

ICP: Machine Learning Based Regression Analysis and Classification of Unmanned Ground Vehicle (UGV) Designs

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ICP GitHub URL: https://github.com/islam-mirajul/ICP-Pattern-Recognition

Project Overview

Regression Analysis

Features = Else All

Clustering and Classification

Target = 'Operational Range'

Low Performance UGV 2131 Advanced Performance UGV 1656 Standard Performance UGV 564 Moderate Performance UGV 231

Custom K-means

Classification

Target = 'Design Class' Features = Else All

Energy

Efficiency

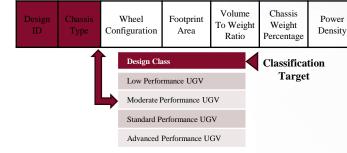
Power

Efficiency



Fig 1. Variety of Unmanned Ground Vehicles (UGVs)

Extract UVGS Performance Metrics 4582 Designs



Motor Speed Wheel Motor Battery Battery Terrain Torque Sensor Sensor To Agility Stability To To Operational Operational Control Control Adaptability Energy To Weight To Weight Coverage Power Range Weight Score Size Chassis Endurance Range Responsiveness Precision Density Density Ratio (ratio) Efficiency Ratio Ratio Ratio





Background, Baselines, and Approach

We are exploring new methods to reduce both the cost and time associated with computer-based simulations of physical systems. As part of this effort, we aim to evaluate and compare models for regression and classification tasks, focusing on minimizing errors (MAE, MSE, RMSE, R²) and maximizing performance metrics (accuracy, precision, recall, F1 score).

This approach involves exploring a variety of machine learning models, including third-party and custom models to predict and optimize simulation parameters, aiming for faster and more cost-effective simulation results.

Baseline Methods

For regression: Mean, Median, Persistence, Zero, and Decile-based predictions.

For classification: Most Frequent Class, Random Classifier, and Stratified Classifier.



Dataset Overview

Table 1. Dataset Overview

Design_ID	Chassis_Type	Wheel_Configuration	Footprint_Are a	Volume_to_W eight_Ratio	Chassis_Weig ht_Percentage	Power_Densit y	Power_Efficie ncy	Energy_Effici ency	Motor_Power _Density	Battery_Energ y_Density	Motor_to_Wei ght_Ratio	Battery_to_W eight_Ratio	Agility_Score	Stability_Fact or	Speed_to_Size _Ratio	Wheel_to_Cha ssis_Ratio	Terrain_Adapt ability (ratio)	Torque_to_We ight_Ratio	Operational_E ndurance	Operational_R ange	Control_Respo nsiveness	Control_Precis	Sensor_Cover age_Ratio	Sensor_Range_ Efficiency
1	chassis_hub_1 2WD_mini	12WD	1750	3.038194444	28.93518519	3.485714286	0.001967213	7.119594595	0.032972973	0.164079823	8.472222222	1157.407407	0.9	0.875	0.36	0.96	0.48	0.177064514	0.1215	1.0537	3529.786891	0.000118519	6.562047683	8.01
10	chassis_hub_4 WD_standard	4WD	600	1.769911504	23.59882006	2.583333333	0.001935484	6.86457529	0.035227273	0.170769231	3.657817109	4129.79351	0.745355992	1.111111111	0.1	0.8	0.4	0.15042649	0.638761062	2.13351	1882.553009	0.000122499	69.40686205	83.41666667
100	chassis_hub_8 WD_heavy_du ty	8WD	1350	2.969543147	33.84094755	2.849002849	0.0038	13.60810811	0.025	0.111213873	6.768189509	219.9661591	0.924484332	0.882352941	0.42222222	1.107692308	0.553846154	0.132746531	0.043979695	0.26182	4792.666201	0.000113475	46.27124137	55.61111111
1000	chassis_hub_8 WD_versatile	8WD	1000	2.264150943	28.30188679	4.083333333	0.000612245	1.883207071	0.025789474	0.093176471	7.396226415	415.0943396	0.730296743	0.833333333	0.075	1.2	0.6	0.399667245	0.006520755	0.02983	642.0435415	0.000117647	10.72717855	12.65

Dataset Splits

For Regression Analysis

Total Data Samples 4582

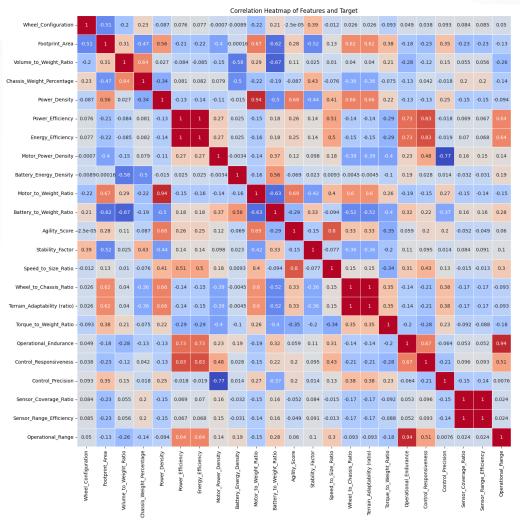
Training set size: 2749 samples - 60% Validation set size: 916 samples – 20% Testing set size: 917 samples – 20%

For Classification- Stratified Shuffle Split

Design Class	Training	Validation	Testing	Total
Low Performance UGV	1278	426	427	2131
Advanced Performance UGV	994	331	331	1656
Standard Performance UGV	338	113	113	564
Moderate Performance UGV	139	46	46	231
Total	2749	916	917	4582
Percentage	60.00%	19.99%	20.01%	100%



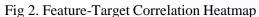
Data Analysis for Regression



Feature Importance Operational Endurance Battery Energy Density -Motor Power Density Torque to Weight Ratio Energy Efficiency Motor to Weight Ratio Footprint Area Control Precision Power Efficiency Speed to Size Ratio Chassis Weight Percentage Volume to Weight Ratio Stability Factor Sensor Coverage Ratio Sensor Range Efficiency Control Responsiveness Battery to Weight Ratio Agility Score Power Density Terrain_Adaptability (ratio) Wheel Configuration Wheel to Chassis Ratio 0.0 0.6 importance

Fig 3. Top Features by Importance using Random Forest Regressor





Methodology - Regression Analysis

Sklearn Models

Support Vector Regression

Random Forest Regressor

Gradient Boosting Regressor

Lasso Regression

Ridge Regression

Custom Model

Custom Bayesian Linear Regression

Baselines Custom Methods

Mean Prediction

Median Prediction

Persistence Model (Last Value Prediction)

Zero Prediction

Decile-based Prediction: This predicts the decile (10% intervals) of the target values

Performance metrics are calculated:

Mean Absolute Error (MAE)

Mean Squared Error (MSE)

Root Mean Squared Error (RMSE)

R-squared (R2)

Performance Visualizations:

Actual vs. Predicted values for each model



Results-Regression Analysis

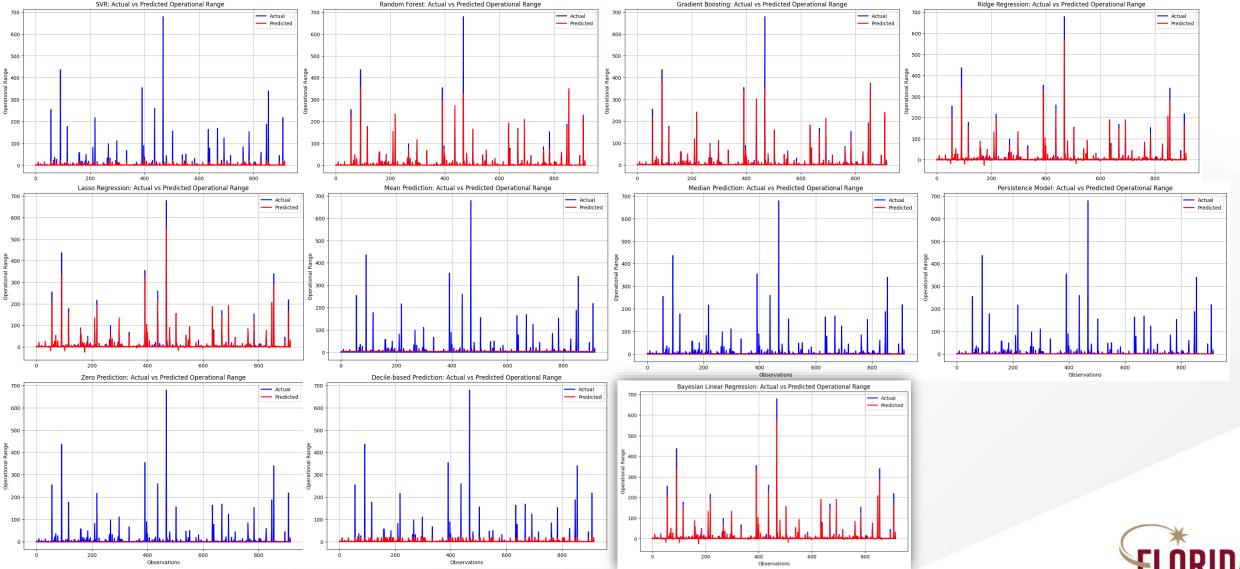
Table 2: Model Performance Metrics Comparison

Custom Bayesian Linear Regression is the best overall performer

Model Group	Model Name	MAE	MSE	RMSE	R ²	
Sklearn	SVR	5.5754	1366.6779	36.9686	0.0794	
Sklearn	Random Forest	1.3521	173.0158	13.1535	0.8834	
Sklearn	Gradient Boosting	1.4401	141.6666	11.9024	0.9046	
Sklearn	Ridge Regression	2.6183	64.7935	8.0494	0.9564	
Sklearn	Lasso Regression	2.4324	69.5298	8.3385	0.9532	
Custom Model	Bayesian Linear Regression	2.5805	64.7743	8.0482	0.9564	
Baselines (Custom)	Mean Prediction	10.1794	1487.9680	38.5742	-0.0024	
Baselines (Custom)	Median Prediction	6.9908	1532.2448	39.1439	-0.0322	
Baselines (Custom)	Persistence Model	7.2899	1521.5258	39.0067	-0.0250	
Baselines (Custom)	Zero Prediction	7.0190	1533.7396	39.1630	-0.0332	
Baselines (Custom)	Decile-based Prediction	5.4560	1333.9443	36.5232	0.1014	



Results-Regression Analysis cont...







Clustering & Classification

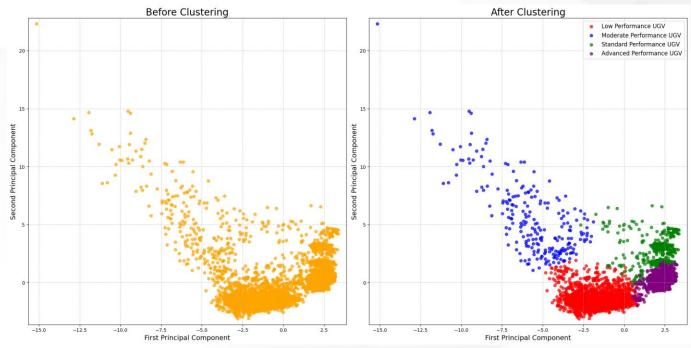


Fig 5. PCA Visualization of UGV Performance Classes: Pre- and Post-Clustering

- PCA (Principal Component Analysis) is used here to reduce the dimensionality of the data, making it easier to visualize and interpret.
- Convex Hulls define the outer boundary of each class, showing the region containing all points. Ellipses visualize the spread and orientation of the class data, reflecting the distribution and variance within the 2D PCA space.

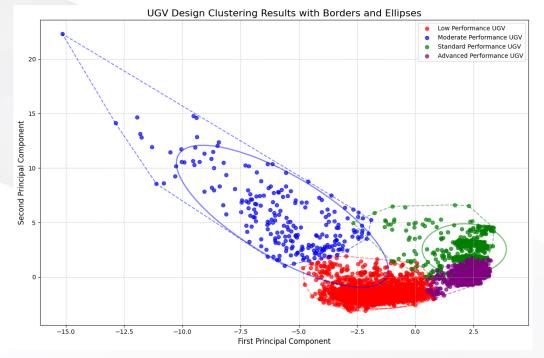


Fig 6. UGV Design Clustering with Convex Hulls and Ellipses in 2D PCA Space

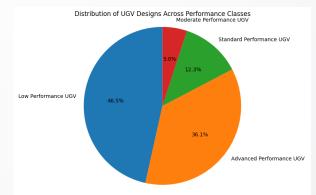


Fig 7. Pir Chart Distribution of UGV Designs

Low Performance UGV 2131 Advanced Performance UGV 1656 Standard Performance UGV 564 Moderate Performance UGV 231



Methodology - Classification

Custom Models

- 1. Custom Linear Discriminant Analysis (LDA)
- 2. Custom Quadratic Discriminant Analysis (QDA)

Sklearn Models

- 1. Support Vector Machine Classifier
- 2. Gaussian Process Classifier
- 3. Random Forest Classifier
- 4. Gradient Boosting Classifier
- 5. Fisher's Linear Discriminant
- 6. Logistic Regression
- 7. Perceptron
- 8. Naive Bayes Classifier
- 9. Stochastic Gradient Descent Classifier

Baseline Sklearn Models

- 1. Baseline Model (Most Frequent Class)
- 2. Random Classifier
- 3. Stratified Classifier

Performance Metrics

Classification Report

- 1. Accuracy
- 2. Precision (weighted average)
- 3. Recall (weighted average)
- 4. F1 Score (weighted average)

Confusion Matrix



Results-Classification

Table 3. Model's Performance Comparison

Model	Туре	Accuracy	Precision	Recall	F1 Score	
Custom LDA	Custom Models	1.0000	1.0000	1.0000	1.0000	
Custom QDA	Custom Models	1.0000	1.0000	1.0000	1.0000	
Baseline Model (Most Frequent Class)	Baseline Sklearn Models	0.4656	0.2168	0.4656	0.2959	
Random Classifier	Baseline Sklearn Models	0.2290	0.3385	0.2290	0.2591	
Stratified Classifier	Baseline Sklearn Models	0.4057	0.4030	0.4057	0.4043	
Support Vector Machine	Sklearn Models	0.9956	0.9956	0.9956	0.9956	
Gaussian Process Classifier	Sklearn Models	0.6325	0.5689	0.6325	0.5838	
Random Forest Classifier	Sklearn Models	0.9989	0.9989	0.9989	0.9989	
Gradient Boosting Classifier	Sklearn Models	0.9989	0.9989	0.9989	0.9989	
Fisher's Linear Discriminant	Sklearn Models	0.9673	0.9682	0.9673	0.9667	
Logistic Regression	Sklearn Models	0.9117	0.9116	0.9117	0.9106	
Perceptron	Sklearn Models	0.7274	0.6703	0.7274	0.6848	
Naive Bayes Classifier	Sklearn Models	0.9477	0.9514	0.9477	0.9476	
Stochastic Gradient Descent Classifier	Sklearn Models	0.7361	0.6830	0.7361	0.6951	

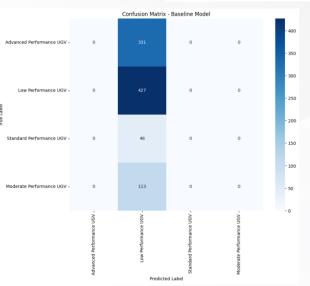
Custom LDA and Custom QDA both have perfect scores (Accuracy: 1.0000, Precision: 1.0000, Recall: 1.0000, F1 Score: 1.0000), making them the best performers.

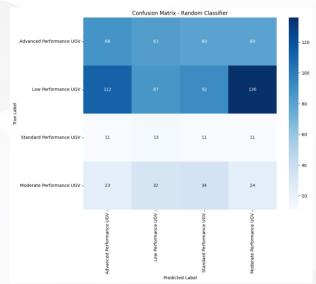


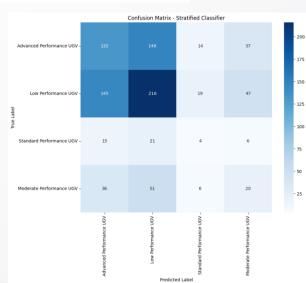
Results-Classification cont...



Fig 8. Confusion Matrix for custom models and baseline sklearn models









Results-Classification cont...

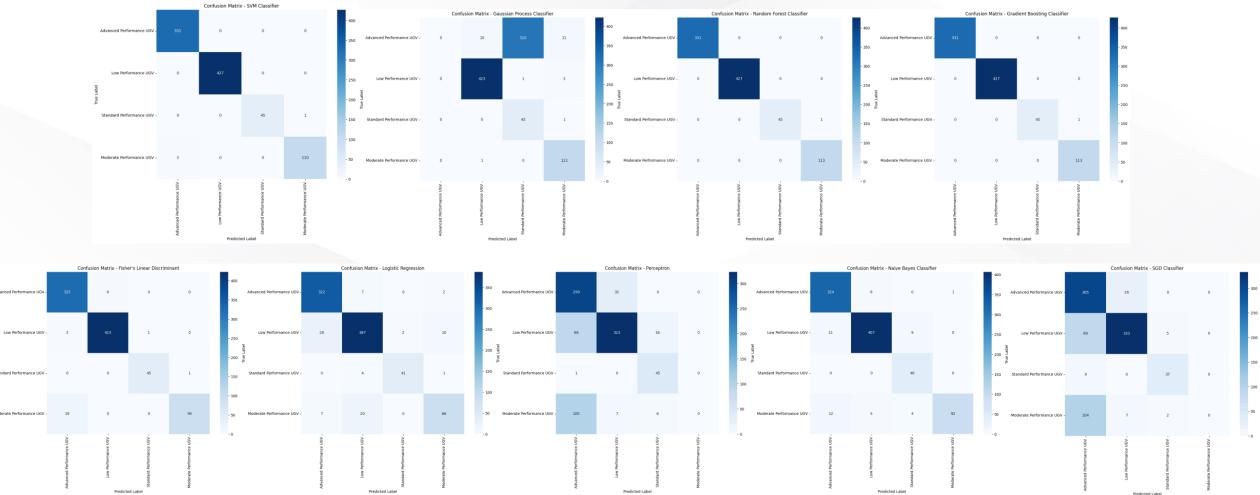


Fig 9. Confusion Matrix for sklearn models



Conclusions

For both regression and classification tasks, custom implementation models performed the best.

Regression Task: The Bayesian Linear Regression model achieved competitive results, with a high *R*2 score of 0.9564 and an RMSE of 8.0482, comparable to Ridge Regression. Among third-party models, Gradient Boosting performed slightly better, but the custom model remains highly effective.

Classification Task: Custom models, particularly Custom LDA and Custom QDA, achieved perfect performance with an accuracy, precision, recall, and F1 score of 1.0000, outperforming all other models. Among third-party models, Random Forest Classifier and Gradient Boosting Classifier achieved near-perfect performance (~99.89%), making them strong contenders.



Thank you!

