

a) kap 7.4
 $y_a, h(t) = 0 \text{ di } t < 0$

b) kap 7.6
 definitionen för stegsvaret för δ :
 $s(t) = \int_{-\infty}^t h(\tau) d\tau \Leftrightarrow$

$$\Leftrightarrow s(t) = \int_0^t e^{-2\tau} d\tau \theta(t) \Leftrightarrow$$

$$\Rightarrow s(t) = \left[-\frac{1}{2} e^{-2\tau} \right]_0^t \cdot \theta(t) \Leftrightarrow$$

$$\Leftrightarrow s(t) = \left(-\frac{1}{2} e^{-2t} + \frac{1}{2} \right) \theta(t) = \frac{1}{2} (1 - e^{-2t}) \theta(t)$$

$$\underline{s(0) = \frac{1}{2} (1 - e^{-2t})}$$

c) kap 7.7
 $h(h)(s) = \frac{1}{s+2}$

d) kap 7.5
 systemet är stabilt di $\int_{-\infty}^{\infty} |h(t)| dt =$

$$= \int_{-\infty}^{\infty} e^{-2t} \theta(t) dt = \begin{cases} \int_0^{\infty} e^{-2t} dt, & t \geq 0 \\ 0, & t < 0 \end{cases} \Rightarrow$$

$$\Rightarrow \int_0^{\infty} e^{-2t} dt = \frac{1}{2} [-e^{-2t}]_0^{\infty} = \underline{\underline{\frac{1}{2}}} \text{ (konvergent)}$$

e) kap 7.8
 $\underline{H(i\omega) = \frac{1}{i\omega + 2}}$

f) $\text{im}(H(i2) \cdot e^{i2t})$

$$H(i2) = \frac{1}{i2 + 2} = \frac{1}{(i2 + 2)(2 - 2i)} =$$

$$= \frac{2(1-i)}{2^2 - (2i)^2} = \frac{1-i}{4} = \frac{1}{4} - \frac{i}{4} =$$

$$= \frac{\sqrt{2}}{4} \left(\frac{1}{\sqrt{2}} - \frac{i}{\sqrt{2}} \right) = \frac{\sqrt{2}}{4} e^{-i\pi/4}$$

$$\text{im} \left(\frac{\sqrt{2}}{4} e^{-i\pi/4} \cdot e^{i2t} \right) =$$

$$= \text{im} \left(\frac{\sqrt{2}}{4} e^{i(2t - \pi/4)} \right) =$$

$$= \underline{\underline{\frac{\sqrt{2}}{4} \sin(2t - \pi/4)}}$$

g) $H(s) \cdot L(f) = \frac{1}{s+2} \cdot \frac{2}{s^2 + 2^2} =$
 $= \frac{2}{(s+2)(s^2+4)} = \frac{A}{s+2} + \frac{Bs+C}{s^2+4} =$
 $= \frac{1}{4} \frac{1}{s+2} + \frac{1}{4} \cdot \frac{2-s}{s^2+4} = \underbrace{\frac{1}{4} \frac{1}{s+2}}_{Z(s)} + \underbrace{\frac{1}{4} \frac{2}{s^2+2^2}}_{F(s)} - \underbrace{\frac{1}{4} \frac{s}{s^2+2^2}}_{G(s)}$

$$z(t) = \frac{1}{4} \cdot e^{-2t} \theta(t)$$

$$f(t) = \frac{1}{4} \sin 2t \theta(t)$$

$$g(t) = \frac{1}{4} \cos 2t \theta(t)$$

$$\underline{\underline{y(t) = \frac{1}{4} (e^{-2t} + \sin 2t - \cos 2t) \theta(t)}}$$