ISO Geodetic Registry

Item class Transformation

Name ITRF89 to ETRF2014 [EUREF v1]

VALID Item status Identifier 760

Information source Title EUREF Technical Note 1: Relationship and

Transformation between the International and the

European Terrestrial Reference Systems

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Other citation details http://etrs89.ensg.ign.fr/pub/EUREF-TN-1.pdf

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Information source Title Guidelines for EUREF Densifications

> C. Bruyninx, Z. Altamimi, A. Caporali, A. **Author**

Kenyeres, J. Legrand, M. Lidberg

Publisher IAG sub-commission for the European Reference

Frame - EUREF

Revision date 2018-03-09

Other citation details http://www.epncb.oma.be/

documentation/quidelines/

Guidelines for EUREF Densifications.pdf

(accessed 2020-20-14)

Data source ISO Geodetic Registry

Remarks Accuracy of transformation is given at the reference epoch for the

> transformation parameters (2010.0); actual accuracy then depends on the epoch at which the transformation parameters are applied (refer to

Citation for accuracies of velocities of the para

Operation version EUREF v1

Scope Spatial referencing

Operation accuracy $0.0 \, m$

Source CRS ITRF89 - XYZ Target CRS ETRF2014 - XYZ

Operation method Time-Dependent Position Vector Transformation (geocentric Cartesian

domain)

Extent

Description

Europe - onshore and offshore: Albania, Andorra, Austria, Belgium, Bosnia and Herzegovina, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Faroe Islands, Finland, France, Germany, Gibraltar, Greece, Hungary, Ireland, Italy, Latvia, Liechtenstein, Lithuania, Luxembourg,

> Macedonia, Malta, Monaco, Montenegro, Netherlands, Norway including Svalbard and Jan Mayen, Poland, Portugal, Romania, San Marino, Serbia, Slovakia, Slovenia, Spain,

Sweden, Switzerland, United Kingdom (UK) including Channel Islands and Isle of Man, Vatican City State.

Geographic Bounding Box West-bound longitude -16.1

North-bound latitude 84.17

North-bound latitude 84.17
East-bound longitude 39.65
South-bound latitude 32.88

Operation parameter values

Time reference	2010.0 year
Rate of change of scale difference	-0.12 parts per billion per year
Rate of change of Z-axis rotation	-0.79 milliarc-second per year
Rate of change of Y-axis rotation	0.531 milliarc-second per year
Rate of change of X-axis rotation	0.085 milliarc-second per year
Rate of change of Z-axis translation	3.3 millimetre per year
Rate of change of Y-axis translation	0.5 millimetre per year
Rate of change of X-axis translation	-0.1 millimetre per year
Scale difference	-8.19 parts per billion
Z-axis rotation	-16.43 milliarc-second
Y-axis rotation	11.151 milliarc-second
X-axis rotation	1.785 milliarc-second
Z-axis translation	130.8 millimetre
Y-axis translation	-35.5 millimetre
X-axis translation	-30.4 millimetre

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Item class OperationMethod

Name Time-Dependent Position Vector

Transformation (geocentric Cartesian domain)

Item statusVALIDIdentifier82

Alias Time-Dependent 7-Parameter Transformation

Alias 14-Parameter Transformation

Alias Time-Dependent Position Vector Transformation

Data source ISO Geodetic Registry

Remarks Note the analogy with the rotation for the Time-dependent Coordinate

Frame Transformation but beware of the differences! The Position

Vector Transformation convention is used by IAG.

Formula Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

Operation parameters

X-axis translation

Y-axis translation

Z-axis translation

X-axis rotation

Y-axis rotation

Z-axis rotation Scale difference

Rate of change of X-axis translation

Rate of change of Y-axis translation

Rate of change of Z-axis translation

Rate of change of X-axis rotation

Rate of change of Y-axis rotation

Rate of change of Z-axis rotation

Rate of change of scale difference

Time reference