ISO Geodetic Registry

Item class Transformation

Name ITRF92 to ITRF93 [IERS v1]

Item statusVALIDIdentifier540

Information source Title Results and Analysis of the ITRF93

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Publisher Central Bureau of IERS - Observatoire de Paris,

61 avenue de l'Observatoire, 75014 Paris, France

Publication date 1994-10-01

Edition date

Series/Journal name IERS Technical Notes

Issue identification 18.0 ISO Geodetic Registry

Remarks Citation gives the transformation from ITRF93 to ITRF92. Accuracy of

transformation is given at the reference epoch for the transformation parameters. Accuracy at other epochs depends on the accuracies of the parameters at the reference epoch and their rates of change. Refer to citations for accuracies of the parameters and their rates of change.

Operation version IERS v1

Scope Spatial referencing

Operation accuracy 0.003 m

Source CRS ITRF92 - XYZ

Target CRS ITRF93 - XYZ

Operation method Time-Dependent Position Vector Transformation (geocentric Cartesian

domain)

Extent

Data source

Description	World.	
Geographic Bounding Box	West-bound longitude	-180.0
	North-bound latitude	90.0
	East-bound longitude	180.0
	South-bound latitude	-90.0

Operation parameter values

Time reference	1988.0 year	
Rate of change of scale difference	0.0 parts per billion per year	
Rate of change of Z-axis rotation	0.05 milliarc-second per year	
Rate of change of Y-axis rotation	-0.19 milliarc-second per year	
Rate of change of X-axis rotation	-0.11 milliarc-second per year	
Rate of change of Z-axis translation	0.8 millimetre per year	
Rate of change of Y-axis translation	0.4 millimetre per year	
Rate of change of X-axis translation	-2.9 millimetre per year	İ
Scale difference	1.2 parts per billion	İ
Z-axis rotation	-0.96 milliarc-second	İ
Y-axis rotation	0.8 milliarc-second	İ
X-axis rotation	-0.39 milliarc-second	İ
Z-axis translation	-0.7 centimetre	İ
Y-axis translation	-0.7 centimetre	İ

ISO Geodetic Registry

Item class OperationMethod

Name Time-Dependent Position Vector

Transformation (geocentric Cartesian domain)

Item statusVALIDIdentifier82

Alias Time-Dependent 7-Parameter Transformation

Alias 14-Parameter Transformation

Alias Time-Dependent Position Vector Transformation

Data source ISO Geodetic Registry

Remarks Note the analogy with the rotation for the Time-dependent Coordinate

Frame Transformation but beware of the differences! The Position

Vector Transformation convention is used by IAG.

Formula Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

Operation parameters

X-axis translation

Y-axis translation

Z-axis translation

X-axis rotation

Y-axis rotation

Z-axis rotation

Scale difference

Rate of change of X-axis translation

Rate of change of Y-axis translation

Rate of change of Z-axis translation

Rate of change of X-axis rotation

Rate of change of Y-axis rotation

Rate of change of Z-axis rotation

Rate of change of scale difference

Time reference