ISO Geodetic Registry

Item class Transformation Name

ITRF2014 to NAD 83 (2011) Epoch 2010 [NGS

v1] **VALID**

987

Information source Title Multi-Year CORS Solution 2 (MYCS2)

Coordinates

Author U.S. National Geodetc Survey (NGS) Publisher National Geodetc Survey (NGS), National

Oceanic and Atmospheric Administration (NOAA)

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mycs2/mycs2.shtml#htdp_params (accessed

2023-01-28)

ISO Geodetic Registry Data source

Remarks Transformation defines NAD 83 (2011) with respect to ITRF2014 and is

treated as errorless.

Operation version NGS v1

Scope Spatial referencing

Operation accuracy 0.0 m

Source CRS ITRF2014 - XYZ

Target CRS NAD 83 (2011) Epoch 2010 - XYZ

Operation method Time-Dependent Coordinate Frame Transformation (geocentric

Cartesian domain)

South-bound latitude

Extent

Item status

Identifier

Operation parameter values

14.92

Time reference 2010.0 year Rate of change of scale difference -0.07201 parts per billion per year Rate of change of Z-axis rotation -0.05133 milliarc-second per year Rate of change of Y-axis rotation -0.75744 milliarc-second per year Rate of change of X-axis rotation 0.06667 milliarc-second per year Rate of change of Z-axis translation -0.00144 metre per year Rate of change of Y-axis translation -6.0E-4 metre per year Rate of change of X-axis translation 7.9E-4 metre per year Scale difference 0.36891 parts per billion Z-axis rotation 10.93206 milliarc-second Y-axis rotation -0.42027 milliarc-second X-axis rotation 26.78138 milliarc-second Z-axis translation -0.54157 metre Y-axis translation -1.90921 metre X-axis translation 1.0053 metre

ISO Geodetic Registry

Item class OperationMethod

Name Time-Dependent Coordinate Frame

Transformation (geocentric Cartesian domain)

Item status VALID
Identifier 94

Alias Time-Dependent 7-Parameter Transformation

Alias 14-Parameter Transformation

Alias Time-Dependent Coordinate Frame Transformation

Data source ISO Geodetic Registry

Remarks Note the analogy with the Time-dependent Position Vector

Transformation but beware of the differences! The Position Vector

Transformation convention is used by IAG.

Formula Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

Operation parameters

X-axis translation

Y-axis translation

Z-axis translation

X-axis rotation

Y-axis rotation

Z-axis rotation

Scale difference

Rate of change of X-axis translation

Rate of change of Y-axis translation

Rate of change of Z-axis translation

Rate of change of X-axis rotation

Rate of change of Y-axis rotation

Rate of change of Z-axis rotation

Rate of change of scale difference

Time reference