ISO Geodetic Registry

Item class Transformation

NAD83(CSRS) v6 to NAD 83 (2011) [v1]

Item statusVALIDIdentifier482

Information source Title The Canadian Spatial Reference System (CSRS)

Author Canadian Geodetic Survey

Publisher Canadian Geodetic Survey, Surveyor General

Branch, Earth Sciences Sector, Natural Resources Canada, Government of Canada

Publication date 2016-08-30

Information source Title Introducing HTDP 3.1 to transform coordinates

across time and spatial reference frames

Author C. Pearson, R.A. Snay
Publisher Springer-Verlag
Publication date 2013-01-01
Edition date 2013-01-01
Series/Journal name GPS Solutions
Issue identification Volume 17, No. 1

Page 1-15

Other citation details NAD83 (2011), NAD83 (MA11), NAD83 (PA11)

transformation from IGb08

Information source Title Reference Frames: National

Author M. Craymer, J. Henton, D. Hutchinson, E. Lapelle,

M. Piraszewski

Publisher Canadian Geodetic Survey, Surveyor General

Branch, Earth Sciences Sector, Natural

Resources Canada

Publication date 2010-04-19

Series/Journal name Presentation to Canadian Geodetic Reference

Systems Committee Meeting, Ottawa, April 19-21,

2010

Data source ISO Geodetic Registry

Remarks Null transformation. NAD83(CSRS)v6 and NAD83(2011) are equivalent

by definition at epoch 2010.

Operation version v1

Scope Spatial referencing

Operation accuracy 0.0 m

Source CRS NAD83(CSRS) v6 - XYZ

Target CRS NAD 83 (2011) Epoch 2010 - XYZ

Operation method Time-Dependent Position Vector Transformation (geocentric Cartesian

domain)

Extent

North America - onshore and offshore: Canada - Alberta, British Columbia, Manitoba, New Brunswick, Newfoundland and Labrador, Northwest Territories, Nova Scotia, Nunavut, Ontario, Prince Edward Island, Quebec, Saskatchewan, Yukon. Puerto Rico. United States (USA) - Alaska, CONUS (Alabama, Arizona, Arkansas, California, Colorado,

Connecticut, Delaware, Florida, Georgia, Idaho, Illinois, Indiana, Iowa, Kansas, Kentucky, Louisiana, Maine, Maryland, Massachusetts, Michigan, Minnesota, Mississippi, Missouri, Montana, Nebraska, Nevada, New Hampshire, New Jersey, New Mexico, New York, North Carolina, North Dakota, Ohio, Oklahoma, Oregon, Pennsylvania, Rhode Island, South Carolina, South Dakota, Tennessee, Texas, Utah, Vermont, Virginia, Washington, West Virginia, Wisconsin, Wyoming). Virgin Islands (US).

Geographic Bounding Box

West-bound longitude167.65North-bound latitude86.46East-bound longitude-47.74South-bound latitude14.92

Operation parameter values

Time reference	2010.0 year
Rate of change of scale difference	0.0 parts per billion per year
Rate of change of Z-axis rotation	0.0 milliarc-second per year
Rate of change of Y-axis rotation	0.0 milliarc-second per year
Rate of change of X-axis rotation	0.0 milliarc-second per year
Rate of change of Z-axis translation	0.0 metre per year
Rate of change of Y-axis translation	0.0 metre per year
Rate of change of X-axis translation	0.0 metre per year
Scale difference	0.0 parts per billion
Z-axis rotation	0.0 milliarc-second
Y-axis rotation	0.0 milliarc-second
X-axis rotation	0.0 milliarc-second
Z-axis translation	0.0 metre
Y-axis translation	0.0 metre
X-axis translation	0.0 metre

ISO Geodetic Registry

Item class OperationMethod

Name Time-Dependent Position Vector

Transformation (geocentric Cartesian domain)

Item status VALID Identifier 82

Alias Time-Dependent 7-Parameter Transformation

Alias 14-Parameter Transformation

Alias Time-Dependent Position Vector Transformation

Data source ISO Geodetic Registry

Remarks Note the analogy with the rotation for the Time-dependent Coordinate

Frame Transformation but beware of the differences! The Position

Vector Transformation convention is used by IAG.

Formula Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

Operation parameters

X-axis translation

Y-axis translation

Z-axis translation

X-axis rotation

Y-axis rotation

Z-axis rotation

Scale difference

Rate of change of X-axis translation

Rate of change of Y-axis translation

Rate of change of Z-axis translation

Rate of change of X-axis rotation

Rate of change of Y-axis rotation

Rate of change of Z-axis rotation

Rate of change of scale difference

Time reference