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% Pierce Zhang, CMOR220, FALL 2023, Competency functions and drivers
% functions_and_drivers.m
% Answers to functions and drivers competency questions
% Last modified: August 26, 2023

% Driver to answer the questions
function functions_and_drivers
    % Problem 1
    [y1] = harm(1,2)
    [y2] = harm(2,4)
    [y3] = harm(3,6)

    % Problem 2
    [sinout1, cosout1, tanout1] = trigs(pi / 3)
    [sinout2, cosout2, tanout2] = trigs(pi / 6)

    % Problem 3
    [x1, x2] = quad(1/3, 5, 3)

    % Problem 4
    H = 0.00344; A = 0.00344; HA = 0.66;
    [Ka, pKa, G] = equil(H, A, HA)

    % Problem 5
    lineqs(-2, 8, 3, 6);
end

% Inputs: a, the amplitude, and t, the time of the simple harmonic motion
% equation
% Outputs: y, the value of the function given a and t
function [y] = harm(a, t)
    % This function will output the value of a simple harmonic motion
    % function for a given amplitude and time, with angular frequency set
    % to 3 and y-offset to +4.
    y = a * sin(3 * t) + 4;
end

% Inputs: x, the input angle in radians
% Outputs: sinout, the value of sin(x), cosout, the value of cos(x), and
% tanout, the value of tan(x)
function [sinout, cosout, tanout] = trigs(x)
    sinout = sin(x);
    cosout = cos(x);
    tanout = tan(x);
end

% Inputs: coefficients a, b, and c, of a second-degree polynomial
% Outputs: x1 and x2, the roots of said polynomial
function [x1, x2] = quad(a, b, c)
    det = sqrt(b^2 - 4*a*c);
    x1 = (-b + det) / (2 * a);
    x2 = (-b - det) / (2 * a);

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end

% Inputs: H, the molar concentration of protons in solution, A, the molar concentration of CH<sub>3</sub>COO<sup>-</sup>, and HA, the molar concentration of acetic acid (all prior to reaction).

% Outputs: Ka, the value of the equilibrium constant, pKa, the "power" of the equilibrium constant, and G, the Gibbs free energy of dissociation

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function [Ka, pKa, G] = equil(H, A, HA)
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    R = 8.1345; % units J / K
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    T = 298;
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    Ka = H * A / HA;
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    pKa = -log10(Ka);
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    G = -R * T * log(Ka);
```

end

% Inputs: x1, y1, the coordinates of the first point, and x2, y2, the

% coordinates of the second

% Outputs: (function does not return a value) a printout of the equations

% of the line that passes through (x1, y1) and (x2, y2) in both point-slope

% and slope-intercept form.

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function lineqs(x1, y1, x2, y2)
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    m = (y2 - y1) / (x2 - x1);
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    disp("y - (" + y1 + ") = (" + m + ")(x - (" + x1 + "))");
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```
    disp("y = (" + m + ")x + (" + (-m * x1 + y1) + ")");
```

end

y1 =

3.7206

y2 =

2.9269

y3 =

1.7470

sinout1 =

0.8660

cosout1 =

0.5000

tanout1 =

---

1.7321

*sinout2* =

0.5000

*cosout2* =

0.8660

*tanout2* =

0.5774

*x1* =

-0.6261

*x2* =

-14.3739

*Ka* =

1.7930e-05

*pKa* =

4.7464

*G* =

2.6493e+04

$y - (8) = (-0.4)(x - (-2))$

$y = (-0.4)x + (7.2)$

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