ISO Geodetic Registry

Item class Transformation

Name ITRF2000 to IGS00 [IGS v1]

Item statusVALIDIdentifier639

Information source Title Chronology of IGS Reference Frame Usage

Author International GNSS Service Analysis Centre

Coordinator

Publisher National Oceanic and Atmospheric Administration

(NOAA), National Geodetic Survey (NGS)

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Information source Title Towards ITRF2000

Author AC Coordinator

Publisher International GNSS Service (IGS)

Publication date 2001-11-20

Edition date

Series/Journal name IGSMAIL Issue identification 3605.0

Data source ISO Geodetic Registry

Remarks Null transformation. IGS00 is aligned to ITRF2000 and is treated as the

same reference frame.

Operation version IGS v1

Scope Spatial referencing

Operation accuracy 0.0 m

Source CRS ITRF2000 - XYZ
Target CRS IGS00 - XYZ

Operation method Time-Dependent Position Vector Transformation (geocentric Cartesian

domain)

Extent

Description	World.	
Geographic Bounding Box	West-bound longitude	-180.0
	North-bound latitude	90.0
	East-bound longitude	180.0
	South-bound latitude	-90.0

Operation parameter values

X-axis translation	0.0 millimetre
Y-axis translation	0.0 millimetre
Z-axis translation	0.0 millimetre
X-axis rotation	0.0 milliarc-second
Y-axis rotation	0.0 milliarc-second
Z-axis rotation	0.0 milliarc-second
Scale difference	0.0 parts per billion
Rate of change of X-axis translation	0.0 millimetre per year
Rate of change of Y-axis translation	0.0 millimetre per year
Rate of change of Z-axis translation	0.0 millimetre per year
Rate of change of X-axis rotation	0.0 milliarc-second per year
Rate of change of Y-axis rotation	0.0 milliarc-second per year

Rate of change of Z-axis rotation
Rate of change of scale difference
Time reference

0.0 milliarc-second per year0.0 parts per billion per year1998.0 year

ISO Geodetic Registry

Item class OperationMethod

Name Time-Dependent Position Vector

Transformation (geocentric Cartesian domain)

Item statusVALIDIdentifier82

Alias Time-Dependent 7-Parameter Transformation

Alias 14-Parameter Transformation

Alias Time-Dependent Position Vector Transformation

Data source ISO Geodetic Registry

Remarks Note the analogy with the rotation for the Time-dependent Coordinate

Frame Transformation but beware of the differences! The Position

Vector Transformation convention is used by IAG.

Formula Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

Operation parameters

X-axis translation

Y-axis translation

Z-axis translation

X-axis rotation

Y-axis rotation

Z-axis rotation

Scale difference

Rate of change of X-axis translation

Rate of change of Y-axis translation

Rate of change of Z-axis translation

Rate of change of X-axis rotation

Rate of change of Y-axis rotation

Rate of change of Z-axis rotation

Rate of change of scale difference

Time reference