

# Ishika Singh

PH.D. STUDENT · COMPUTER SCIENCE · USC

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## Education

### University of Southern California

PHD IN COMPUTER SCIENCE

Advisor: Prof. Jesse Thomason | Coursework: Robotics, Grounding Natural Language

Los Angeles, CA

2021-present

### Indian Institute of Technology (IIT) Kanpur

B.TECH, DOUBLE MAJOR IN COMPUTER SCIENCE AND CHEMICAL ENGINEERING

India

2016 - 2021

## Publications

**Research Interests:** Language for Robotics, Embodied AI, Robot-Learning, Vision and Language Navigation

### Noisy Instructions Are All You Need for VLN Pretraining

WANG ZHU, **ISHIKA SINGH\***, YUAN HUANG\*, ROBIN JIA, JESSE THOMASON

In Submission

ACL'23 Submission

### Transformer Adapters for Robot Learning

ANTHONY LIANG, **ISHIKA SINGH**, KARL PERTSCH, JESSE THOMASON

Pretraining for Robot Learning workshop @ CoRL 2022

PRL-CoRL'22

[pdf]

### ProgPrompt: Generating Situated Robot Task Plans using Large Language Models

**ISHIKA SINGH**, VALTS BLUKIS, ARSALAN MOUSAVIAN, ANKIT GOYAL, DANFEI XU, JONATHAN TREMBLAY, DIETER FOX, JESSE THOMASON, ANIMESH GARG

IEEE International Conference on Robotics and Automation (ICRA) 2023

Also in LaReL workshop @ NeurIPS 2022; LangRob workshop @ CoRL 2022

ICRA'23

[arXiv] [website]

### Pre-trained Language Models as Prior Knowledge for Playing Text-based Games

**ISHIKA SINGH**, GARGI SINGH, ASHUTOSH MODI

International Conference on Autonomous Agents and Multiagent Systems 2022: Extended Abstracts

AAMAS'22

[arXiv] [code]

### Machine-Learning Techniques for Augmenting Electronic Documents with Data-Verification Indicators

NAVITA GOYAL, VIPUL SHANKHPAL, PRIYANSHU GUPTA, **ISHIKA SINGH**, BALDIP BIJLANI, ANANDHAVELU N

US Patent No. 2022/0171935 | Adobe Research

US Patent 2022

[pdf]

### Adapting a Language Model for Controlled Affective Text Generation

**ISHIKA SINGH\***, AHSAN BARKATI\*, TUSHAR GOSWAMY, ASHUTOSH MODI

International Conference on Computational Linguistics 2020 (Long Paper, Oral)

Also in Wordplay: When Language Meets Games workshop @ NeurIPS 2020

COLING'20

[arXiv] [talk] [code]

### Differentially-private Federated Neural Architecture Search

**ISHIKA SINGH\***, HAOYI ZHOU\*, KUNLIN YANG, MENG DING, BILL LIN, PENGTAO XIE

Federated Learning for User Privacy & Data Confidentiality workshop @ ICML 2020 (Long Presentation)

FL-ICML'20

[arXiv] [code]

## Experience

**GLAMOR Lab, USC** | PI: PROF. JESSE THOMASON

Aug'21 - Present | LA, CA

Research topic(s): Vision and language navigation, Multi-agent collaborative hierarchical planning, Generative data augmentation for robot learning, Data Cartography.

Simulators worked with: AI2THOR, Habitat, RL Bench, VirtualHome, Matterport 3D Simulator (topological and Habitat-based continuous)

**NVIDIA Seattle Robotics Lab** | RESEARCH INTERN W/ VALTS BLUKIS AND PROF. ANIMESH GARG

May - Aug'22 | *Seattle, WA*

Research topic(s): Long-horizon robot task planning using LLMs

Ongoing collaboration project: Adaptive task specification using logical constraints planner

**Exploration Lab, IIT Kanpur** | PI: PROF. ASHUTOSH MODI

Jan'20 - Jul'21 | *India*

Research topic(s): Text-based games, RL, Affective Language Modeling, Text Generation

**Big Data Labs, Adobe Research** | RESEARCH INTERN

Apr - July'20 | *India*

Research topic(s): Information Retrieval, Natural Language Reasoning

**UC San Diego** | PI: PROF. PENGTAO XIE

Jan - May'20 | *Remote*

Research topic(s): Differential Privacy, Theoretical ML, Federated Neural Architecture Search, Optimization

## Awards

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2021	<b>USC Graduate Fellowship</b> , for 1 year of the Ph.D. program	<i>USA</i>
2020	<b>Adobe India Women in Technology Scholarship</b> , 5 undergrad/masters awardees nation-wide	<i>India</i>
2019-20	<b>Academic Excellence Award</b> , for both majors, given to <b>top 10%</b> students in the department	<i>India</i>
2019	<b>Grand Prize</b> , worth 6,800 USD, Deloitte TechnoUtsav2.0 AI competition, <b>1<sup>st</sup></b> in 9.5K+ contestants	<i>India</i>

## Academic Service

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- Co-mentored a BS and an MS student for research projects in GLAMOR lab, on vision-language robot navigation in simulation and real-world.
- Co-organized vision-and-dialogue TEACH TATC Challenge at Embodied AI Workshop, CVPR'22.
- Served as secondary reviewer for EMNLP'21; as student volunteer for virtual organization of ICLR'20, ICML'20, etc.