

Applications of Graph-Search Algorithms

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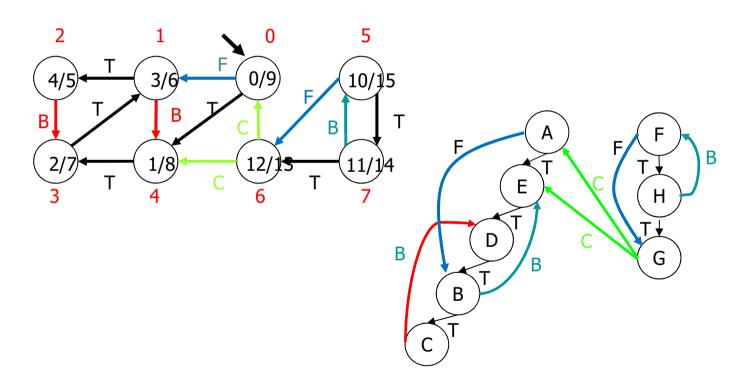
Reverse graph

- Given a directed graph G = (V, E)
 - > Its reverse (or tanspose) graph $G^T = (V, E^T)$ is such that $(u, v) \in E$ $(v,u) \in E^T$

```
graph_t *graph_transpose(graph_t *g, int nv) {
   graph_t *t;
   int i, j;
   t = (graph_t *)util_calloc(nv, sizeof(graph_t));
   for (i=0; i<nv; i++) {
     t[i] = g[i];
     t[i].rowAdj = (int *)util_calloc(nv, sizeof(int));
     for (j=0; j<nv; j++) {
        t[i].rowAdj[j] = g[j].rowAdj[i];
     }
   }
   return t;
}</pre>
```

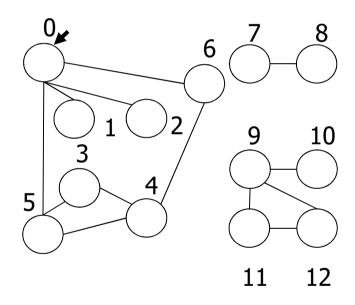
Loop detection

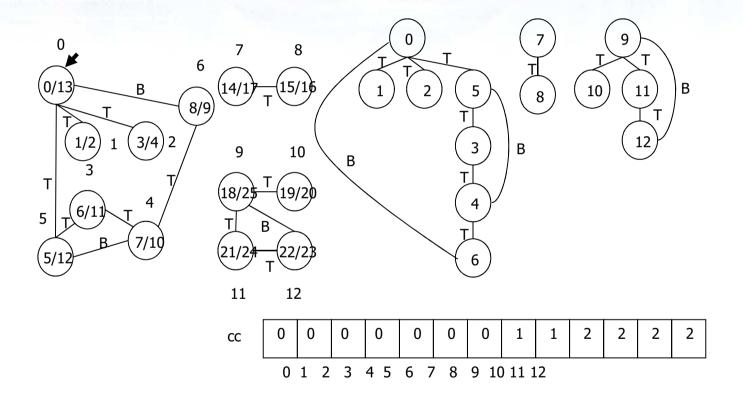
A graph is acyclic if and only if in a DFS there are no edges labelled Backward (B)



Connected components

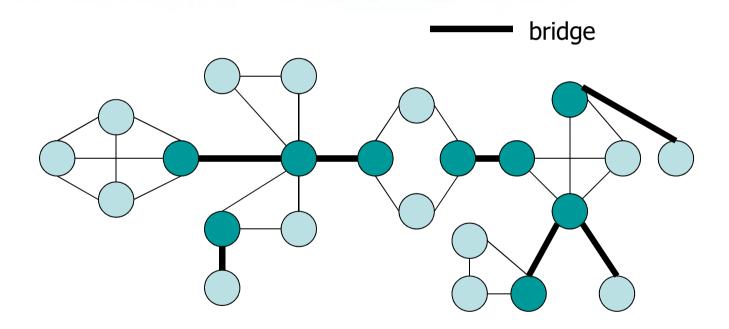
- In an undirected graph represented as an adjacency list
 - ➤ Each tree of the DFS forest is a connected component
 - CC is an array that stores an integer identifying each connected component. Nodes serve as indexes of the array





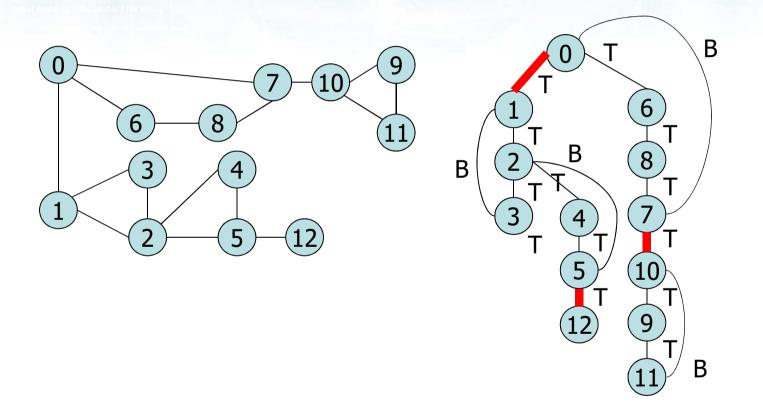
Bridges

- Given an undirected and connected graph, find out whether the property of being connected is lost because
 - An edge is removed
- Bridge
 - > Edge whose removal disconnects the graph



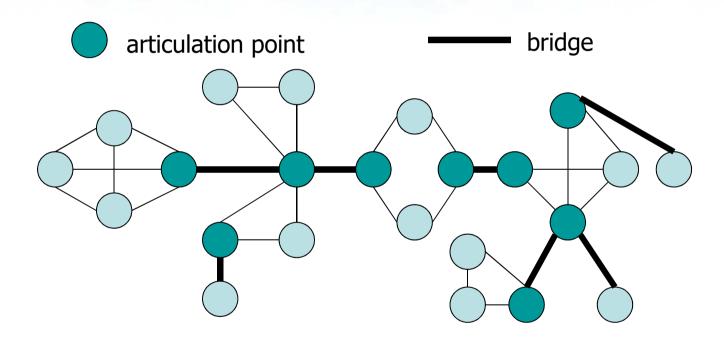
Bridges

- An edge (v,w)
 - ➤ Labelled Back (B) can't be a brigdge
 - Nodes v and w are also connected by a path in the DFS tree
 - ➤ Labelled Tree (T) is a bridge if and only if there are no edges labelled Back that connect a descendant of w to an ancestor of v in the DFS tree



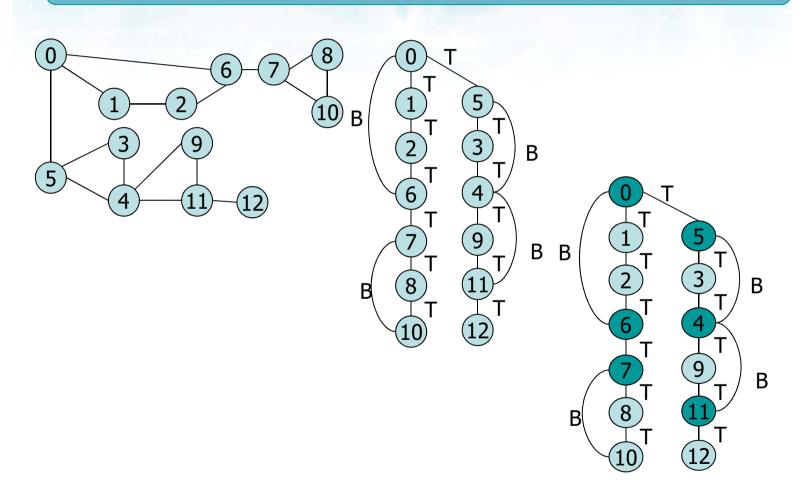
Articulation points

- Given an undirected and connected graph, find out whether the property of being connected is lost because
 - A node is removed
- Articulation point
 - Node whose removal disconnects the graph
 - Removing the vertex entails the removal of insisting (incoming and outgoing) edges as well



Articulation points

- ❖ Given an undirected graph G, given the DFS tree G_D
 - ➤ The root of G_p is an articulation point if and only if it has at least two children
 - > Levaes cannot be articulation points
 - Any internal node v is an articulation point of G if and only if v has at least one child s such that there is no edge labelled B from s or from one of its descendants to a proper ancestor of v



Directed Acyclic Graph (DAG)

DAG

implicit models for partial orderings used in scheduling problems

Scheduling

- > Given tasks and precedence constraints
- How can we schedule tasks so that they are all executed satisfying the constraints

Directed Acyclic Graph (DAG)

Topological sort (reverse)

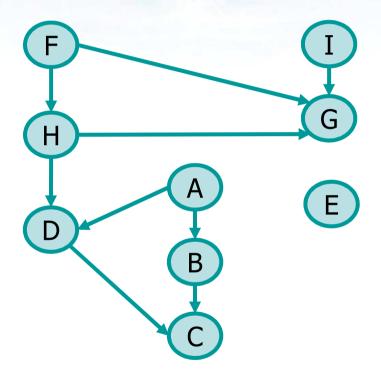
➤ Reordering the nodes according to a horizontal line, so that if the (u, v) edge exists, node u appears to the left (right) of node v and all edges go from left (right) to right (left)

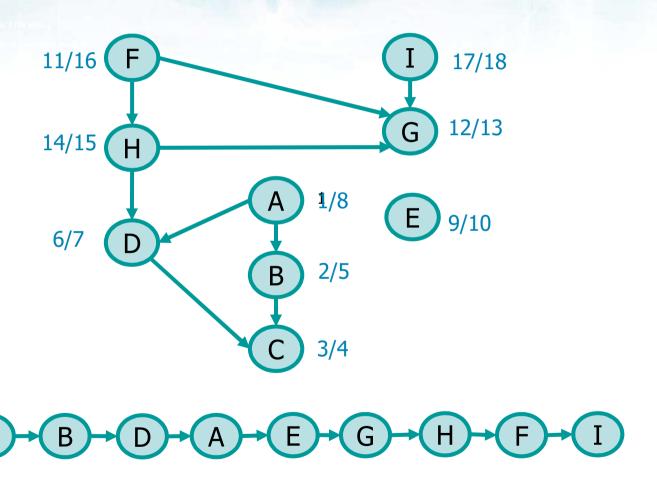
Algorithm

- > Perform a DFS computing **end-processing** times
- Order vertices using the end-processing times

Alternative algorithm

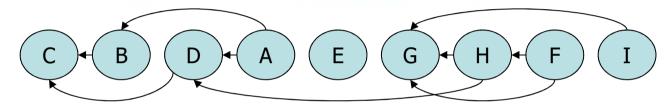
Perform a DFS and when assigning end-processing times insert the vertex into a LIFO list



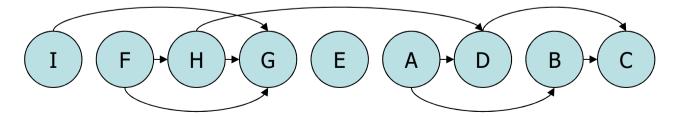


Topological Sort

Reverse topological sort



- Topological sort
 - With a DAG represented by an adjacency matrix, it is enough to invert references to rows and columns



Graph library: Topological Sort

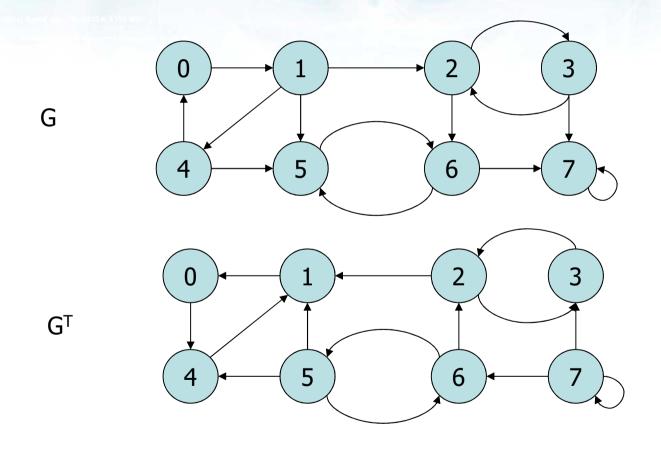
```
void graph_dag(graph_t *g, int nv){
int i, *post, loop=0, timer=0;
post = (int *)util_malloc(nv*sizeof(int));
for (i=0; i<nv; i++) {
  if (g[i].color == WHITE) {
    timer = graph_dag_r(g, nv, i, post, timer, &loop);
if (loop != 0) {
  printf("Loop detected!\n");
} else {
  printf("Topological sort (direct):");
  for (i=nv-1; i>=0; i--) {
    printf(" %d", post[i]);
  printf("\n");
free(post);
```

Graph library: Topological Sort

```
int graph_dag_r(
  graph_t *g, int nv, int i, int *post, int t,
  int *loop) {
int j;
g[i].color = GREY;
for (j=0; j<nv; j++) {
  if (g[i].rowAdj[j] != 0) {
    if (g[j].color == GREY) {
       *loop = 1;
    if (g[j].color == WHITE) {
      t = graph_dag_r(g, nv, j, post, t, loop);
g[i].color = BLACK;
post[t++] = i;
return t;
```

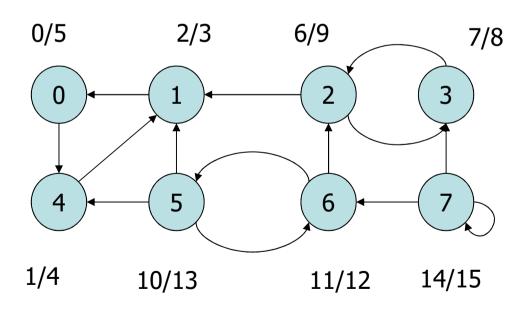
Strongly Connected Component (SCC)

- Kosaraju's algorithm ('80s)
 - > Reverse the graph
 - Execute DFS on the reverse graph, computing Discovery/Endprocessing times
 - Execute DFS on the original graph according to decresasing Endprocessing times
 - ➤ The trees of this last DFS are the strongly connected components



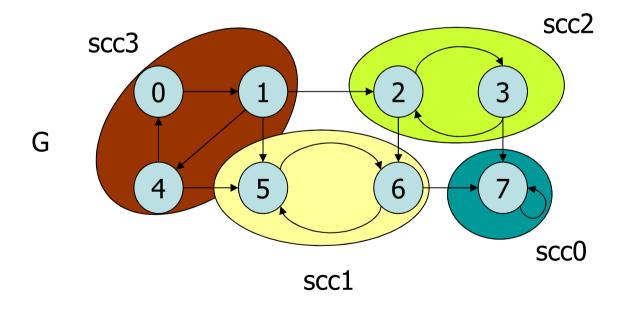
Algorithm

❖ DFS of the reverse graph G^T (time stamps pre[v] and post[v] are displayed, though only post[v] time stamps are used)



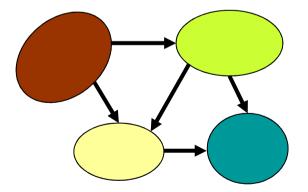
Algorithm

DFS of the original graph according to decreasing endprocessing times computed in the DFS of the reverse graph G^T



Considerations

- SCCs are equivalence classes with respect to the mutual reachability property
- We can "extract" a reduced graph G' considering 1 node as representing each equivalence class
- The reduced graph G' is a DAG



Graph library: SCC

```
int graph_scc(graph_t *g, int nv)
 graph t *t;
 int i, id=0, timer=0;
 int *post, *tmp;
 t = graph transpose(g, nv);
 post = (int *)util_malloc(nv*sizeof(int));
 for (i=0; i<nv; i++) {
   if (t[i].color == WHITE) {
     timer = graph_scc_r(t, nv, i, post, id, timer);
 graph dispose(t, nv);
```

Graph library: SCC

```
id = timer = 0;
tmp = (int *)util malloc(nv*sizeof(int));
for (i=nv-1; i>=0; i--) {
  if (g[post[i]].color == WHITE) {
    timer = graph_scc_r(
      g, nv, post[i], tmp, id, timer);
    id++;
free(post);
free(tmp);
return id;
```

Graph library: SCC

```
int graph_scc_r(
 graph_t *g, int nv, int i, int *post,
 int id, int t)
 int j;
 g[i].color = GREY;
 g[i].scc = id;
 for (j=0; j<nv; j++) {
   if (g[i].rowAdj[j]!=0 && g[j].color==WHITE) {
      t = graph_scc_r(g, nv, j, post, id, t);
 g[i].color = BLACK;
 post[t++] = i;
 return t;
```