ISO Geodetic Registry

Item class Transformation

Name ITRF2000 to SIRGAS2000 [SIRv1]

Item statusVALIDIdentifier485

Information source Title Sistema de Referencia Geocentrico para las

Americas (SIRGAS)

Author Sistema de Referencia Geocéntrico para las

Américas (SIRGAS)

Publisher Sistema de Referencia Geocéntrico para las

Américas (SIRGAS)

Publication date 2018
Other citation details Website

Information source Title Use of velocities in the processing of GNSS data

Author Sistema de Referencia Geocéntrico para las

Américas (SIRGAS)

Publisher Sistema de Referencia Geocéntrico para las

Américas (SIRGAS)

Publication date 2017 Other citation details Website

Data source ISO Geodetic Registry

Remarks Null reference frame transformation between ITRF2000 and

SIRGAS2000.

Operation version SIRv1

Scope Spatial referencing

Operation accuracy 0.01 m

Source CRS ITRF2000 - LatLon
Target CRS SIRGAS2000 - LatLon

Operation method Time-Dependent Position Vector Transformation (geocentric Cartesian

domain)

Extent

Description	South America - onshor America - onshore and onshore and offshore.	
Geographic Bounding Box	West-bound longitude	-122.19
	North-bound latitude	32.72
	East-bound longitude	-25.28
	South-bound latitude	-59.87

Operation parameter values

2000.4 year
0.0 parts per billion per year
0.0 milliarc-second per year
0.0 milliarc-second per year
0.0 milliarc-second per year
0.0 millimetre per year
0.0 millimetre per year
0.0 millimetre per year
0.0 parts per billion

Z-axis rotation	0.0 milliarc-second	
Y-axis rotation	0.0 milliarc-second	
X-axis rotation	0.0 milliarc-second	
Z-axis translation	0.0 millimetre	
Y-axis translation	0.0 millimetre	
X-axis translation	0.0 millimetre	

ISO Geodetic Registry

Item class OperationMethod

Name Time-Dependent Position Vector

Transformation (geocentric Cartesian domain)

Item statusVALIDIdentifier82

Alias Time-Dependent 7-Parameter Transformation

Alias 14-Parameter Transformation

Alias Time-Dependent Position Vector Transformation

Data source ISO Geodetic Registry

Remarks Note the analogy with the rotation for the Time-dependent Coordinate

Frame Transformation but beware of the differences! The Position

Vector Transformation convention is used by IAG.

Formula Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

Operation parameters

X-axis translation

Y-axis translation

Z-axis translation

X-axis rotation

Y-axis rotation

Z-axis rotation

Scale difference

Rate of change of X-axis translation

Rate of change of Y-axis translation

Rate of change of Z-axis translation

Rate of change of X-axis rotation

Rate of change of Y-axis rotation

Rate of change of Z-axis rotation

Rate of change of scale difference

Time reference