

# ISO Geodetic Registry

|                           |  |  |
|---------------------------|--|--|
| <i>Item class</i>         | Transformation   |  |
| <i>Name</i>               | <b>ITRF91 to ITRF92 [IERS v1]</b>                                    |  |
| <i>Item status</i>        | VALID  |  |
| <i>Identifier</i>         | 490  |  |
| <i>Information source</i> | <i>Title</i>   | IERS Conventions (2010)  |
|                           | <i>Author</i>  | G. Petit, B.J. Luzum (eds)   |
|                           | <i>Publisher</i>   | Verlag des Bundesamts fur Kartographie und Geodasie  |
|                           | <i>Publication date</i>  | 2010   |
|                           | <i>Edition date</i>  |  |
|                           | <i>Series/Journal name</i>   | IERS Technical Notes   |
|                           | <i>Issue identification</i>  | 36.0   |
| <i>Information source</i> | <i>Other citation details</i>  | ISSN: 1019-4568  |
|                           | <i>Title</i>   | ITRF 92 and its associated velocity field  |
|                           | <i>Author</i>  | C. Boucher, Z. Altamimi, L. Duhem  |
|                           | <i>Publisher</i>   | Central Bureau of IERS - Observatoire de Paris, 61 avenue de l'Observatoire, 75014 Paris, France |
|                           | <i>Publication date</i>  | 1993-10-01   |
|                           | <i>Edition date</i>  |  |
|                           | <i>Series/Journal name</i>   | IERS Technical Notes   |
| <i>Data source</i>        | <i>Issue identification</i>  | 15.0   |
|                           | <i>ISO Geodetic Registry</i>   |  |
| <i>Remarks</i>            | No rates of change were estimated for the transformation parameters. |  |
| <i>Operation version</i>  | IERS v1  |  |
| <i>Scope</i>              | Spatial referencing  |  |
| <i>Operation accuracy</i> | 0.005 m  |  |
| <i>Source CRS</i>         | ITRF91 - XYZ   |  |
| <i>Target CRS</i>         | ITRF92 - XYZ   |  |
| <i>Operation method</i>   | Position Vector Transformation (geocentric Cartesian domain)         |  |

## Extent

|                                |                             |        |
|--------------------------------|-----------------------------|--------|
| <i>Description</i>             | <b>World.</b>               |        |
| <i>Geographic Bounding Box</i> | <i>West-bound longitude</i> | -180.0 |
|                                | <i>North-bound latitude</i> | 90.0   |
|                                | <i>East-bound longitude</i> | 180.0  |
|                                | <i>South-bound latitude</i> | -90.0  |

## Operation parameter values

|                           |                        |
|---------------------------|------------------------|
| <i>X-axis translation</i> | -1.1 centimetre        |
| <i>Y-axis translation</i> | -1.4 centimetre        |
| <i>Z-axis translation</i> | 0.6 centimetre         |
| <i>X-axis rotation</i>    | 0.0 milliarc-second    |
| <i>Y-axis rotation</i>    | 0.0 milliarc-second    |
| <i>Z-axis rotation</i>    | 0.0 milliarc-second    |
| <i>Scale difference</i>   | -1.4 parts per billion |

# ISO Geodetic Registry

|                    |   |
|--------------------|---|
| <i>Item class</i>  | OperationMethod   |
| <i>Name</i>        | <b>Position Vector Transformation (geocentric Cartesian domain)</b>   |
| <i>Item status</i> | VALID   |
| <i>Identifier</i>  | 88  |
| <i>Alias</i>       | 7-Parameter Transformation  |
| <i>Alias</i>       | Bursa-Wolf Transformation   |
| <i>Alias</i>       | Position Vector Transformation  |
| <i>Alias</i>       | Helmert Transformation  |
| <i>Data source</i> | ISO Geodetic Registry   |
| <i>Remarks</i>     | This method is a specific case of the Molodensky-Badekas (PV) method in which the evaluation point is the geocentre with coordinate values of zero. Note the analogy with the Coordinate Frame Transformation method but beware of the differences! |
| <i>Formula</i>     | Geomatics Guidance Note No 7, part 2: Coordinate Conversions and Transformations including Formulas   |

## Operation parameters

|                           |
|---------------------------|
| <i>X-axis translation</i> |
| <i>Y-axis translation</i> |
| <i>Z-axis translation</i> |
| <i>X-axis rotation</i>    |
| <i>Y-axis rotation</i>    |
| <i>Z-axis rotation</i>    |
| <i>Scale difference</i>   |