povm

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# 1 Unambiguous binary state discrimination

Given the states:

$$|\Psi_0> = \cos(\theta)|0> + \sin(\theta)|1> |\Psi_1> = \cos(\theta)|0> -\sin(\theta)|1>$$

where:  $*\theta \in [0, \pi] * \eta_0$ : probability  $|\Psi_0\rangle$  to be chosen  $*\eta_1$ : probability  $|\Psi_1\rangle$  to be chosen with probability  $\eta_0 * |\Psi_1\rangle$  is chosen with probability  $\eta_1$  and the POVM:

$$\pi_0 = \mu_0 | \Psi_1^{\perp} > < \Psi_1^{\perp} | \pi_1 = \mu_1 | \Psi_0^{\perp} > < \Psi_0^{\perp} | \pi_2 = \mathbb{1} - \pi_0 - \pi_1$$

subject to the constraints:

$$\mu_0 \ge 0 \mu_1 \ge 0 \pi_2 \ge 0$$

**Proof** that the minimum probability of error, given by  $P(\pi_2)$ , is:

$$P(\pi_2)^{min} = 2\sqrt{\eta_o \eta_1} < \Psi_0 | \Psi_1 > = 2\sqrt{\eta_o \eta_1} \cos(2\theta)$$

#### 1.1 Demostration

#### 1.1.1 Some results

Some results that will be used:

$$|\Psi_0^{\perp}> = \sin(\theta)|0> -\cos(\theta)|1> |\Psi_1^{\perp}> = \sin(\theta)|0> +\cos(\theta)|1> \\ <\Psi_0^{\perp}|\Psi_1> = <\Psi_1^{\perp}|\Psi_0> = \sin(2\theta)|1> \\ <\Psi_0^{\perp}|\Psi_0> = \sin(2\theta)|1> \\ <\Psi_$$

where:  $^*<\Psi_0^{\perp}|\Psi_0>=(\sin(\theta)<0|-\cos(\theta)<1|)(\cos(\theta)|0>+\sin(\theta)|1>)=\sin(\theta)\cos(\theta)<0|0>+\sin^2(\theta)<0|1>-\cos^2(\theta)<1|0>-\cos(\theta)\sin(\theta)<1|1>=0 *<\Psi_1^{\perp}|\Psi_1>=(\sin(\theta)<0|+\cos(\theta)<1|)(\cos(\theta)|0>-\sin(\theta)|1>)=0 *<\Psi_0^{\perp}|\Psi_1>=(\sin(\theta)<0|-\cos(\theta)<1|)(\cos(\theta)|0>)=\sin(\theta)<0|0>+\cos(\theta)<1|)(\cos(\theta)|0>>\cos(\theta)<0|0>+\cos(\theta)<1|1>=\sin(\theta)\cos(\theta)<0|0>+\cos(\theta)<1|1>=\sin(\theta)\cos(\theta)<0|0>+\cos(\theta)<1|)(\cos(\theta)|0>+\sin(\theta)<0|0>+\sin(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0|0>+\cos(\theta)<0$ 

The probability distribution  $P(\pi_i|\Psi_i)$ :

	$\Psi_0$	$\Psi_1$
$\pi_0$	$\mu_0 \sin^2(2\theta)$	0
$\pi_1$	0	$\mu_1 \sin^2(2\theta)$
$\pi_2$	$1 - \mu_0 \sin^2(2\theta)$	$1 - \mu_1 \sin^2(2\theta)$

where: \* 
$$P(\pi_0|\Psi_0) = tr(\pi_0|\Psi_0 > < \Psi_0|) = tr(\mu_0|\Psi_1^{\perp} > < \Psi_1^{\perp}|\Psi_0 > < \Psi_0|) = \mu_0| < \Psi_1^{\perp}|\Psi_0 > |^2 = \mu_0 \sin^2(2\theta)$$
 \*  $P(\pi_1|\Psi_1) = tr(\pi_1|\Psi_1 > < \Psi_1|) = tr(\mu_1|\Psi_0^{\perp} > < \Psi_0^{\perp}|\Psi_1 > < \Psi_1|) = \mu_1| < \Psi_0^{\perp}|\Psi_1 > |^2 = \mu_1 \sin^2(2\theta)$ 

## 1.1.2 Calculate $P(\pi_2)$

$$P(\pi_2) = P(\pi_2|\Psi_0)P(\Psi_0) + P(\pi_2|\Psi_1)P(\Psi_1) = \eta_0(1 - \mu_0\sin^2(2\theta)) + \eta_1(1 - \mu_1\sin^2(2\theta)) = \eta_0 + \eta_1 - (\eta_0\mu_0 + \eta_1\mu_1)\sin^2(2\theta)$$

This is the quantity we want to minimize. We know the quantities  $\eta_0$ ,  $\eta_1$  and  $\theta$  and the unknown are  $\mu_0$  and  $\mu_1$  and we want to find the values that minimize this function and this minimum value.

The next step is to try to find a relation between  $\mu_0$  and  $\mu_1$  using the constraints we know and specially the fact that  $\pi_2 \geq 0$ 

### 1.1.3 Use the fact $\pi_2 \geq 0$

The fact that  $\pi_2 \geq 0$  means its eigenvalues are  $\geq 0$ 

$$\pi_2 = \mathbb{X} - \pi_0 - \pi_1 = \mathbb{X} - \mu_0 |\Psi_1^{\perp} > <\Psi_1^{\perp}| - \mu_1 |\Psi_0^{\perp} > <\Psi_0^{\perp}| = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \mu_0 \begin{pmatrix} \sin(\theta) \\ \cos(\theta) \end{pmatrix} \left(\sin(\theta) & \cos(\theta)\right) - \mu_1 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) & \cos(\theta)\right) = \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) & \cos(\theta)\right) - \mu_1 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) & \cos(\theta)\right) + \mu_2 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) & \cos(\theta) \end{pmatrix} \left(\sin(\theta) & \cos(\theta)\right) + \mu_3 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) & \cos(\theta) \end{pmatrix} \left(\sin(\theta) & \cos(\theta)\right) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} 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\begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) & \cos(\theta) \end{pmatrix} \left(\sin(\theta) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \right) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \right) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \right) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \right) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \right) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \right) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \right) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \right) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \right) + \mu_4 \begin{pmatrix} \sin(\theta) \\ -\cos(\theta) \end{pmatrix} \left(\sin(\theta) + \mu_4 \begin{pmatrix} \sin(\theta)$$

If we compute the eigenvalues:

$$\lambda_1 = \frac{1}{2} \left( -\sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right) \ge 0 \\ \lambda_2 = \frac{1}{2} \left( \sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right) \ge 0 \\ \lambda_1 = \frac{1}{2} \left( \sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right) \ge 0 \\ \lambda_2 = \frac{1}{2} \left( \sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right) \ge 0 \\ \lambda_2 = \frac{1}{2} \left( \sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right) \ge 0 \\ \lambda_3 = \frac{1}{2} \left( \sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right) \ge 0 \\ \lambda_4 = \frac{1}{2} \left( \sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right) \ge 0 \\ \lambda_4 = \frac{1}{2} \left( \sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right) \ge 0 \\ \lambda_4 = \frac{1}{2} \left( \sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right) \ge 0 \\ \lambda_5 = \frac{1}{2} \left( \sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right) \ge 0 \\ \lambda_5 = \frac{1}{2} \left( \sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right) \ge 0 \\ \lambda_5 = \frac{1}{2} \left( \sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} + 2 - (\mu_0 + \mu_1) \right)$$

We can see easily the relation between  $\mu_0$  and  $\mu_1$  if we write the inequalities as

$$-A + B \ge 0A + B \ge 0$$

from what we easily deduce that the only possibility is

$$A = B$$

and that means in our case:

$$\sqrt{\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2} = 2 - (\mu_0 + \mu_1)\mu_0^2 + 2\mu_0\mu_1\cos(4\theta) + \mu_1^2 = 4 + \mu_0^2 + \mu_1^2 + 2\mu_0\mu_1 - 4\mu_0 - 4\mu_12\mu_0\mu_1\cos(4\theta) = 4 + 2\mu_0^2 + \mu_1^2 + 2\mu_0^2 + 2\mu$$

Now let's replace this relation in our expression for  $P_{\pi_2}(\mu_0, \mu_1)$  so we get an expression depending only of one variable:

$$P_{\pi_2}(\mu_0, \mu_1) = 1 - (\eta_0 \mu_0 + \eta_1 \mu_1) \sin^2(2\theta) = 1 - \left(\eta_0 \left(\frac{2 - 2\mu_1}{\mu_1 \cos(4\theta) - \mu_1 + 2}\right) + \eta_1 \mu_1\right) \sin^2(2\theta) = \left(\frac{\mu_1 \cos(4\theta) - \mu_1 + 2 + \mu_1 \sin^2(2\theta)}{\mu_1 \cos(4\theta) - \mu_1 + 2}\right) \sin^2(2\theta) = \left(\frac{\mu_1 \cos(4\theta) - \mu_1 + 2 + \mu_1 \sin^2(2\theta)}{\mu_1 \cos(4\theta) - \mu_1 + 2}\right) \sin^2(2\theta) = \left(\frac{\mu_1 \cos(4\theta) - \mu_1 + 2 + \mu_1 \sin^2(2\theta)}{\mu_1 \cos(4\theta) - \mu_1 + 2}\right) \sin^2(2\theta)$$

So get get an expression that only depends of one parameter  $\mu_1$ . Now the nest steps is to find the minimum of this function with

$$\frac{\partial P_{\pi_2}(\mu_1)}{\partial \mu_1} = 0$$

Once we resolve this equation, we get a value for  $\mu_1^{min}$  that we can verify if it is in fact a minimum using its second derivative. Once we get it we replace in  $P_{\pi_2}$  to get the desired result:

$$P(\pi_2)^{min} \equiv P_{\pi_2}(\mu_1^{min}) = 2\sqrt{\eta_o \eta_1} \cos(2\theta)$$