ISO Geodetic Registry				
Item class	GeodeticCRS			
Name	ETRF89 - XYZ			
Item status	VALID			
Identifier	308			
Alias	ETRF89			
Alias	ETRS89-XYZ			
Alias	ETRS89 / (X, Y, Z)			
Alias	EUREF89			
Information source	Title	Report on the Symposium of the IAG Subcommission for the EUREF held in Florence 28 - 31 May 1990		
	Author Publisher	IAG Verlag des Bayerischen Akademie der		
	Publication date	Wissenschaften 1992		
	Edition date	IAG Subcommission for the European Reference		
		Frame (EUREF) Publication		
Information source	Issue identification Title	1.0 EUREF Technical Note 1: Relationship and Transformation between the International and the European Terrestrial Reference Systems		
	Author	Z. Altamimi		
	Publisher	Institut National de l'Information Géographique et Forestière (IGN), France		
	Publication date	2018-06-28		
		IERS Technical Note		
Information source	Issue identification Title	1.0 ETRS89 realization: Current status, ETRF2005 and Future Development		
	Author	Z. Altamimi		
	Publication date Edition date	2008-06-17		
Information source	Title	Report on the Symposium of the IAG Subcommission for the EUREF held in Vienna 14 and 16 August 1991		
	Author	IAG		
	Publisher	Verlag des Bayerischen Akademie der Wissenschaften		
	Publication date Edition date	1992		
		IAG Subcommission for the European Reference Frame (EUREF) Publication		
lists mass tis as a sum a	Issue identification	1.0		
Information source	Title	Report on the Symposium of the IAG Subcommission for the EUREF held in Berne 4 - 6 March 1992		
	Author	IAG		
	Publisher	Verlag des Bayerischen Akademie der Wissenschaften		
	Publication date	1992		
	Edition date Series/Journal name	IAG Subcommission for the European Reference		
Dete course	Issue identification	Frame (EUREF) Publication 1.0		
Data source	ISO Geodetic Registr	У		

Remarks	The distinction in usage between ETRF89 and ETRS89 is confused: although in principle conceptually different in practice both are used as synonyms.
Scope	Spatial referencing
Datum	European Terrestrial Reference Frame 1989
Coordinate System	Geocentric 3D right-handed Cartesian CS. Axes: Geocentric X,Y,Z. Orientation: Z to North Pole, [X and Y in the equatorial plane, X at Prime Meridian X in the equatorial plane at the Prime Meridian]. UoM: m.

Extent

Description	Europe - onshore and offshore: Albania,			
	Andorra, Austria, Belgium, Bosnia and			
	Herzegovina, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Faroe			
	Islands, Finland, France, Germany, Gibraltar,			
	Greece, Hungary, Ireland, Italy, Latvia, Liechtenstein, Lithuania, Luxembourg, Macedonia, Malta, Monaco, Montenegro,			
	Netherlands, Norway including Svalbard at			
	Jan Mayen, Poland, Portugal, Romania, San Marino, Serbia, Slovakia, Slovenia, Spain, Sweden, Switzerland, United Kingdom (UK)			
	including Channel Islands and Isle of Man,			
	Vatican City State.			
Geographic Bounding Box	West-bound longitude	-16.1		
	North-bound latitude	84.17		
	East-bound longitude South-bound latitude	39.65 32.88		
	Codii Dodiia lalitado	02.00		

Item class GeodeticDatum

Name European Terrestrial Reference Frame 1989

Item statusVALIDIdentifier128AliasETRF89AliasEUREF 89

Alias European Terrestrial Reference System 1989

Alias ETRS89
Alias ETRS 89

Information source Title Report on the Symposium of the IAG

Subcommission for the EUREF held in Vienna 14

and 16 August 1991

Author IAG

Publisher Verlag des Bayerischen Akademie der

Wissenschaften

Publication date 1992

Edition date

Series/Journal name IAG Subcommission for the European Reference

Frame (EUREF) Publication

Issue identification 1.0

Information source Title EUREF Technical Note 1: Relationship and

Transformation between the International and the

European Terrestrial Reference Systems

Author Z. Altamimi

Publisher Institut National de l'Information Géographique et

Forestière (IGN), France

Publication date 2018-06-28

Series/Journal name IERS Technical Note

Issue identification 1.0

Information source Title Report on the Symposium of the IAG

Subcommission for the EUREF held in Florence

28 - 31 May 1990

Author IAG

Publisher Verlag des Bayerischen Akademie der

Wissenschaften

Publication date 1992

Edition date

Series/Journal name IAG Subcommission for the European Reference

Frame (EUREF) Publication

Issue identification 1.0

Information source Title Report on the Symposium of the IAG

Subcommission for the EUREF held in Berne 4 -

6 March 1992

Author IAG

Publisher Verlag des Bayerischen Akademie der

Wissenschaften

Publication date 1992

Edition date

Series/Journal name IAG Subcommission for the European Reference

Frame (EUREF) Publication

Issue identification 1.0

Information source Title ETRS89 realization: Current status, ETRF2005

and Future Development

Author Z. Altamimi Publication date 2008-06-17

Edition date

Data source ISO Geodetic Registry

Remarks ETRS89 is the reference system and ETRF89 is its first realization.

Unfortunately the two terms have been used synonymously, which has caused some confusion amongst users. The reference frame should be referred to as ETRF89 to distinguish it from other realizations of

ETRS89.

Anchor definition Coincides with ITRF89 at epoch 1989.0 and is fixed to the stable part

of the Eurasian tectonic plate through 3 rotation rates derived from the AM02 geophysical model, representing the Eurasian plate's angular

velocity about its Euler pole.

Release date 1990 Coordinate Reference Epoch 1989.0

Scope Spatial referencing

Ellipsoid GRS 1980
Prime Meridian Greenwich

Extent

Description	Europe - onshore and offshore: Albania,		
	Andorra, Austria, Belgium, Bosnia and Herzegovina, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Faroe Islands, Finland, France, Germany, Gibraltar,		
	Greece, Hungary, Ireland, Italy, Latvia,		
	Liechtenstein, Lithuania, Luxembourg,		
	Macedonia, Malta, Monaco, Montenegro, Netherlands, Norway including Svalbard and Jan Mayen, Poland, Portugal, Romania, San Marino, Serbia, Slovakia, Slovenia, Spain, Sweden, Switzerland, United Kingdom (UK)		
	Vatican City State.		
Goographic Pounding Poy	West-bound longitude	-16.1	
Geographic Bounding Box	North-bound latitude	84.17	
	East-bound longitude	39.65	
	South-bound latitude	32.88	

Item class Ellipsoid

Name GRS 1980

Item statusVALIDIdentifier27

Alias Geodetic Reference System 1980

Alias GRS1980
Alias IAG GRS80

Alias International 1979

Alias GRS80

Information source Title Geodetic Reference System 1980

Author H. Moritz

Publisher Springer International Publishing

Publication date 2003-03

Series/Journal name Journal of Geodesy Issue identification Volume 74, No. 1

Page 128–162

Information source Title Geodetic Reference System 1980

Author H. Moritz

Publisher International Association of Geodesy

Publication date 1984

Series/Journal name Bulletin Geodesique Issue identification Volume 58, No. 3

Page 395-405

Data source ISO Geodetic Registry

Remarks Adopted by IUGG 1979 Canberra. Inverse flattening is derived from

geocentric gravitational constant GM = 3986005e8 m*m*m/s/s, dynamic form factor J2 = 108263e-8 and Earth's angular velocity =

7292115e-11 rad/s.

Semi-major axis 6378137.0 m
Inverse flattening 298.257222101 m

Item class PrimeMeridian

Name Greenwich

Item status VALID
Identifier 25

Alias Zero meridian

Information source Title Why the Greenwich meridian moved

Author S. Malys, J.H. Seago, N.K. Pavlis, P.K.

Seidelmann, G.H. Kaplan

Publisher Springer International Publishing

Publication date 2015-12

Series/Journal name Journal of Geodesy Issue identification Volume 89, No. 12

Page 1263–1272

Information source Title IERS Conventions (2010)

Author G. Petit, B.J. Luzum (eds)

Publisher Verlag des Bundesamts fur Kartographie und

Geodasie

Publication date 2010

Edition date

Series/Journal name IERS Technical Notes

Issue identification 36.0

Other citation details ISSN: 1019-4568

Data source ISO Geodetic Registry

Greenwich longitude 0.0 °

CartesianCS Item class

Name Geocentric 3D right-handed Cartesian CS.

Axes: Geocentric X,Y,Z. Orientation: Z to North

Pole, [X and Y in the equatorial plane, X at

Prime Meridian | X in the equatorial plane at the

Prime Meridian]. UoM: m.

Item status **VALID** Identifier 45

Alias Earth centred, earth fixed, right-handed 3D coordinate system,

> consisting of 3 orthogonal axes with X and Y axes in the equatorial plane, positive Z-axis parallel to mean earth rotation axis and pointing

towards North Pole. UoM: m.

Alias **ECEF**

Information source Title ISO 19111 Geographical information - Spatial

referencing by coordinates

International Organization for Standardization Author

(ISO)

Publisher International Organization for Standardization

(ISO)

2007-07-01 Publication date Second Edition Edition Series/Journal name International Standard

Issue identification ISO 19111:2007

Data source ISO Geodetic Registry

Used in geocentric coordinate reference systems. Remarks

Axes

Item class CoordinateSystemAxis Name **Geocentric X** Item status **VALID** Identifier 33 Information source Title ISO 19111 Geographical information - Spatial referencing by coordinates Author International Organization for Standardization Publisher International Organization for Standardization (ISO) Publication date 2007-07-01 Edition Second Edition Series/Journal name International Standard Issue identification ISO 19111:2007 Data source ISO Geodetic Registry Abbreviation Χ Direction Geocentre > equator/0°E Unit metre

Item class CoordinateSystemAxis

Name **Geocentric Y**

VALID Item status Identifier 37

Information source Title ISO 19111 Geographical information - Spatial

referencing by coordinates

Author International Organization for Standardization

(ISO)

Publisher International Organization for Standardization

(ISO)

Publication date 2007-07-01

Edition Second Edition

Series/Journal name International Standard

Issue identification ISO 19111:2007

Data source ISO Geodetic Registry

Abbreviation Y

Direction Geocentre > equator/90°E

Unit metre

Item class CoordinateSystemAxis

Name Geocentric Z

Item statusVALIDIdentifier39

Information source Title ISO 19111 Geographical information - Spatial

referencing by coordinates

Author International Organization for Standardization

(ISO)

Publisher International Organization for Standardization

(ISO)

Publication date 2007-07-01

Edition Second Edition

Series/Journal name International Standard

Issue identification ISO 19111:2007

Data source ISO Geodetic Registry

Abbreviation Z

Direction Geocentre > north pole

Unit metre