

Planets Queries I

You are playing a game consisting of n planets. Each planet has a teleporter to another planet (or the planet itself). Your task is to process q queries of the form: when you begin on planet x and travel through k teleporters, which planet will you reach?

Input
The first input line has two integers n and q : the number of planets and queries. The planets are numbered 1, 2, ..., n .

The second line has n integers t_1, t_2, \dots, t_n : for each planet, the destination of the teleporter. It is possible that $t_i = i$.

Finally, there are q lines describing the queries. Each line has two integers x and k : you start on planet x and travel through k teleporters.

Output
Print the answer to each query.

Constraints

$1 \leq n, q \leq 2 \cdot 10^5$
 $1 \leq t_i \leq n$
 $1 \leq x \leq n$
 $0 \leq k \leq 10^9$

Example

Input:
4
2 1 4
1 2
3 4
4 1

Output:
1
2
2
4

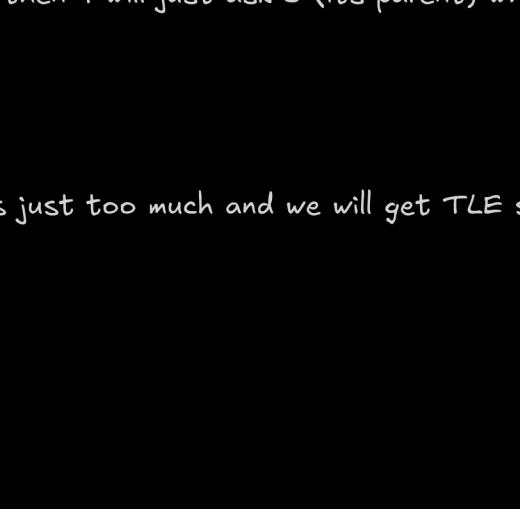
Problem Breakdown

Lets understand the problem first

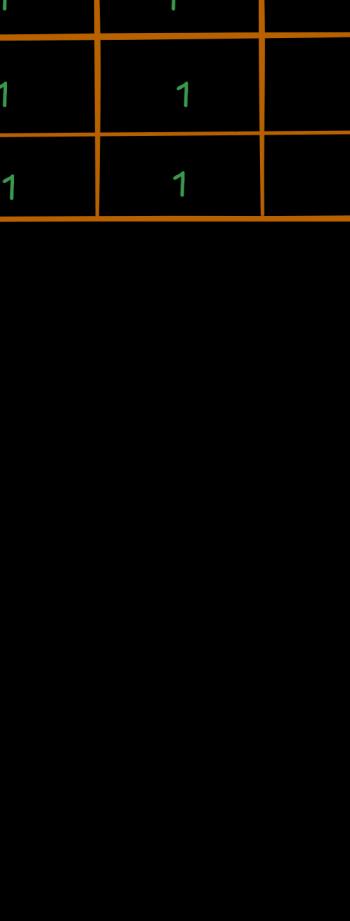
You're given n planets. Each planet has exactly one portal that leads to another planet (possibly itself).

You're also given q queries, where each query asks:

If I start at planet a , where will I be after k portal jumps?



Let's look at a similar problem (k -th ancestor)



nodes → 1 2 3 4

kth step → 2

1	1	1	1
1	1	1	1
1	1	1	1

there's only one outgoing edge from every node so we can just use parent[] array to construct first row

Now for the second row instead of going all the way we will just ask our parent who is their $(k-1)$ th ancestor and so on

Like if we want to know the 3rd ancestor of node 4 instead of doing this what we will do is since 3 is 4's parent then 4 will just ask 3 (its parent) what's your 2nd($k-1$) ancestor and so on

But we fail here as $k = 10^9$ which is just too much and we will get TLE so we need a better approach

Binary Lifting

It's a technique that lets you jump in powers of two instead of jumping one step at a time.

Why is this useful?

Because any number k can be written as a sum of powers of 2.

For example:

$$k = 13 = 8 + 4 + 1 = 2^3 + 2^2 + 2^0$$

So, instead of 13 individual steps, we do just 3 jumps:

Jump 8 steps

Then 4 steps

Then 1 step

Each of these jumps can be done in constant time using preprocessed data.

nodes → 1 2 3 4

kth step → 2

1	1	1	1
1	1	1	1
1	1	1	1

in rows now we will store 2^m answers

This means:

To find the 2^i -th jump from node j , first jump $2^{(i-1)}$ from j , then jump 2^i again from that location.

Thus we compute:

$$up[1][i] = 2 \text{ jumps from } i$$

$$up[2][i] = 4 \text{ jumps from } i$$

...

$$up[30][i] = 2^{30} \text{ jumps from } i$$

check if i th bit is set then jump up

int main() {

ios::sync_with_stdio(false);

cin.tie(nullptr);

int n, q;

vector<int> parents(n);

for (int i = 0; i < n; i++) {

cin >> parents[i];

parents[i]--;

}

build(parents);

while (q--) {

int a, k;

cin >> a >> k;

a--; // Convert to 0-based

cout << query(a, k) + 1 << '\n'; // Convert back to 1-based for output

}

return 0;

Answering Queries

Time Complexity

Preprocessing (build) $O(n \log k)$

Query (query) $O(\log k)$

Total for q queries $O((n+q) \log k)$

Space Complexity

$O(n \log k)$

Common Questions

Why is $\text{MAX} = 30$?

Because 2^{30} is $\sim 10^9$. Even 2^{30} is sufficient for 10^{18} .

Can this be used in tree problems too?

YES! Binary Lifting is commonly used in Lowest Common Ancestor (LCA) problems on trees.

Is this similar to matrix exponentiation?

Similar concept: breaking down large operations using powers of 2.

Real-World Applications

Jump queries in linked structures or parent chains

LCA in trees

Range lifting in sparse structures

Time travel simulations in functional graphs