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# Mini Shell

This is a minimal shell implementation for the Minix system.

Note: it should also work on other Unix systems, but has only been tested on Minix and Linux.

## Structure

It consists of a simple a parser on minhaMiniShell.c that can call binaries.

Four commands are made available, namely:

- nem\_eu\_nem\_de\_ninguem FILE
  This command will change permissions of the specified FILE to 0000.
- soh\_eumesmo FILE

This command will change permissions of the specified FILE to 0700.

• rodaeolhe PATH\_TO\_CMD [ARGS ...]

This command will run the specified PATH\_TO\_CMD with [ARGS ...] on the foreground, then print:

- => programa 'PATH\_TO\_CMD' retornou com código RETVAL where RETVAL is the return code of the program.
- sohroda PATH\_TO\_CMD [ARGS ...]

This command will run the specified PATH\_TO\_CMD with [ARGS ...] on the background.

Each command has its own binary.

## Building and installing

To build simply run make, and to install run make install. Binaries will be installed to /usr/local/bin.

# **Implementation**

## Error checking

Error checking is performed with errno as needed, using exit to terminate the process in case of unrecoverable errors or signals – where due, i.e. rodaeolhe

was specifically asked to return the child's exit status thus it does not comply to this.

#### Shell

The minhaMiniShell binary acts as a simple parser, with an initialization step and its main loop. As every variable is located on the stack there's no need for an after step.

Initialization The shell first creates local variables for holding user input, then we assign a simple (\*handle\_sig)(int) function as a signal handler, that should just exit the parser once it gets either SIGINT or SIGQUIT. Signal handlers are dealt with using the signal syscall.

**Parser loop** We also begin by defining local variables to hold command specific state (e.g. arguments and their count).

Then we use the write syscall to insert the prompt on the standard output (file description 1) and use the read syscall to get user input from the standard input (file descriptor 0). As the input is not formatted, we use the string library's strtok r function to parse the command and its arguments.

Note: This shell implementation fails to hold string arguments together, and can only handle simple space delimiters.

Finally, we fork the process: - The parent uses waitpid in order to wait for its children to finish. - The child uses execvp in order to execute the command provided by the user.

#### Commands

File permissions management Both nem\_eu\_nem\_de\_ninguem and soh\_eumesmo will use the chmod syscall in order to change permissions. Before calling chmod both commands will use the stat syscall in order to check whether the file exists.

**Process execution** Both rodaeolhe and sohroda use the fork and execve syscalls in order to execute the commands passed in. As we use arguments on both commands, we can simply get them using the char \*argv[] then execve directly.

On sohroda we must first explicit that we wish to ignore SIGINT and SIGQUIT signals, as we wish for the program to run on the background, thus it must not intercept those signals. As in the shell, we use the signal syscall for that, specifying SIG\_IGN as the handler.

On rodaeolhe we don't bother handling signals as the shell already does that for us, but in order to print the exit message:

## => programa 'PATH\_TO\_CMD' retornou com código RETVAL

we must use the waitpid syscall on the parent process in order to wait for the children to execute. After we wait, we can simply write the output piece by piece.

Before we can print the child's exit code we must convert it to a string, thus we've implemented a simplified itoa (which we call \_utoa) that converts an unsigned integer to a string. We know that waitpid takes in an int \*statloc that holds both the child's exit status and its termination status, thus, we use the WEXITSTATUS macro to get the exit status.

The \_utoa function works by, first, successively getting the remainder of the number divided by the base (10) and shifting this value into its ASCII equivalent (by summing it to '0'). The loop ensures we get the next digit every iteration by also dividing the number by the base. Finally, we must reverse the number as we read it backwards.

We print the exit message to the standard output for rodaeolhe using the write syscall again.