

ISO Geodetic Registry

<i>Item class</i>	GeodeticCRS	
<i>Name</i>	SIRGAS95 - XYZ	
<i>Item status</i>	VALID	
<i>Identifier</i>	278	
<i>Alias</i>	South American Geocentric Reference System 1995	
<i>Alias</i>	SIRGAS	
<i>Alias</i>	SIRGAS 1995	
<i>Alias</i>	SIRGAS1995	
<i>Alias</i>	SIRGAS95	
<i>Alias</i>	Geocentric Reference System for South America	
<i>Information source</i>	<i>Title</i>	South American Geocentric Reference System: Final Report, Working Groups I and II
	<i>Author</i>	SIRGAS Working Groups I and II
	<i>Publisher</i>	Instituto Brasileiro de Geografia e Estatística (IBGE), Rio de Janeiro, Brasil
	<i>Publication date</i>	1997
	<i>Other citation details</i>	Report in both English and Spanish.
<i>Information source</i>	<i>Title</i>	Sistema de Referencia Geocentrico para las Americas (SIRGAS)
	<i>Author</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	<i>Publisher</i>	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	<i>Publication date</i>	2018
	<i>Other citation details</i>	Website
<i>Information source</i>	<i>Title</i>	Deformation of the South American crust estimated from finite element and collocation methods
	<i>Author</i>	H. Drewes, O. Heidbach
	<i>Publisher</i>	Springer Berlin Heidelberg
	<i>Publication date</i>	2005
	<i>Series/Journal name</i>	International Association of Geodesy Symposia
	<i>Issue identification</i>	128.0
	<i>Page</i>	544-549
	<i>Other citation details</i>	In Sanso F. (eds) A Window on the Future of Geodesy. International Association of Geodesy Symposia, Vol 128. Springer, Berlin, Heidelberg
<i>Data source</i>	ISO Geodetic Registry	
<i>Scope</i>	Spatial referencing	
<i>Datum</i>	Sistema de Referencia Geocentrico para America del Sur 1995	
<i>Coordinate System</i>	Geocentric 3D right-handed Cartesian CS. Axes: Geocentric X,Y,Z. Orientation: Z to North Pole, [X and Y in the equatorial plane, X at Prime Meridian X in the equatorial plane at the Prime Meridian]. UoM: m.	

Extent

<i>Description</i>	South America - onshore and offshore	
<i>Geographic Bounding Box</i>	<i>West-bound longitude</i>	-113.21
	<i>North-bound latitude</i>	16.75
	<i>East-bound longitude</i>	-26.0
	<i>South-bound latitude</i>	-59.87

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Item class	GeodeticDatum	
Name	Sistema de Referencia Geocentrico para America del Sur 1995	
Item status	VALID	
Identifier	150	
Alias	South American Geocentric Reference System 1995	
Alias	SIRGAS	
Alias	SIRGAS 1995	
Alias	SIRGAS1995	
Alias	SIRGAS95	
Alias	Geocentric Reference System for South America	
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	Publication date	1997
	Other citation details	Report in both English and Spanish.
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	Publisher	Sistema de Referencia Geocéntrico para las Américas (SIRGAS)
	Publication date	2018
	Other citation details	Website
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	Publisher	Springer Berlin Heidelberg
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	Series/Journal name	International Association of Geodesy Symposia
	Issue identification	128.0
	Page	544-549
	Other citation details	In Sanso F. (eds) A Window on the Future of Geodesy. International Association of Geodesy Symposia, Vol 128. Springer, Berlin, Heidelberg
Data source	ISO Geodetic Registry	
Remarks	Replaced by SIRGAS2000.	
Anchor definition	Realized by a frame of 58 stations observed in 1995 and aligned to ITRF94 at epoch 1995.4. Velocity model VEMOS2003 used to propagate coordinates from an arbitrary epoch to the 1995.4 reference epoch.	
Release date	1997	
Coordinate Reference Epoch	1995.4	
Scope	Spatial referencing	
Ellipsoid	GRS 1980	
Prime Meridian	Greenwich	

Extent

<i>Description</i>	South America - onshore and offshore	
<i>Geographic Bounding Box</i>	<i>West-bound longitude</i>	-113.21
	<i>North-bound latitude</i>	16.75
	<i>East-bound longitude</i>	-26.0
	<i>South-bound latitude</i>	-59.87

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<i>Item class</i>	Ellipsoid														
<i>Name</i>	GRS 1980														
<i>Item status</i>	VALID														
<i>Identifier</i>	27														
<i>Alias</i>	Geodetic Reference System 1980														
<i>Alias</i>	GRS1980														
<i>Alias</i>	IAG GRS80														
<i>Alias</i>	International 1979														
<i>Alias</i>	GRS80														
<i>Information source</i>	<table> <tr> <td><i>Title</i></td><td>Geodetic Reference System 1980</td></tr> <tr> <td><i>Author</i></td><td>H. Moritz</td></tr> <tr> <td><i>Publisher</i></td><td>Springer International Publishing</td></tr> <tr> <td><i>Publication date</i></td><td>2003-03</td></tr> <tr> <td><i>Series/Journal name</i></td><td>Journal of Geodesy</td></tr> <tr> <td><i>Issue identification</i></td><td>Volume 74, No. 1</td></tr> <tr> <td><i>Page</i></td><td>128–162</td></tr> </table>	<i>Title</i>	Geodetic Reference System 1980	<i>Author</i>	H. Moritz	<i>Publisher</i>	Springer International Publishing	<i>Publication date</i>	2003-03	<i>Series/Journal name</i>	Journal of Geodesy	<i>Issue identification</i>	Volume 74, No. 1	<i>Page</i>	128–162
<i>Title</i>	Geodetic Reference System 1980														
<i>Author</i>	H. Moritz														
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<i>Title</i>	Geodetic Reference System 1980														
<i>Author</i>	H. Moritz														
<i>Publisher</i>	International Association of Geodesy														
<i>Publication date</i>	1984														
<i>Series/Journal name</i>	Bulletin Geodesique														
<i>Issue identification</i>	Volume 58, No. 3														
<i>Page</i>	395-405														
<i>Data source</i>	ISO Geodetic Registry														
<i>Remarks</i>	Adopted by IUGG 1979 Canberra. Inverse flattening is derived from geocentric gravitational constant $GM = 3986005e8 \text{ m}^3/\text{s}^2$, dynamic form factor $J_2 = 108263e-8$ and Earth's angular velocity = $7292115e-11 \text{ rad/s}$.														
<i>Semi-major axis</i>	6378137.0 m														
<i>Inverse flattening</i>	298.257222101 m														

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<i>Item class</i>	PrimeMeridian	
<i>Name</i>	Greenwich	
<i>Item status</i>	VALID	
<i>Identifier</i>	25	
<i>Alias</i>	Zero meridian	
<i>Information source</i>	<i>Title</i>	Why the Greenwich meridian moved
	<i>Author</i>	S. Malys, J.H. Seago, N.K. Pavlis, P.K. Seidelmann, G.H. Kaplan
	<i>Publisher</i>	Springer International Publishing
	<i>Publication date</i>	2015-12
	<i>Series/Journal name</i>	Journal of Geodesy
	<i>Issue identification</i>	Volume 89, No. 12
	<i>Page</i>	1263–1272
	<i>Title</i>	IERS Conventions (2010)
	<i>Author</i>	G. Petit, B.J. Luzum (eds)
	<i>Publisher</i>	Verlag des Bundesamts für Kartographie und Geodäsie
<i>Information source</i>	<i>Publication date</i>	2010
	<i>Edition date</i>	
	<i>Series/Journal name</i>	IERS Technical Notes
	<i>Issue identification</i>	36.0
	<i>Other citation details</i>	ISSN: 1019-4568
<i>Data source</i>	ISO Geodetic Registry	
<i>Greenwich longitude</i>	0.0 °	

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Item class	CartesianCS	
Name	Geocentric 3D right-handed Cartesian CS. Axes: Geocentric X,Y,Z. Orientation: Z to North Pole, [X and Y in the equatorial plane, X at Prime Meridian X in the equatorial plane at the Prime Meridian]. UoM: m.	
Item status	VALID	
Identifier	45	
Alias	Earth centred, earth fixed, right-handed 3D coordinate system, consisting of 3 orthogonal axes with X and Y axes in the equatorial plane, positive Z-axis parallel to mean earth rotation axis and pointing towards North Pole. UoM: m.	
Alias	ECEF	
Information source	Title	ISO 19111 Geographical information - Spatial referencing by coordinates
	Author	International Organization for Standardization (ISO)
	Publisher	International Organization for Standardization (ISO)
	Publication date	2007-07-01
	Edition	Second Edition
	Series/Journal name	International Standard
	Issue identification	ISO 19111:2007
Data source	ISO Geodetic Registry	
Remarks	Used in geocentric coordinate reference systems.	

Axes

Item class	CoordinateSystemAxis	
Name	Geocentric X	
Item status	VALID	
Identifier	33	
Information source	Title	ISO 19111 Geographical information - Spatial referencing by coordinates
	Author	International Organization for Standardization (ISO)
	Publisher	International Organization for Standardization (ISO)
	Publication date	2007-07-01
	Edition	Second Edition
	Series/Journal name	International Standard
	Issue identification	ISO 19111:2007
Data source	ISO Geodetic Registry	
Abbreviation	X	
Direction	Geocentre > equator/0°E	
Unit	metre	

Item class	CoordinateSystemAxis	
Name	Geocentric Y	
Item status	VALID	
Identifier	37	

<i>Information source</i>	<i>Title</i>	ISO 19111 Geographical information - Spatial referencing by coordinates
	<i>Author</i>	International Organization for Standardization (ISO)
	<i>Publisher</i>	International Organization for Standardization (ISO)
	<i>Publication date</i>	2007-07-01
	<i>Edition</i>	Second Edition
	<i>Series/Journal name</i>	International Standard
	<i>Issue identification</i>	ISO 19111:2007
<i>Data source</i>	ISO Geodetic Registry	
<i>Abbreviation</i>	Y	
<i>Direction</i>	Geocentre > equator/90°E	
<i>Unit</i>	metre	

<i>Item class</i>	CoordinateSystemAxis	
<i>Name</i>	Geocentric Z	
<i>Item status</i>	VALID	
<i>Identifier</i>	39	
<i>Information source</i>	<i>Title</i>	ISO 19111 Geographical information - Spatial referencing by coordinates
	<i>Author</i>	International Organization for Standardization (ISO)
	<i>Publisher</i>	International Organization for Standardization (ISO)
	<i>Publication date</i>	2007-07-01
	<i>Edition</i>	Second Edition
	<i>Series/Journal name</i>	International Standard
	<i>Issue identification</i>	ISO 19111:2007
<i>Data source</i>	ISO Geodetic Registry	
<i>Abbreviation</i>	Z	
<i>Direction</i>	Geocentre > north pole	
<i>Unit</i>	metre	