## ISO Geodetic Registry

Item class Transformation

Name ITRF88 to ITRF89 [IERS v1]

Item statusVALIDIdentifier669

Information source Title IERS Conventions (2010)

Author G. Petit, B.J. Luzum (eds)

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Terrestrial Reference System for 1989

Author C. Boucher, Z. Altamimi

Publisher Central Bureau of IERS - Observatoire de Paris,

61 avenue de l'Observatoire, 75014 Paris, France

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Remarks No rates of change were estimated for the transformation parameters.

Operation version IERS v1

Scope Spatial referencing

Operation accuracy 0.01 m

Source CRS ITRF88 - XYZ
Target CRS ITRF89 - XYZ

Operation method Position Vector Transformation (geocentric Cartesian domain)

#### Extent

Data source

Description	World.	
Geographic Bounding Box	West-bound longitude	-180.0
	North-bound latitude	90.0
	East-bound longitude	180.0
	South-bound latitude	-90.0

### Operation parameter values

X-axis translation	5.0 millimetre	
Y-axis translation	36.0 millimetre	
Z-axis translation	24.0 millimetre	
X-axis rotation	0.0 milliarc-second	
Y-axis rotation	0.0 milliarc-second	
Z-axis rotation	0.0 milliarc-second	
Scale difference	-3.0 parts per billion	

# **ISO Geodetic Registry**

Item class OperationMethod

Name Position Vector Transformation (geocentric

**Cartesian domain)** 

Item statusVALIDIdentifier88

Alias 7-Parameter Transformation

Alias Bursa-Wolf Transformation

Alias Position Vector Transformation

Alias Helmert Transformation

Data source ISO Geodetic Registry

Remarks This method is a specific case of the Molodensky-Badekas (PV)

method in which the evaluation point is the geocentre with coordinate

values of zero. Note the analogy with the Coordinate Frame

Transformation method but beware of the differences!

Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

### Operation parameters

Formula

X-axis translation
Y-axis translation
Z-axis translation
X-axis rotation
Y-axis rotation
Z-axis rotation
Z-axis rotation
Scale difference