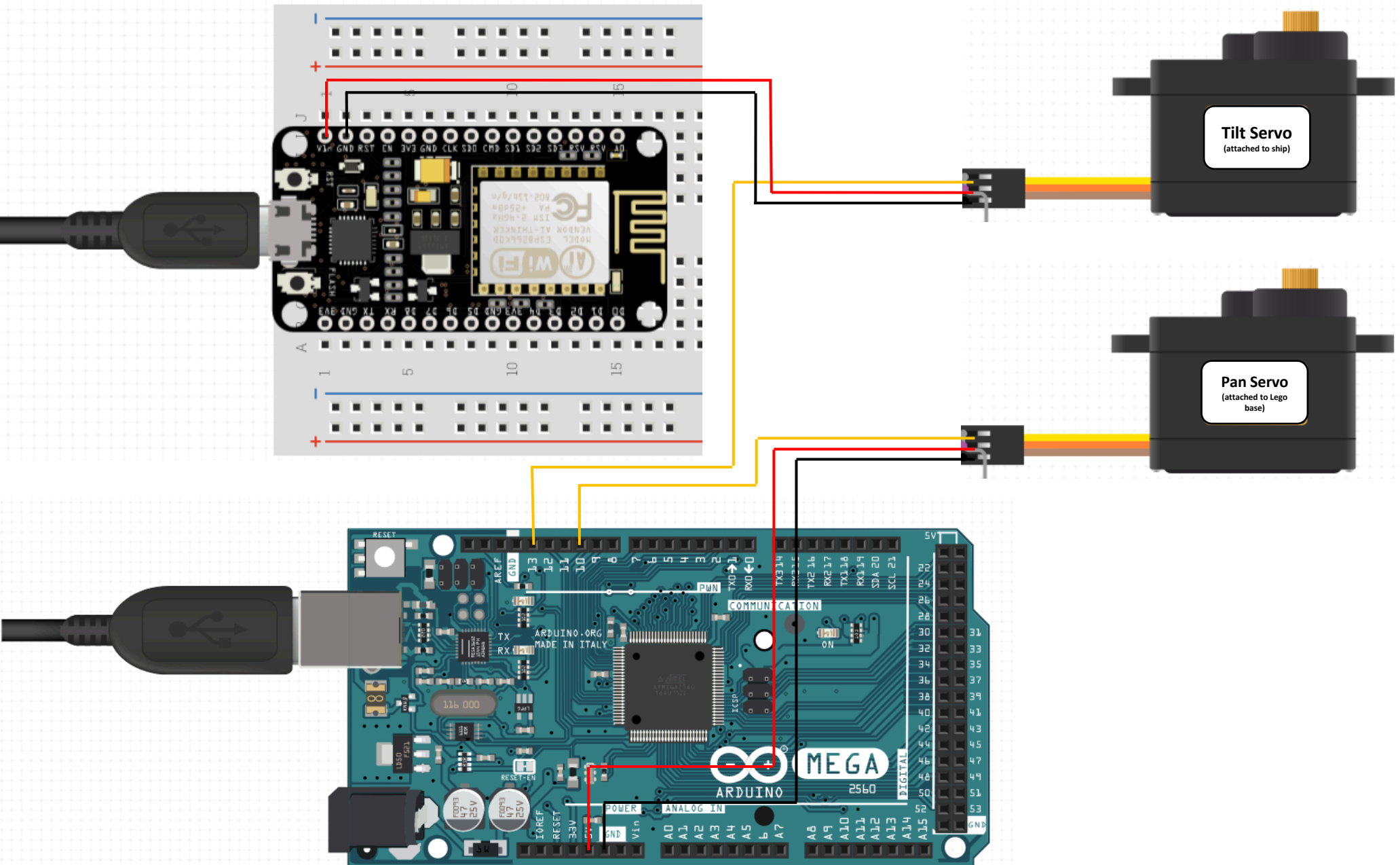


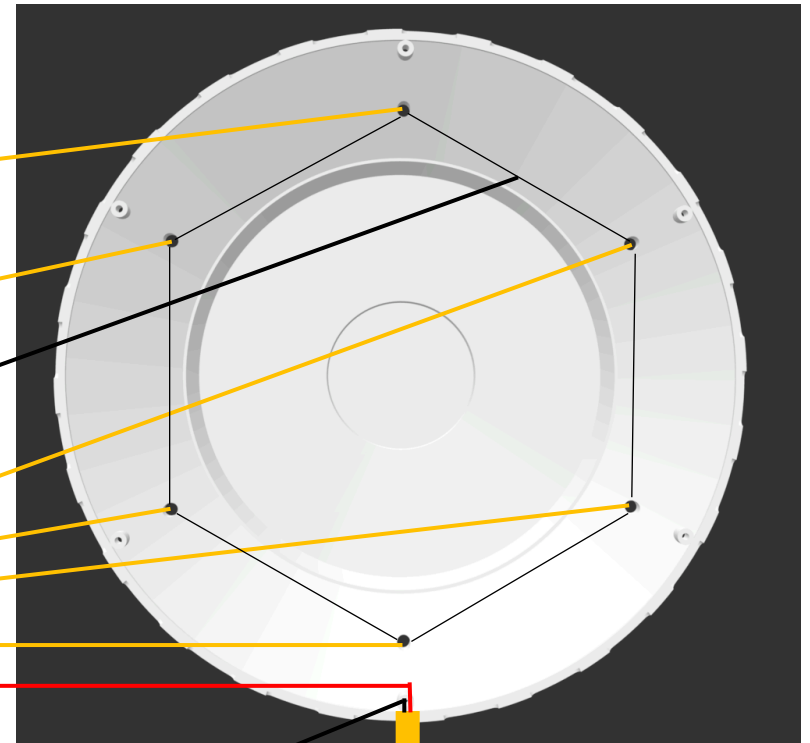
Connecting the Pan and Tilt servos for the spaceship to the Arduino Mega



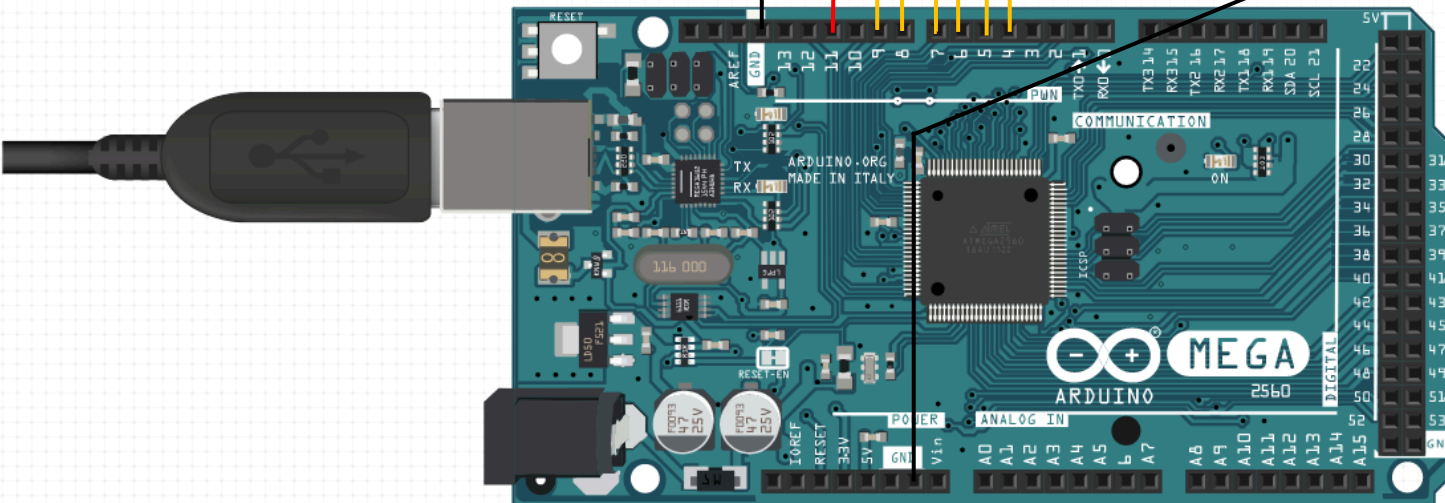
Connecting the LEDs and Laser on the spaceship to the Arduino Mega

Birds-eye view of the spaceship (without top cover)

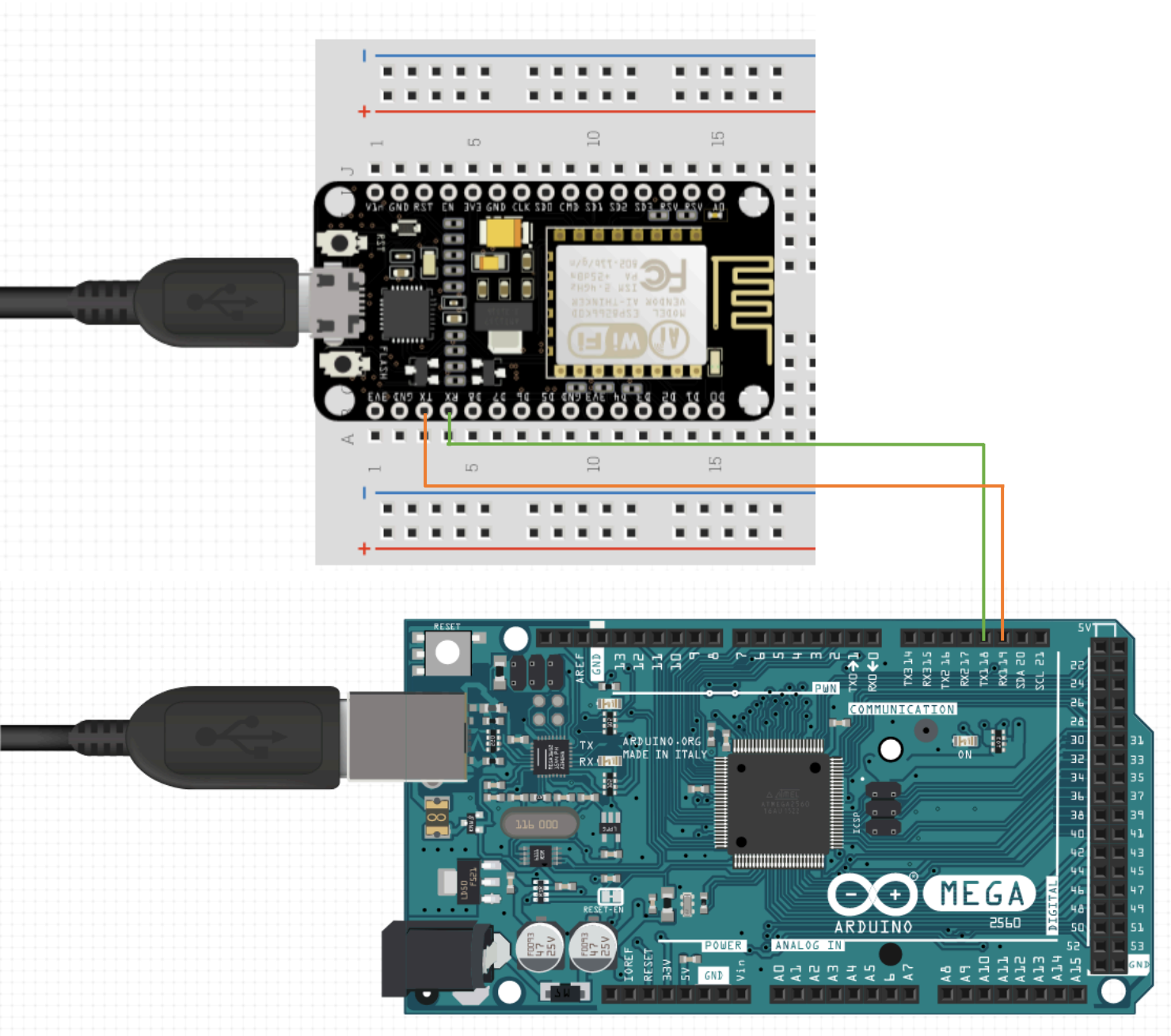
Back side



Front side with Laser Pointer (on top cover)



Connecting the WiFi module for the spaceship to the Arduino Mega



Overall Schematic

