11/5 minutes

At the beginning file sharing was a bit chaotic in github but now it is better.

Communication could be improved, the minutes were late in week 2 and some people didn’t know what they needed to do.

Minutes need to be uploaded the same day!

Do we want a template to show what you did in your sprint? Ismail is going to give a template for this.

Let the rest of the group if you are not able to come to the meeting.

Conclusion last sprint: it was a good start, with small points of improvements

Celine finished state machine and deadlocks, Marios looked into ros, Metehan worked further on the material list

Push mechanism, push the disk-> buffer-> gripper moves disk from buffer

Ismail will send a picture with an idea of a finalized design with a push mechanism.

Metehan will update the material list

Marios thinks webots whould be the best option for simulation of the robot.

Can is working on the gripper, 2 motors would be nice, 3 would maybe cause problems

We will not have enough disks to create a pattern, what do we want to do with it.

Everyone: think of ideas what to do with the disks.