## ISO Geodetic Registry

Item class Transformation

Name ITRF93 to ITRF94 [IERS v1]

Item statusVALIDIdentifier579

Information source Title IERS Conventions (2010)

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Publisher Verlag des Bundesamts fur Kartographie und

Geodasie

D.D. McCarthy

Publication date 2010

Edition date

Series/Journal name IERS Technical Notes

Issue identification 36.0

Other citation details ISSN: 1019-4568

Information source Title IERS Conventions (1992)

Author

Publisher Central Bureau of IERS - Observatoire de Paris,

61 avenue de l'Observatoire, 75014 Paris, France

Publication date 1996-07-01

Edition date

Series/Journal name IERS Technical Notes

Issue identification 21.0 ISO Geodetic Registry

Remarks Citation decribes the ITRF94 to ITRF93 transformation Accuracy of

transformation is given at the reference epoch for the transformation parameters. Accuracy at other epochs depends on the accuracies of the parameters at the reference epoch and their rates of change. Refer to citations for accuracies of the parameters and their rates of change.

Operation version IERS v1

Scope Spatial referencing

Operation accuracy 0.01 m

Source CRS ITRF93 - XYZ

Target CRS ITRF94 - XYZ

Operation method Time-Dependent Position Vector Transformation (geocentric Cartesian

domain)

#### Extent

Data source

Description	World.	
Geographic Bounding Box	West-bound longitude	-180.0
	North-bound latitude	90.0
	East-bound longitude	180.0
	South-bound latitude	-90.0

#### Operation parameter values

Time reference 1988.0 year

Rate of change of scale difference 0.0 parts per billion per year

Rate of change of Z-axis rotation -0.05 milliarc-second per year

Rate of change of Y-axis rotation 0.19 milliarc-second per year

Rate of change of X-axis rotation 0.11 milliarc-second per year

Rate of change of Z-axis translation -0.08 centimetre per year

Rate of change of Y-axis translation -0.04 centimetre per year

Rate of change of X-axis translation	0.29 centimetre per year	
Scale difference	-0.4 parts per billion	
Z-axis rotation	0.96 milliarc-second	
Y-axis rotation	-0.8 milliarc-second	
X-axis rotation	0.39 milliarc-second	
Z-axis translation	1.5 centimetre	
Y-axis translation	0.5 centimetre	
X-axis translation	-0.6 centimetre	

# **ISO Geodetic Registry**

Item class OperationMethod

Name Time-Dependent Position Vector

**Transformation (geocentric Cartesian domain)** 

Item status VALID Identifier 82

Alias Time-Dependent 7-Parameter Transformation

Alias 14-Parameter Transformation

Alias Time-Dependent Position Vector Transformation

Data source ISO Geodetic Registry

Remarks Note the analogy with the rotation for the Time-dependent Coordinate

Frame Transformation but beware of the differences! The Position

Vector Transformation convention is used by IAG.

Formula Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

### Operation parameters

X-axis translation

Y-axis translation

Z-axis translation

X-axis rotation

Y-axis rotation

Z-axis rotation

Scale difference

Rate of change of X-axis translation

Rate of change of Y-axis translation

Rate of change of Z-axis translation

Rate of change of X-axis rotation

Rate of change of Y-axis rotation

Rate of change of Z-axis rotation

Rate of change of scale difference

Time reference