

ISO Geodetic Registry

<i>Item class</i>	GeodeticCRS	
<i>Name</i>	IGS20 - XYZ	
<i>Item status</i>	VALID	
<i>Identifier</i>	980	
<i>Alias</i>	International GNSS Service 2020	
<i>Information source</i>	<i>Title</i>	Switch of the IGS products to the IGS20.igs20.atx, repro3 standards and long filenames
	<i>Author</i>	Salim Masoumi
	<i>Publisher</i>	International GNSS Service (IGS)
	<i>Publication date</i>	2022-11-25
	<i>Series/Journal name</i>	IGSMail
	<i>Issue identification</i>	8282
	<i>Other citation details</i>	https://lists.igs.org/pipermail/igsmail/2022/008278.html (accessed 2023-01-27)
<i>Information source</i>	<i>Title</i>	Upcoming switch to IGS20/igs20.atx and repro3 standards
	<i>Author</i>	Arturo Villiger
	<i>Publisher</i>	International GNSS Service (IGS)
	<i>Publication date</i>	2022-07-26
	<i>Series/Journal name</i>	IGSMail
	<i>Issue identification</i>	8238
	<i>Other citation details</i>	https://lists.igs.org/pipermail/igsmail/2022/008234.html (accessed 2023-01-27)
<i>Data source</i>	ISO Geodetic Registry	
<i>Remarks</i>	Replaces IGB14 - XYZ. Used by IGS products from 2022-11-27. An updated set of satellite and ground antenna calibrations defined in igs20.atx and post-seismic deformation models defined in psd_IGS20.snx must be used together with IGS20.	
<i>Scope</i>	Spatial referencing	
<i>Datum</i>	IGS20	
<i>Coordinate System</i>	Geocentric 3D right-handed Cartesian CS. Axes: Geocentric X,Y,Z. Orientation: Z to North Pole, [X and Y in the equatorial plane, X at Prime Meridian X in the equatorial plane at the Prime Meridian]. UoM: m.	

Extent

<i>Description</i>	World.	
<i>Geographic Bounding Box</i>	<i>West-bound longitude</i>	-180.0
	<i>North-bound latitude</i>	90.0
	<i>East-bound longitude</i>	180.0
	<i>South-bound latitude</i>	-90.0

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<i>Item class</i>	GeodeticDatum	
<i>Name</i>	IGS20	
<i>Item status</i>	VALID	
<i>Identifier</i>	979	
<i>Alias</i>	International GNSS Service 2020	
<i>Information source</i>	<i>Title</i>	Switch of the IGS products to the IGS20.igs20.atx, repro3 standards and long filenames
	<i>Author</i>	Salim Masoumi
	<i>Publisher</i>	International GNSS Service (IGS)
	<i>Publication date</i>	2022-11-25
	<i>Series/Journal name</i>	IGSMail
	<i>Issue identification</i>	8282
	<i>Other citation details</i>	https://lists.igs.org/pipermail/igsmail/2022/008278.html (accessed 2023-01-27)
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	<i>Publisher</i>	International GNSS Service (IGS)
	<i>Publication date</i>	2022-07-26
	<i>Series/Journal name</i>	IGSMail
	<i>Issue identification</i>	8238
	<i>Other citation details</i>	https://lists.igs.org/pipermail/igsmail/2022/008234.html (accessed 2023-01-27)
<i>Data source</i>	ISO Geodetic Registry	
<i>Remarks</i>	Replaces IGB14. Used by IGS products from 2022-11-27. An updated set of satellite and ground antenna calibrations defined in igs20.atx and post-seismic deformation models defined in psd_IGS20.snx must be used together with IGS20.	
<i>Anchor definition</i>	Derived from a long-term combination of daily IGS repro3 solutions from 1994 to 2020 and aligned in origin, scale and orientation and their rates of change to ITRF2020 at epoch 2015.0 via a subset of 332 stable, well performing IGS stations.	
<i>Release date</i>	2022-11-27	
<i>Coordinate Reference Epoch</i>	2015.0	
<i>Scope</i>	Spatial referencing	
<i>Ellipsoid</i>	GRS 1980	
<i>Prime Meridian</i>	Greenwich	

Extent

<i>Description</i>	World.	
<i>Geographic Bounding Box</i>	<i>West-bound longitude</i>	-180.0
	<i>North-bound latitude</i>	90.0
	<i>East-bound longitude</i>	180.0
	<i>South-bound latitude</i>	-90.0

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<i>Item class</i>	Ellipsoid														
<i>Name</i>	GRS 1980														
<i>Item status</i>	VALID														
<i>Identifier</i>	27														
<i>Alias</i>	Geodetic Reference System 1980														
<i>Alias</i>	GRS1980														
<i>Alias</i>	IAG GRS80														
<i>Alias</i>	International 1979														
<i>Alias</i>	GRS80														
<i>Information source</i>	<table> <tr> <td><i>Title</i></td><td>Geodetic Reference System 1980</td></tr> <tr> <td><i>Author</i></td><td>H. Moritz</td></tr> <tr> <td><i>Publisher</i></td><td>Springer International Publishing</td></tr> <tr> <td><i>Publication date</i></td><td>2003-03</td></tr> <tr> <td><i>Series/Journal name</i></td><td>Journal of Geodesy</td></tr> <tr> <td><i>Issue identification</i></td><td>Volume 74, No. 1</td></tr> <tr> <td><i>Page</i></td><td>128–162</td></tr> </table>	<i>Title</i>	Geodetic Reference System 1980	<i>Author</i>	H. Moritz	<i>Publisher</i>	Springer International Publishing	<i>Publication date</i>	2003-03	<i>Series/Journal name</i>	Journal of Geodesy	<i>Issue identification</i>	Volume 74, No. 1	<i>Page</i>	128–162
<i>Title</i>	Geodetic Reference System 1980														
<i>Author</i>	H. Moritz														
<i>Publisher</i>	Springer International Publishing														
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<i>Page</i>	128–162														
<i>Information source</i>	<table> <tr> <td><i>Title</i></td><td>Geodetic Reference System 1980</td></tr> <tr> <td><i>Author</i></td><td>H. Moritz</td></tr> <tr> <td><i>Publisher</i></td><td>International Association of Geodesy</td></tr> <tr> <td><i>Publication date</i></td><td>1984</td></tr> <tr> <td><i>Series/Journal name</i></td><td>Bulletin Geodesique</td></tr> <tr> <td><i>Issue identification</i></td><td>Volume 58, No. 3</td></tr> <tr> <td><i>Page</i></td><td>395-405</td></tr> </table>	<i>Title</i>	Geodetic Reference System 1980	<i>Author</i>	H. Moritz	<i>Publisher</i>	International Association of Geodesy	<i>Publication date</i>	1984	<i>Series/Journal name</i>	Bulletin Geodesique	<i>Issue identification</i>	Volume 58, No. 3	<i>Page</i>	395-405
<i>Title</i>	Geodetic Reference System 1980														
<i>Author</i>	H. Moritz														
<i>Publisher</i>	International Association of Geodesy														
<i>Publication date</i>	1984														
<i>Series/Journal name</i>	Bulletin Geodesique														
<i>Issue identification</i>	Volume 58, No. 3														
<i>Page</i>	395-405														
<i>Data source</i>	ISO Geodetic Registry														
<i>Remarks</i>	Adopted by IUGG 1979 Canberra. Inverse flattening is derived from geocentric gravitational constant $GM = 3986005e8 \text{ m}^3/\text{s}^2$, dynamic form factor $J_2 = 108263e-8$ and Earth's angular velocity = $7292115e-11 \text{ rad/s}$.														
<i>Semi-major axis</i>	6378137.0 m														
<i>Inverse flattening</i>	298.257222101 m														

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<i>Item class</i>	PrimeMeridian	
<i>Name</i>	Greenwich	
<i>Item status</i>	VALID	
<i>Identifier</i>	25	
<i>Alias</i>	Zero meridian	
<i>Information source</i>	<i>Title</i>	Why the Greenwich meridian moved
	<i>Author</i>	S. Malys, J.H. Seago, N.K. Pavlis, P.K. Seidelmann, G.H. Kaplan
	<i>Publisher</i>	Springer International Publishing
	<i>Publication date</i>	2015-12
	<i>Series/Journal name</i>	Journal of Geodesy
	<i>Issue identification</i>	Volume 89, No. 12
	<i>Page</i>	1263–1272
	<i>Title</i>	IERS Conventions (2010)
	<i>Author</i>	G. Petit, B.J. Luzum (eds)
	<i>Publisher</i>	Verlag des Bundesamts für Kartographie und Geodäsie
<i>Information source</i>	<i>Publication date</i>	2010
	<i>Edition date</i>	
	<i>Series/Journal name</i>	IERS Technical Notes
	<i>Issue identification</i>	36.0
	<i>Other citation details</i>	ISSN: 1019-4568
<i>Data source</i>	ISO Geodetic Registry	
<i>Greenwich longitude</i>	0.0 °	

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Item class	CartesianCS	
Name	Geocentric 3D right-handed Cartesian CS. Axes: Geocentric X,Y,Z. Orientation: Z to North Pole, [X and Y in the equatorial plane, X at Prime Meridian X in the equatorial plane at the Prime Meridian]. UoM: m.	
Item status	VALID	
Identifier	45	
Alias	Earth centred, earth fixed, right-handed 3D coordinate system, consisting of 3 orthogonal axes with X and Y axes in the equatorial plane, positive Z-axis parallel to mean earth rotation axis and pointing towards North Pole. UoM: m.	
Alias	ECEF	
Information source	Title	ISO 19111 Geographical information - Spatial referencing by coordinates
	Author	International Organization for Standardization (ISO)
	Publisher	International Organization for Standardization (ISO)
	Publication date	2007-07-01
	Edition	Second Edition
	Series/Journal name	International Standard
	Issue identification	ISO 19111:2007
Data source	ISO Geodetic Registry	
Remarks	Used in geocentric coordinate reference systems.	

Axes

Item class	CoordinateSystemAxis	
Name	Geocentric X	
Item status	VALID	
Identifier	33	
Information source	Title	ISO 19111 Geographical information - Spatial referencing by coordinates
	Author	International Organization for Standardization (ISO)
	Publisher	International Organization for Standardization (ISO)
	Publication date	2007-07-01
	Edition	Second Edition
	Series/Journal name	International Standard
	Issue identification	ISO 19111:2007
Data source	ISO Geodetic Registry	
Abbreviation	X	
Direction	Geocentre > equator/0°E	
Unit	metre	

Item class	CoordinateSystemAxis	
Name	Geocentric Y	
Item status	VALID	
Identifier	37	

<i>Information source</i>	<i>Title</i> ISO 19111 Geographical information - Spatial referencing by coordinates <i>Author</i> International Organization for Standardization (ISO) <i>Publisher</i> International Organization for Standardization (ISO) <i>Publication date</i> 2007-07-01 <i>Edition</i> Second Edition <i>Series/Journal name</i> International Standard <i>Issue identification</i> ISO 19111:2007
<i>Data source</i>	ISO Geodetic Registry
<i>Abbreviation</i>	Y
<i>Direction</i>	Geocentre > equator/90°E
<i>Unit</i>	metre

<i>Item class</i>	CoordinateSystemAxis
<i>Name</i>	Geocentric Z
<i>Item status</i>	VALID
<i>Identifier</i>	39
<i>Information source</i>	<i>Title</i> ISO 19111 Geographical information - Spatial referencing by coordinates <i>Author</i> International Organization for Standardization (ISO) <i>Publisher</i> International Organization for Standardization (ISO) <i>Publication date</i> 2007-07-01 <i>Edition</i> Second Edition <i>Series/Journal name</i> International Standard <i>Issue identification</i> ISO 19111:2007
<i>Data source</i>	ISO Geodetic Registry
<i>Abbreviation</i>	Z
<i>Direction</i>	Geocentre > north pole
<i>Unit</i>	metre