Ansi) while (low <= high)

mid = (low + high)/2;

if (aver [mid] == hey)

seturn true;

else if (aver [mid] > hey)

high = mid - I;

else low = mid + I;

?

? return false;

Ansz Iterative insertion sort:

for (inti=1/i<n; it+)

\$ j=i-1;

X = A[i];

while (j>-11 = A[j]>n)

\$ A[j+1] = A[j];

\$ A[j+1] = n;

\$ 2

Recursive Insertion Rort:

Insertion sort is online sorting because whenever a new element come, insertion sort defines its right place.

Void insertion Sort (int avoi [], int n)

sif (n<=1)

return;

insertion sort (avu, n-1); int last = avu[n-1]; j=n-2;

```
While (j = 0 & & avr [j] > last)

Savr [j+1] = avr [j];

j--;

day [j+1] = last;
```

Ans3

Bubblesort - O(n2)

Insertion Sort - O(n2)

Selection Sort - O(n2)

Merge Sort - O(n x logn)

Avich Sort - O(nlogn)

Count Sort - O(n)

By chet Sort - O(n)

Ans4 Online Sorting -> Insertion Sort

Stable Sorting -> Merge Sort, Insertion Sort,

Bubble Sort

Inplace Sorting -> Bubble Sort, Insertion Sort,

Selection Sort.

Anss Iterative Binary Search: while (low <= high)

int mid = (low + high)/2

if (awl [mid] == hey)

return true;

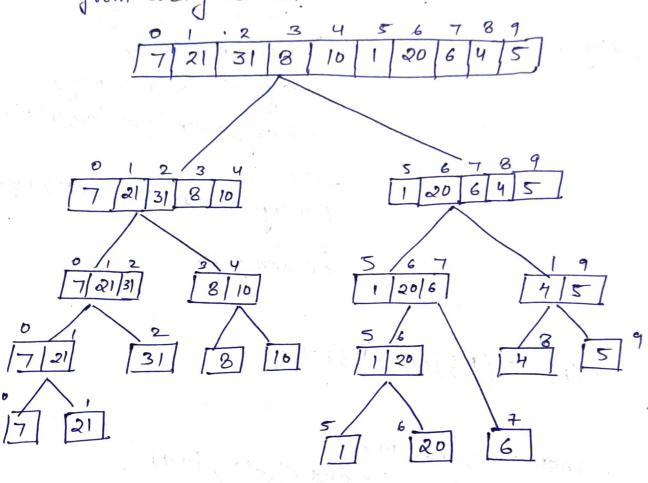
else if (awl [mid] > hey)

High = mid-1;

else low = mid+I;

```
Recursive Binary Search:
                             while (low <= high)
                              int mid = (fow + high)/2
                               if (aws [mid] = = ney)
     0 (log n)
                              return true;
                               else if (aw [mid] 7 hey)
                                Binaryseauch (au, low, mid-I)
                               Binary- Search (avor, midtl, high);
                              else
                               neturn false;
         T(n) = T(n/2) + + (n/2) + c
Ans 7
           map < int, int > m;
            for (inti=0; i< aux size(); i++)
           ig (m. find (target - avu [i]) = m. end())
                m [aux [i]] = i
                 cont « i « « " « « mp [ avu [i]] ;
Ans8 Ovicksort is the fastest general purpose sort.
  In most paratical situation, quicksout is the
  method of choice. It stability is important and
   space is available, mergesort might be best.
```

Inversion indicates - how far or close the array is from being sorted.



Inversion = 31

Ans-10

worstcase: - The worstcase occurs when the piched pivot is always an extreme (smallest or largest) element.

This happens when input away is sorted as neverse sorted and either first or last element is piched as pivot $O(n^2)$.

Best case: Best case occurs when Pirot element in the middle element as near to the middle element. O (nlogn)

Ans 11

Merge sort:
$$T(n) = 2T(n/2) + o(n)$$

Quich sort: $T(n) = 2T(n/2) + n + 1$

Basic	QuickSort	Mergesort
· Partition		Avray is parted into just 2 halves.
· Works well	splitting is done in any station. Smaller away	time on any size of
· Additional	Len (in-place)	away. More (Not -in-place)
Space	inefficient for larger	More efficient
· Sorting Method	away Iternal	External
· Stability	Notstable.	Stable

- Ans14 We will me Mergesort became me can divide the 4G1B data into 4 packets of IG1B and sont. Them seperately and combine them latter.
- Internal Souting all the data to Bort is stored in memory at all times while sorting is in progress.
- · External sorting all the data is stored outside memory and only loaded into memory in small chanks.