Bhumi Gupta - EN19cs301094 Page No. (Assignment - V) 8.1 what is Turing Machine? Explain different types of living machine in shoul Turing Machine was invented by Alan Turing in 1936 and it is used to accept Recursive Enumenable languages. A turing machine consists of a tape of infinite length on which read and writes operation can be performed. The tape consists of infinite cells on which each cell either contains input symbol on a special symbol called blank, It also consists of a head pointer which points to cell currently being read and it can more in both directions. al a2 an b b b b b R/w head Can move left or white. finite | Read white | control head The different types of turing machines are: 1) Twing machines with 2-dimensional tapes - They have one read write head, one finite control and one two-dimensional take 2) Puring machines with multiple tapes - They have one finite control and over one take with a read-write head for each take. 3) Turing machines with multiple heads - They have one finite control one tape, and over one read-write head 1) Puring machines with infinite take - They have one finite control and one take entending in both directions infinitely. 2) Nondeterministic turing machines - They have the ability to perform any action from a given set of actions reather than performing a definite predetermined actions.

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Design a TM that accepts the language of odd integer is written in binary.

Any The difference between an odd and even integer is simply the presence on absence of 1 in the LSB i.e. if the binary number contains 1 in LSB it is odd, else it is wen.

There will be 3 states qo, q1 and final state qe. The machine will remain in qo state and the R/w head will continue to move right in each step, until a B (B=Blank) is encountered, i.e. the R/w head reaches the end of the string, in which case the R/w head will move left one step and changes the state to q1. If the R/w head point to 1, then the string is accepted, else it isn't.

S(q0,0) = S(q0,0,8)

S(q0,1) ‡ S(q0,1,8)

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1) Juning completeness can be measured for a system of instructions, based on how they can simulate a luring

 $\delta(q_0,B) = \delta(q_1,B,L)$

 $d(q_1, 1) = \delta(q_2, 1, R)$

for Ex:- a programming language that can theoretically express
all tasks accomplishable by computers is said to be
Awing complete.

Recently, researchers at Hauvard University have xueated what is termed as chemical Juring machine - basically a vot of chemicals their can theoretically function as a computer 3) To put this turing machine in action, the researchers

devised a chemical language, based on existing Juring m/c model of language called 13, containing the letteres 'a, b and 'c'. Words can be composed through equal combinations of letters, put together in alphabetical profer, such as 'a b c'on about

4. With this language, it is said to be Iwing complete and can be used to solve complex publiens. Once it can recognise improper combinations it can act as a fully valid general purpose competter. It's a fairly simple system but what it should us is immense. They've truicd to find out answers about the origin of life on earth, and how a complex chemical computing system such as this could have led to the rise of sentiont creatures. This gives researches great ensights ento how such chemical mixtures have led to biological organisms. They believe that such naturally occurring competers would have been the first steps towards life on earth.