# **ISO Geodetic Registry**

Item class Transformation

Name ITRF94 to ITRF96 [IERS v1]

Item status **VALID** Identifier 685

Information source Title Results and analysis of ITRF96 C. Boucher, Z. Altamimi, P. Sillard Author

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Remarks Null transformation. ITRF96 is aligned to ITRF94.

Operation version IERS v1

Scope Spatial referencing

0.0 m Operation accuracy

Source CRS ITRF94 - XYZ Target CRS ITRF96 - XYZ

Operation method Time-Dependent Position Vector Transformation (geocentric Cartesian

domain)

#### Extent

Data source

Description	World.	
Geographic Bounding Box	West-bound longitude	-180.0
	North-bound latitude	90.0
	East-bound longitude	180.0
	South-bound latitude	-90.0

### Operation parameter values

Time reference	1988.0 year
Rate of change of scale difference	0.0 parts per billion per year
Rate of change of Z-axis rotation	0.0 milliarc-second per year
Rate of change of Y-axis rotation	0.0 milliarc-second per year
Rate of change of X-axis rotation	0.0 milliarc-second per year
Rate of change of Z-axis translation	0.0 centimetre per year
Rate of change of Y-axis translation	0.0 centimetre per year
Rate of change of X-axis translation	0.0 centimetre per year
Scale difference	0.0 parts per billion
Z-axis rotation	0.0 milliarc-second
Y-axis rotation	0.0 milliarc-second
X-axis rotation	0.0 milliarc-second
Z-axis translation	0.0 centimetre
Y-axis translation	0.0 centimetre
X-axis translation	0.0 centimetre

## **ISO Geodetic Registry**

Item class OperationMethod

Name Time-Dependent Position Vector

**Transformation (geocentric Cartesian domain)** 

Item statusVALIDIdentifier82

Alias Time-Dependent 7-Parameter Transformation

Alias 14-Parameter Transformation

Alias Time-Dependent Position Vector Transformation

Data source ISO Geodetic Registry

Remarks Note the analogy with the rotation for the Time-dependent Coordinate

Frame Transformation but beware of the differences! The Position

Vector Transformation convention is used by IAG.

Formula Geomatics Guidance Note No 7, part 2: Coordinate Conversions and

Transformations including Formulas

#### Operation parameters

X-axis translation

Y-axis translation

Z-axis translation

X-axis rotation

Y-axis rotation

Z-axis rotation

Scale difference

Rate of change of X-axis translation

Rate of change of Y-axis translation

Rate of change of Z-axis translation

Rate of change of X-axis rotation

Rate of change of Y-axis rotation

Rate of change of Z-axis rotation

Rate of change of scale difference

Time reference