

# ISO Geodetic Registry

<i>Item class</i>	GeodeticCRS	
<i>Name</i>	<b>ETRF94 - XYZ</b>	
<i>Item status</i>	VALID	
<i>Identifier</i>	206	
<i>Alias</i>	European Terrestrial Reference Frame 1994	
<i>Information source</i>	<i>Title</i>	ETRS89 realization: Current status, ETRF2005 and Future Development
	<i>Author</i>	Z. Altamimi
	<i>Publication date</i>	2008-06-17
	<i>Edition date</i>	
<i>Information source</i>	<i>Title</i>	EUREF Technical Note 1: Relationship and Transformation between the International and the European Terrestrial Reference Systems
	<i>Author</i>	Z. Altamimi
	<i>Publisher</i>	Institut National de l'Information Géographique et Forestière (IGN), France
	<i>Publication date</i>	2018-06-28
<i>Information source</i>	<i>Series/Journal name</i>	IERS Technical Note
	<i>Issue identification</i>	1.0
	<i>Title</i>	Effect of recent revisions to the geomagnetic reversal time scale on estimates of current plate motions
	<i>Author</i>	C.S. DeMets, R.G. Gordon, D.F. Argus, S. Stein
<i>Information source</i>	<i>Publisher</i>	American Geophysical Union
	<i>Publication date</i>	1994-10-01
	<i>Edition date</i>	
	<i>Series/Journal name</i>	Geophysical Research Letters
<i>Information source</i>	<i>Issue identification</i>	Volume 21, Issue 20
	<i>Title</i>	Memo : Specifications for reference frame fixing in the analysis of a EUREF GPS campaign (version 8)
	<i>Author</i>	C. Boucher, Z. Altamimi
	<i>Publisher</i>	Institute National de l'Information Geographique et Forestiere (IGN), Laboratoire de Recherche en Geodesie (LAREG)
<i>Data source</i>	<i>Publication date</i>	2011-05-18
	<i>Edition date</i>	
<i>Scope</i>	Spatial referencing	
<i>Datum</i>	European Terrestrial Reference Frame 1994	
<i>Coordinate System</i>	Geocentric 3D right-handed Cartesian CS. Axes: Geocentric X,Y,Z. Orientation: Z to North Pole, [X and Y in the equatorial plane, X at Prime Meridian   X in the equatorial plane at the Prime Meridian]. UoM: m.	

## Extent

<i>Description</i>	<b>Europe - onshore and offshore: Albania, Andorra, Austria, Belgium, Bosnia and Herzegovina, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Faroe Islands, Finland, France, Germany, Gibraltar, Greece, Hungary, Ireland, Italy, Latvia,</b>
--------------------	---

**Liechtenstein, Lithuania, Luxembourg, Macedonia, Malta, Monaco, Montenegro, Netherlands, Norway including Svalbard and Jan Mayen, Poland, Portugal, Romania, San Marino, Serbia, Slovakia, Slovenia, Spain, Sweden, Switzerland, United Kingdom (UK) including Channel Islands and Isle of Man, Vatican City State.**

*Geographic Bounding Box*

*West-bound longitude*

-16.1

*North-bound latitude*

84.17

*East-bound longitude*

39.65

*South-bound latitude*

32.88

# ISO Geodetic Registry

<i>Item class</i>	GeodeticDatum	
<i>Name</i>	<b>European Terrestrial Reference Frame 1994</b>	
<i>Item status</i>	VALID	
<i>Identifier</i>	172	
<i>Alias</i>	ETRF94	
<i>Information source</i>	<i>Title</i>	EUREF Technical Note 1: Relationship and Transformation between the International and the European Terrestrial Reference Systems
	<i>Author</i>	Z. Altamimi
	<i>Publisher</i>	Institut National de l'Information Géographique et Forestière (IGN), France
	<i>Publication date</i>	2018-06-28
	<i>Series/Journal name</i>	IERS Technical Note
<i>Information source</i>	<i>Issue identification</i>	1.0
	<i>Title</i>	Memo : Specifications for reference frame fixing in the analysis of a EUREF GPS campaign (version 8)
	<i>Author</i>	C. Boucher, Z. Altamimi
	<i>Publisher</i>	Institute National de l'Information Geographique et Forestiere (IGN), Laboratoire de Recherche en Geodesie (LAREG)
	<i>Publication date</i>	2011-05-18
<i>Information source</i>	<i>Edition date</i>	
	<i>Title</i>	ETRS89 realization: Current status, ETRF2005 and Future Development
	<i>Author</i>	Z. Altamimi
	<i>Publication date</i>	2008-06-17
	<i>Edition date</i>	
<i>Data source</i>	ISO Geodetic Registry	
<i>Remarks</i>	The ETRF94 reference frame is a realisation of the ETRS89 reference system.	
<i>Anchor definition</i>	Coincides with ITRF94 in orientation and scale at epoch 1989.0 realigned to ITRF89 at epoch 1989.0 using 3 translations and is fixed to the stable part of the Eurasian tectonic plate through 3 rotation rates derived from the NNR-NUVEL-1A geophysical model, representing the Eurasian plate's angular velocity about its Euler pole.	
<i>Coordinate Reference Epoch</i>	1989.0	
<i>Scope</i>	Spatial referencing	
<i>Ellipsoid</i>	GRS 1980	
<i>Prime Meridian</i>	Greenwich	

## Extent

<i>Description</i>	<b>Europe - onshore and offshore: Albania, Andorra, Austria, Belgium, Bosnia and Herzegovina, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Faroe Islands, Finland, France, Germany, Gibraltar, Greece, Hungary, Ireland, Italy, Latvia, Liechtenstein, Lithuania, Luxembourg, Macedonia, Malta, Monaco, Montenegro,</b>
--------------------	---

**Netherlands, Norway including Svalbard and Jan Mayen, Poland, Portugal, Romania, San Marino, Serbia, Slovakia, Slovenia, Spain, Sweden, Switzerland, United Kingdom (UK) including Channel Islands and Isle of Man, Vatican City State.**

*Geographic Bounding Box*

*West-bound longitude*

-16.1

*North-bound latitude*

84.17

*East-bound longitude*

39.65

*South-bound latitude*

32.88

# ISO Geodetic Registry

<i>Item class</i>	Ellipsoid														
<i>Name</i>	<b>GRS 1980</b>														
<i>Item status</i>	VALID														
<i>Identifier</i>	27														
<i>Alias</i>	Geodetic Reference System 1980														
<i>Alias</i>	GRS1980														
<i>Alias</i>	IAG GRS80														
<i>Alias</i>	International 1979														
<i>Alias</i>	GRS80														
<i>Information source</i>	<table> <tr> <td><i>Title</i></td><td>Geodetic Reference System 1980</td></tr> <tr> <td><i>Author</i></td><td>H. Moritz</td></tr> <tr> <td><i>Publisher</i></td><td>Springer International Publishing</td></tr> <tr> <td><i>Publication date</i></td><td>2003-03</td></tr> <tr> <td><i>Series/Journal name</i></td><td>Journal of Geodesy</td></tr> <tr> <td><i>Issue identification</i></td><td>Volume 74, No. 1</td></tr> <tr> <td><i>Page</i></td><td>128–162</td></tr> </table>	<i>Title</i>	Geodetic Reference System 1980	<i>Author</i>	H. Moritz	<i>Publisher</i>	Springer International Publishing	<i>Publication date</i>	2003-03	<i>Series/Journal name</i>	Journal of Geodesy	<i>Issue identification</i>	Volume 74, No. 1	<i>Page</i>	128–162
<i>Title</i>	Geodetic Reference System 1980														
<i>Author</i>	H. Moritz														
<i>Publisher</i>	Springer International Publishing														
<i>Publication date</i>	2003-03														
<i>Series/Journal name</i>	Journal of Geodesy														
<i>Issue identification</i>	Volume 74, No. 1														
<i>Page</i>	128–162														
<i>Information source</i>	<table> <tr> <td><i>Title</i></td><td>Geodetic Reference System 1980</td></tr> <tr> <td><i>Author</i></td><td>H. Moritz</td></tr> <tr> <td><i>Publisher</i></td><td>International Association of Geodesy</td></tr> <tr> <td><i>Publication date</i></td><td>1984</td></tr> <tr> <td><i>Series/Journal name</i></td><td>Bulletin Geodesique</td></tr> <tr> <td><i>Issue identification</i></td><td>Volume 58, No. 3</td></tr> <tr> <td><i>Page</i></td><td>395-405</td></tr> </table>	<i>Title</i>	Geodetic Reference System 1980	<i>Author</i>	H. Moritz	<i>Publisher</i>	International Association of Geodesy	<i>Publication date</i>	1984	<i>Series/Journal name</i>	Bulletin Geodesique	<i>Issue identification</i>	Volume 58, No. 3	<i>Page</i>	395-405
<i>Title</i>	Geodetic Reference System 1980														
<i>Author</i>	H. Moritz														
<i>Publisher</i>	International Association of Geodesy														
<i>Publication date</i>	1984														
<i>Series/Journal name</i>	Bulletin Geodesique														
<i>Issue identification</i>	Volume 58, No. 3														
<i>Page</i>	395-405														
<i>Data source</i>	ISO Geodetic Registry														
<i>Remarks</i>	Adopted by IUGG 1979 Canberra. Inverse flattening is derived from geocentric gravitational constant $GM = 3986005e8 \text{ m}^3/\text{s}^2$ , dynamic form factor $J_2 = 108263e-8$ and Earth's angular velocity = $7292115e-11 \text{ rad/s}$ .														
<i>Semi-major axis</i>	6378137.0 m														
<i>Inverse flattening</i>	298.257222101 m														

# ISO Geodetic Registry

<i>Item class</i>	PrimeMeridian	
<i>Name</i>	<b>Greenwich</b>	
<i>Item status</i>	VALID	
<i>Identifier</i>	25	
<i>Alias</i>	Zero meridian	
<i>Information source</i>	<i>Title</i>	Why the Greenwich meridian moved
	<i>Author</i>	S. Malys, J.H. Seago, N.K. Pavlis, P.K. Seidelmann, G.H. Kaplan
	<i>Publisher</i>	Springer International Publishing
	<i>Publication date</i>	2015-12
	<i>Series/Journal name</i>	Journal of Geodesy
	<i>Issue identification</i>	Volume 89, No. 12
	<i>Page</i>	1263–1272
<i>Information source</i>	<i>Title</i>	IERS Conventions (2010)
	<i>Author</i>	G. Petit, B.J. Luzum (eds)
	<i>Publisher</i>	Verlag des Bundesamts fur Kartographie und Geodasie
	<i>Publication date</i>	2010
	<i>Edition date</i>	
	<i>Series/Journal name</i>	IERS Technical Notes
	<i>Issue identification</i>	36.0
<i>Data source</i>	<i>Other citation details</i>	ISSN: 1019-4568
	ISO Geodetic Registry	
<i>Greenwich longitude</i>	0.0 °	

# ISO Geodetic Registry

Item class	CartesianCS	
Name	<b>Geocentric 3D right-handed Cartesian CS.</b> <b>Axes: Geocentric X,Y,Z. Orientation: Z to North Pole, [X and Y in the equatorial plane, X at Prime Meridian   X in the equatorial plane at the Prime Meridian]. UoM: m.</b>	
Item status	VALID	
Identifier	45	
Alias	Earth centred, earth fixed, right-handed 3D coordinate system, consisting of 3 orthogonal axes with X and Y axes in the equatorial plane, positive Z-axis parallel to mean earth rotation axis and pointing towards North Pole. UoM: m.	
Alias	ECEF	
Information source	Title	ISO 19111 Geographical information - Spatial referencing by coordinates
	Author	International Organization for Standardization (ISO)
	Publisher	International Organization for Standardization (ISO)
	Publication date	2007-07-01
	Edition	Second Edition
	Series/Journal name	International Standard
	Issue identification	ISO 19111:2007
Data source	ISO Geodetic Registry	
Remarks	Used in geocentric coordinate reference systems.	

## Axes

Item class	CoordinateSystemAxis	
Name	<b>Geocentric X</b>	
Item status	VALID	
Identifier	33	
Information source	Title	ISO 19111 Geographical information - Spatial referencing by coordinates
	Author	International Organization for Standardization (ISO)
	Publisher	International Organization for Standardization (ISO)
	Publication date	2007-07-01
	Edition	Second Edition
	Series/Journal name	International Standard
	Issue identification	ISO 19111:2007
Data source	ISO Geodetic Registry	
Abbreviation	X	
Direction	Geocentre > equator/0°E	
Unit	metre	

Item class	CoordinateSystemAxis	
Name	<b>Geocentric Y</b>	
Item status	VALID	
Identifier	37	

<i>Information source</i>	<i>Title</i>	ISO 19111 Geographical information - Spatial referencing by coordinates
	<i>Author</i>	International Organization for Standardization (ISO)
	<i>Publisher</i>	International Organization for Standardization (ISO)
	<i>Publication date</i>	2007-07-01
	<i>Edition</i>	Second Edition
	<i>Series/Journal name</i>	International Standard
	<i>Issue identification</i>	ISO 19111:2007
<i>Data source</i>	ISO Geodetic Registry	
<i>Abbreviation</i>	Y	
<i>Direction</i>	Geocentre > equator/90°E	
<i>Unit</i>	metre	

<i>Item class</i>	CoordinateSystemAxis	
<i>Name</i>	<b>Geocentric Z</b>	
<i>Item status</i>	VALID	
<i>Identifier</i>	39	
<i>Information source</i>	<i>Title</i>	ISO 19111 Geographical information - Spatial referencing by coordinates
	<i>Author</i>	International Organization for Standardization (ISO)
	<i>Publisher</i>	International Organization for Standardization (ISO)
	<i>Publication date</i>	2007-07-01
	<i>Edition</i>	Second Edition
	<i>Series/Journal name</i>	International Standard
	<i>Issue identification</i>	ISO 19111:2007
<i>Data source</i>	ISO Geodetic Registry	
<i>Abbreviation</i>	Z	
<i>Direction</i>	Geocentre > north pole	
<i>Unit</i>	metre	