

# Planets Queries I

You are playing a game consisting of  $n$  planets.  
Each planet has a teleporter to another planet (or the planet itself).

Your task is to process  $q$  queries of the form:  
when you begin on planet  $x$  and travel through  $k$  teleporters,  
which planet will you reach?

Input

The first input line has two integers  $n$  and  $q$ : the number of planets and queries.  
The planets are numbered  $1, 2, \dots, n$ .

The second line has  $n$  integers  $t_1, t_2, \dots, t_n$ : for each planet, the destination of the teleporter. It is possible that  $t_i = i$ .

Finally, there are  $q$  lines describing the queries.  
Each line has two integers  $x$  and  $k$ : you start on planet  $x$  and travel through  $k$  teleporters.

Output

Print the answer to each query.

Constraints

$1 \leq n, q \leq 2 \cdot 10^5$   
 $1 \leq t_i \leq n$   
 $1 \leq x \leq n$   
 $0 \leq k \leq 10^9$

Example

Input:

4 3  
2 1 1 4  
1 2  
3 4  
4 1

Output:

1  
2  
4

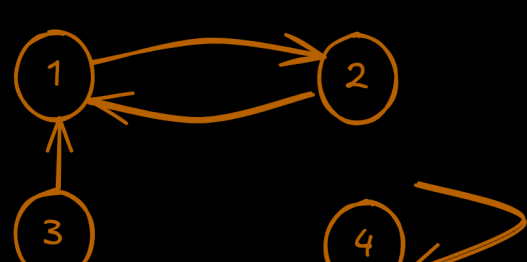
## Problem Breakdown

### Lets understand the problem first

You're given  $n$  planets. Each planet has exactly one portal that leads to another planet (possibly itself).

You're also given  $q$  queries, where each query asks:

If I start at planet  $a$ , where will I be after  $k$  portal jumps?



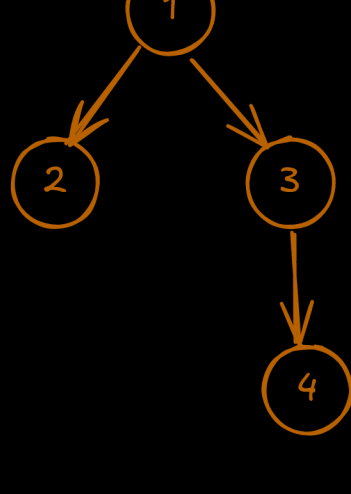
### Why Can't We Simulate?

Let's say  $k = 10^{15}$ . If we try to simulate each of the  $k$  steps naively, the time complexity will be:

$O(k * q) \rightarrow TLE$  (Time Limit Exceeded)

We need a way to "jump" through the planets faster.

### Let's look at a similar problem (k-th ancestor)



nodes	1	2	3	4
kth step	1	1	1	3
2	1	1	1	1
3	1	1	1	1

there's only one outgoing edge from every node  
so we can just use `parent[]` array to construct  
first row

Now for the second row instead of going all the way we will just ask our parent  
who is their (k-1)th ancestor and so on

Like if we want to know the 3rd ancestor of node 4 instead of doing this what we  
will do is since 3 is 4's parent then 4 will just ask 3 (its parent) what's your 2nd(k-1)  
ancestor and so on

But we fail here as  $k = 10^9$  which is just too much and we will get TLE so we need a better approach

## Binary Lifting

It's a technique that lets you jump in powers of two instead of jumping one step at a time.

Why is this useful?

Because any number  $k$  can be written as a sum of powers of 2.  
For example:

$$k = 13 = 8 + 4 + 1 = 2^3 + 2^2 + 2^0$$

So, instead of 13 individual steps, we do just 3 jumps:

Jump 8 steps

Then 4 steps

Then 1 step

Each of these jumps can be done in constant time using preprocessed data.

nodes	1	2	3	4
kth step	1	1	1	3
2	1	1	1	1
3	1	1	1	1

in rows now we will store  $2^i$  answers

$$2^3 = 8$$

## Algorithm

```
#include <bits/stdc++.h>
using namespace std;
```

```
const int LOG = 30; // Enough for k up to 1e9 (2^30 > 1e9)
vector<vector<int>> up; // up[i][j] = planet after 2^i jumps from j
```

```
void build(const vector<int>& parents) {
    int n = parents.size();
    up.assign(LOG, vector<int>(n));

    // Base case: 2^0 = 1 jump
    for (int j = 0; j < n; j++) {
        up[0][j] = parents[j];
    }

    // Fill the binary lifting table
    for (int i = 1; i < LOG; i++) {
        for (int j = 0; j < n; j++) {
            up[i][j] = up[i-1][up[i-1][j]];
        }
    }
}
```

```
up[0][i] = p[i]; // Where do you land after 2^0 = 1 jump from i
```

```
up[i][j] = up[i-1][up[i-1][j]];
```

This means:

To find the  $2^i$ -th jump from node  $j$ :

→ First jump  $2^{i-1}$  from  $j$ , then jump  $2^{i-1}$  again from that location.

Thus we compute:

```
up[1][i] = 2 jumps from i
```

```
up[2][i] = 4 jumps from i
```

```
...
```

```
up[30][i] = 2^30 jumps from i
```

```
int query(int start, int jumps) {
    int current = start;
    for (int i = 0; i < LOG; i++) {
        if (jumps & (1 << i)) { // If the i-th bit is set
            current = up[i][current];
        }
    }
    return current;
}
```

check if  $i$ th bit is set  
then jump up

```
int main() {
    ios::sync_with_stdio(false);
    cin.tie(nullptr);
```

```
int n, q;
cin >> n >> q;

vector<int> parents(n);
for (int i = 0; i < n; i++) {
    cin >> parents[i];
    parents[i]--; // Convert to 0-based
}
```

Reading input and creating parent array

```
build(parents);
```

```
while (q--) {
    int a, k;
    cin >> a >> k;
    a--; // Convert to 0-based
    cout << query(a, k) + 1 << '\n'; // Convert back to 1-based for output
}
```

Answering Queries

```
return 0;
```

```
}
```

### Time Complexity

Preprocessing (build)  $O(n * \log k)$   
Query (query)  $O(\log k)$   
Total for  $q$  queries  $O((n + q) * \log k)$

### Space Complexity

$O(n * \log k)$

### Common Questions

Why is MAX = 30?

Because  $2^{30}$  is  $\sim 10^9$ . Even  $2^{30}$  is sufficient for  $10^{15}$ .

Can this be used in tree problems too?

YES! Binary Lifting is commonly used in Lowest Common Ancestor (LCA) problems on trees.

Is this similar to matrix exponentiation?

Similar concept: breaking down large operations using powers of 2.

### Real-World Applications

Jump queries in linked structures or parent chains

LCA in trees

Range lifting in sparse structures

Time travel simulations in functional graphs