### ISO Geodetic Registry

Item class Transformation

Name ITRF2020 to NAD83(CSRS) v8 [v1]

Item statusVALIDIdentifier995

Information source Title The Canadian Spatial Reference System (CSRS)

Author Canadian Geodetic Survey

Publisher Canadian Geodetic Survey, Surveyor General

Branch, Lands and Minerals Sector, Natural Resources Canada, Government of Canada

Revision date 2021-04-09

Other citation details Web page: http://www.nrcan.gc.ca/earth-

sciences/geomatics/geodetic-referencesystems/9052 (accessed 2023-06-04)

Information source Title Coordinate Transformations

Author Canadian Geodetic Survey

Publisher Canadian Geodetic Survey, Surveyor General Branch, Lands and Minerals Sector, Natural

Resources Canada, Government of Canada

Revision date 2022-04-29

Other citation details Web page: https://webapp.csrs-scrs.nrcan-

rncan.gc.ca/geod/data-donnees/

transformations.php (accessed 2023-06-04)

Information source Title transformations\_2010\_EN.zip

Author Canadian Geodetic Survey

Publisher Canadian Geodetic Survey

Canadian Geodetic Survey, Surveyor General

Branch, Lands and Minerals Sector, Natural Resources Canada, Government of Canada

Revision date 2022-10-07

Other citation details Transformation parameters file: https://

webapp.csrs-scrs.nrcan-rncan.gc.ca/geod/process/download-helper.php?

file\_id=NAD83toITRF\_EN (accessed 2023-06-04)

Information source Title National & International Reference Frames

Author M. Craymer

Publisher Canadian Geodetic Survey, Surveyor General

Branch, Lands and Minerals Sector, Natural Resources Canada, Government of Canada

Publication date 2023-05-10

Series/Journal name Presentation to Canadian Geodetic Reference

Systems Committee Meeting, Ottawa, May 10-12,

2023

Data source ISO Geodetic Registry

Remarks Transformation defines NAD83(CSRS) v8 and is treated as errorless.

Operation version v1

Scope Spatial referencing

Operation accuracy 0.0 m

Source CRS ITRF2020 - XYZ

Target CRS NAD83(CSRS) v8 - XYZ

Operation method Time-Dependent Position Vector Transformation (geocentric Cartesian

domain)

#### Extent

Canada - onshore and offshore - Alberta,
British Columbia, Manitoba, New Brunswick,

# **Newfoundland and Labrador, Northwest** Territories, Nova Scotia, Nunavut, Ontario, Prince Edward Island, Quebec, Saskatchewan,

Yukon.

Geographic Bounding Box West-bound longitude -141.01

> North-bound latitude 90.0 -47.74 East-bound longitude South-bound latitude 40.04

#### Operation parameter values

X-axis translation	1.0039 metre
Y-axis translation	-1.90961 metre
Z-axis translation	-0.54117 metre
X-axis rotation	-26.78138 milliarc-second
Y-axis rotation	0.42027 milliarc-second
<b>_</b>	40.00000 '!!!'

Z-axis rotation -10.93206 milliarc-second Scale difference -0.05109 parts per billion Rate of change of X-axis translation 7.9E-4 metre per year Rate of change of Y-axis translation -7.0E-4 metre per year Rate of change of Z-axis translation -0.00124 metre per year

Rate of change of X-axis rotation -0.06667 milliarc-second per year Rate of change of Y-axis rotation 0.75744 milliarc-second per year Rate of change of Z-axis rotation 0.05133 milliarc-second per year Rate of change of scale difference -0.07201 parts per billion per year

Time reference 2010.0 year

## **ISO Geodetic Registry**

Item class OperationMethod

Name Time-Dependent Position Vector

**Transformation (geocentric Cartesian domain)** 

Item status VALID Identifier 82

Alias Time-Dependent 7-Parameter Transformation

Alias 14-Parameter Transformation

Alias Time-Dependent Position Vector Transformation

Data source ISO Geodetic Registry

Remarks Note the analogy with the rotation for the Time-dependent Coordinate

Frame Transformation but beware of the differences! The Position

Vector Transformation convention is used by IAG.

Formula Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

### Operation parameters

X-axis translation

Y-axis translation

Z-axis translation

X-axis rotation

Y-axis rotation

Z-axis rotation

Scale difference

Rate of change of X-axis translation

Rate of change of Y-axis translation

Rate of change of Z-axis translation

Rate of change of X-axis rotation

Rate of change of Y-axis rotation

Rate of change of Z-axis rotation

Rate of change of scale difference

Time reference