

ISO Geodetic Registry

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|---------------------------|--|---|
| <i>Item class</i> | Transformation | |
| <i>Name</i> | ITRF2008 to NAD 83 (PA11) Epoch 2010 [v1] | |
| <i>Item status</i> | VALID | |
| <i>Identifier</i> | 565 | |
| <i>Information source</i> | <i>Title</i> | Introducing HTDP 3.1 to transform coordinates across time and spatial reference frames |
| | <i>Author</i> | C. Pearson, R.A. Snay |
| | <i>Publisher</i> | Springer-Verlag |
| | <i>Publication date</i> | 2013-01-01 |
| | <i>Edition date</i> | 2013-01-01 |
| | <i>Series/Journal name</i> | GPS Solutions |
| | <i>Issue identification</i> | Volume 17, No. 1 |
| | <i>Page</i> | 1-15 |
| | <i>Other citation details</i> | NAD83 (2011), NAD83 (MA11), NAD83 (PA11) transformation from IGB08 |
| <i>Information source</i> | <i>Title</i> | Publication of North American Datum of 1983 (2011) Epoch 2010.00, North American Datum of 1983 (PA2011) Epoch 2010.00 and North American Datum of 1983 (MA2011) Epoch 2010.00 |
| | <i>Author</i> | US Government |
| | <i>Publisher</i> | Office of Federal Register, NARA |
| | <i>Publication date</i> | 2013-08-08 |
| | <i>Edition date</i> | 2013-08-08 |
| | <i>Series/Journal name</i> | Federal Register Notice |
| | <i>Issue identification</i> | Volume 78, No. 153, Document: 2013–19167, Citation: 78 FR 48421 |
| | <i>Page</i> | 48421-48422 |
| | <i>Other citation details</i> | |
| <i>Information source</i> | <i>Title</i> | CORS Coordinates |
| | <i>Author</i> | National Geodetic Survey |
| | <i>Publisher</i> | National Oceanic and Atmospheric Administration (NOAA) National Geodetic Survey (NGS) |
| | <i>Revision date</i> | 2017-05-16 |
| | <i>Series/Journal name</i> | NGS Online listing of transformation parameters |
| | <i>Other citation details</i> | webpage |
| | <i>Data source</i> | ISO Geodetic Registry |
| | <i>Remarks</i> | Transformation defines NAD83(PA11) and is treated as errorless. |
| | <i>Operation version</i> | v1 |
| <i>Scope</i> | Spatial referencing | |
| <i>Operation accuracy</i> | 0.0 m | |
| <i>Source CRS</i> | ITRF2008 - XYZ | |
| <i>Target CRS</i> | NAD 83 (PA11) Epoch 2010 - XYZ | |
| <i>Operation method</i> | Time-Dependent Coordinate Frame Transformation (geocentric Cartesian domain) | |

Extent

| | |
|--------------------|--|
| <i>Description</i> | American Samoa - onshore and offshore. Marshall Islands - onshore and offshore. United States (USA) - onshore and offshore - Hawaii. United States Minor Outlying Islands - onshore and offshore. |
|--------------------|--|

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|--------------------------------|-----------------------------|---------|
| <i>Geographic Bounding Box</i> | <i>West-bound longitude</i> | 157.47 |
| | <i>North-bound latitude</i> | 31.8 |
| | <i>East-bound longitude</i> | -151.27 |
| | <i>South-bound latitude</i> | -17.56 |

Operation parameter values

| | |
|---|---------------------------------|
| <i>Time reference</i> | 1997.0 year |
| <i>Rate of change of scale difference</i> | 0.08 parts per billion per year |
| <i>Rate of change of Z-axis rotation</i> | -2.186 milliarc-second per year |
| <i>Rate of change of Y-axis rotation</i> | 1.007 milliarc-second per year |
| <i>Rate of change of X-axis rotation</i> | -0.384 milliarc-second per year |
| <i>Rate of change of Z-axis translation</i> | -0.0018 metre per year |
| <i>Rate of change of Y-axis translation</i> | 1.0E-4 metre per year |
| <i>Rate of change of X-axis translation</i> | 1.0E-4 metre per year |
| <i>Scale difference</i> | 1.1 parts per billion |
| <i>Z-axis rotation</i> | 2.712 milliarc-second |
| <i>Y-axis rotation</i> | 13.469 milliarc-second |
| <i>X-axis rotation</i> | 27.741 milliarc-second |
| <i>Z-axis translation</i> | -0.5653 metre |
| <i>Y-axis translation</i> | -2.0161 metre |
| <i>X-axis translation</i> | 0.908 metre |

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|--------------------|--|
| <i>Item class</i> | OperationMethod |
| <i>Name</i> | Time-Dependent Coordinate Frame Transformation (geocentric Cartesian domain) |
| <i>Item status</i> | VALID |
| <i>Identifier</i> | 94 |
| <i>Alias</i> | Time-Dependent 7-Parameter Transformation |
| <i>Alias</i> | 14-Parameter Transformation |
| <i>Alias</i> | Time-Dependent Coordinate Frame Transformation |
| <i>Data source</i> | ISO Geodetic Registry |
| <i>Remarks</i> | Note the analogy with the Time-dependent Position Vector Transformation but beware of the differences! The Position Vector Transformation convention is used by IAG. |
| <i>Formula</i> | Geomatics Guidance Note No 7, part 2: Coordinate Conversions and Transformations including Formulas |

Operation parameters

| |
|---|
| <i>X-axis translation</i> |
| <i>Y-axis translation</i> |
| <i>Z-axis translation</i> |
| <i>X-axis rotation</i> |
| <i>Y-axis rotation</i> |
| <i>Z-axis rotation</i> |
| <i>Scale difference</i> |
| <i>Rate of change of X-axis translation</i> |
| <i>Rate of change of Y-axis translation</i> |
| <i>Rate of change of Z-axis translation</i> |
| <i>Rate of change of X-axis rotation</i> |
| <i>Rate of change of Y-axis rotation</i> |
| <i>Rate of change of Z-axis rotation</i> |
| <i>Rate of change of scale difference</i> |
| <i>Time reference</i> |