

# ISO Geodetic Registry

<i>Item class</i>	GeodeticCRS	
<i>Name</i>	<b>SIRGAS-CON DGF06P01 - LatLon</b>	
<i>Item status</i>	VALID	
<i>Identifier</i>	223	
<i>Alias</i>	SIRGAS	
<i>Alias</i>	DGFI06P01	
<i>Alias</i>	SIRGAS-CON	
<i>Alias</i>	DGF06P01	
<i>Alias</i>	SIRGAS Multi-Year Solution 2006	
<i>Alias</i>	Geocentric Reference System for the Americas	
<i>Alias</i>	Sistema de Referencia Geocentrico para las Americas	
<i>Information source</i>	<i>Title</i>	Deformation of the South American crust estimated from finite element and collocation methods
	<i>Author</i>	H. Drewes, O. Heidbach
	<i>Publisher</i>	Springer Berlin Heidelberg
	<i>Publication date</i>	2005
	<i>Series/Journal name</i>	International Association of Geodesy Symposia
	<i>Issue identification</i>	128.0
	<i>Page</i>	544-549
	<i>Other citation details</i>	In Sanso F. (eds) A Window on the Future of Geodesy. International Association of Geodesy Symposia, Vol 128. Springer, Berlin, Heidelberg
	<i>Title</i>	The Position and Velocity Solution DGF06P01 for SIRGAS
	<i>Author</i>	W. Seemueller
<i>Information source</i>	<i>Publisher</i>	Springer Berlin Heidelberg
	<i>Publication date</i>	2009
	<i>Series/Journal name</i>	International Association of Geodesy Symposia
	<i>Issue identification</i>	134.0
	<i>Page</i>	167-172
<i>Information source</i>	<i>Title</i>	Sistema de Referencia Geocentrico para las Americas (SIRGAS)
	<i>Author</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	<i>Publisher</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	<i>Publication date</i>	2018
	<i>Other citation details</i>	Website
<i>Data source</i>	ISO Geodetic Registry	
<i>Scope</i>	Spatial referencing	
<i>Datum</i>	SIRGAS Continuously Operating Network DGF06P01	
<i>Coordinate System</i>	Ellipsoidal 2D CS. Axes: latitude, longitude. Orientations: north, east. UoM: degree	

## Extent

<i>Description</i>	<b>South America - onshore and offshore. Central America - onshore and offshore. Mexico - onshore and offshore.</b>	
<i>Geographic Bounding Box</i>	<i>West-bound longitude</i>	-122.19
	<i>North-bound latitude</i>	32.72

<i>East-bound longitude</i>
<i>South-bound latitude</i>

-25.28
-59.87

# ISO Geodetic Registry

Item class	GeodeticDatum	
Name	SIRGAS Continuously Operating Network DGF06P01	
Item status	VALID	
Identifier	124	
Alias	SIRGAS	
Alias	DGFI06P01	
Alias	SIRGAS-CON	
Alias	DGF06P01	
Alias	SIRGAS Multi-Year Solution 2006	
Alias	Geocentric Reference System for the Americas	
Alias	Sistema de Referencia Geocentrico para las Americas	
Information source	Title	The Position and Velocity Solution DGF06P01 for SIRGAS
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	Series/Journal name	International Association of Geodesy Symposia
	Issue identification	128.0
	Page	544-549
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	Title	Sistema de Referencia Geocentrico para las Americas (SIRGAS)
	Author	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	Publisher	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
Data source	Publication date	2018
	Other citation details	Website
	ISO Geodetic Registry	
Remarks	Replaces DGF05P01. Replaced by DGF07P01.	
Anchor definition	Realized by a frame of 94 continuously operating stations using GPS observations from June 1996 to June 2006 and aligned to ITRF2000 at epoch 2004.0. Velocity model VEMOS2003 used to propagate coordinates from an arbitrary epoch to the 2004.0 reference epoch.	
Release date	2006	
Coordinate Reference Epoch	2004.0	
Scope	Spatial referencing	
Ellipsoid	GRS 1980	
Prime Meridian	Greenwich	

Extent

<i>Description</i>	<b>South America - onshore and offshore. Central America - onshore and offshore. Mexico - onshore and offshore.</b>		
<i>Geographic Bounding Box</i>	<i>West-bound longitude</i>	-122.19	
	<i>North-bound latitude</i>	32.72	
	<i>East-bound longitude</i>	-25.28	
	<i>South-bound latitude</i>	-59.87	

# ISO Geodetic Registry

<i>Item class</i>	Ellipsoid														
<i>Name</i>	<b>GRS 1980</b>														
<i>Item status</i>	VALID														
<i>Identifier</i>	27														
<i>Alias</i>	Geodetic Reference System 1980														
<i>Alias</i>	GRS1980														
<i>Alias</i>	IAG GRS80														
<i>Alias</i>	International 1979														
<i>Alias</i>	GRS80														
<i>Information source</i>	<table> <tr> <td><i>Title</i></td><td>Geodetic Reference System 1980</td></tr> <tr> <td><i>Author</i></td><td>H. Moritz</td></tr> <tr> <td><i>Publisher</i></td><td>Springer International Publishing</td></tr> <tr> <td><i>Publication date</i></td><td>2003-03</td></tr> <tr> <td><i>Series/Journal name</i></td><td>Journal of Geodesy</td></tr> <tr> <td><i>Issue identification</i></td><td>Volume 74, No. 1</td></tr> <tr> <td><i>Page</i></td><td>128–162</td></tr> </table>	<i>Title</i>	Geodetic Reference System 1980	<i>Author</i>	H. Moritz	<i>Publisher</i>	Springer International Publishing	<i>Publication date</i>	2003-03	<i>Series/Journal name</i>	Journal of Geodesy	<i>Issue identification</i>	Volume 74, No. 1	<i>Page</i>	128–162
<i>Title</i>	Geodetic Reference System 1980														
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<i>Publisher</i>	Springer International Publishing														
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<i>Page</i>	128–162														
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<i>Title</i>	Geodetic Reference System 1980														
<i>Author</i>	H. Moritz														
<i>Publisher</i>	International Association of Geodesy														
<i>Publication date</i>	1984														
<i>Series/Journal name</i>	Bulletin Geodesique														
<i>Issue identification</i>	Volume 58, No. 3														
<i>Page</i>	395-405														
<i>Data source</i>	ISO Geodetic Registry														
<i>Remarks</i>	Adopted by IUGG 1979 Canberra. Inverse flattening is derived from geocentric gravitational constant $GM = 3986005e8 \text{ m}^3/\text{s}^2$ , dynamic form factor $J_2 = 108263e-8$ and Earth's angular velocity = $7292115e-11 \text{ rad/s}$ .														
<i>Semi-major axis</i>	6378137.0 m														
<i>Inverse flattening</i>	298.257222101 m														

# ISO Geodetic Registry

<i>Item class</i>	PrimeMeridian	
<i>Name</i>	<b>Greenwich</b>	
<i>Item status</i>	VALID	
<i>Identifier</i>	25	
<i>Alias</i>	Zero meridian	
<i>Information source</i>	<i>Title</i>	Why the Greenwich meridian moved
	<i>Author</i>	S. Malys, J.H. Seago, N.K. Pavlis, P.K. Seidelmann, G.H. Kaplan
	<i>Publisher</i>	Springer International Publishing
	<i>Publication date</i>	2015-12
	<i>Series/Journal name</i>	Journal of Geodesy
	<i>Issue identification</i>	Volume 89, No. 12
	<i>Page</i>	1263–1272
<i>Information source</i>	<i>Title</i>	IERS Conventions (2010)
	<i>Author</i>	G. Petit, B.J. Luzum (eds)
	<i>Publisher</i>	Verlag des Bundesamts fur Kartographie und Geodasie
	<i>Publication date</i>	2010
	<i>Edition date</i>	
	<i>Series/Journal name</i>	IERS Technical Notes
	<i>Issue identification</i>	36.0
<i>Data source</i>	<i>Other citation details</i>	ISSN: 1019-4568
	ISO Geodetic Registry	
<i>Greenwich longitude</i>	0.0 °	

# ISO Geodetic Registry

<i>Item class</i>	EllipsoidalCS	
<i>Name</i>	<b>Ellipsoidal 2D CS. Axes: latitude, longitude. Orientations: north, east. UoM: degree</b>	
<i>Item status</i>	VALID	
<i>Identifier</i>	43	
<i>Information source</i>	<i>Title</i>	ISO 19111 Geographical information - Spatial referencing by coordinates
	<i>Author</i>	International Organization for Standardization (ISO)
	<i>Publisher</i>	International Organization for Standardization (ISO)
	<i>Publication date</i>	2007-07-01
	<i>Edition</i>	Second Edition
	<i>Series/Journal name</i>	International Standard
	<i>Issue identification</i>	ISO 19111:2007
<i>Data source</i>	ISO Geodetic Registry	
<i>Remarks</i>	Used in geographic 2D coordinate reference systems. Coordinates referenced to this CS are in degrees. Any degree representation (e.g. DMSH, decimal, etc.) may be used but that used must be declared for the user by the supplier of data.	

## Axes

<i>Item class</i>	CoordinateSystemAxis	
<i>Name</i>	<b>Geodetic latitude</b>	
<i>Item status</i>	VALID	
<i>Identifier</i>	38	
<i>Information source</i>	<i>Title</i>	ISO 19111 Geographical information - Spatial referencing by coordinates
	<i>Author</i>	International Organization for Standardization (ISO)
	<i>Publisher</i>	International Organization for Standardization (ISO)
	<i>Publication date</i>	2007-07-01
	<i>Edition</i>	Second Edition
	<i>Series/Journal name</i>	International Standard
	<i>Issue identification</i>	ISO 19111:2007
<i>Data source</i>	ISO Geodetic Registry	
<i>Remarks</i>	Used in geographic 2D and geographic 3D coordinate reference systems.	
<i>Abbreviation</i>	Lat	
<i>Direction</i>	north	
<i>Unit</i>	degree (supplier to define representation)	

  

<i>Item class</i>	CoordinateSystemAxis	
<i>Name</i>	<b>Geodetic longitude</b>	
<i>Item status</i>	VALID	
<i>Identifier</i>	34	
<i>Information source</i>	<i>Title</i>	ISO 19111 Geographical information - Spatial referencing by coordinates
	<i>Author</i>	International Organization for Standardization (ISO)

	<i>Publisher</i>	International Organization for Standardization (ISO)
	<i>Publication date</i>	2007-07-01
	<i>Edition</i>	Second Edition
	<i>Series/Journal name</i>	International Standard
	<i>Issue identification</i>	ISO 19111:2007
<i>Data source</i>		ISO Geodetic Registry
<i>Remarks</i>		Used in geographic 2D and geographic 3D coordinate reference systems.
<i>Abbreviation</i>		Lon
<i>Direction</i>		east
<i>Unit</i>		degree (supplier to define representation)