Github link: https://github.com/ishu98goyal/Computer-Vision-CSC8830/tree/main/Assignment%203

PART B

Name: Ishu Goyal

Ques 5

Code: GitHub repo → Part B → Ques 5

Steps:

- 1. Read the target image containing a cluttered scene.
- 2. Read the reference image containing the object of interest.
- 3. Detect feature points in both images.
- 4. Visualize the strongest feature points found in the target image.
- 5. Visualize the strongest feature points found in the target image.
- 6. Extract feature descriptors at the interest points in both images.
- 7. Match the features using their descriptors.
- 8. Display putatively matched features.
- 9. Locate the Object in the Scene Using Putative Matches
- 10. Get the bounding polygon of the reference image.
- 11. Transform the polygon into the coordinate system of the target image.
- 12. The transformed polygon indicates the location of the object in the scene.
- 13. Display the detected object.

Output:







Ques 6

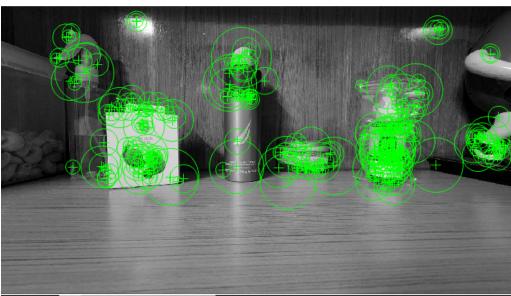
Code: GitHub repo \rightarrow Part B \rightarrow Ques 6

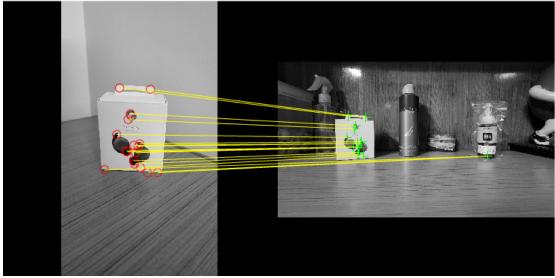
Steps:

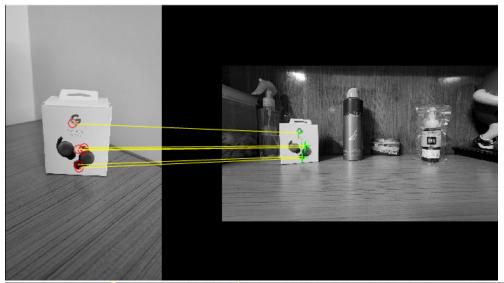
- 1. Read the target image containing a cluttered scene.
- 2. Read the reference image containing the object of interest.
- 3. Detect feature points in both images.
- 4. Visualize the strongest feature points found in the target image.
- 5. Visualize the strongest feature points found in the target image.
- 6. Extract feature descriptors at the interest points in both images.
- 7. Match the features using their descriptors.
- 8. Locate the Object in the Scene Using Putative Matches
- 9. Get the bounding polygon of the reference image.
- 10. Transform the polygon into the coordinate system of the target image.
- 11. The transformed polygon indicates the location of the object in the scene.
- 12. Display the detected object.

Output:











Ques 7

Code: GitHub repo → Part B → Ques 7

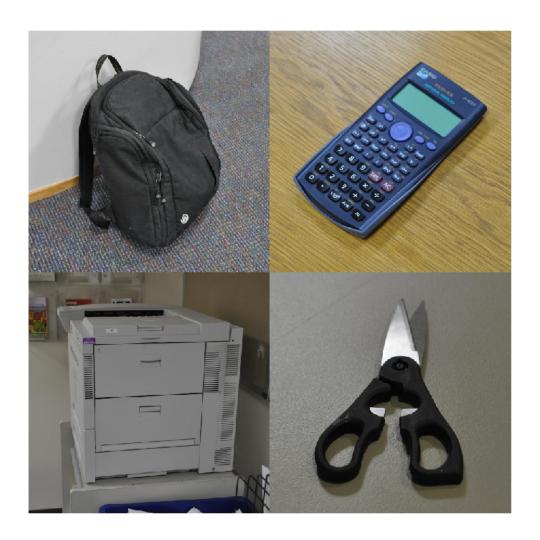
Steps:

- 1. Load Image Dataset
- 2. inspect the number of images per category, as well as category labels
- 3. Prepare Training and Validation Image Sets
- 4. Create a Visual Vocabulary and Train an Image Category Classifier
- 5. Creating Bag-Of-Features.
- 6. Encoding images using Bag-Of-Features.
- 7. Plot the histogram of visual word occurrences
- 8. Training an image category classifier for 5 categories.
- 9. Evaluate Classifier Performance on training set and on validation set
- 10. Run classification

Output:

 $tbl = 5 \times 2 \ table$

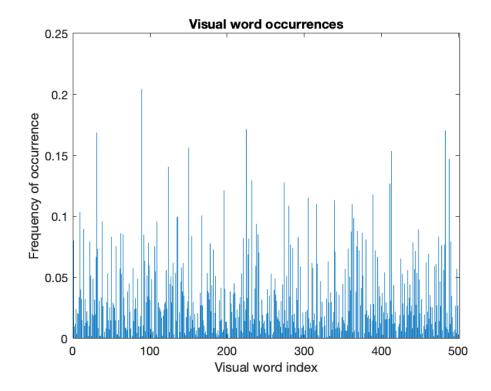
CDI - JAZ CADIC		
	Label	Count
1	backpack	10
2	calculator	10
3	pen	10
4	printer	10
5	scissors	10



Creating Bag-Of-Features.

- * Image category 1: backpack
- * Image category 2: calculator
- * Image category 3: pen
- * Image category 4: printer * Image category 5: scissors
- * Selecting feature point locations using the Grid method.
 * Extracting SURF features from the selected feature point locations.
- ** The GridStep is [8 8] and the BlockWidth is [32 64 96 128].

- * Extracting features from 30 images...done. Extracted 1875000 features.
- * Keeping 80 percent of the strongest features from each category.
- * Creating a 500 word visual vocabulary.
- * Number of levels: 1
- * Branching factor: 500
- * Number of clustering steps: 1
- * [Step 1/1] Clustering vocabulary level 1.
- * Number of features : 1500000
- * Number of clusters : 500
- * Initializing cluster centers...100.00%.
- * Clustering...completed 42/100 iterations (~4.95 seconds/iteration)...converged in 42 iterations.
- * Finished creating Bag-Of-Features Encoding images using Bag-Of-Features.
- * Encoding an image...done.



PART C

Ques 9

Code: GitHub repo → Part C

Output:

