Assignment-4

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Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cm send "Alert" to IBM cloud and display in device recent events.

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PROGRAM:
```

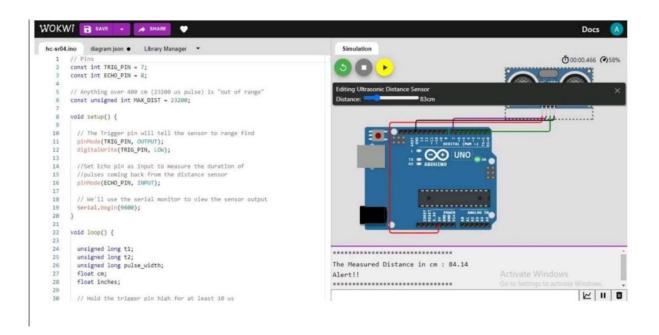
```
//Pins
const int TRIG_PIN = 7;
const int ECHO_PIN = 8;
//Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX_DIST = 23200;
void setup() {
// The Trigger pin will tell the sensor to range find
Pin Mode(TRIG_PIN, OUTPUT);
digital Write(TRIG_PIN, LOW);
//Set Echo pin as input to measure the duration of
```

```
//pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT);
// We'll use the serial monitor to view the sensor output
 Serial.begin(9600);
}
void loop() {
unsigned long t1
unsigned long t2;
 unsigned long pulse_width;
 float cm;
 float inches;
// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
// Wait for pulse on echo pin
while (digitalRead( ECHO_PIN )==0);
// Measure how long the echo pin was held high (pulse width)
 // Note: the micros() counter will overflow after-70 min
 t1 = micros();
 while (digitalRead(ECHO_PIN) == 1);
  t2= micros ();
  pulse_width = t2-t1;
 // Calculate distance in centimeters and inches. The constants
```

```
//are found in the datasheet, and calculated from the assumed speed
 // of sound in air at sea level (-340m/s)
 cm=pulse_Width / 58;
 inches = pulse width/148.0;
 // Print out results
 if (pulse_width >MAX _ DIST){
 Serial.println("Out of range");
} else {
 Serial.println("*********************************);
 Serial.print("The Measured Distance in cm: ");
 Serial.println(cm);
if( cm < 100){
    //while(true){
    Serial.println("Alert!!");
    //}
 }
 Serial.print("**********************************);
 }
 //wait at least 1000ms before next measurement
 Delay(1000);
```

Output:

1. If the distance is less than 100 cm, it alerts.



2. If the distance is more than 100 cm, it won't alert

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         // Anything over 400 cm (23200 us pulse) is "out of range"
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pinMode(TRIG_PIN, OUTPUT);
   11
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                                                                                                                   OOU UNO
   13
          //Set Echo pin as input to measure the duration of
          //pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT);
   15
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18
          // We'll use the serial monitor to view the sensor output
          Serial.begin(9600);
                                                                                                                  POWER ANALOG
   20
21
         void loop() {
   24
25
          unsigned long t1;
          unsigned long t2;
                                                                                       The Measured Distance in cm : 227.10
           unsigned long pulse_width;
                                                                                       *********************
                                                                                                                                         Activate Windows
           float cm;
           float inches;
```

3. Simulation and code execution

