ISO Geodetic Registry

Item class Transformation

Name ITRF2020 to NAD 83 (PA11) Epoch 2010 [NGS

v1]

Item status VALID
Identifier 989

Information source Title HTDP User Guide (Version 3.5.0)

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Other citation details https://geodesy.noaa.gov/TOOLS/Htdp/HTDP-

user-guide.pdf (accessed 2023-01-28)

Data source ISO Geodetic Registry

Remarks Transformation defines NAD 83 (PA11) with respect to ITRF2020 and

is treated as errorless.

Operation version NGS v1

Scope Spatial referencing

Operation accuracy 0.0 m

Source CRS ITRF2020 - XYZ

Target CRS NAD 83 (PA11) Epoch 2010 - XYZ

Operation method Time-Dependent Coordinate Frame Transformation (geocentric

Cartesian domain)

Extent

Description	American Samoa - onshore and offshore. Marshall Islands - onshore and offshore. United States (USA) - onshore and offshore - Hawaii. United States Minor Outlying Islands - onshore	
	and offshore.	
Geographic Bounding Box	West-bound longitude	157.47
	North-bound latitude	31.8
	East-bound longitude	-151.27
	South-bound latitude	-17.56

Operation parameter values

2010.0 year
0.11 parts per billion per year
-2.186 milliarc-second per year
1.007 milliarc-second per year
-0.384 milliarc-second per year
-0.0017 metre per year
0.0 metre per year
1.0E-4 metre per year
1.7 parts per billion
-25.706 milliarc-second
26.56 milliarc-second
22.749 milliarc-second

Z-axis translation	-0.5859 metre
Y-axis translation	-2.0133 metre
X-axis translation	0.9095 metre

ISO Geodetic Registry

Item class OperationMethod

Name Time-Dependent Coordinate Frame

Transformation (geocentric Cartesian domain)

Item status VALID
Identifier 94

Alias Time-Dependent 7-Parameter Transformation

Alias 14-Parameter Transformation

Alias Time-Dependent Coordinate Frame Transformation

Data source ISO Geodetic Registry

Remarks Note the analogy with the Time-dependent Position Vector

Transformation but beware of the differences! The Position Vector

Transformation convention is used by IAG.

Formula Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

Operation parameters

X-axis translation

Y-axis translation

Z-axis translation

X-axis rotation

Y-axis rotation

Z-axis rotation

Scale difference

Rate of change of X-axis translation

Rate of change of Y-axis translation

Rate of change of Z-axis translation

Rate of change of X-axis rotation

Rate of change of Y-axis rotation

Rate of change of Z-axis rotation

Rate of change of scale difference

Time reference