Item class GeodeticCRS

Name ITRF89 - XYZ

Item status VALID Identifier 387

Alias International Terrestrial Reference Frame 1989

Alias IERS Terrestrial Reference Frame 1989

Information source Title ITRF 89 and other realizations of the IERS

Terrestrial Reference System for 1989

Author C. Boucher, Z. Altamimi

Publisher Central Bureau of IERS - Observatoire de Paris,

61 avenue de l'Observatoire, 75014 Paris, France

Publication date 1991-04-01

Edition date

Series/Journal name IERS Technical Notes

Issue identification 6.0 ISO Geodetic Registry

Remarks Replaces ITRF88 - XYZ. Replaced by ITRF90 - XYZ.

Scope Spatial referencing

Datum International Terrestrial Reference Frame 1989

Coordinate System Geocentric 3D right-handed Cartesian CS. Axes: Geocentric X,Y,Z.

Orientation: Z to North Pole, [X and Y in the equatorial plane, X at Prime Meridian | X in the equatorial plane at the Prime Meridian]. UoM:

m.

Extent

Data source

Description	World.	
Geographic Bounding Box	West-bound longitude	-180.0
	North-bound latitude	90.0
	East-bound longitude	180.0
	South-bound latitude	-90.0

Item class GeodeticDatum

Name International Terrestrial Reference Frame 1989

Item statusVALIDIdentifier192AliasITRF 89

Alias IERS Terrestrial Reference Frame 1989

Alias ITRF89

Information source Title ITRF 89 and other realizations of the IERS

Terrestrial Reference System for 1989

Author C. Boucher, Z. Altamimi

Publisher Central Bureau of IERS - Observatoire de Paris,

61 avenue de l'Observatoire, 75014 Paris, France

Publication date 1991-04-01

Edition date

Series/Journal name IERS Technical Notes

Issue identification 6.0

Information source Title IERS Conventions (2010)

Author G. Petit, B.J. Luzum (eds)

Publisher Verlag des Bundesamts fur Kartographie und

Geodasie

Publication date 2010

Edition date

Series/Journal name IERS Technical Notes

Issue identification 36.0

Other citation details ISSN: 1019-4568

Data source ISO Geodetic Registry

Remarks Replaces ITRF88. Replaced by ITRF90. This is a purely Cartesian

reference frame with no ellipsoid defined. GRS80 is the ellipsoid

recommended by the IAG and IERS.

Anchor definition Realisation of the IERS Terrestrial Reference System (ITRS) at

reference epoch 1988.0. Origin and scale are defined by an average of selected SLR solutions. Orientation is defined such that no global rotation exists with respect to ITRF88. Time evolution is defined by the AMO-2 plate motion model of Minster and Jordan (1978); no global velocity field was estimated for ITRF88. The AMO-2 model is used to estimate positions at other epochs. Datum defined by a set of 3 dimensional Cartesian station coordinates given by the citations.

Release date 1991-04-01 Coordinate Reference Epoch 1988.0

Scope Spatial referencing

Ellipsoid GRS 1980
Prime Meridian Greenwich

Extent

Description

World.

Geographic Bounding Box

North-bound latitude
East-bound longitude
South-bound latitude
90.0
180.0
90.0
90.0

Item class Ellipsoid

Name GRS 1980

Item status VALID Identifier 27

Alias Geodetic Reference System 1980

Alias GRS1980
Alias IAG GRS80

Alias International 1979

Alias GRS80

Information source Title Geodetic Reference System 1980

Author H. Moritz

Publisher Springer International Publishing

Publication date 2003-03

Series/Journal name Journal of Geodesy Issue identification Volume 74, No. 1

Page 128–162

Information source Title Geodetic Reference System 1980

Author H. Moritz

Publisher International Association of Geodesy

Publication date 1984

Series/Journal name Bulletin Geodesique Issue identification Volume 58, No. 3

Page 395-405

Data source ISO Geodetic Registry

Remarks Adopted by IUGG 1979 Canberra. Inverse flattening is derived from

geocentric gravitational constant GM = 3986005e8 m*m*m/s/s, dynamic form factor J2 = 108263e-8 and Earth's angular velocity =

7292115e-11 rad/s.

 Semi-major axis
 6378137.0 m

 Inverse flattening
 298.257222101 m

Item class PrimeMeridian

Name Greenwich

Item status VALID
Identifier 25

Alias Zero meridian

Information source Title Why the Greenwich meridian moved

Author S. Malys, J.H. Seago, N.K. Pavlis, P.K.

Seidelmann, G.H. Kaplan

Publisher Springer International Publishing

Publication date 2015-12

Series/Journal name Journal of Geodesy Issue identification Volume 89, No. 12

Page 1263–1272

Information source Title IERS Conventions (2010)

Author G. Petit, B.J. Luzum (eds)

Publisher Verlag des Bundesamts fur Kartographie und

Geodasie

Publication date 2010

Edition date

Series/Journal name IERS Technical Notes

Issue identification 36.0

Other citation details ISSN: 1019-4568

Data source ISO Geodetic Registry

Greenwich longitude 0.0 °

CartesianCS Item class

Name Geocentric 3D right-handed Cartesian CS.

Axes: Geocentric X,Y,Z. Orientation: Z to North

Pole, [X and Y in the equatorial plane, X at

Prime Meridian | X in the equatorial plane at the

Prime Meridian]. UoM: m.

Item status **VALID** Identifier 45

Alias Earth centred, earth fixed, right-handed 3D coordinate system,

> consisting of 3 orthogonal axes with X and Y axes in the equatorial plane, positive Z-axis parallel to mean earth rotation axis and pointing

towards North Pole. UoM: m.

Alias **ECEF**

Information source Title ISO 19111 Geographical information - Spatial

referencing by coordinates

International Organization for Standardization Author

(ISO)

Publisher International Organization for Standardization

(ISO)

2007-07-01 Publication date Second Edition Edition Series/Journal name International Standard Issue identification ISO 19111:2007

Data source ISO Geodetic Registry

Used in geocentric coordinate reference systems. Remarks

Axes

Item class CoordinateSystemAxis Name **Geocentric X** Item status **VALID** Identifier 33 Information source Title ISO 19111 Geographical information - Spatial referencing by coordinates Author International Organization for Standardization Publisher International Organization for Standardization (ISO) Publication date 2007-07-01 Edition Second Edition Series/Journal name International Standard Issue identification ISO 19111:2007

Data source ISO Geodetic Registry

Abbreviation Χ

Direction Geocentre > equator/0°E

Unit metre

Item class CoordinateSystemAxis

Name **Geocentric Y**

VALID Item status Identifier 37

Title ISO 19111 Geographical information - Spatial Information source

referencing by coordinates

Author International Organization for Standardization

(ISO)

Publisher International Organization for Standardization

(ISO)

2007-07-01 Publication date Edition Second Edition Series/Journal name International Standard

Issue identification ISO 19111:2007

Data source ISO Geodetic Registry

Abbreviation

Direction Geocentre > equator/90°E

Unit metre

CoordinateSystemAxis Item class

Name **Geocentric Z**

VALID Item status Identifier 39

Information source Title ISO 19111 Geographical information - Spatial

referencing by coordinates

Author International Organization for Standardization

(ISO)

Publisher International Organization for Standardization

(ISO)

2007-07-01 Publication date Edition Second Edition Series/Journal name International Standard Issue identification ISO 19111:2007

ISO Geodetic Registry

Abbreviation Ζ

Data source

Direction Geocentre > north pole

Unit metre