

Can Exposure To Forgiving AI Foster Cooperative Play?

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1 Introduction

Trust is fundamental to human social interactions, enabling smooth relationships at both interpersonal and intergroup levels. The study of psychopathology has linked deficits in trust-based constructs to the development of mental health disorders (Fonagy and Campbell 2017). Individuals with personality disorders often struggle to form and maintain social connections, a difficulty reflected in uncooperative behaviors – a marker for the severity of PD symptoms (Herpertz and Bertsch 2014; Mulder et al. 1999).

One explanation for such social challenges lies in early caregiver experiences. Attachment theory (Bowlby 1978) suggests that the quality of these relationships shapes our capacity for secure attachments and trust. Individuals with higher levels of insecure attachment may recall negative trust-related experiences more easily, report fewer positive trust experiences, and use less constructive coping strategies when trust is broken (Mikulincer 1998). Similarly, learners exposed to unreliable communicators could develop mistrust of social knowledge as a protective strategy (Fonagy and Allison 2014).

If this adaptive mistrust is the source of social dysfunction, we can ask whether exposing those who exhibit it to cooperative and forgiving interaction partners might correct this bias. Research in the fields of behavioral economics and psychology has explored how positive social interactions influence trust and cooperation. The use of the repeated trust game (RTG), a well-established experimental approach, has allowed for the analysis of the development of trust through ongoing interactions (Joyce, Dickhaut, and McCabe 1995). In this paradigm, cycles of mutual trust, where each party’s trust is reciprocated with trustworthiness, have the effect of enhancing cooperative behaviors and trust levels, even among individuals who are initially inclined to be distrustful (King-Casas et al. 2005). Fowler and Christakis (2010) studied behavior in social networks interacting in a public goods game and found that cooperative behavior tends to cluster, suggesting that exposure to cooperative peers can lead to more cooperative behavior. Similarly, research on social learning theory (Bandura 1977) has long demonstrated that individuals learn and model the behavior of those around them, indicating that if someone is consistently exposed to cooperative and positive individuals, they’re likely to emulate this behavior. These insights highlight that engaging with compassionate and forgiving others can be an effective method for mitigating deeply ingrained mistrust.

In this study, we use a randomized control trial to test an exposure manipulation aimed at repairing potential breakdowns in RTG cooperation. We stratify the sample of participants based on rejection sensitivity (RS): a tendency to anxiously expect, readily perceive, and intensely react to rejection. It has been identified as a potential mechanism linking early interpersonal trauma to negative mental health outcomes (Downey, Khouri, and Feldman 1997). Extensive research demonstrates strong associations between rejection sensitivity and various mental health conditions, including depression, anxiety, personality disorders, and self-harm (for a review, see Gao et al. (2017)). However little is known about whether rejection sensitivity is linked to mistrust and difficulties in cooperation in social dilemmas.

Participants are exposed to artificial agents designed with a limited propensity for retaliation, potentially mitigating ingrained mistrust. The computerized investor in the RTG was programmed to play using a generative model of how humans play fit to real players’ data from prior studies. A key aspect of this model is that the actions of the investor depend on a latent “trust state” which reacts dynamically to the trustees’ returns simulating real-life trust-building scenarios. An advantage of having a generative model of behavior is the possibility of controlling different aspects of the agent’s strategy such as its general policy,

the propensity to cooperate actively or the propensity to retaliate after breakdowns of cooperation. Such generative model of behavior, informed by empirical data and integrating a responsive trust mechanism, represent a novel approach to study interactive behavior in multi-player games whilst keeping a high degree of experimental control.

2 Methods

2.1 Participants

A total of 206 participants were recruited on the Prolific Academic platform (prolific.co). Participants were paid a fixed fee of £6 plus a bonus payment dependent on their performance that averaged £0.5. Participants were pre-screened on Prolific using the Rejection Sensitivity Questionnaire to form two similarly sized groups: One with high (RSQ score > 15) and the other with low rejection sensitivity (RSQ score < 10).

2.2 Design and Procedure

The experiment had a 2 (Condition: Manipulation or Control) by 2 (Rejection Sensitivity : high or low) by 2 (Game: Trust-Game Pre Manipulation, Trust-Game Post Manipulation) design, with repeated measures on the third factor. Participants within each pre-screened group were randomly assigned to one of the two levels of the first factor. The games were designed and implemented online using Empirica v1 (Almaatouq et al. 2021).

2.3 Tasks and Measures

2.3.1 Repeated Trust Game

Participants played a 15-round Repeated Trust Game (Joyce, Dickhaut, and McCabe 1995) in the trustee role against a computer-programmed investor. On each round the investor is endowed with 20 units and decides how much of that endowment to invest. This investment is tripled and the trustee then decides how to split this tripled amount between them and the investor. If the trustee returns more than one third of the amount, the investor makes a gain. Each player was represented with an icon with the participant always on the left of the screen and the co-player on the right (Figure 1.A). The participants were able to choose the icon that represents them at the start of the experiment. The icon representing the co-player changed at the start of each new game, to simulate a new interaction partner. Participants were not told they were facing computerised co-players.

The strategy of the computerised investor was modelled on behavior of human investors in the Repeated Trust Game (RTG) over 10-rounds with the same (human) co-player. Full detail on the datasets used in the Supplementary Information. Using this data, we estimated a hidden Markov model (HMM) on investors' behavior with three latent states. Each latent state was associated with a state-conditional distribution over the possible investments from 0 to 20 (Figure 1.B). These distributions reflect "low-trust", "medium-trust", or "high-trust". Over rounds, the investor can move between states, and the probability of these transitions was modelled as a function of their net return (i.e return - investment) in the previous round (see Figure 1.C). In order to instigate a potential breakdown of trust, thereby allowing us to probe efforts to repair trust, the computerised agent was programmed to provide a low investment on round 12 (pre-manipulation) or round 13 (post-manipulation). On all other rounds, the investor's actions were determined by randomly drawing an investment from the state-conditional distribution, with the state over rounds determined by randomly drawing the next state from the state-transition distribution as determined from the net return on the previous round (disregarding the net return immediately after the pre-programmed low investment rounds). The initial state for the HMM investor in each instance of the game was the "mid-trust" state.

2.4 Manipulation

To design a forgiving and ultimately more cooperative agent, we change the transition function of the investor HMM to make it impossible to remain in a low trust state once the agent transitions there. This is achieved by choosing the parameters of the transition function to make the probability of remaining in the “low-trust” state, when the agent is in that state, effectively nil. The policies conditional on the state and the transition function in the other states remain unchanged. The resulting transition function is shown in Figure 1.D.

2.5 Procedure

At the start of the experiment, participants provided informed consent and were instructed the study would consist of three phases in which they would face a different other player. Participants were told their goal was to maximise the number of points in all phases. They were not told the number of rounds of each phase. Phase one was a 15 round Repeated Trust Game (RTG) in which participants took the role of trustee, facing the same investor over all 15 rounds. On each round, after being informed about the amount sent by the investor participants decided how much of the tripled investment to return to the investor, before continuing to the next round. After completing 15 rounds of the RTG, participants rated how cooperative, forgiving they perceived the investor to be, and whether they would like to play with them again (all on a scale from 1 to 10).

After phase one, participants in the manipulation condition played three games of 7 rounds each against the forgiving HMM agent, whilst those in the control condition faced the human-like HMM agent. To keep the experience similar to the pre-manipulation game, the agent in the control condition was also designed to send a very low investment in round 5 of each of the three games. Subsequent phase two was similar to phase one, with participants being told they would face a new player. Participants then completed the Levels of Personality Functioning Scale (LPFS) questionnaire (see the supplement for details). Finally, participants were asked whether they thought the other players were human or computer agents, then debriefed and thanked for their participation.

2.6 Statistical analysis

To explore whether participants behaved differently in the RTG after the manipulation compared to the control group, we model the percentage return (percentage of tripled investment returned to investor) using a linear mixed-effects model as described below:

$$\begin{aligned} R_{ij} = & \beta_0 + \beta_1 \text{Phase}_i + \beta_2 \text{Condition}_i + \beta_3 \text{Investment}_i + \beta_4 \text{RS}_i + \\ & \beta_5(\text{Phase} \times \text{Condition})_i + \beta_6(\text{Phase} \times \text{Investment})_i + \beta_7(\text{Phase} \times \text{RS})_i + \\ & \beta_8(\text{Condition} \times \text{Investment})_i + \beta_9(\text{Condition} \times \text{RS})_i + \beta_{10}(\text{Investment} \times \text{RS})_i + \\ & \beta_{11}(\text{Phase} \times \text{Condition} \times \text{Investment})_i + \beta_{12}(\text{Phase} \times \text{Condition} \times \text{RS})_i + \\ & \beta_{13}(\text{Phase} \times \text{Investment} \times \text{RS})_i + \beta_{14}(\text{Condition} \times \text{Investment} \times \text{RS})_i + \\ & \beta_{15}(\text{Phase} \times \text{Condition} \times \text{Investment} \times \text{RS})_i + \\ & b_{0j} + b_{1j} (\text{Phase})_i + \epsilon_{ij} \end{aligned}$$

where:

- R_{ij} : percentage of tripled investment returned to investor for participant j in observation i
- β_0 : intercept
- β_1 to β_4 : main effects of Phase (RTG game pre vs. post-manipulation), Condition (manipulation vs. control), Investment, and RS (High vs Low RS), respectively

- β_5 to β_{10} : interaction effects between each pair of the four factors, showing how the relationship between one factor and the return percentage not available changes depending on the level of another factor
- β_{11} to β_{14} : three-way interaction effects among the four factors, indicating how the interaction between two factors is further modified by the third factor
- β_{15} : four-way interaction effect between Phase, Condition, Investment, and RS, describing how the interaction among three factors is modified by the fourth factor
- b_{0j} : player-wise random intercept for player j
- b_{1j} : player-wise random slope for Phase for player j
- ϵ_{ij} : error term for player j in observation i

The model was estimated using the **afex** package (Singmann et al. 2022) in R. More complex models with additional random effects could not be estimated reliably, and as such the estimated model can be considered to include the optimal random effects structure (Matuschek et al. 2017). A similar process was used to establish the random effects structures of other linear mixed-effects models used throughout the statistical analyses. For the F -tests, we used the Kenward-Roger approximation to the degrees of freedom, as implemented in the R package “afex”. We Z-transform the Investment variable (subtract the overall investment mean and divide by overall standard deviation) as centering is beneficial to interpreting the main effects more easily in the presence of interactions.

3 Behavioral Results

3.1 Player ratings

Figure 2 shows participants’ ratings of each player they faced by condition and RS group. We will focus on two contrasts to analyse the ratings, by Condition and RS group. The first is between the rating in the first phase (“pre”) when participants phase the human-like HMM, and the average rating during the exposure phase (average of “expo1”, “expo2” and “expo3”) where they either face the forgiving HMM (Manipulation condition) or the human-like HMM again (Control condition). The second contrast is between the “pre” and “post” phases of the experiment where in both conditions participants face the same human-like HMM.

3.1.1 Comparing pre and exposure ratings

For those with high Rejection Sensitivity, participants in the Manipulation condition rated the investors they faced in the exposure phase (the forgiving HMM) as more Cooperative $\Delta M = 2.57$, 95% CI [0.84, 4.30], $t(808) = 2.91$, $p = .004$. There was no difference in ratings on forgiveness and whether they would like to face the co-players again. Those in the control condition rated the investors faced in the exposure group (same HMM) as less cooperative $\Delta M = -2.65$, 95% CI [-4.37, -0.94], $t(808) = -3.04$, $p = .002$, less forgiving $\Delta M = -2.19$, 95% CI [-4.00, -0.39], $t(808) = -2.38$, $p = .017$, and were less keen on facing them again $\Delta M = -3.62$, 95% CI [-5.73, -1.50], $t(808) = -3.36$, $p = .001$.

For those with low Rejection Sensitivity, there was no difference in any of the ratings between the “pre” and “exposure” phases for the Manipulation condition. For the Control condition, participants indicated less willingness to face the exposure co-player compared to the “pre” player, $\Delta M = -2.43$, 95% CI [-4.52, -0.34], $t(808) = -2.29$, $p = .023$ but also did not differ on cooperation and forgiveness ratings. In summary, those with low rejection sensitivity had a mostly undifferentiated perception of players between the pre and exposure phases, even when the co-player was in fact designed to be more forgiving. In contrast, we see that exposing participants with high Rejection Sensitivity to a more cooperative and more forgiving agent has compensated for the decrease in ratings that would have occurred if faced with a co-player with the exact same strategy.

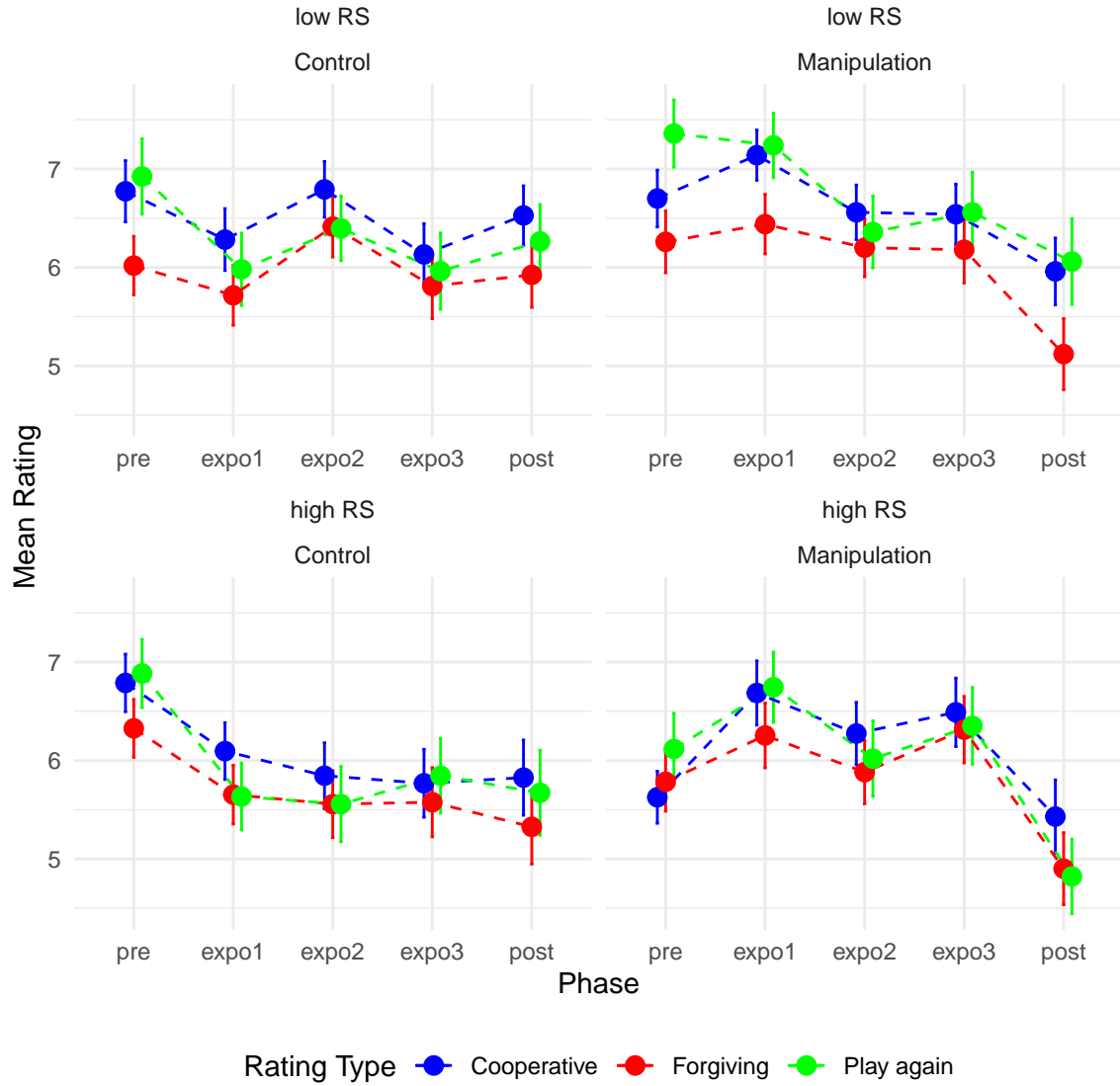


Figure 2: Averages and standard errors of the participants ratings of the opponent for each game and condition. Pre and post are the 15 round repeated trust games before and after the exposure phase respectively. The games titled expo 1 to 3 are the three 7 round games during the exposure phase. We note that absent the exposure to the forgiving AI, the ratings get worse on aggregate even though the participant faces the same human like HMM. In the manipulation condition, participants rate the nicer HMM as more cooperative but not more forgiving. When they face the human-like HMM again, its rating are considerably worse.

3.1.2 Comparing pre and post ratings

Participants high on Rejection Sensitivity in the Manipulation condition rated the co-players in the “post” phase similarly on cooperation, lower on forgiveness $\Delta M = -0.88$, 95% CI $[-1.63, -0.14]$, $t(808) = -2.33$, $p = .020$, and lower on willingness to face them again $\Delta M = -1.29$, 95% CI $[-2.16, -0.42]$, $t(808) = -2.92$, $p = .004$. Those in the Control condition rated the investors post the exposure phase lower on all three attributes (Cooperation: $\Delta M = -0.96$, 95% CI $[-1.66, -0.26]$, $t(808) = -2.70$, $p = .007$, Forgiveness: $\Delta M = -1.00$, 95% CI $[-1.74, -0.26]$, $t(808) = -2.66$, $p = .008$, Play again: $\Delta M = -1.21$, 95% CI $[-2.07, -0.35]$, $t(808) = -2.76$, $p = .006$).

For participants low on Rejection Sensitivity, those in the Manipulation condition rated the co-players in the “post” phase lower on all three attributes (Cooperation: $\Delta M = -0.74$, 95% CI $[-1.45, -0.03]$, $t(808) = -2.03$, $p = .042$, Forgiveness: $\Delta M = -1.14$, 95% CI $[-1.89, -0.39]$, $t(808) = -2.98$, $p = .003$, Play again: $\Delta M = -1.30$, 95% CI $[-2.18, -0.42]$, $t(808) = -2.90$, $p = .004$). Those in the Control condition did not differ in their ratings of the “pre” and “post” phase players.

In summary, we again see that those with low RS accurately perceive the co-player as similar on all attributes throughout the phases in the control condition. In contrast, the high RS group shows a negative bias towards the co-players after the “pre” phase in the control condition even though the player continues to use the same strategy. After exposure to the forgiving HMM, both groups rates the “post” co-player worse than the “pre” even though they are the same.

3.2 Analysis of participant returns

On average, investments and returns, as shown in Figure 3, fell within the documented range of 40-60% of the endowment for investments and 35-50% of the total yield for returns, as reported in previous studies (Charness, Cobo-Reyes, and Jiménez 2008; Fiedler, Haruvy, and Li 2011).

Mixed-effects analysis on the percentage returns shows a significant main effect of Phase (Pre vs. Post RTG game), $F(1, 201.63) = 5.81$, $p = .017$, with higher percentage returns in the first RTG compared to the second. Importantly, we also find an interaction between Condition and Phase (RTG pre- vs. post-manipulation), $F(1, 201.63) = 4.38$, $p = .038$. As shown in Figure 5, post-hoc tests confirm a decrease in the percentage returned only in the manipulation condition, pre - post, $\Delta M = 0.03$, 95% CI $[0.01, 0.05]$, $t(201.50) = 3.15$, $p = .002$, but no change in the control condition. We find no interaction between Phase, Condition and RS, suggesting that there was no difference between RS groups for this interaction.

There was also a significant main effect of Investment, $F(1, 5955.67) = 325.35$, $p < .001$, such that higher investments were associated with higher percentage returns indicating positive reciprocity. An Investment by Condition interaction, $F(1, 5955.67) = 13.92$, $p < .001$, reflected that returns were more affected by investments in the control condition. We also find a three way interaction between Phase, Investment and RS, showing that the differentiated effect of the investment on the proportion returned by RS group is itself moderated by the Phase (pre- vs post manipulation). Finally, we find a four-way interaction between Condition, Phase, Investment and RS $F(1, 5864.62) = 9.24$, $p = .002$.

To interpret this interaction we plot the effect of the Investment on returns for each level of Condition, Phase and RS. Figure 4 shows that while the effect of investment on returns is similar across RS groups and across phases in the Control condition, the Manipulation condition shows a higher effect of investment in the post phase compared to pre in the low RS group, but a lower effect of investment compared to before for the high RS group. This suggests that high RS participants based their return less on the investment after being exposed to the forgiving AI compared to the low RS group.

3.2.1 Post Defection Trials

Did participants learn to be more forgiving and cooperative after witnessing the pre-programmed defection by the HMM investor?. To explore this question, we restrict the analysis to the trials following the pre-programmed defection by the HMM agent in both the “pre” (trials 12 to 15) and the “post” phases (trials

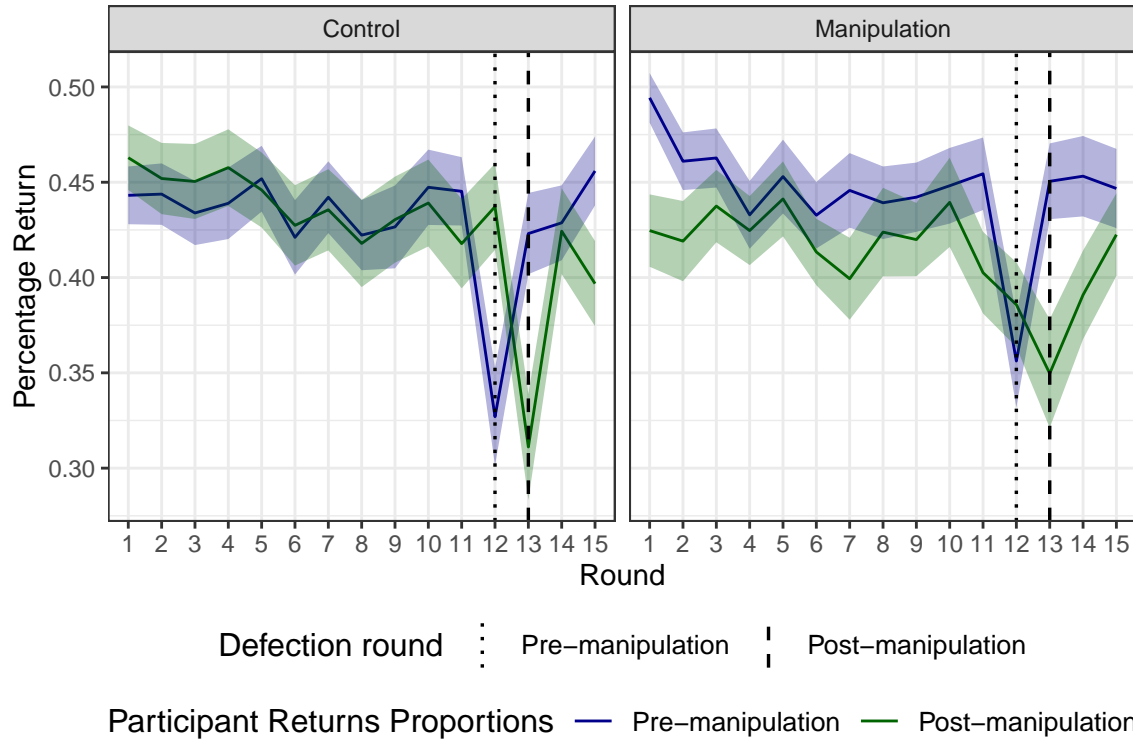


Figure 3: Averages and standard errors of the trustee's return as a percentage of the multiplied investment received by Condition, Phase, and game round. The blue line shows the returns pre-manipulation and the green line post-manipulation. We note a different reaction to the pre-programmed one-off low investment between the two conditions: Whilst there is a dip in returns pre-manipulation for both conditions, post manipulation we see higher returns in the manipulation condition compared to the dip in returns seen in the control condition in the right panel

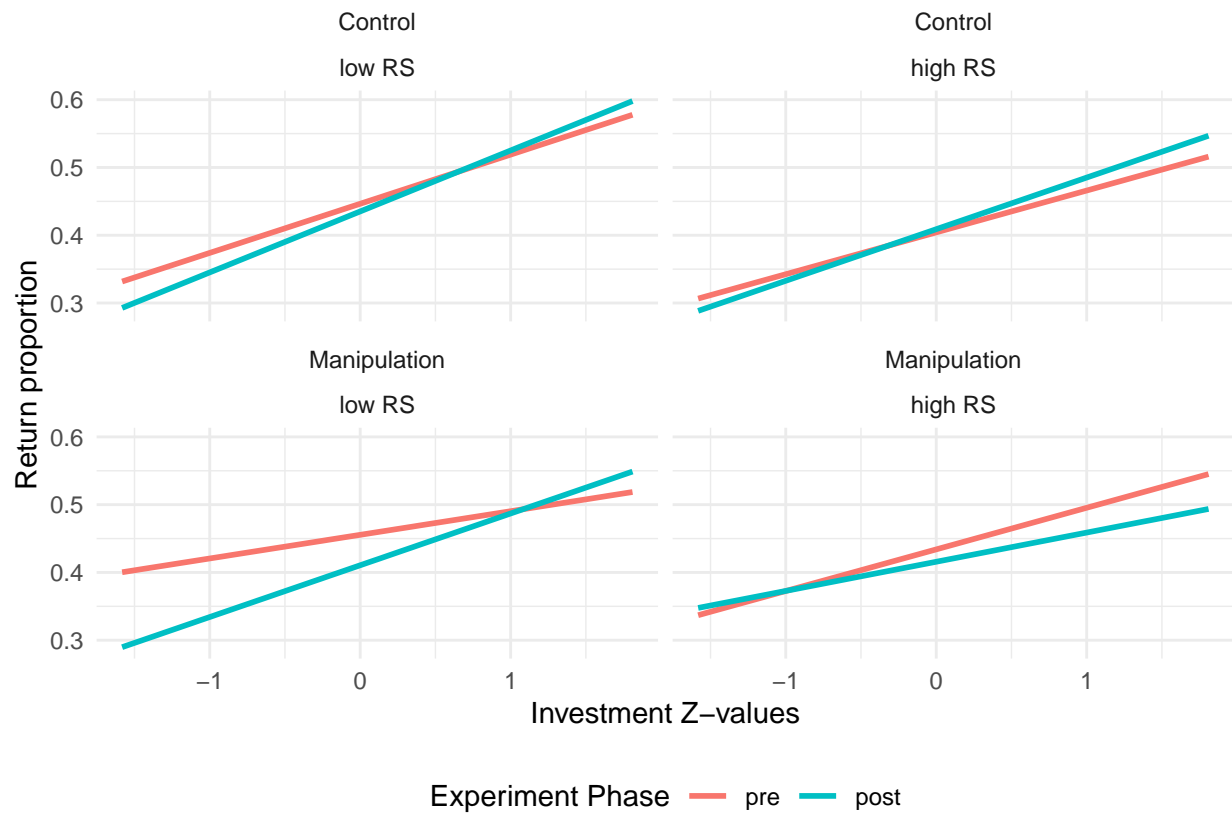


Figure 4: Effect of investment on returns by condition, phase and RS group

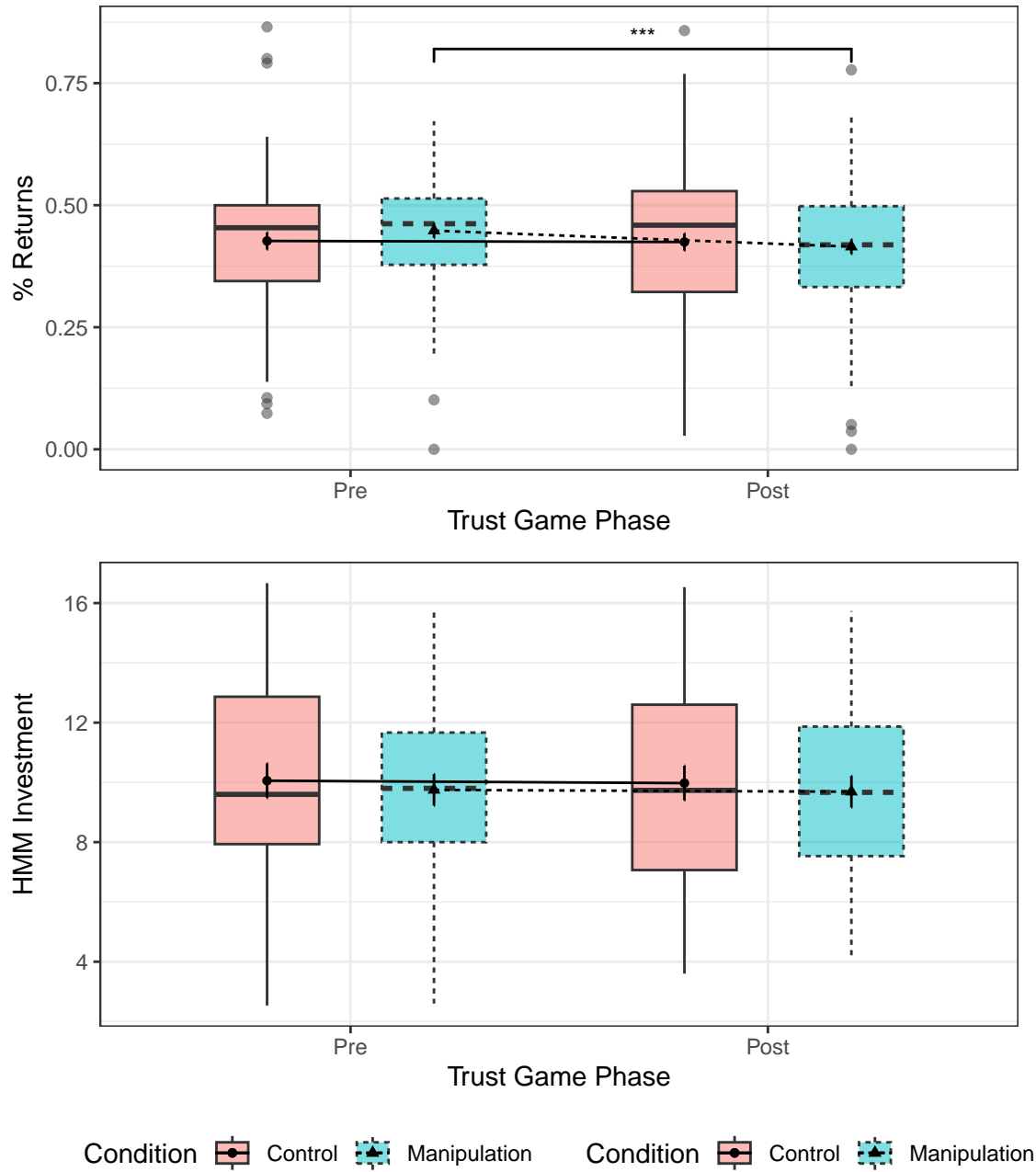


Figure 5: Marginal means and distributions of either investments or percentage returns across participants by Phase and Condition. The top panel shows that participants in the Intervention condition returned lower proportions of the multiplied investment received in the second game compared to the first game over all rounds, whilst those in the Control condition sent back similar returns. The bottom panel shows no difference on aggregate of how the HMM invested across Phases and Conditions.

13 to 15). We fit the same mixed effects model as for all the trials with the exception of the RS variable. This is because RS did not show main or interaction effects in the main model, and also due to the necessity of running a simpler model to accommodate the low number of trials. We find a significant main effect of Phase $F(1, 227.47) = 4.76$, $p = .030$ with returns lower in the second game post defection trials compared to the first. We also find a main effect of Investment $F(1, 1296.14) = 156.41$, $p < .001$ where participants continued to return higher proportions when receiving higher investments. Finally, we still find an Investment by Condition interaction $F(1, 5955.67) = 13.92$, $p < .001$ showing a lower effects of investment on the manipulation condition compared to the control condition in post-defection trials.

3.2.2 HMM investor

To test whether the HMM investors' behavior differed between Phases, Conditions and RS groups, we estimate a linear mixed-effects model of investments sent by the computerised HMM agent with Condition, Phase and RS and their interaction as fixed effects, and a similar random effects structure to the returns model. As seen in Figure 5, we find no main or interaction effects, indicating HMM behavior was on aggregate similar across Phase, Conditions and RS groups.

When asked during debrief whether they thought the investors they faced were Human or not, 41% of participants thought they were either facing a human or were not sure of the nature of the co-player. When asked to justify their choice, many answers reflected participants projecting human traits such as "spitefulness" or "greed" onto the artificial co-player's behavior.

3.2.3 Questionnaire scores and performance

Whilst we found a significant correlation between participant's Levels of Personality Functioning Score (LPFS) and the Rejection Sensitivity score $r_s = .52$, $S = 704, 474.68$, $p < .001$, there was no correlation between these and participant's return or overall task performance.

4 Discussion

This study leveraged a novel approach to examining the dynamics of trust and cooperation in social interactions through the utilization of Hidden Markov Models (HMMs) as artificial agents in economic games. The use of HMM-based artificial agents in economic games led to similar investment and returns to those recorded in human dyadic interactions. Participants were often uncertain whether they interacted with human or artificial investors, highlighting the agents' realism. This validates the use of these artificial agents to probe the effectiveness of manipulations whilst keeping a high degree of experimental control.

Following the exposure manipulation, participants reduced their returns overall whilst the returns of those in the control group did not change between the pre and post phase of the experiment. Why did participants reduce their returns even though they were repeatedly exposed to a more cooperative and more forgiving AI? A look at how the participants rated their co-players might shed some light on what is driving this reduction in returns for those exposed to the forgiving AI.

Those exposed to the forgiving AI rated their opponent in the post-exposure phase lower on all attributes even though they faced the same dynamic human-like HMM as pre-exposure. One possible explanation for this drop in rating is that participants exhibited a negative contrast effect. This occurs when the evaluation of a person, object, or situation is influenced by comparisons with recently encountered contrasting objects or people. If we've recently interacted with someone exceptionally nice, our perception of a normal level of niceness might be skewed, making normal behavior seem less favourable or even negative by comparison (Kobre and Lipsitt 1972). As the most recently faced opponents were more forgiving and cooperative, this negative contrast effect may have trumped any learning transfer from being repeatedly exposed to cooperative and forgiving AI (Zentall 2005). If this contrast effect is indeed replicable, then an avenue for future research would be to use it to our benefit by making the participants play agents with low cooperation perception.

It is worth highlighting that Rejection Sensitivity was not correlated to overall performance in the task. Neither did it moderate the change in returns between Conditions or have an effect on participant returns. However, in examining the player ratings by rejection sensitivity (RS) group more closely, we observe that individuals with high rejection sensitivity demonstrate a heightened attunement to changes in the behavior of their AI co-players. Specifically, when exposed to a more forgiving AI agent, these participants accurately increased their ratings of the agent, indicating a sensitive and appropriate response to the behavioral manipulation. This adjustment reflects a nuanced perception of social cues and a capacity to modify judgments based on the behavior of interaction partners, potentially indicating a perceived alignment or support from the co-player that mitigates their heightened sensitivity to potential social rebuffs. High RS participants' lower ratings of essentially similar co-players as they continued to face them may indicate that the occasional pre-programmed defections of the AI agents failed to mitigate concerns over rejection and possibly exacerbated perceptions of uncooperativeness and unforgiveness, leading to a stronger preference against future interactions. Individuals with low RS were less affected by AI behavioral variations, showing a less volatile baseline of social perception. They still exhibit behavior consistent with a contrast effect in the manipulation condition. This dichotomy highlights the potential of tailored interactions, mediated by advanced AI agents, to address and modulate specific social and psychological predispositions in human participants.

Importantly, our approach utilizing HMMs to simulate interactive partners in social dilemmas offers a promising avenue for future research, especially in understanding and potentially mitigating trust deficits in individuals with high rejection sensitivity. The nuanced behaviors elicited through the interaction with HMM agents highlight the complexity of trust dynamics and the potential for computational models to offer novel insights into human social behaviors.

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