COMN - Computer Communications and Networks Assignment 2: Implement & Analyse Sliding Window Protocols

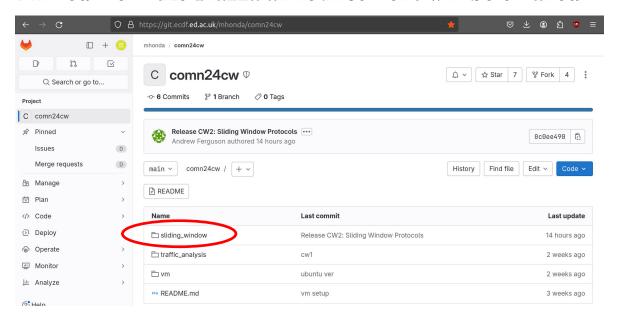
Michio Honda

With acknowledge to Andrew Ferguson and Jon Larrea
School of Informatics
University of Edinburgh
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Assignment 2 Released

- Due Monday 31th March, midday (1200 UTC / GMT)
- Available at https://git.ecdf.ed.ac.uk/mhonda/comn25cw
 - Linked from the Piazza announcement will be emailed



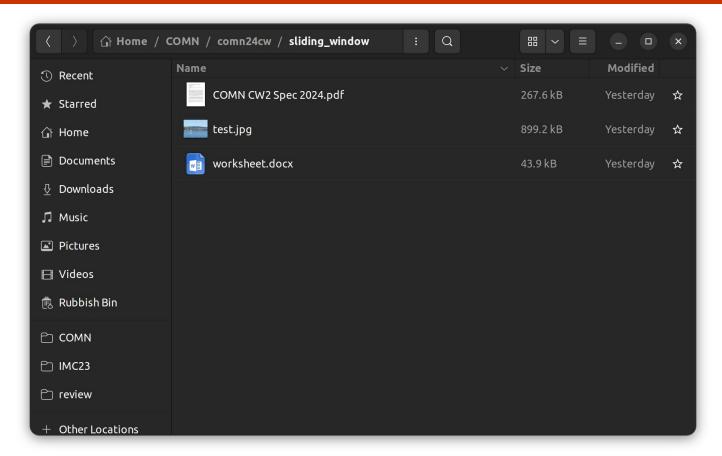


Assignment 2 Released

- "I have already cloned the git repo (e.g. to setup the VM, or attempt CW1"
 - cd comn25cw
 - git pull
 - <enter your username / password>
- "I have not yet cloned the git repo"
 - git clone https://git.ecdf.ed.ac.uk/mhonda/comn25cw.git
 - <follow the VM setup instructions in comn24cw/vm>



Assignment 2 Released





Coursework Overview

- Goal
 - Implementation and evaluation of three end-to-end reliable data transfer protocols
- Assessment: 30% of course mark
 - Part 1 (4.2%): rdt1.0
 - Part 2 (8.6%): rdt 3.0 (Stop-and-Wait)
 - Part 3 (8.6%): Go-back-N
 - Part 4 (8.6%): Selective Repeat + iPerf experiment



Reliable Data Transport Protocols

Why do we need a reliable data transport protocol?

Consider TCP (reliable) vs UDP (unreliable)









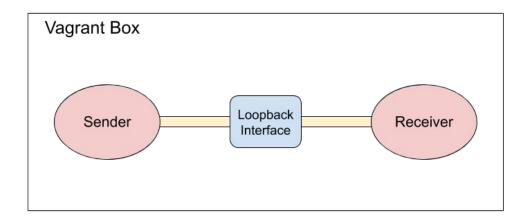
Reliable Data Transport Protocols

- TCP: Ensures each packet is received by the receiver
- UDP: sends data without caring what the receiver is doing (or even if there is one at all)

- For this assignment: "reliable" == no **lost** packets
 - Data corruption is a separate concern
 - We assume no corruption can occur
 - In the real world checksums can detect and correct errors



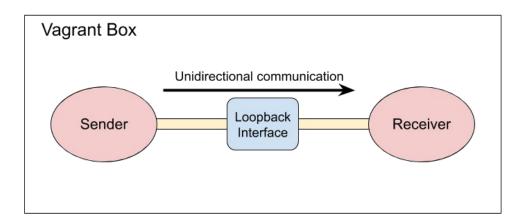
Conceptual Structure



- Linux Traffic Control (The <u>tr</u> utility)
 - Allows you to modify the packet scheduler for a given interface
 - Configuration of interface characteristics (bandwidth, delay, loss)
 - Command-line program: tc



Conceptual Structure



Sender

- Reads the file and breaks it into a number of packets
- Sends the packets to a receiver over the loopback interface which has the forwarding rules modified

Receiver

■ Receives the packets; extracts data in the packets; and saves the data in a file



Header format

- The following formats should be used across all parts
 - Exception: no ACK packets needed in part 1
- Data packet
 - (Sender to Receiver)

0	1	2	3 ~ up to 1026
16-bit sequence number		8-bit EoF flag	Data

- ACK packet
 - (Receiver to Sender)

0	1		
16-bit sequence number			



Useful Links

- ■These two links are for simulators for the go-back N / selective repeat protocols that you need to implement.
- ■They are one of the best ways to improve your understanding of how the algorithm works and how it handles edge cases.
- https://media.pearsoncmg.com/aw/ecs_kurose_compnetwork_7/cw/content/interactiveanimations/go-back-n-protocol/index.html

https://media.pearsoncmg.com/aw/ecs_kurose_compnetwork_7/cw/content/interactiveanimations/selective-repeat-protocol/index.html



Useful tools: iPerf

■ **iPerf** is a tool used to measure network performance measurement in terms of throughput and latency.

Client

```
openair@openair-1:~$ iperf -c 192.168.4.5 -i1 -t10
Client connecting to 192.168.4.5, TCP port 5001
TCP window size: 85.0 KByte (default)
  3] local 192.168.4.10 port 34562 connected with 192.168.4.5 port 5001
  ID1 Interval
                   Transfer
                                Bandwidth
  3] 0.0- 1.0 sec 11.2 MBytes 94.4 Mbits/sec
  3] 1.0- 2.0 sec 11.2 MBytes 94.4 Mbits/sec
     2.0- 3.0 sec 11.1 MBytes 93.3 Mbits/sec
     3.0- 4.0 sec 11.2 MBytes 94.4 Mbits/sec
     4.0- 5.0 sec 11.2 MBytes 94.4 Mbits/sec
     5.0- 6.0 sec 11.1 MBytes 93.3 Mbits/sec
     6.0- 7.0 sec 11.2 MBytes 94.4 Mbits/sec
     7.0- 8.0 sec 11.1 MBytes 93.3 Mbits/sec
     8.0- 9.0 sec 11.2 MBytes 94.4 Mbits/sec
     9.0-10.0 sec 11.1 MBytes 93.3 Mbits/sec
      0.0-10.0 sec 112 MBytes 93.9 Mbits/sec
```

Server

```
openair@openair-1:~$ iperf -s
Server listening on TCP port 5001
TCP window size: 85.3 KByte (default)
```



Useful tools: iPerf

```
iperf -c 192.168.4.5 -i1 -t10
iperf -c 192.168.4.5 -i1 -n 30MB
iperf -c 192.168.4.5 -i1 -F test.jpg -M 1KB
 -c \rightarrow Receiver IP address
   -i \rightarrow Interval, seconds between periodic bandwidth reports
    -t \rightarrow time in seconds to transmit for (default 10 secs)
     -n \rightarrow number of bytes to transmit (instead of -t)
    -F \rightarrow \text{input the data to be transmitted from a file}
 \blacksquare -M \rightarrow set TCP maximum segment size
```



Useful tools: tcpdump

- **tcpdump** is a data-network packet analyser tool. (Command line version of **Wireshark**).
- Due to the lack of a GUI in the COMN VM, we cannot run **Wireshark** in the VM. We can however obtain the packet capture trace from inside the VM using **tcpdump**, then examine it outside the VM on our host machine using **Wireshark**.

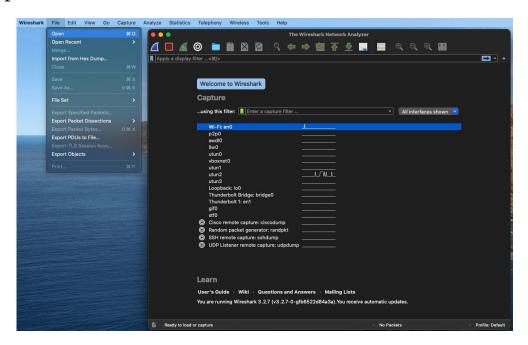
sudo tcpdump -i lo -w out.pcap

- $-i \rightarrow Interface (loopback).$
- $-\mathbf{w} \rightarrow \text{Write the raw packets to a file.}$



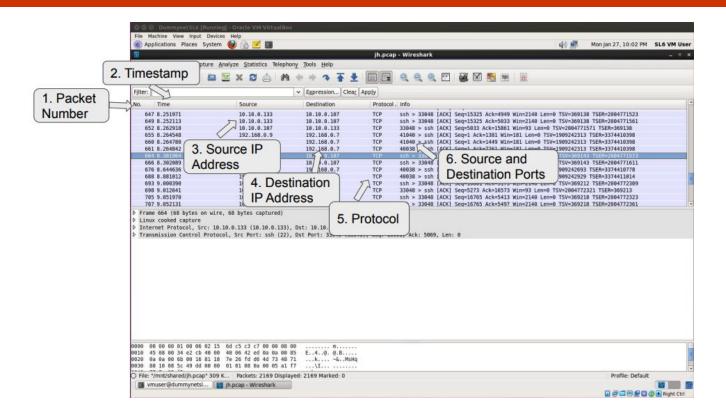
Useful tools: Wireshark

■ Wireshark is an open-source packet analyser tool that is used to capture network packets to understand and troubleshoot network behaviour.



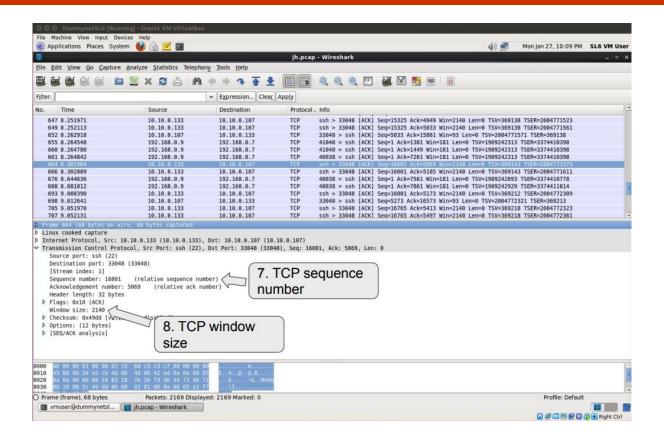


Useful tools: Wireshark





Useful tools: Wireshark





Miscellaneous

- Some useful Python libraries for the assignment:
 - sys
 - socket
 - math
 - time
 - Thread from threading
 - Lock from threading



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- Some useful Python libraries for the assignment:
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All of these are installed by default (in Python standard library). **Do not install your own modules – you will FAIL.**



Design choices for Part 3 and 4

- Both sender and receiver are implementable without multithreading
 - Definitely no need for multithreading at the receiver side
 - Multithreading may be useful for sender implementation
 - e.g. threads for (a) sending, (b) receiving (ACKs), (c) checking timeouts
- Use non-blocking socket for non-multithreaded implementation
 - setblocking(0) and select()
 - Why? Whilst waiting to receive an ACK (or a timeout) you may need to send another packet
- Many design choices for the sender are possible



How is CW2 marked?

- 1. We (the markers) manually run your code.
- 2. We check that:
 - O The file is transferred correctly (byte level).
 - O Your code did not crash.
 - Your code did not hang.
- 3. We run **tcpdump** to capture the network traffic caused by your code.
- 4. We use **WireShark** to check the captured packets to see if you have implemented the protocols correctly.



5. The worksheet is marked more conventionally using a marks scheme.

Common Mistakes

- 1. Your code does not run or crashes.
 - DO NOT INSTALL ANY ADDITIONAL PYTHON PACKAGES
 - O If in doubt, create a fresh version of the vagrant VM, and check there.
- 2. Your codes does not exit.
 - o e.g. receiver waits for the final packet with EoF flag, that packet is lost
 - O More marks lost for code that does not exit than incorrectly transferred file
- 3. Timeouts are in milliseconds
 - O Not seconds!



Less Common Mistakes

- 1. Please don't try using TCP
 - O (We will notice)



Getting Help

- Piazza
 - Ask general questions to the entire class
 - Ask code-specific questions to the instructors only
- Weekly Q+A Sessions
 - Will be focusing on CW2 for the next four weeks



Questions?

Optional: slides on multithreading (borrowed from Operating Systems lectures)



Appendix: Multithreading



What is multithreading?

- Multithreading is similar to multi-processing
- A multi-processing OS can run several processes at the same time
 - Each process has its own address/memory space
 - Separate processes do not have access to each other's memory space
- In a multithreaded application, there are several points of execution within the same memory space
 - Each point of execution is called a thread
 - Threads share access to memory



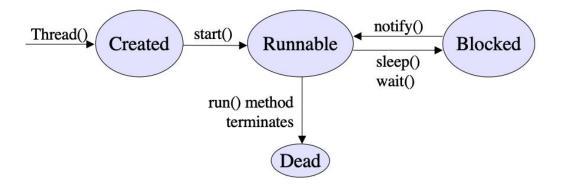
Thread support in Python

- Python threading allows you to have different parts of your program running concurrently.
- Threads are represented by a Thread object
 - A thread object maintains the state of the thread
 - It provides control methods such as start, run, sleep, join
- When an application executes, the main method is executed by a single thread
 - If the application requires more threads, the application must create them



Threads States

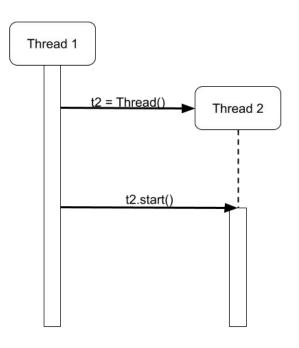
- Threads can be in one of four states as shown in the figure below
- A thread's state changes based on:
 - Control methods such as start, sleep, wait, notify
 - Termination of the run method





How does a thread run?

- The thread class has a run() method
 - run() is executed when the thread's start method is invoked
- The thread terminates if the run method terminates
 - run() method often has an endless loop to prevent thread termination
- One thread starts another by calling its start method





Creating your own thread

■ The Python standard library provides **threading**, which contains all the primitives you'll need for this assignment.

```
import threading
import time

def thread_function(name):
    print('Hello from ' + name)

for i in range(5):
    print(i)
    time.sleep(1)

if __name__ == '__main__':
    print('Before creating the thread')
    your_thread = threading.Thread(target=thread_function, args=('My Thread', ))
    print('Before running thread')
    your_thread.start()

    print('Wait for the thread to finish')
    your_thread.join()
    print('End')
```

```
|jon@macbook:~/Desktop$ python test.py
Before creating the thread
Before running thread
Hello from My Thread
Wait for the thread to finish
0
1
2
3
4
End
```

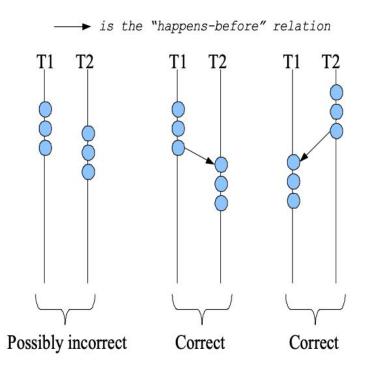


Synchronization: Critical Sections/Mutual Exclusion

- Sequence of instructions that may get incorrect results if executed simultaneously are called **critical sections**
- We also use the term **race condition** to refer a situation in which the results depends on timing
- Mutual exclusion means "not simultaneous"
 - \blacksquare A < B or B < A
 - We don't care which
- Forcing mutual exclusions between two critical section executions is sufficient to ensure the correct execution guarantees ordering
- One way to guarantee mutually exclusive executions is using locks



Critical sections





When do critical sections arise?

- One common pattern:
 - read-modify-write of a shared value (variable) in code that can be executed concurrently
- Shared variable:
 - Globals and heap-allocated variables
 - NOT local variables (which are on the stack)



Example: Shared bank account

Suppose we have to implement a function to withdraw money from a bank account:

```
int withdraw(account, amount) {
  int balance = get_balance(account);  // read
  balance -= amount;  // modify
  put_balance(account, balance);  // write
  spit out cash;
}
```

- Now suppose you and your partner share a bank account with a balance of \$100.00
 - What happened if you both go to separate ATM machines, and simultaneously withdraw \$10.00 from the account?



Example: Shared bank account

- Assume the bank's application is multi-threaded
- A random thread is assigned a transaction when that transaction is submitted

```
int withdraw(account, amount) {
  int balance = get_balance(account);
  balance -= amount;
  put_balance(account, balance);
  spit out cash;
}
```

```
int withdraw(account, amount) {
  int balance = get_balance(account);
  balance -= amount;
  put_balance(account, balance);
  spit out cash;
}
```



Interleaved schedules

■ The problem is that the execution of the two threads can be interleaved, assuming preemptive scheduling:

Execution sequence as seen by CPU

```
balance = get_balance(account);
balance -= amount;
balance = get_balance(account);
balance -= amount;
put_balance(account, balance);
spit out cash;
put_balance(account, balance);
spit out cash;
context switch
```

- What's the account's balance after this sequence?
 - Who's happy, the bank or you?



Locks

- A lock is a memory object with two operations:
 - **acquire():** obtain the right to enter the critical section
 - release(): give up the right to be in the critical section
- **acquire():** prevents progress of the thread until the lock can be acquired

