

# ISO Geodetic Registry

|                           |   |  |
|---------------------------|---|--|
| <i>Item class</i>         | Transformation  |  |
| <i>Name</i>               | <b>ITRF2008 to ETRF2000 [EUREF v1]</b>  |  |
| <i>Item status</i>        | VALID   |  |
| <i>Identifier</i>         | 527   |  |
| <i>Information source</i> | <i>Title</i>  | Memo : Specifications for reference frame fixing in the analysis of a EUREF GPS campaign (version 8)                             |
|                           | <i>Author</i>   | C. Boucher, Z. Altamimi  |
|                           | <i>Publisher</i>  | Institute National de l'Information Geographique et Forestiere (IGN), Laboratoire de Recherche en Geodesie (LAREG)               |
|                           | <i>Publication date</i>   | 2011-05-18   |
|                           | <i>Edition date</i>   |  |
| <i>Information source</i> | <i>Title</i>  | EUREF Technical Note 1: Relationship and Transformation between the International and the European Terrestrial Reference Systems |
|                           | <i>Author</i>   | Z. Altamimi  |
|                           | <i>Publisher</i>  | Institut National de l'Information Géographique et Forestière (IGN), France  |
|                           | <i>Publication date</i>   | 2018-06-28   |
|                           | <i>Series/Journal name</i>  | IERS Technical Note  |
|                           | <i>Issue identification</i>   | 1.0  |
| <i>Data source</i>        | ISO Geodetic Registry   |  |
| <i>Remarks</i>            | Accuracy of transformation is given at the reference epoch for the transformation parameters (2000.0); actual accuracy then depends on the epoch at which the transformation parameters are applied (refer to Citation for accuracies of velocities of the parameters). |  |
| <i>Operation version</i>  | EUREF v1  |  |
| <i>Scope</i>              | Spatial referencing   |  |
| <i>Operation accuracy</i> | 0.001 m   |  |
| <i>Source CRS</i>         | ITRF2008 - XYZ  |  |
| <i>Target CRS</i>         | ETRF2000 - XYZ  |  |
| <i>Operation method</i>   | Time-Dependent Position Vector Transformation (geocentric Cartesian domain)   |  |

## Extent

|                    |   |
|--------------------|---|
| <i>Description</i> | <p><b>Europe - onshore and offshore: Albania, Andorra, Austria, Belgium, Bosnia and Herzegovina, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Faroe Islands, Finland, France, Germany, Gibraltar, Greece, Hungary, Ireland, Italy, Latvia, Liechtenstein, Lithuania, Luxembourg, Macedonia, Malta, Monaco, Montenegro, Netherlands, Norway including Svalbard and Jan Mayen, Poland, Portugal, Romania, San Marino, Serbia, Slovakia, Slovenia, Spain, Sweden, Switzerland, United Kingdom (UK)</b></p> |
|--------------------|---|

|   |                             |       |
|---|-----------------------------|-------|
| <b>including Channel Islands and Isle of Man,<br/>Vatican City State.</b> |                             |       |
| <i>Geographic Bounding Box</i>  | <i>West-bound longitude</i> | -16.1 |
|   | <i>North-bound latitude</i> | 84.17 |
|   | <i>East-bound longitude</i> | 39.65 |
|   | <i>South-bound latitude</i> | 32.88 |

Operation parameter values

|   |                                 |
|---|---------------------------------|
| <i>X-axis translation</i>                   | 52.1 millimetre                 |
| <i>Y-axis translation</i>                   | 49.3 millimetre                 |
| <i>Z-axis translation</i>                   | -58.5 millimetre                |
| <i>X-axis rotation</i>                      | 0.891 milliarc-second           |
| <i>Y-axis rotation</i>                      | 5.39 milliarc-second            |
| <i>Z-axis rotation</i>                      | -8.712 milliarc-second          |
| <i>Scale difference</i>                     | 1.34 parts per billion          |
| <i>Rate of change of X-axis translation</i> | 0.1 millimetre per year         |
| <i>Rate of change of Y-axis translation</i> | 0.1 millimetre per year         |
| <i>Rate of change of Z-axis translation</i> | -1.8 millimetre per year        |
| <i>Rate of change of X-axis rotation</i>    | 0.081 milliarc-second per year  |
| <i>Rate of change of Y-axis rotation</i>    | 0.49 milliarc-second per year   |
| <i>Rate of change of Z-axis rotation</i>    | -0.792 milliarc-second per year |
| <i>Rate of change of scale difference</i>   | 0.08 parts per billion per year |
| <i>Time reference</i>                       | 2000.0 year                     |

# ISO Geodetic Registry

|                    |  |
|--------------------|--|
| <i>Item class</i>  | OperationMethod  |
| <i>Name</i>        | <b>Time-Dependent Position Vector Transformation (geocentric Cartesian domain)</b>   |
| <i>Item status</i> | VALID  |
| <i>Identifier</i>  | 82   |
| <i>Alias</i>       | Time-Dependent 7-Parameter Transformation  |
| <i>Alias</i>       | 14-Parameter Transformation  |
| <i>Alias</i>       | Time-Dependent Position Vector Transformation  |
| <i>Data source</i> | ISO Geodetic Registry  |
| <i>Remarks</i>     | Note the analogy with the rotation for the Time-dependent Coordinate Frame Transformation but beware of the differences! The Position Vector Transformation convention is used by IAG. |
| <i>Formula</i>     | Geomatics Guidance Note No 7, part 2: Coordinate Conversions and Transformations including Formulas  |

## Operation parameters

|   |
|---|
| <i>X-axis translation</i>                   |
| <i>Y-axis translation</i>                   |
| <i>Z-axis translation</i>                   |
| <i>X-axis rotation</i>                      |
| <i>Y-axis rotation</i>                      |
| <i>Z-axis rotation</i>                      |
| <i>Scale difference</i>                     |
| <i>Rate of change of X-axis translation</i> |
| <i>Rate of change of Y-axis translation</i> |
| <i>Rate of change of Z-axis translation</i> |
| <i>Rate of change of X-axis rotation</i>    |
| <i>Rate of change of Y-axis rotation</i>    |
| <i>Rate of change of Z-axis rotation</i>    |
| <i>Rate of change of scale difference</i>   |
| <i>Time reference</i>                       |