



# BSTs: Binary Search Trees

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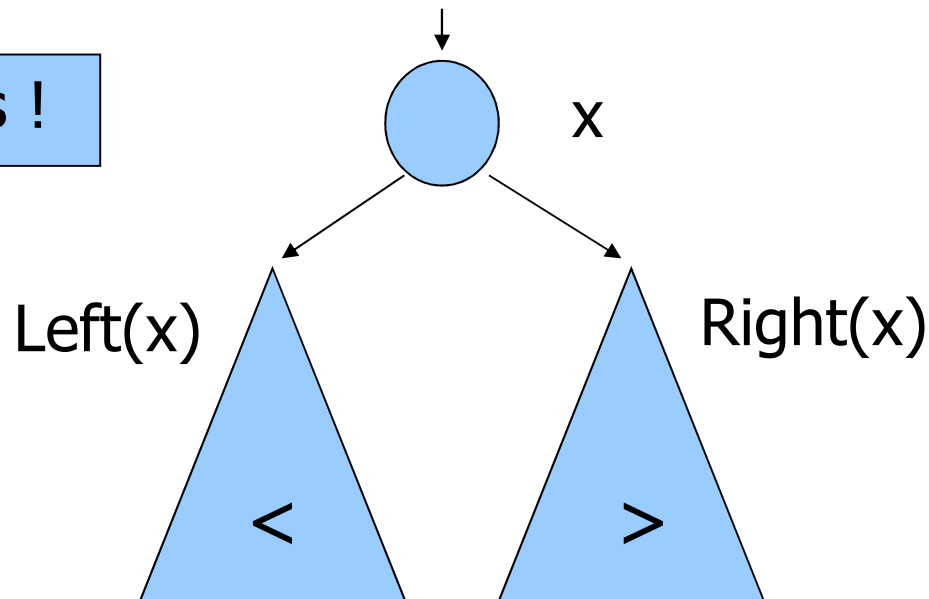


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# Binary Search Trees (BSTs)

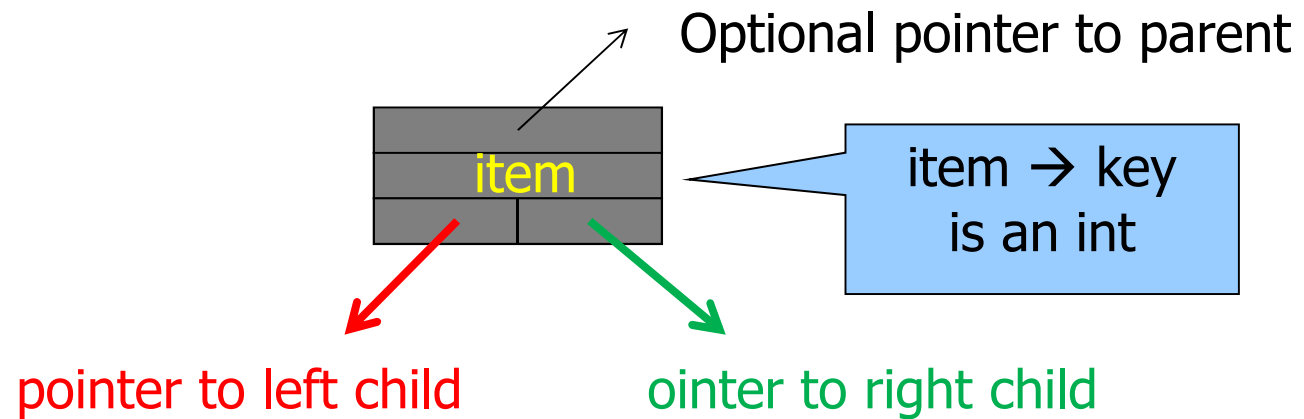
- Binary tree with the following property
- $\forall$  node  $x$ 
  - $\forall$  node  $y \in \text{Left}(x)$ ,  $\text{key}[y] < \text{key}[x]$
  - $\forall$  node  $y \in \text{Right}(x)$ ,  $\text{key}[y] > \text{key}[x]$

Distinct keys !



# Binary Search Trees

## ■ Node



```
typedef struct node *link;  
struct node {  
    Item item;  
    link l;  
    link r;  
};
```



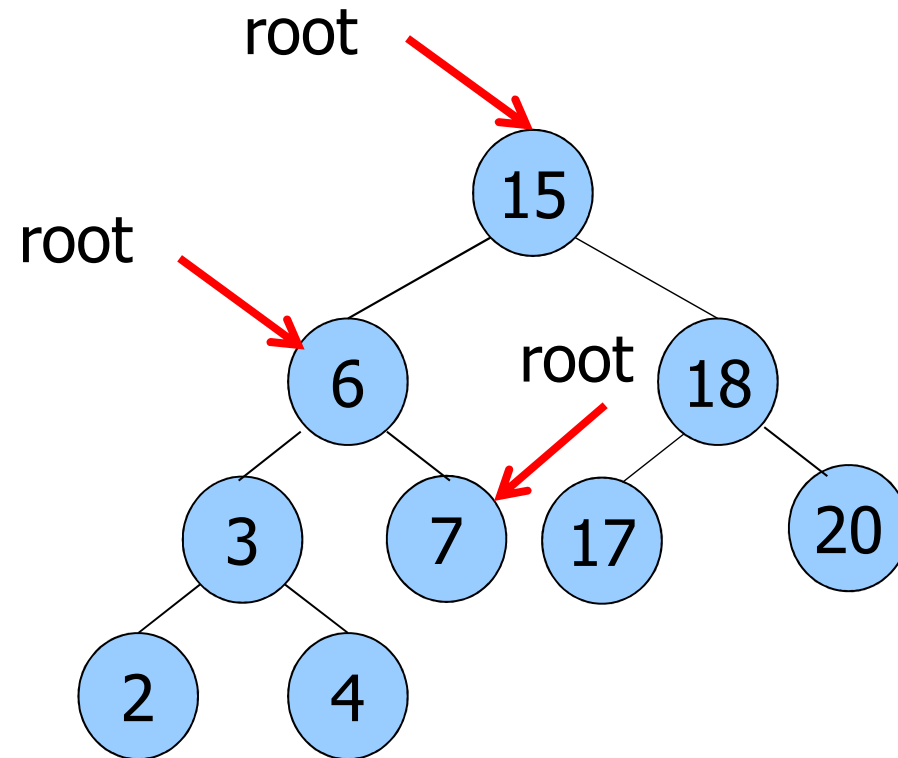
# Search

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- Recursive search of a node storing a node with the desired key
  - Visit tree from the root
  - Termination: Either the searched key is the one of the current node (**search hit**) or an empty tree has been reached (**search miss**)
  - Recursion: from the current node
    - On the left sub-tree if the searched key is smaller than the key of the current node
    - On the right sub-tree otherwise

# Example

Search node with item (key) 7





# Implementation

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```
link search_r (link root, Item item, link z) {  
    if (root == z)  
        return (z);  
  
    if (ITEMless(item, root->item))  
        return search_r (root->l, item, z);  
  
    if (ITEMless(root->item, item))  
        return search_r (root->r, item, z);  
  
    return root;  
}
```



# Minimum and Maximum

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## ■ Minimum

- Follow pointers onto left sub-trees until they exist

## ■ Maximum

- Follow pointers onto right sub-trees until they exist



# Implementation

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```
link min_r (link root, link z) {  
    if (root == z)  
        return (z);  
    if (root->l == z)  
        return (root);  
    return min_r (root->l, z);  
}
```

```
link max_r (link root, link z) {  
    if (root == z)  
        return (z);  
    if (root->r == z)  
        return (root);  
    return max_r (root->r, z);  
}
```





## Leaf Insert

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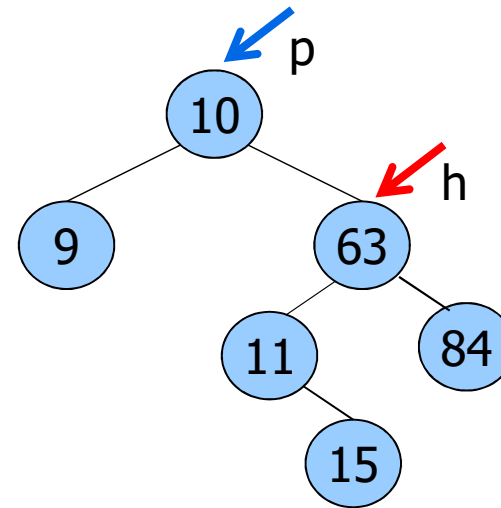
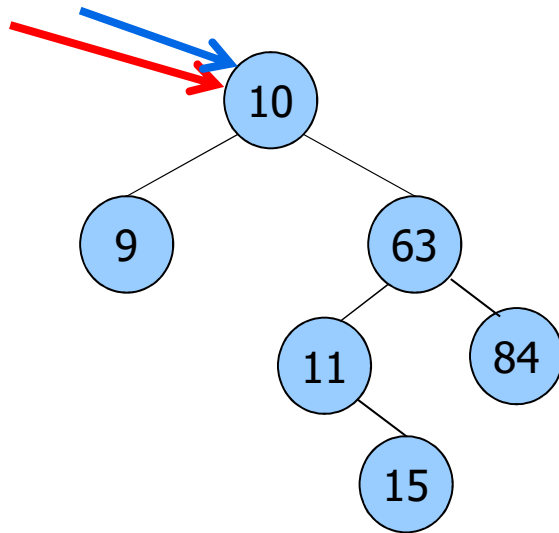
Insert into a BST a node storing a new item (maintaining the BST property)

- If the BST is empty, create a new tree
- **Recursive** insert: Insert into the left or right sub-tree depending on the comparison between the item and the current node key
- **Iterative** insert: Find the position first, then add the new node

# Example

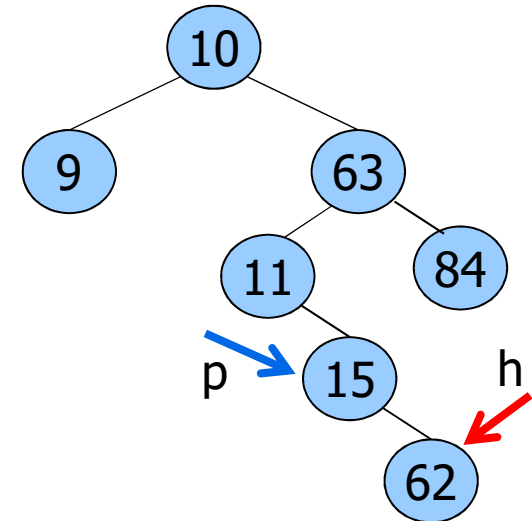
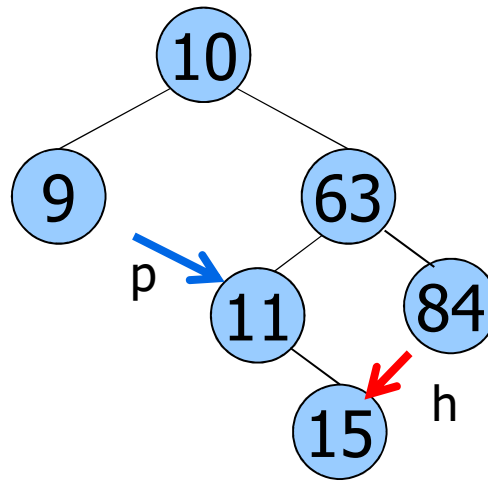
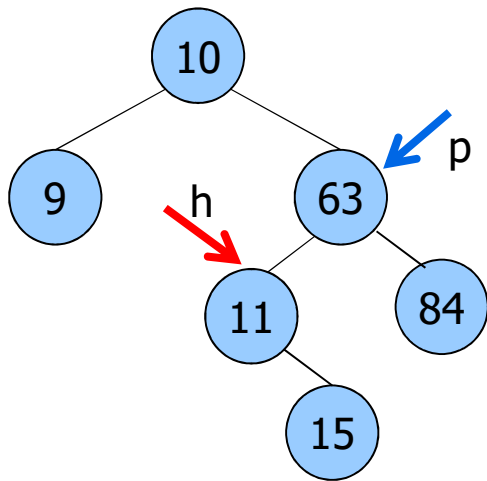
Insert node with item (key) 62

$h = p = \text{root}$



# Example

Insert node with item (key) 62





# Implementation

## Recursive

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```
link insert_r (link root, Item x, link z) {  
    if (root == z)  
        return (NEW(x, z, z));  
  
    if (ITEMless(x, root->item))  
        root->l = insert_r (root->l, x, z);  
    else  
        root->r = insert_r (root->r, x, z);  
  
    return root;  
}
```



# Implementation

## Iterative

```
link insert_i (link root, Item x, link z) {
    link p = root, h = p;
    if (root == z) {
        return (NEW(x, z, z));
    }
    while (h != z) {
        p = h;
        h = (ITEMless(x, h->item)) ? h->l : h->r;
    }
    h = NEW(x, z, z);
    if (ITEMless(x, p->item))
        p->l = h;
    else
        p->r = h;
    return root;
}
```



## Delete

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To delete a previously stored node from a BST we have to recursively search the key into the BST

- Delete from the left or right sub-tree depending on the comparison between the item and the current node key
- If the BST is empty, just return doing nothing



# Delete

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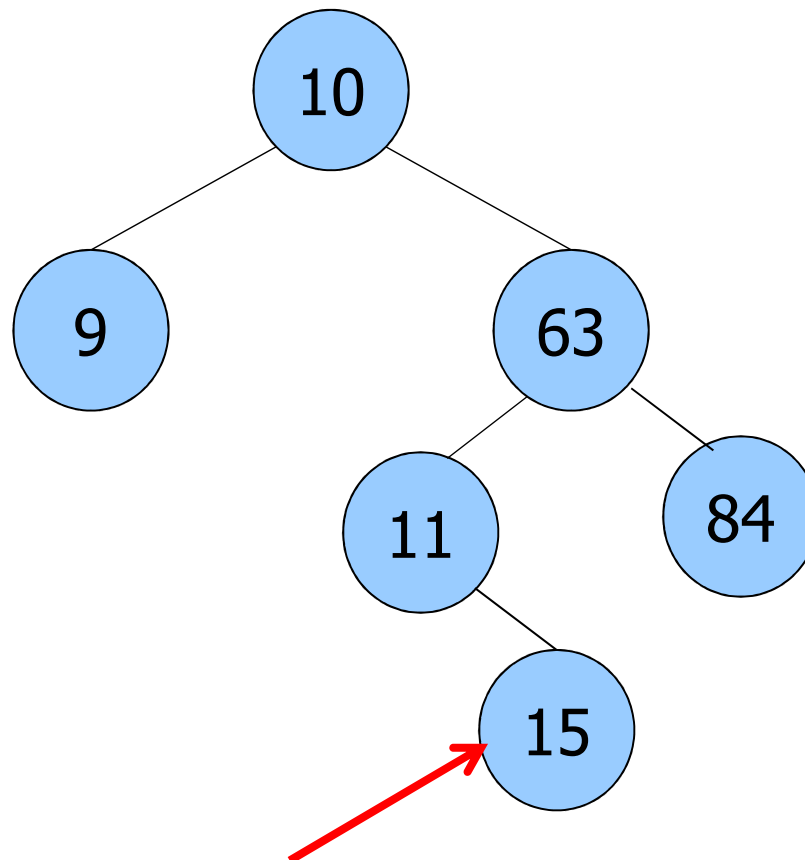
- If the node with the desired key is found, apply one of the following three basic rules
  - If the node has no children, simply remove it
  - If the node has one child, then elevate that child to take the node position in the tree
  - If the node has two children, find the greatest node in its left subtree (or the smallest node in its right subtree) and substitute the node with it



## Example: Rule 1

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Delete node with item (key) 15



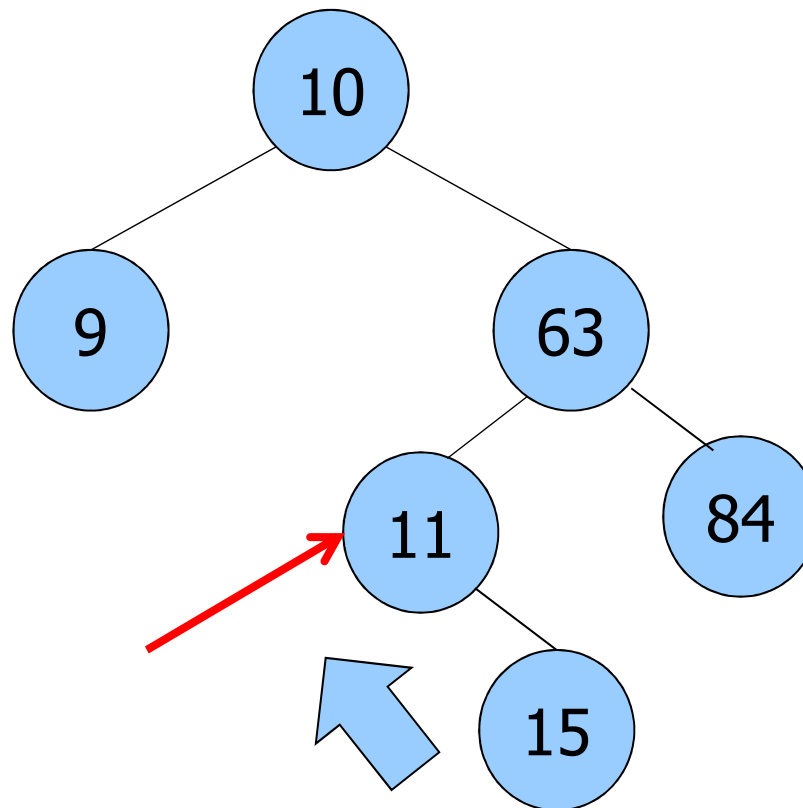




## Example: Rule 2

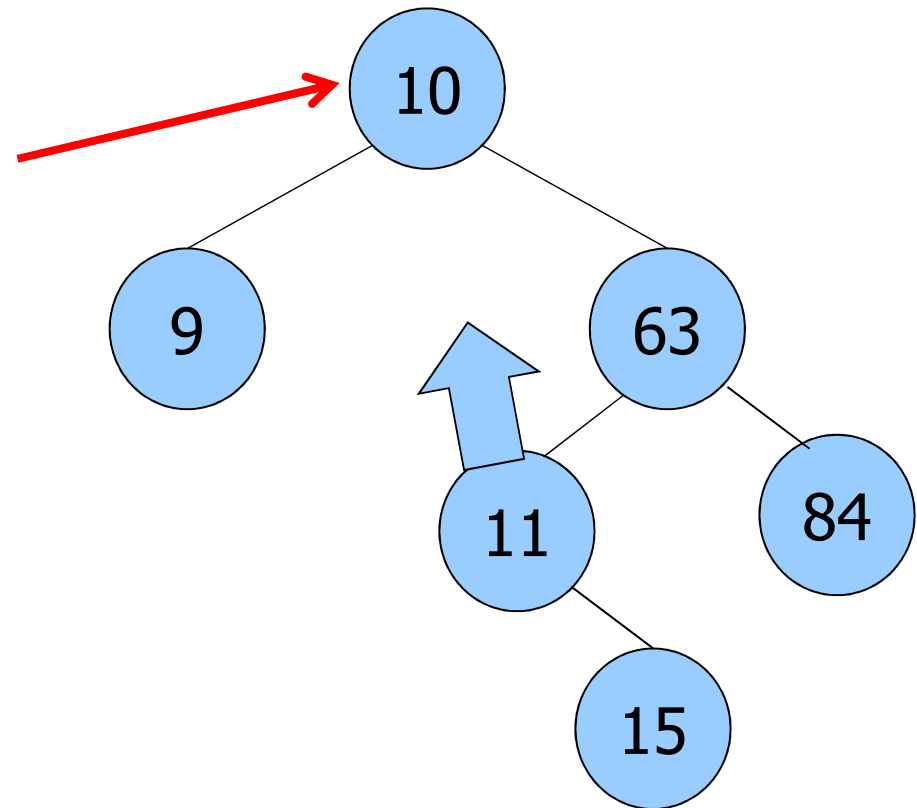
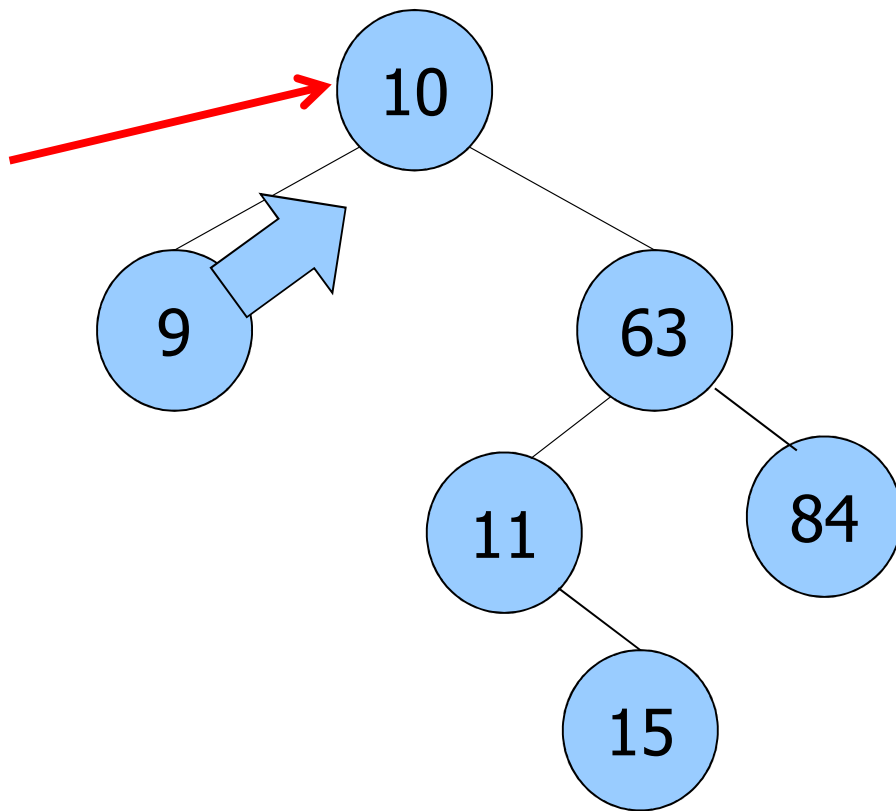
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Delete node with item (key) 11



## Example: Rule 3 (A and B)

Delete node with item (key) 10





# Implementation

## Recursive

```
link delete_r (link root, Item x, link z) {
    link p;
    Item val;

    if (root == z)
        return (root);
    if (ITEMless (x, root->item)) {
        root->l = delete_r (root->l, x, z);
        return (root);
    }
    if (ITEMless(root->item, x)) {
        root->r = delete_r (root->r, x, z);
        return (root);
    }
}
```

# Implementation

## Recursive

```
p = root;
if (root->r == z) {
    root = root->l;
    free (p);
    return (root);
}
if (root->l == z) {
    root = root->r;
    free (p);
    return (root);
}
root->l = max_delete_r (&val, root->l, z);
root->item = val;
return (root);
}
```

Node found

Rule 0 or 1 apply  
(right child NULL get left one)

Rule 0 or 1 apply  
(left child NULL get right one)

Rule 2 apply



# Implementation

## Recursive

```
link max_delete_r (Item *x, link root, link z) {  
    link tmp;  
  
    if (root->r == z) {  
        *x = root->item;  
        tmp = root->l;  
        free (root);  
        return (tmp);  
    }  
  
    root->r = max_delete_r (x, root->r, z);  
    return (root);  
}
```

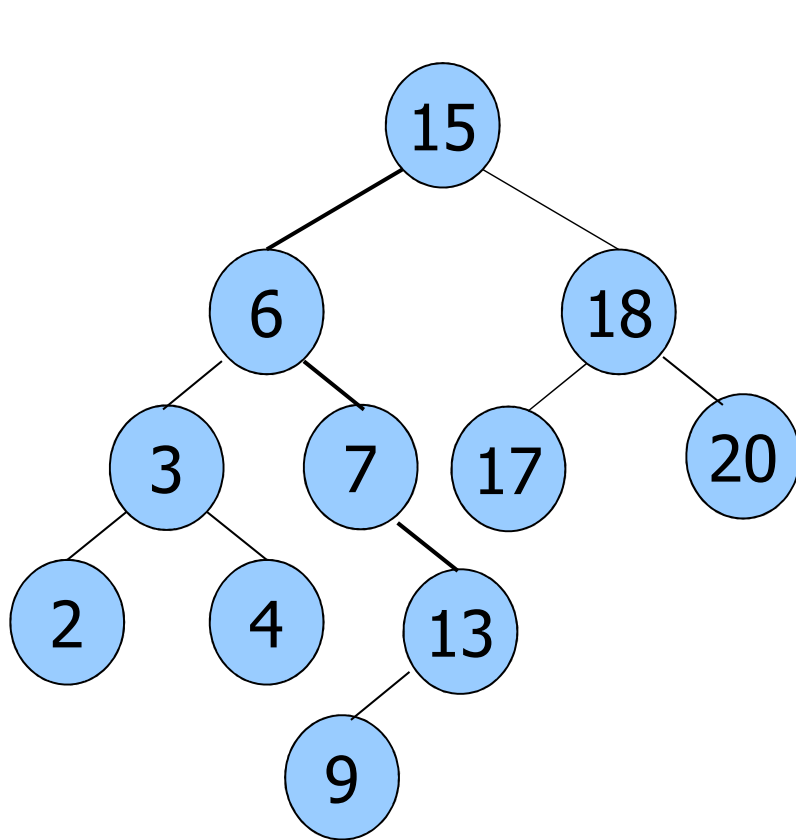
Find and delete  
max value  
into left child

Get key  
Free node  
Return pointer to left child

Recur until  
there is a  
right child

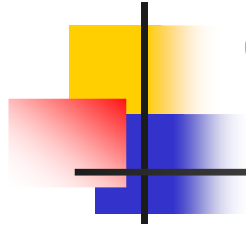
# Sort

An in-order visit delivers keys in **ascending order**



2 3 4 6 7 9 13 15 17 18 20

The (inferior) **median key** of a set of  $n$  element is the element stored in position  $\lfloor (n + 1)/2 \rfloor$  in the ordered sequence of the element set



# Complexity

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Operations on BSTs have complexity  $T(n) = O(h)$  where  $h$  is the height of the tree

- Tree fully balanced with  $n$  nodes
  - Height  $h = \alpha(\log_2 n)$
- Tree completely unbalanced with  $n$  nodes
  - Height  $h = \alpha(n)$
- $O(\log n) \leq T(n) \leq O(n)$