

ISO Geodetic Registry

<i>Item class</i>	GeodeticCRS	
<i>Name</i>	SIRGAS-CON SIR17P01 - XYZ	
<i>Item status</i>	VALID	
<i>Identifier</i>	273	
<i>Alias</i>	SIRGAS	
<i>Alias</i>	SIRGAS-CON	
<i>Alias</i>	SIRGAS Multi-Year Solution 2017	
<i>Alias</i>	Geocentric Reference System for the Americas	
<i>Alias</i>	Sistema de Referencia Geocentrico para las Americas	
<i>Alias</i>	SIR17P01	
<i>Information source</i>	<i>Title</i>	The varying surface kinematics in Latin America: VEMOS 2009, 2015, and 2017
	<i>Author</i>	L. Sanchez, H. Drewes
	<i>Publisher</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	<i>Publication date</i>	2017-11-28
	<i>Series/Journal name</i>	Symposium SIRGAS2017. Mendoza, Argentina. November 28, 2017
	<i>Other citation details</i>	Data for paper included in supplement: Drewes H. and Sanchez L. (2017): Velocity model for SIRGAS 2017: VEMOS2017, Technische Universitaet Muenchen, Deutsches Geodaetisches Forschungsinstitut (DGFI-TUM), IGS RNAAC
<i>Information source</i>	<i>Title</i>	SIRGAS reference frame realization SIR17P01
	<i>Author</i>	L. Sanchez
	<i>Publisher</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	<i>Publication date</i>	2018-08-14
	<i>Other citation details</i>	In supplement to: Sanchez L. (2017) Kinematics of the SIRGAS reference frame, Symposium SIRGAS2018. Mendoza, Argentina. November 28, 2017
<i>Information source</i>	<i>Title</i>	Velocity model for SIRGAS 2017: VEMOS2017
	<i>Author</i>	L. Sanchez, H. Drewes
	<i>Publisher</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	<i>Publication date</i>	2018-08-14
	<i>Other citation details</i>	In supplement to: Drewes H. and Sanchez L. (2017) The varying surface kinematics in Latin America: VEMOS 2009, 2015, and 2017, Symposium SIRGAS2017. Mendoza, Argentina. November 28, 2017
<i>Information source</i>	<i>Title</i>	Sistema de Referencia Geocentrico para las Americas (SIRGAS)
	<i>Author</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	<i>Publisher</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	<i>Publication date</i>	2018
	<i>Other citation details</i>	Website
<i>Information source</i>	<i>Title</i>	Kinematics of the SIRGAS reference frame
	<i>Author</i>	L. Sanchez
	<i>Publisher</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)

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<i>Data source</i>	ISO Geodetic Registry	
<i>Scope</i>	Spatial referencing	
<i>Datum</i>	SIRGAS Continuously Operating Network SIR17P01	
<i>Coordinate System</i>	Geocentric 3D right-handed Cartesian CS. Axes: Geocentric X,Y,Z. Orientation: Z to North Pole, [X and Y in the equatorial plane, X at Prime Meridian X in the equatorial plane at the Prime Meridian]. UoM: m.	

Extent

<i>Description</i>	South America - onshore and offshore. Central America - onshore and offshore. Mexico - onshore and offshore.	
<i>Geographic Bounding Box</i>	<i>West-bound longitude</i>	-122.19
	<i>North-bound latitude</i>	32.72
	<i>East-bound longitude</i>	-25.28
	<i>South-bound latitude</i>	-59.87

ISO Geodetic Registry

<i>Item class</i>	GeodeticDatum	
<i>Name</i>	SIRGAS Continuously Operating Network SIR17P01	
<i>Item status</i>	VALID	
<i>Identifier</i>	129	
<i>Alias</i>	SIRGAS	
<i>Alias</i>	SIRGAS-CON	
<i>Alias</i>	SIRGAS Multi-Year Solution 2017	
<i>Alias</i>	Geocentric Reference System for the Americas	
<i>Alias</i>	Sistema de Referencia Geocentrico para las Americas	
<i>Alias</i>	SIR17P01	
<i>Information source</i>	<i>Title</i>	Velocity model for SIRGAS 2017: VEMOS2017
	<i>Author</i>	L. Sanchez, H. Drewes
	<i>Publisher</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	<i>Publication date</i>	2018-08-14
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<i>Information source</i>	<i>Title</i>	Kinematics of the SIRGAS reference frame
	<i>Author</i>	L. Sanchez
	<i>Publisher</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
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	<i>Series/Journal name</i>	Symposium SIRGAS2017. Mendoza, Argentina. November 28, 2017
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	<i>Title</i>	Sistema de Referencia Geocentrico para las Americas (SIRGAS)
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	<i>Publication date</i>	2018
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<i>Information source</i>	<i>Title</i> SIRGAS reference frame realization SIR17P01 <i>Author</i> L. Sanchez <i>Publisher</i> Sistema de Referencia Geocéntrico para las Américas (SIRGAS) <i>Publication date</i> 2018-08-14 <i>Other citation details</i> In supplement to: Sanchez L. (2017) Kinematics of the SIRGAS reference frame, Symposium SIRGAS2018. Mendoza, Argentina. November 28, 2017
<i>Data source</i>	ISO Geodetic Registry
<i>Remarks</i>	Replaces SIR15P01.
<i>Anchor definition</i>	Realized by a frame of 345 continuously operating stations using GPS and GLONASS observations from April 2011 to January 2017 and aligned to IGS14 at epoch 2015.0. This cumulative solution has been made consistent with the phase centre calibrations referring to the IGS14 reference frame using the latitude-dependent phase centre correction model by the International GNSS Service. Velocity model VEMOS2017 used to propagate coordinates from an arbitrary epoch to the 2015.0 reference epoch.
<i>Release date</i>	2018
<i>Coordinate Reference Epoch</i>	2015.0
<i>Scope</i>	Spatial referencing
<i>Ellipsoid</i>	GRS 1980
<i>Prime Meridian</i>	Greenwich

Extent

<i>Description</i>	South America - onshore and offshore. Central America - onshore and offshore. Mexico - onshore and offshore.	
<i>Geographic Bounding Box</i>	<i>West-bound longitude</i>	-122.19
	<i>North-bound latitude</i>	32.72
	<i>East-bound longitude</i>	-25.28
	<i>South-bound latitude</i>	-59.87

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<i>Item class</i>	Ellipsoid														
<i>Name</i>	GRS 1980														
<i>Item status</i>	VALID														
<i>Identifier</i>	27														
<i>Alias</i>	Geodetic Reference System 1980														
<i>Alias</i>	GRS1980														
<i>Alias</i>	IAG GRS80														
<i>Alias</i>	International 1979														
<i>Alias</i>	GRS80														
<i>Information source</i>	<table> <tr> <td><i>Title</i></td><td>Geodetic Reference System 1980</td></tr> <tr> <td><i>Author</i></td><td>H. Moritz</td></tr> <tr> <td><i>Publisher</i></td><td>Springer International Publishing</td></tr> <tr> <td><i>Publication date</i></td><td>2003-03</td></tr> <tr> <td><i>Series/Journal name</i></td><td>Journal of Geodesy</td></tr> <tr> <td><i>Issue identification</i></td><td>Volume 74, No. 1</td></tr> <tr> <td><i>Page</i></td><td>128–162</td></tr> </table>	<i>Title</i>	Geodetic Reference System 1980	<i>Author</i>	H. Moritz	<i>Publisher</i>	Springer International Publishing	<i>Publication date</i>	2003-03	<i>Series/Journal name</i>	Journal of Geodesy	<i>Issue identification</i>	Volume 74, No. 1	<i>Page</i>	128–162
<i>Title</i>	Geodetic Reference System 1980														
<i>Author</i>	H. Moritz														
<i>Publisher</i>	Springer International Publishing														
<i>Publication date</i>	2003-03														
<i>Series/Journal name</i>	Journal of Geodesy														
<i>Issue identification</i>	Volume 74, No. 1														
<i>Page</i>	128–162														
<i>Information source</i>	<table> <tr> <td><i>Title</i></td><td>Geodetic Reference System 1980</td></tr> <tr> <td><i>Author</i></td><td>H. Moritz</td></tr> <tr> <td><i>Publisher</i></td><td>International Association of Geodesy</td></tr> <tr> <td><i>Publication date</i></td><td>1984</td></tr> <tr> <td><i>Series/Journal name</i></td><td>Bulletin Geodesique</td></tr> <tr> <td><i>Issue identification</i></td><td>Volume 58, No. 3</td></tr> <tr> <td><i>Page</i></td><td>395-405</td></tr> </table>	<i>Title</i>	Geodetic Reference System 1980	<i>Author</i>	H. Moritz	<i>Publisher</i>	International Association of Geodesy	<i>Publication date</i>	1984	<i>Series/Journal name</i>	Bulletin Geodesique	<i>Issue identification</i>	Volume 58, No. 3	<i>Page</i>	395-405
<i>Title</i>	Geodetic Reference System 1980														
<i>Author</i>	H. Moritz														
<i>Publisher</i>	International Association of Geodesy														
<i>Publication date</i>	1984														
<i>Series/Journal name</i>	Bulletin Geodesique														
<i>Issue identification</i>	Volume 58, No. 3														
<i>Page</i>	395-405														
<i>Data source</i>	ISO Geodetic Registry														
<i>Remarks</i>	Adopted by IUGG 1979 Canberra. Inverse flattening is derived from geocentric gravitational constant $GM = 3986005e8 \text{ m}^3/\text{s}^2$, dynamic form factor $J_2 = 108263e-8$ and Earth's angular velocity = $7292115e-11 \text{ rad/s}$.														
<i>Semi-major axis</i>	6378137.0 m														
<i>Inverse flattening</i>	298.257222101 m														

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<i>Item class</i>	PrimeMeridian	
<i>Name</i>	Greenwich	
<i>Item status</i>	VALID	
<i>Identifier</i>	25	
<i>Alias</i>	Zero meridian	
<i>Information source</i>	<i>Title</i>	Why the Greenwich meridian moved
	<i>Author</i>	S. Malys, J.H. Seago, N.K. Pavlis, P.K. Seidelmann, G.H. Kaplan
	<i>Publisher</i>	Springer International Publishing
	<i>Publication date</i>	2015-12
	<i>Series/Journal name</i>	Journal of Geodesy
	<i>Issue identification</i>	Volume 89, No. 12
	<i>Page</i>	1263–1272
<i>Information source</i>	<i>Title</i>	IERS Conventions (2010)
	<i>Author</i>	G. Petit, B.J. Luzum (eds)
	<i>Publisher</i>	Verlag des Bundesamts für Kartographie und Geodäsie
	<i>Publication date</i>	2010
	<i>Edition date</i>	
	<i>Series/Journal name</i>	IERS Technical Notes
	<i>Issue identification</i>	36.0
<i>Data source</i>	<i>Other citation details</i>	ISSN: 1019-4568
	ISO Geodetic Registry	
<i>Greenwich longitude</i>	0.0 °	

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Item class	CartesianCS	
Name	Geocentric 3D right-handed Cartesian CS. Axes: Geocentric X,Y,Z. Orientation: Z to North Pole, [X and Y in the equatorial plane, X at Prime Meridian X in the equatorial plane at the Prime Meridian]. UoM: m.	
Item status	VALID	
Identifier	45	
Alias	Earth centred, earth fixed, right-handed 3D coordinate system, consisting of 3 orthogonal axes with X and Y axes in the equatorial plane, positive Z-axis parallel to mean earth rotation axis and pointing towards North Pole. UoM: m.	
Alias	ECEF	
Information source	Title	ISO 19111 Geographical information - Spatial referencing by coordinates
	Author	International Organization for Standardization (ISO)
	Publisher	International Organization for Standardization (ISO)
	Publication date	2007-07-01
	Edition	Second Edition
	Series/Journal name	International Standard
	Issue identification	ISO 19111:2007
Data source	ISO Geodetic Registry	
Remarks	Used in geocentric coordinate reference systems.	

Axes

Item class	CoordinateSystemAxis	
Name	Geocentric X	
Item status	VALID	
Identifier	33	
Information source	Title	ISO 19111 Geographical information - Spatial referencing by coordinates
	Author	International Organization for Standardization (ISO)
	Publisher	International Organization for Standardization (ISO)
	Publication date	2007-07-01
	Edition	Second Edition
	Series/Journal name	International Standard
	Issue identification	ISO 19111:2007
Data source	ISO Geodetic Registry	
Abbreviation	X	
Direction	Geocentre > equator/0°E	
Unit	metre	

Item class	CoordinateSystemAxis	
Name	Geocentric Y	
Item status	VALID	
Identifier	37	

<i>Information source</i>	<i>Title</i>	ISO 19111 Geographical information - Spatial referencing by coordinates
	<i>Author</i>	International Organization for Standardization (ISO)
	<i>Publisher</i>	International Organization for Standardization (ISO)
	<i>Publication date</i>	2007-07-01
	<i>Edition</i>	Second Edition
	<i>Series/Journal name</i>	International Standard
	<i>Issue identification</i>	ISO 19111:2007
<i>Data source</i>	ISO Geodetic Registry	
<i>Abbreviation</i>	Y	
<i>Direction</i>	Geocentre > equator/90°E	
<i>Unit</i>	metre	

<i>Item class</i>	CoordinateSystemAxis	
<i>Name</i>	Geocentric Z	
<i>Item status</i>	VALID	
<i>Identifier</i>	39	
<i>Information source</i>	<i>Title</i>	ISO 19111 Geographical information - Spatial referencing by coordinates
	<i>Author</i>	International Organization for Standardization (ISO)
	<i>Publisher</i>	International Organization for Standardization (ISO)
	<i>Publication date</i>	2007-07-01
	<i>Edition</i>	Second Edition
	<i>Series/Journal name</i>	International Standard
	<i>Issue identification</i>	ISO 19111:2007
<i>Data source</i>	ISO Geodetic Registry	
<i>Abbreviation</i>	Z	
<i>Direction</i>	Geocentre > north pole	
<i>Unit</i>	metre	