ISHIKAA LUNAWAT

Stanford, CA | Mobile: +1 (650) 531-9656 | Email: ishikaa@stanford.edu | LinkedIn: Ishikaa

EDUCATION

Stanford University

Sep '23 - Present (Expected Mar '25)

MS Electrical Engineering

CGPA: 3.9/4.0

Coursework: 3D Computer Vision and Reconstruction, Virtual Reality (AR/VR), Artificial Intelligence, Machine Learning

National Institute of Technology Tiruchirappalli

Jul '19 - May '23

B.Tech. Electrical Engineering

CGPA: 9.5/10.0

Coursework: Machine Learning and Deep Learning, Industrial Automation, Modern Control Systems

TECHNICAL SKILLS

Programming Languages: Python, C/C++, JavaScript

Tools & Frameworks: PyTorch, OpenCV, Pybullet, Open3D, Trimesh, SciPy, Gazebo, Scikit Learn, OpenGL

Software: MATLAB, Visual Studio Code, Git, Anaconda, ROS2, ROS

RELEVANT EXPERIENCE

VPG Systems Intern | Apple Inc.

Jun '24 - Present

Sunnyvale, CA

- Analyzed state-of-the literature for intrinsic and extrinsic calibration of 3D optical coherence tomography system
- Designed end-to-end software/hardware integration pipeline for pose estimation, tracking and point cloud processing
- Developed geometric algorithms using differentiable optical ray tracing with end-to-end uncertainty in the sub-mm range
- Selected to present internship work to **VPG leadership**, as one of only 6 interns from a pool of 30-40 across sub-teams

Machine Learning Intern | Omnyk Inc.

Aug '22 - Mar '23

San Jose, CA (remote)

- Reviewed 5+ papers to correlate EEG/ECG data with heart health for sleep-stage classification using LSTM/RNNs
- Devised a novel deep learning architecture squeeze & excite blocks improving sleep classification accuracy by 10%

3D Perception for Robotics Researcher | Intelligent Autonomous System Laboratory

May '22 - Jul '23

TU Darmstadt, Germany

- Developed a novel semi-implicit NeRF-style neural surface rendering network to learn 3D scene representation with TSDF
- Conducted method evaluation through Pybullet simulations achieving average 6-DoF grasp test success rate of 86%
- Performed real-robot experiments on the TIAGo robot with ZED2 depth camera with a high success rate of ~ 90%

Computer Vision Intern | Pattern Recognition Laboratory

May '21 - Jul '21

IIT BHU, India

- Examined state-of-the-art literature and implemented 3+ methods to understand of effect of image static occlusions
- Designed a novel spatio-temporal model for inpainting occluded frames using 3D CNN models and embedding layers
- Enhanced person classification accuracy by 20% through key-pose embedding surpassing frame averaging methods

PROJECTS

Multi-View 3D Reconstruction using Knowledge Distillation | Manpreet Kaur (Apple)

Apr '24 - Jun '24

- Engineered a knowledge-distillation pipeline using Vision Transformers for 3D reconstruction from foundation models
- Optimized and performed hyper-parameter tuning on small student model leading to a 40x reduction in model size
- Implemented scripts for training & evaluation using L2 loss and visualization comparing 3+ architectures on Tensorboard

PUBLICATIONS

• Georgia Chalvatzaki, Ishikaa Lunawat et al. (2024) | Learning Any-View 6-DoF Robotic Grasping in Cluttered Scenes

Link

- Chelsea Finn, Ishikaa Lunawat et al. (2024) | Evaluating Real-World Robot Manipulation Policies in Simulation
- Link
- Ishikaa Lunawat et al. (2022) | SIHeDA-Net: Sensor Fusion Heterogeneous Domain Adaptation Network

<u>Link</u>