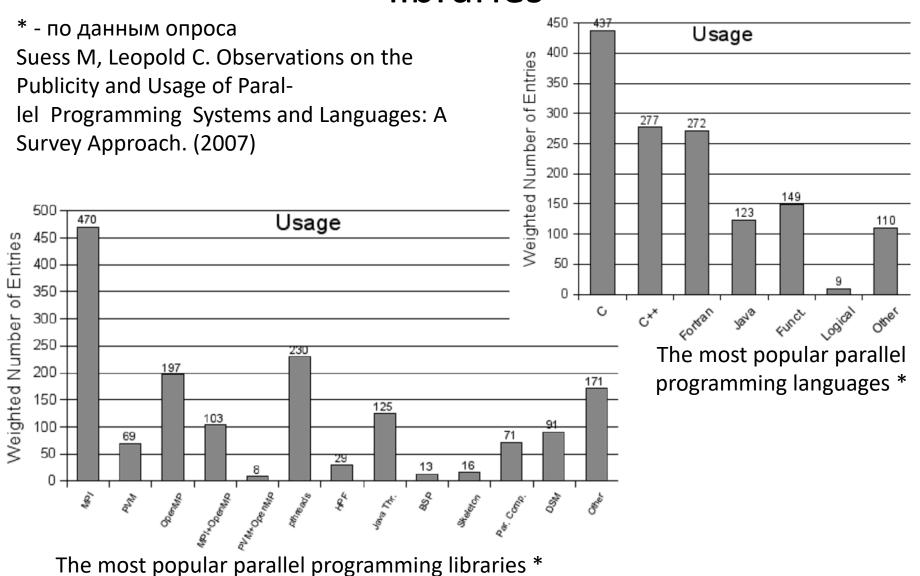
Introduction into the Posix threads (Pthreads)

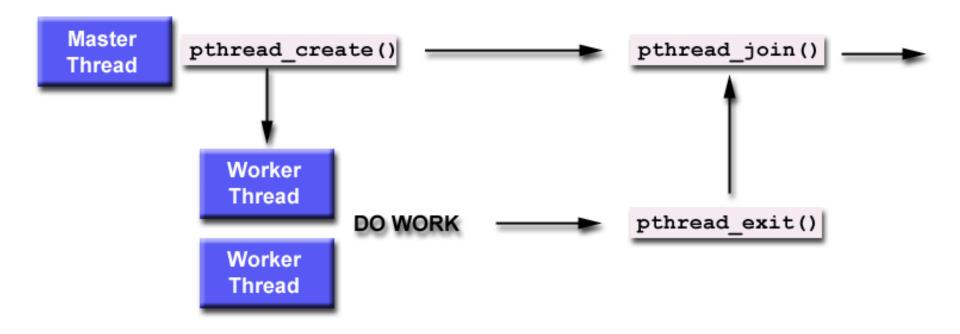
Role and place of parallel languages and libraries



Programming with Posix threads

- Thread is very similar to a process. It is also called as lightweight process.
- The main differences from a process. Process has its own memory area, independent of other processes, table of open files, current directory, and other kernel-level information. All threads, belonging to the same process, have all these entities in common.
- The Posix standard was adopted in 1995 and exists on UNIX and Linux-like systems (until 1995 it was only on UNIX-like systems). Almost all existing operating systems are compatible or practically compatible with this standard: BSD, Mac OS, Solaris, etc. There is an implementation of the corresponding libraries for Windows OS.
- In addition to Posix threads, there are the following common programming implementations for systems with shared memory (SMP symmetric multiprocessing): OpenMP, Windows threads.

Scheme of a parallel program using Pthreads



Compilation and running

Compilation:

```
gcc file_name.c -lpthread -lrt
(by default the executable is named "a.out")
```

Running:

```
./a.out – as usual
```

1st program, part 1 thread creation

```
#include<stdio.h>
#include<stdlib.h>
#include<pthread.h> // pthread header file
int main(int argc, char *argv[]){
int param;
int rc;
void *arg;
pthread_t pthr; // data type pthread
1) rc = pthread create(&pthr, NULL, start func, NULL); // thread
creation, simplified call
2) rc = pthread_create(&pthr, NULL, start_func, (void*) &param);
```

1st program, part 2

```
/* thread finishes when it exits the start_func function. If you
need to get the return value of a function, then you need to use
*/
```

- 1) pthread_join(pthr, NULL); // accept nothing by default
- 2) pthread_join(pthr, &arg); // write the address of the returned variable into &arg
- // end of the main function

1st program, part 3 thread's function

```
/* Thread's work function (thread's life area) */
void* start_func(void* param){
   int *local;
   local = (int*) param;
   1) pthread exit( NULL); // used by default
   2) pthread_exit( (void*) & arg); // it is used if it is necessary to
terminate the execution of a thread earlier with a return value. It is
possible to use NULL as an argument, the arg variable must be
dynamically allocated or have a static memory class
   3) return NULL; // or like this
} // at the moment of exiting the start_func function, thread releases its
resources (dies)
```

1st program, part 4 semaphores

Thread synchronization mechanism. There are several mechanisms for organizing access to the critical section.

Critical section is a piece of program code that contains a shared resource and is only accessible to one thread.

An N-dimensional semaphore takes values from 0 to N, we will only use a binary semaphore that takes values 0 and 1

1st program, part 5 semaphores

```
#include<semaphore.h>
sem t sem; // semaphore declaration – as a global variable
int main(int argc, char *argv[]){
   sem_init (&sem, 0, 1); // semaphore initialization
                    initial value
       attribute
  sem_destroy(&sem); // releasing of the semaphore
  return 0;
```

1st program, part 6 semaphores

```
void* start_func(void* param){
       int val;
       sem_wait(&sem); // decreases the semaphore value by 1
Critical section
                       if sem = 0 at the time of this function
                       execution, then thread waits
                       // actions on a shared variable
        sem_post(&sem); // increases the semaphore value by 1
     sem getvalue(&sem, &val); // checking the semaphore value
     return NULL;
```

Some software design

```
// several threads creation
#define NUM THREADS
int main (int argc, char *argv[])
  pthread t pthr[NUM THREADS];
  void *arg;
  for(i = 0; i < NUM THREADS; i++){
     rc = pthread_create(&pthr[i], NULL, start_func, NULL);
     if (rc) printf("ERROR; return code from pthread_create() is %d \n", rc);
  for(i = 0; i < NUM_THREADS; i++){
     rc = pthread join(pthr[i], &arg);
      printf("value from func %d \n", *(int*)arg); // example
     if (rc) printf("ERROR; return code from pthread_join() is %d \n", rc);
```

Determining the running time of a parallel program

```
#include<time.h> // header file containing types and functions for working
with date and time
struct timespec begin, end; // requires key -lrt!
double elapsed;
clock gettime(CLOCK REALTIME, &begin); /* returns a reference to a record
                                  of type timespec, which is declared in
                                  time.h and has fields:
                                  time t tv sec; – seconds,
                                  long tv_nsec; – nanoseconds.
... // threads work here
clock_gettime(CLOCK_REALTIME, &end);
elapsed = end.tv_sec - begin.tv_sec; // time in seconds
elapsed += (end.tv nsec - begin.tv nsec) / 1000000000.0; // add time down
to nanoseconds
```

On the function of generating random numbers 1

```
The rand () function is not thread-safe. It looks like this: unsigned int next = 1;

/* rand - return pseudo-random integer on 0..32767 */
int rand(void) {
    next = next*1103515245 + 12345;
    return (unsigned int)(next/65536) % 32768;
}

/* srand - set seed for rand() */
void srand(unsigned int seed) {
    next = seed;
}
```

and deals with the global intermediate variable next, which changes every time each thread is called. This intermediate value is stored in a static memory area, that is, it is shared. In addition to the non-repeatability of the result, this leads to a strong slowdown in the program.

On the function of generating random numbers 2

An analogue of the rand () function is supplied with the Posix standard library, but already thread-safe. Its appearance:

```
/* rand_r - a reentrant pseudo-random integer on 0..32767 */
int rand_r(unsigned int *nextp) {
   *nextp = *nextp * 1103515245 + 12345;
   return (unsigned int)(*nextp / 65536) % 32768;
}
```

that is, the function deals with a thread local variable to be declared in the thread handler function. Such a function is called reentrant. Since the intermediate value is already a local variable, there is no access conflict.

In a program:

```
int x_k, y_k, z_k;

x = ((float)rand_r(&x_k) / RAND_MAX) * (i_final - i_init) + i_init;
y = (float)rand_r(&y_k) / RAND_MAX;
z = (float)rand_r(&z_k) * ZO / RAND_MAX;
```