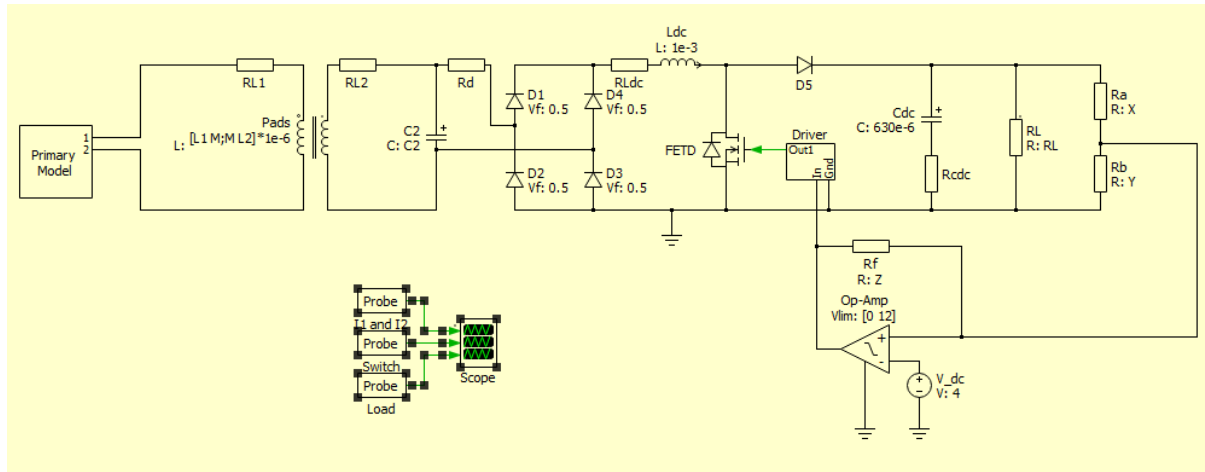
Questions

- Plot theoretical (assuming no losses) output voltage and output power for load resistance values of 2, 4, 8, 12 and 16 Ω (R_2 on x-axis and P_o/V_o on y-axis). Verify your theoretical answers using the simulation model. You are expected to do individual simulations for each load resistance value and plot the results alongside the theoretical results.
- Compare the output power of the compensated system with maximum output power of the uncompensated pick-up. Which system can deliver more power? By how much? Why?

Task III - Short Circuit Controller

As discussed in the lectures, the parallel compensated pick-up acts as an AC current source. This is rectified, filtered and regulated to produce a constant DC voltage to supply the Buck converter, which can be modelled as a load resistor. A slow-switching short circuit controller with a hysteretic controller is used to

A partially completed simulation model is provided to you, simply comment out IPTQ2 and ensure IPTQ3 is the only circuit uncommented and double click to open it. You will have to fill in the Mutual Inductor model parameters and C2 value you calculated earlier before continuing.



Questions

- Hint: Set $R_a = 10\text{ k}\Omega$

- 04/03/2018

Task IV - Impact of coupling change

The coupling factor has increased by 6x to 30% ($M = 6 \mu\text{H}$). Rerun the simulation at 12 ohms.

Questions

- a) What is the short circuit current and uncompensated volt-amps of the parallel tuned system at this coupling factor?
- b) What are the main differences between this simulation and the previous (task 3a) simulation when you observe:
 - a. Secondary coil current
 - b. Switching frequency
 - c. Duty cycle
 - d. Output voltage
 - e. Output power

You are not required to do any calculations.

- c) What practical considerations do you need to think about when designing a system with large coupling swings?

Hint: Think about your copper diameter, and losses in the switch

Optional Tasks

- a) Look at the sensitivity of the output power to variations in the value of compensation capacitor. (*Do a parameter sweep from MATLAB and plot power for different capacitor values.*)
- b) Investigate losses of the pick-up circuit. (*Thermal simulation is done separately and thus is not included in standard simulation. Resistance losses can be measured from $P_{in} - P_{out}$, but switch losses and diode losses need to be accounted for in thermal simulation.*)