ISO Geodetic Registry

Item class Transformation

Name WGS 84 (G1762) to WGS 84 (G2139) [1]

Item statusVALIDIdentifier800

Information source Title Recent Update to WGS 84 Reference Frame and

NGA Transition to IGS ANTEX

Author Office of Geomatics / GNSS Division, National

Geospatial-Intelligence Agency

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file=(U)WGS%2084(G2139).pdf (accessed

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Information source Title Personal communication

Author Robert Wong

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Data source ISO Geodetic Registry

Remarks Transformation between WGS 84 ephemerides, derived at epoch

2016.0.

Operation version 1.0

Scope Spatial referencing and GPS satellite navigation.

Operation accuracy 0.01 m

 Source CRS
 WGS 84 (G1762) - XYZ

 Target CRS
 WGS 84 (G2139) - XYZ

Operation method Coordinate Frame Transformation (geocentric Cartesian domain)

Extent

Description	World	
Geographic Bounding Box	West-bound longitude	-180.0
	North-bound latitude	90.0
	East-bound longitude	180.0
	South-bound latitude	-90.0

Operation parameter values

X-axis translation	0.0058 metre	
Y-axis translation	-0.0064 metre	
Z-axis translation	0.007 metre	
X-axis rotation	0.08 milliarc-second	
Y-axis rotation	0.04 milliarc-second	
Z-axis rotation	0.12 milliarc-second	
Scale difference	-4.4 parts per billion	

ISO Geodetic Registry

Item class OperationMethod

Name Coordinate Frame Transformation (geocentric

Cartesian domain)

Item status VALID Identifier 74

Alias Coordinate Frame Transformation

Alias 7-Parameter Transformation

Alias Bursa-Wolf Transformation

Data source ISO Geodetic Registry

Remarks This method is a specific case of the Molodensky-Badekas (CF)

method in which the evaluation point is at the geocentre with

coordinate values of zero. Note the analogy with the Position Vector

transformation method but beware of the differences!

Formula Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

Operation parameters

X-axis translation
Y-axis translation
Z-axis translation
X-axis rotation
Y-axis rotation
Z-axis rotation
Scale difference