

# ISO Geodetic Registry

<i>Item class</i>	Transformation	
<i>Name</i>	<b>ITRF2008 to IGS08 [IGS v1]</b>	
<i>Item status</i>	VALID	
<i>Identifier</i>	641	
<i>Information source</i>	<i>Title</i>	Chronology of IGS Reference Frame Usage
	<i>Author</i>	International GNSS Service Analysis Centre Coordinator
	<i>Publisher</i>	National Oceanic and Atmospheric Administration (NOAA), National Geodetic Survey (NGS)
	<i>Publication date</i>	2012-10-04
	<i>Other citation details</i>	Website
<i>Information source</i>	<i>Title</i>	Upcoming switch to IGS08/igs08.atx
	<i>Author</i>	P. Rebischung, R. Schmid, J. Ray
	<i>Publisher</i>	International GNSS Service (IGS)
	<i>Publication date</i>	2011-03-07
	<i>Edition date</i>	
<i>Information source</i>	<i>Series/Journal name</i>	IGSMail
	<i>Issue identification</i>	6354.0
	<i>Title</i>	IGS08: the IGS realization of ITRF2008
	<i>Author</i>	P. Rebischung
	<i>Publisher</i>	Springer
<i>Information source</i>	<i>Publication date</i>	2012-10-01
	<i>Edition date</i>	
	<i>Series/Journal name</i>	GPS Solutions
	<i>Issue identification</i>	Volume 16, Issue 4
<i>Data source</i>	ISO Geodetic Registry	
<i>Remarks</i>	Null transformation. IGS08 is aligned to ITRF2008 and is treated as the same reference frame.	
<i>Operation version</i>	IGS v1	
<i>Scope</i>	Spatial referencing	
<i>Operation accuracy</i>	0.0 m	
<i>Source CRS</i>	ITRF2008 - XYZ	
<i>Target CRS</i>	IGS08 - XYZ	
<i>Operation method</i>	Time-Dependent Position Vector Transformation (geocentric Cartesian domain)	

## Extent

<i>Description</i>	<b>World.</b>	
<i>Geographic Bounding Box</i>	<i>West-bound longitude</i>	-180.0
	<i>North-bound latitude</i>	90.0
	<i>East-bound longitude</i>	180.0
	<i>South-bound latitude</i>	-90.0

## Operation parameter values

<i>X-axis translation</i>	0.0 millimetre
<i>Y-axis translation</i>	0.0 millimetre
<i>Z-axis translation</i>	0.0 millimetre
<i>X-axis rotation</i>	0.0 milliarc-second
<i>Y-axis rotation</i>	0.0 milliarc-second
<i>Z-axis rotation</i>	0.0 milliarc-second

<i>Scale difference</i>	0.0 parts per billion
<i>Rate of change of X-axis translation</i>	0.0 millimetre per year
<i>Rate of change of Y-axis translation</i>	0.0 millimetre per year
<i>Rate of change of Z-axis translation</i>	0.0 millimetre per year
<i>Rate of change of X-axis rotation</i>	0.0 milliarc-second per year
<i>Rate of change of Y-axis rotation</i>	0.0 milliarc-second per year
<i>Rate of change of Z-axis rotation</i>	0.0 milliarc-second per year
<i>Rate of change of scale difference</i>	0.0 parts per billion per year
<i>Time reference</i>	2005.0 year

# ISO Geodetic Registry

<i>Item class</i>	OperationMethod
<i>Name</i>	<b>Time-Dependent Position Vector Transformation (geocentric Cartesian domain)</b>
<i>Item status</i>	VALID
<i>Identifier</i>	82
<i>Alias</i>	Time-Dependent 7-Parameter Transformation
<i>Alias</i>	14-Parameter Transformation
<i>Alias</i>	Time-Dependent Position Vector Transformation
<i>Data source</i>	ISO Geodetic Registry
<i>Remarks</i>	Note the analogy with the rotation for the Time-dependent Coordinate Frame Transformation but beware of the differences! The Position Vector Transformation convention is used by IAG.
<i>Formula</i>	Geomatics Guidance Note No 7, part 2: Coordinate Conversions and Transformations including Formulas

## Operation parameters

<i>X-axis translation</i>
<i>Y-axis translation</i>
<i>Z-axis translation</i>
<i>X-axis rotation</i>
<i>Y-axis rotation</i>
<i>Z-axis rotation</i>
<i>Scale difference</i>
<i>Rate of change of X-axis translation</i>
<i>Rate of change of Y-axis translation</i>
<i>Rate of change of Z-axis translation</i>
<i>Rate of change of X-axis rotation</i>
<i>Rate of change of Y-axis rotation</i>
<i>Rate of change of Z-axis rotation</i>
<i>Rate of change of scale difference</i>
<i>Time reference</i>