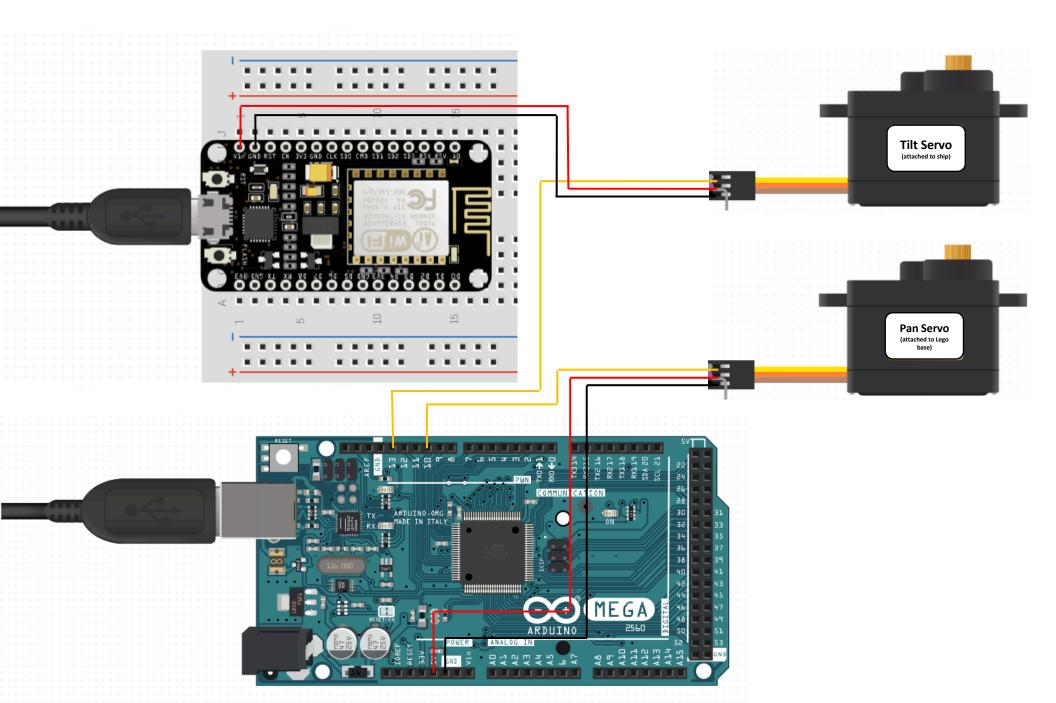
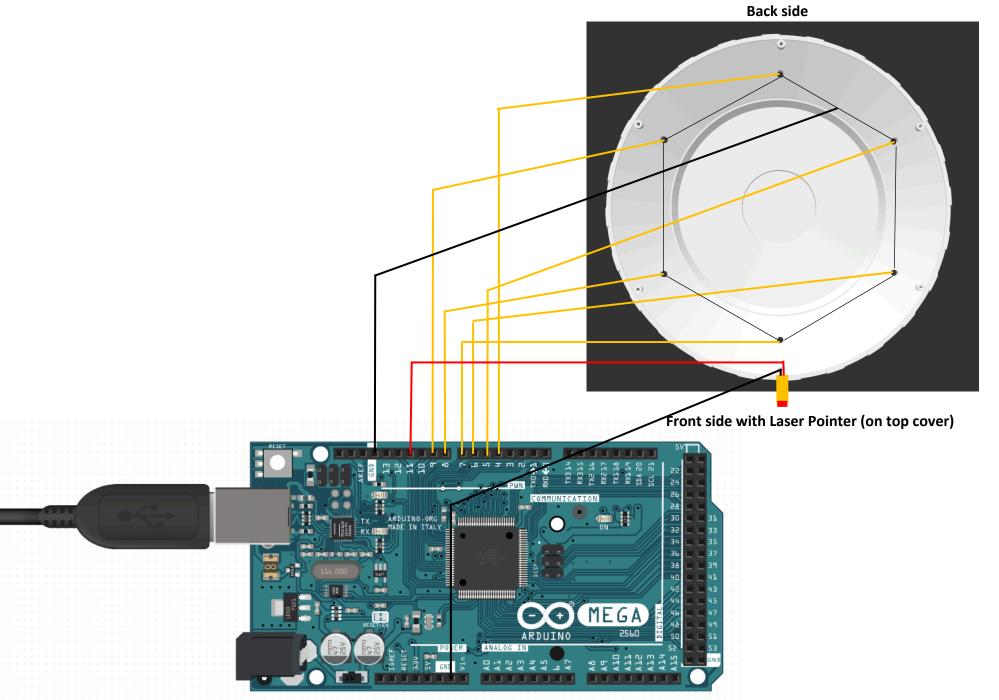
## Connecting the Pan and Tilt servos for the spaceship to the Arduino Mega

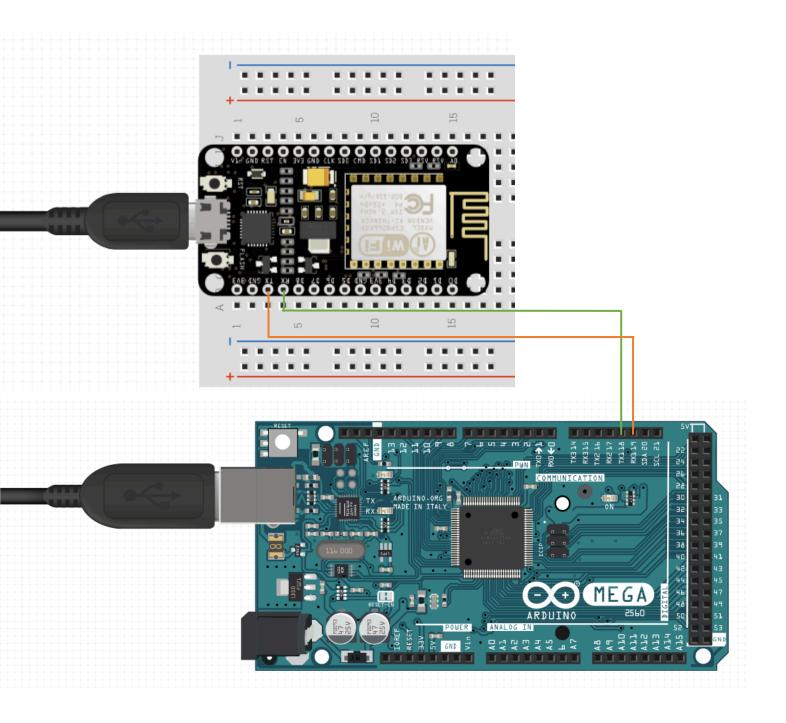


## Connecting the LEDs and Laser on the spaceship to the Arduino Mega

Birds-eye view of the spaceship (without top cover)



## Connecting the WiFi module for the spaceship to the Arduino Mega



## **Overall Schematic** Birds-eye view of the spaceship (without top cover) **Back side Tilt Servo** (attached to ship) Front side with Laser Pointer (on top cover) 26 30 32 34 36 36 40 Pan Servo (attached to Lego base) ARDUINO